

# CSC 226

Algorithms and Data Structures: II

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ECS 516

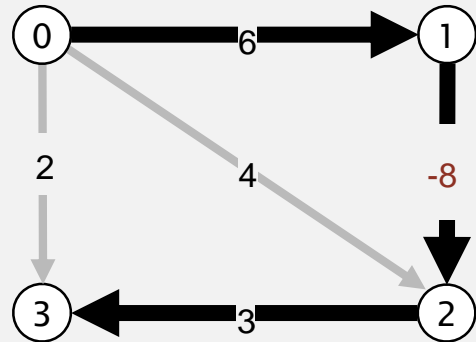
# Question

- When solving the single source shortest path problem using Dijkstra's algorithm for an undirected graph with positive edge weights, the paths found result in a spanning tree  $T$ .
- Is  $T$  a minimum spanning tree for  $G$ ?

## Shortest paths with negative weights: failed attempts

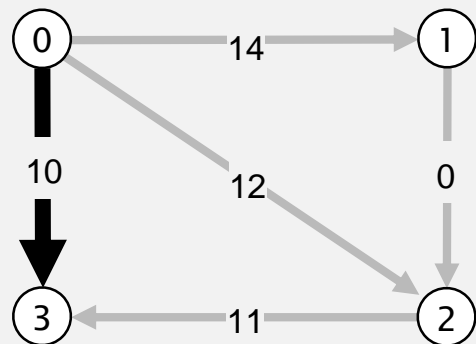
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Dijkstra. Doesn't work with negative edge weights.



Dijkstra selects vertex 3 immediately after 0.  
But shortest path from 0 to 3 is  $0 \rightarrow 1 \rightarrow 2 \rightarrow 3$ .

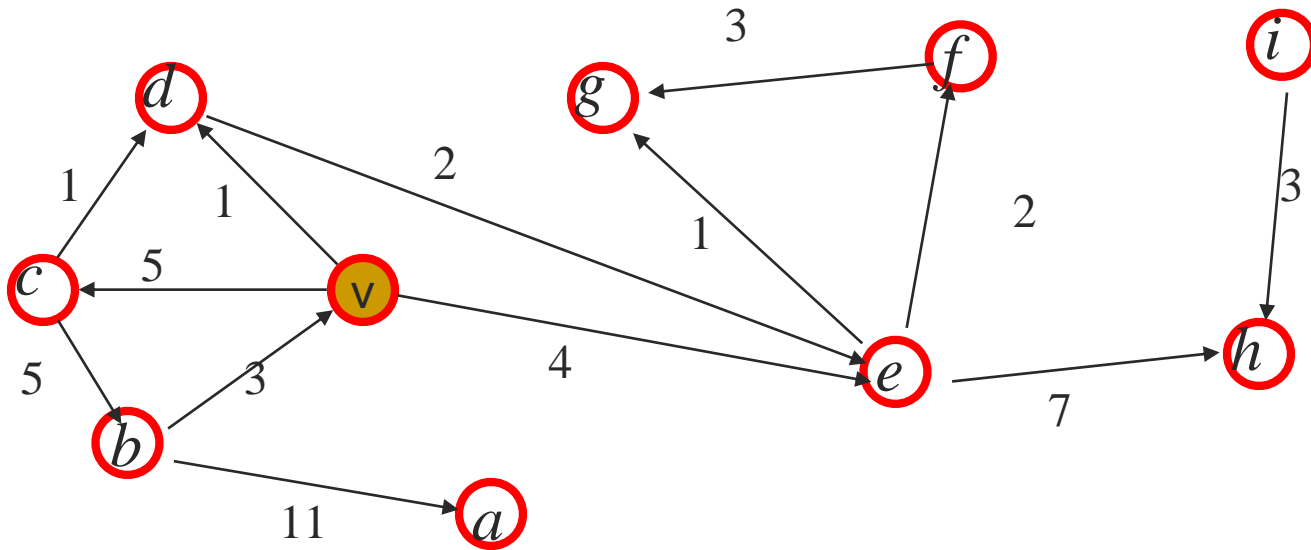
Re-weighting. Add a constant to every edge weight doesn't work.



Adding 8 to each edge weight changes the  
shortest path from  $0 \rightarrow 1 \rightarrow 2 \rightarrow 3$  to  $0 \rightarrow 3$ .

Conclusion. Need a different algorithm.

# Directed graphs with positive edge weights



Does Dijkstra's algorithm work?

# Single source shortest paths for *directed* graphs with positive edge weights

- Dijkstra's algorithm works without changes except here edges are directed, that is  $(a,b) \neq (b,a)$
- The big-oh worst case running time remains the same

# Dijkstra's algorithm: Java implementation

```
public class DijkstraSP
{
    private DirectedEdge[] edgeTo;
    private double[] distTo;
    private IndexMinPQ<Double> pq;

    public DijkstraSP(EdgeWeightedDigraph G, int s)
    {
        edgeTo = new DirectedEdge[G.V()];
        distTo = new double[G.V()];
        pq = new IndexMinPQ<Double>(G.V());

        for (int v = 0; v < G.V(); v++)
            distTo[v] = Double.POSITIVE_INFINITY;
        distTo[s] = 0.0;

        pq.insert(s, 0.0);
        while (!pq.isEmpty())
        {
            int v = pq.delMin();
            for (DirectedEdge e : G.adj(v))
                relax(e);
        }
    }
}
```

← relax vertices in order  
of distance from s

## Dijkstra's algorithm: Java implementation

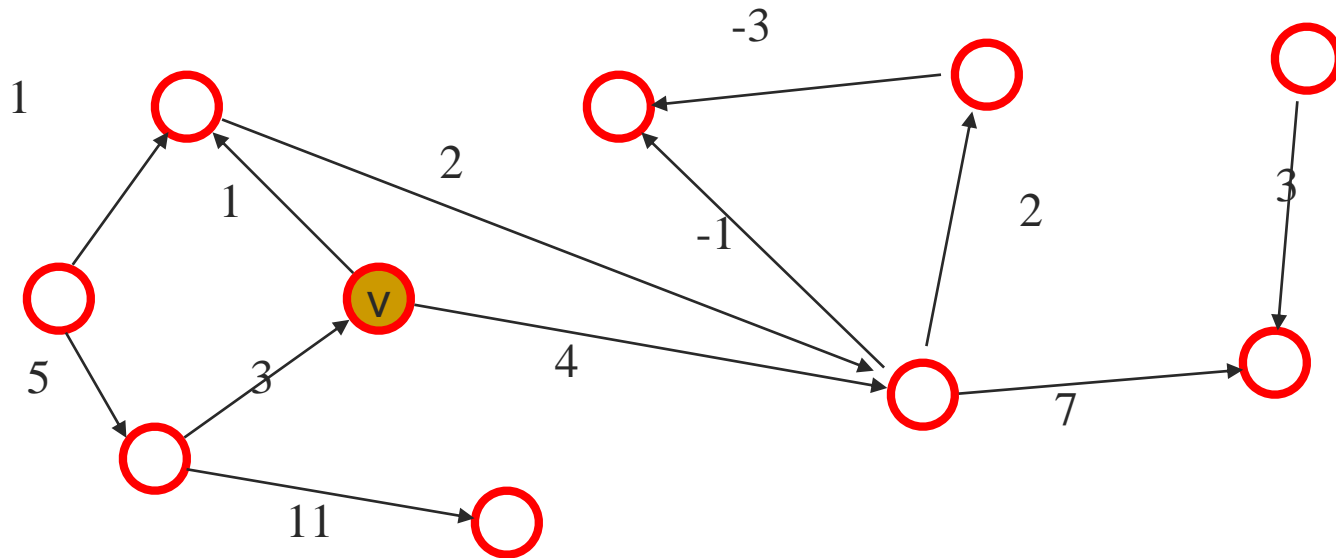
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```
private void relax(DirectedEdge e)
{
    int v = e.from(), w = e.to();
    if (distTo[w] > distTo[v] + e.weight())
    {
        distTo[w] = distTo[v] + e.weight();
        edgeTo[w] = e;
        if (pq.contains(w)) pq.decreaseKey(w, distTo[w]);
        else                pq.insert (w, distTo[w]);
    }
}
```

← update PQ

# Shortest paths in graphs containing *negative* edges

- Not possible for undirected graphs
- What about directed graphs?





# Negative edges and negative-weight cycles

- If  $G$  is directed, compute single-source shortest path problem using Bellman-Ford shortest path algorithm
- Negative-weight cycles are discovered

# Algorithm Bellman-Ford( $G, v$ )

- Input:** A simple undirected graph  $G$  with nonnegative edge-weights, a distinguished vertex  $v$  in  $G$
- Output:** A label  $D[u]$  for each vertex  $u$  in  $G$  such that  $D[u]$  is the distance from  $v$  to  $u$  in  $G$ .

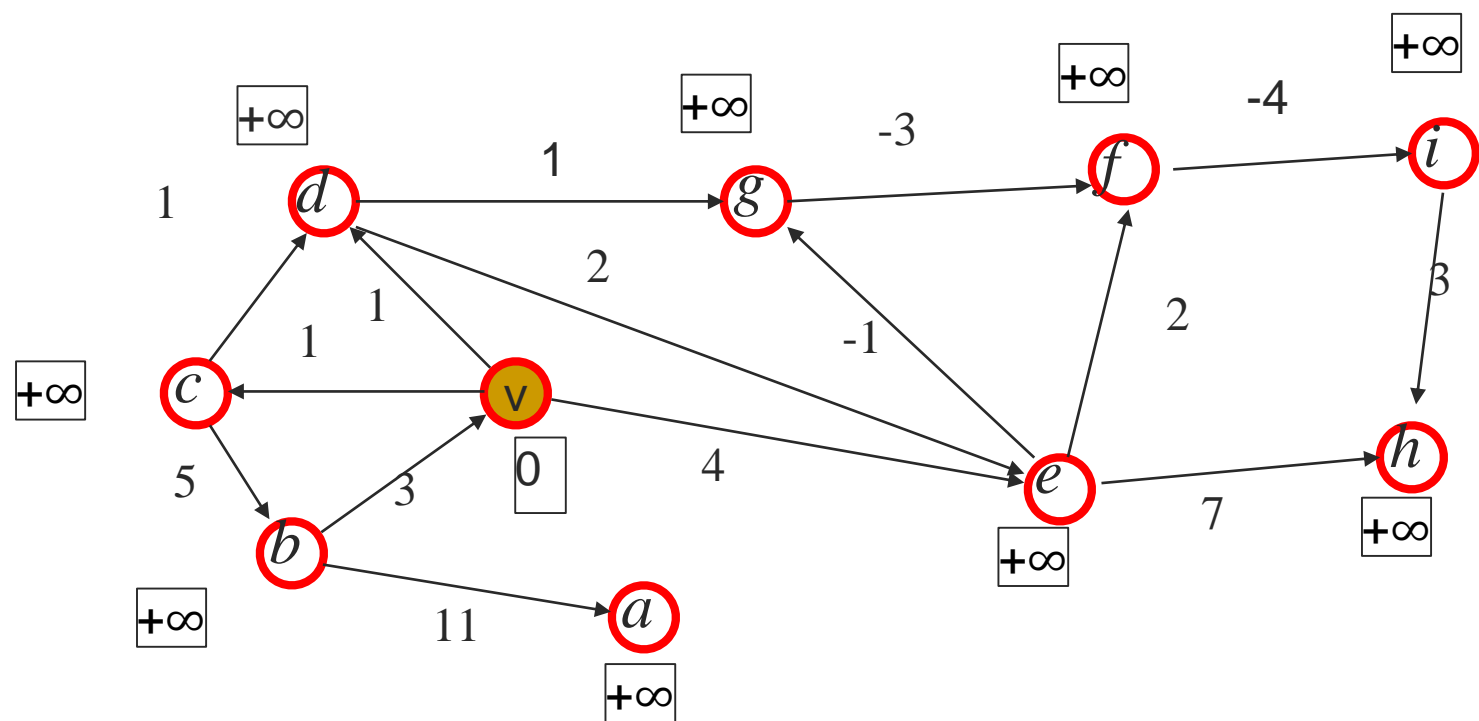
# Algorithm Bellman-Ford( $G, v$ )



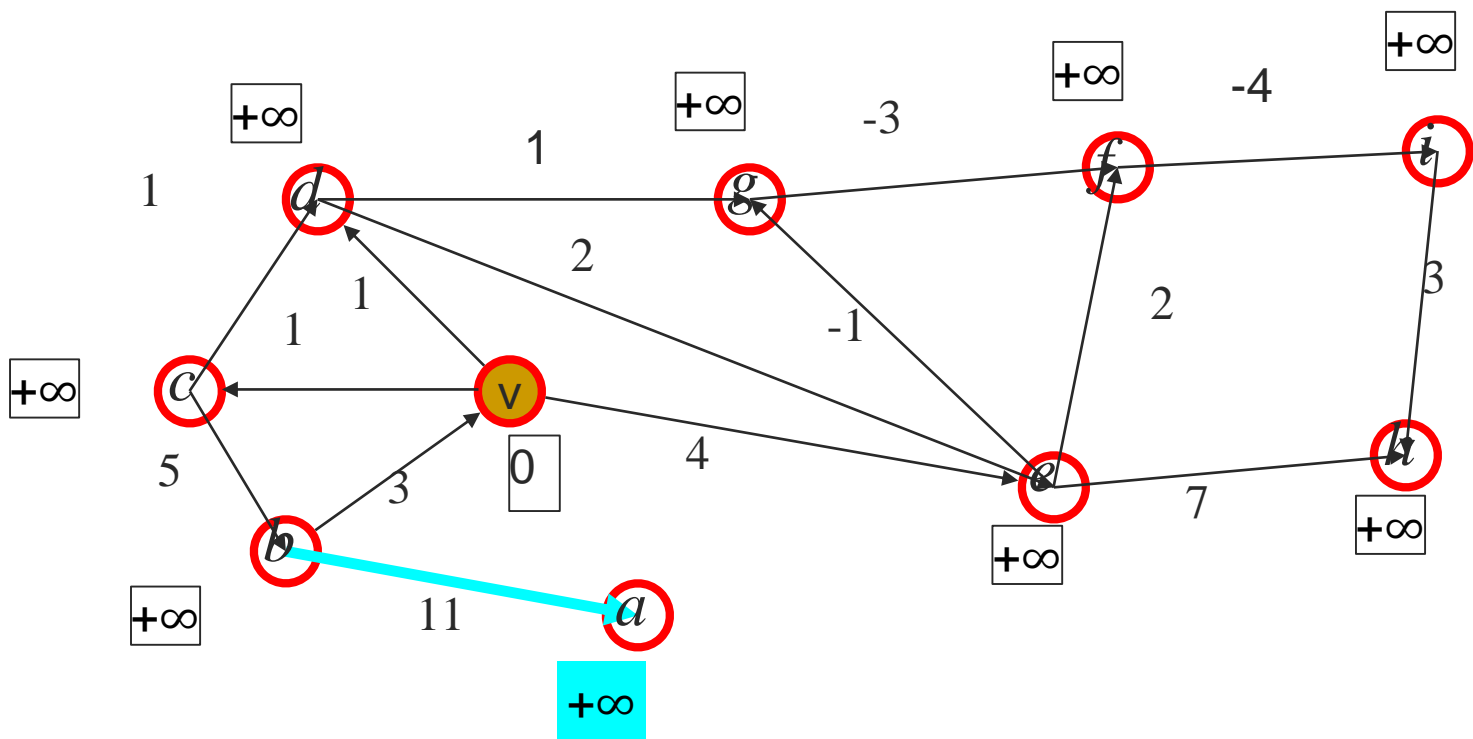
```
D[v] ← 0
for each vertex u ≠ v of G do
    D[u] ← +∞
for i ← 1 to n-1 do
    for each edge (u,z) in G do
        if D[u] + w((u,z)) < D[z] then
            D[z] ← D[u] + w((u,z))
if there are no edges left with potential
relaxation operations then
    return D
else
    return "G contains a negative cycle"
```

performs  $n-1$   
times a  
relaxation of  
every edge  
in the graph

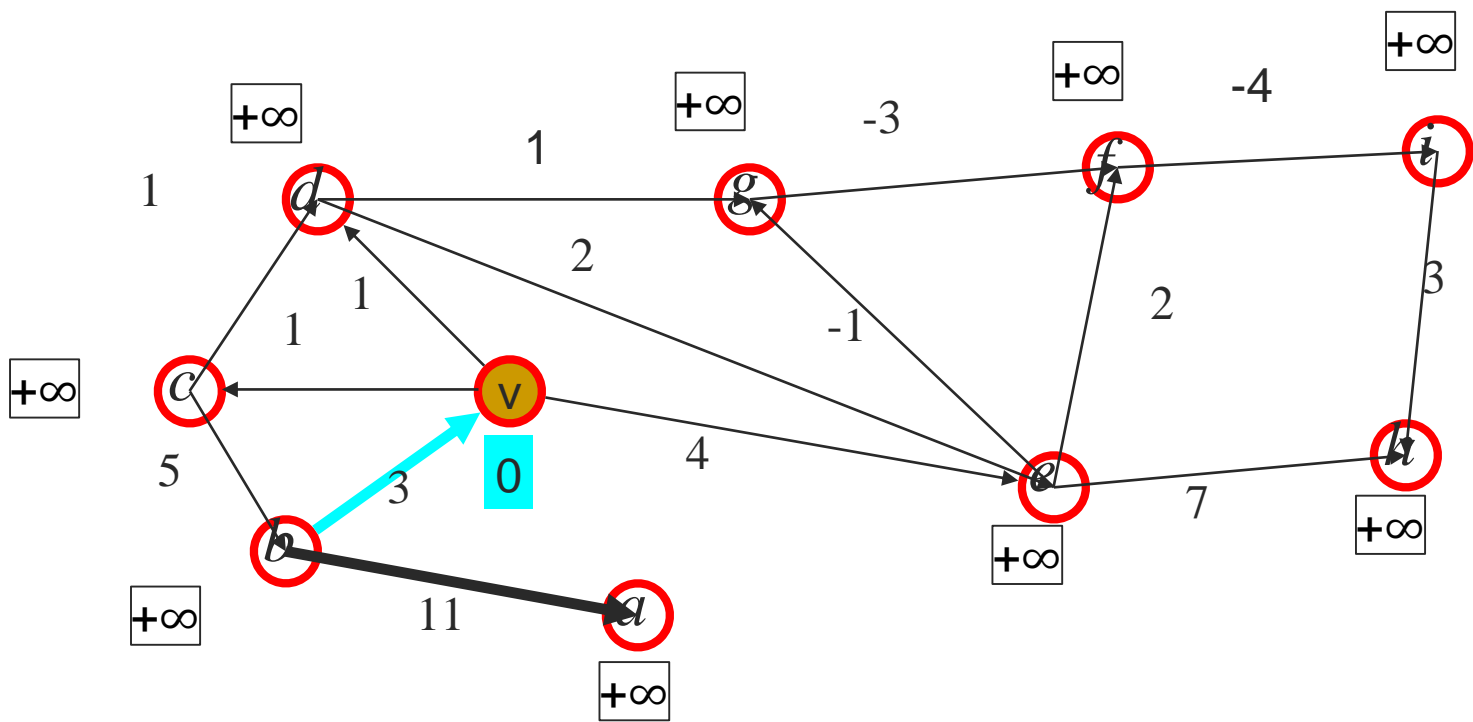
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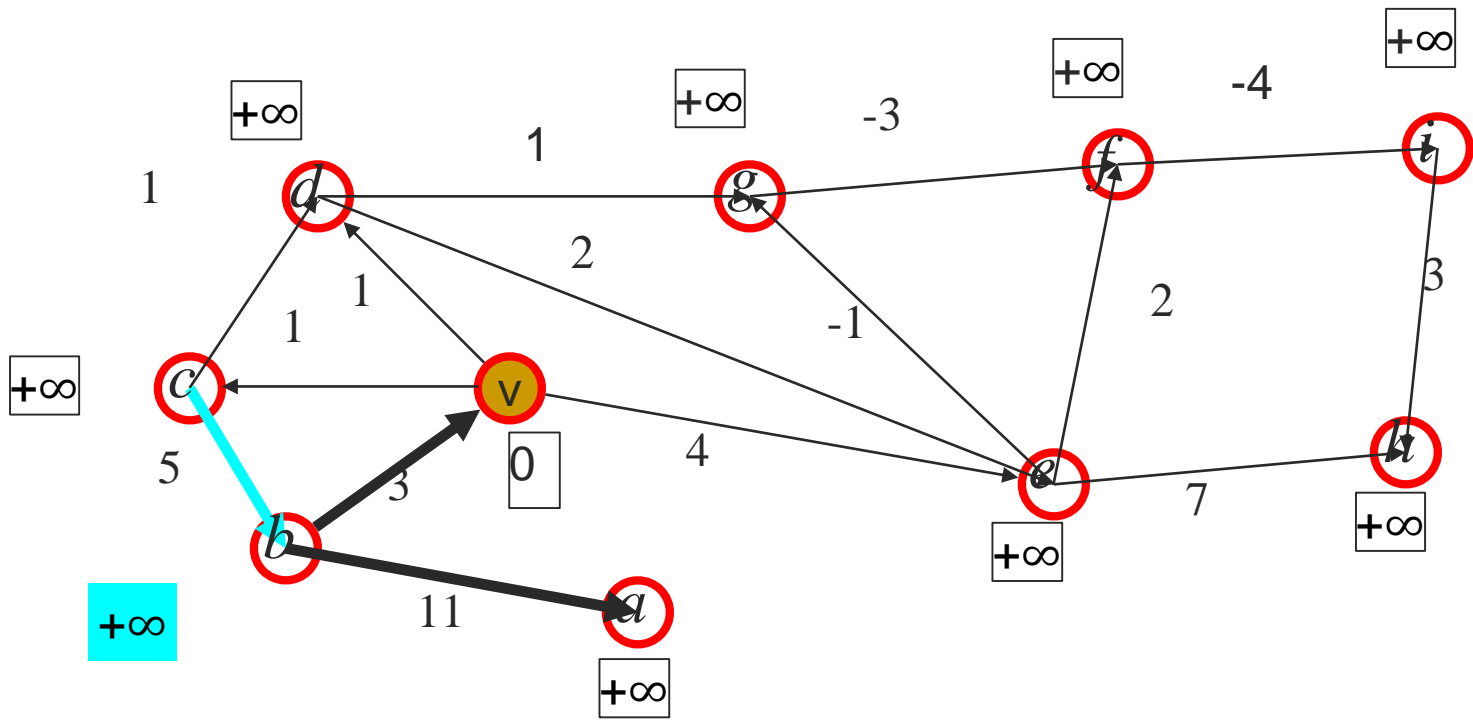
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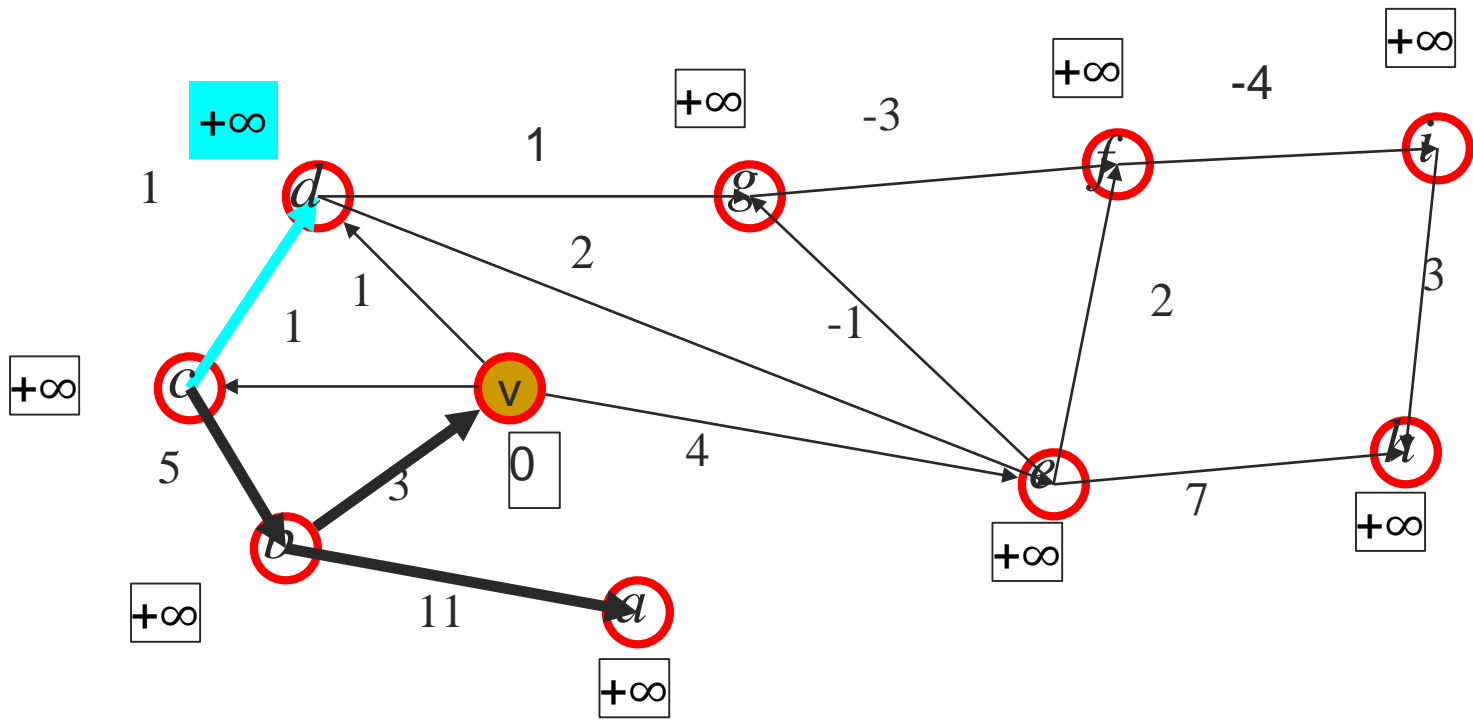
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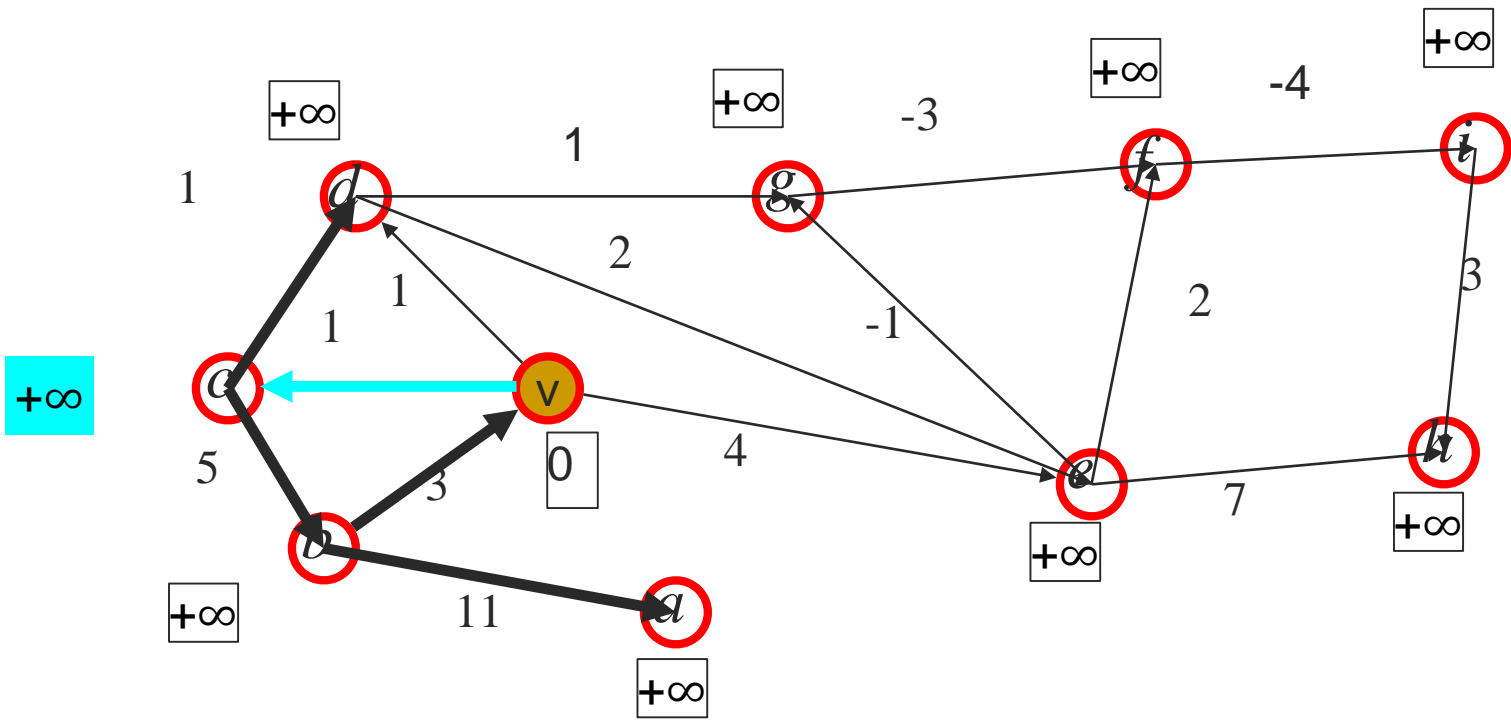


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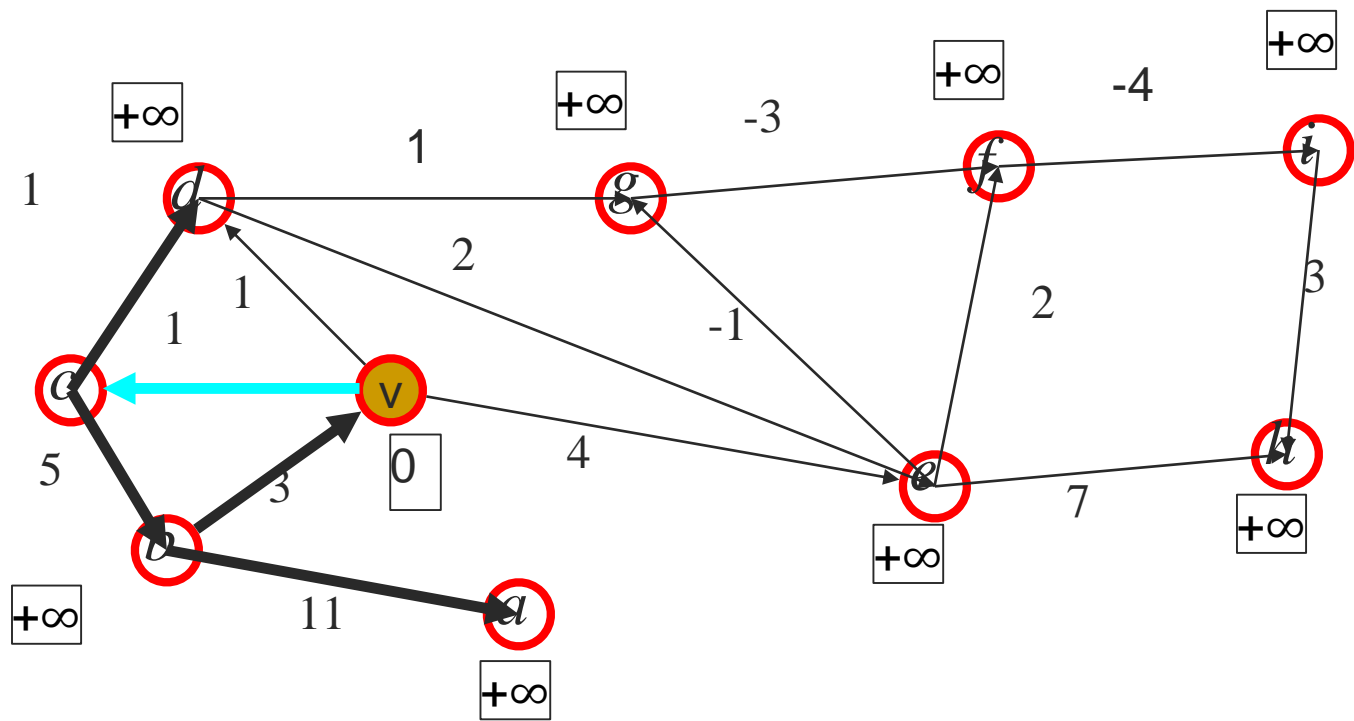


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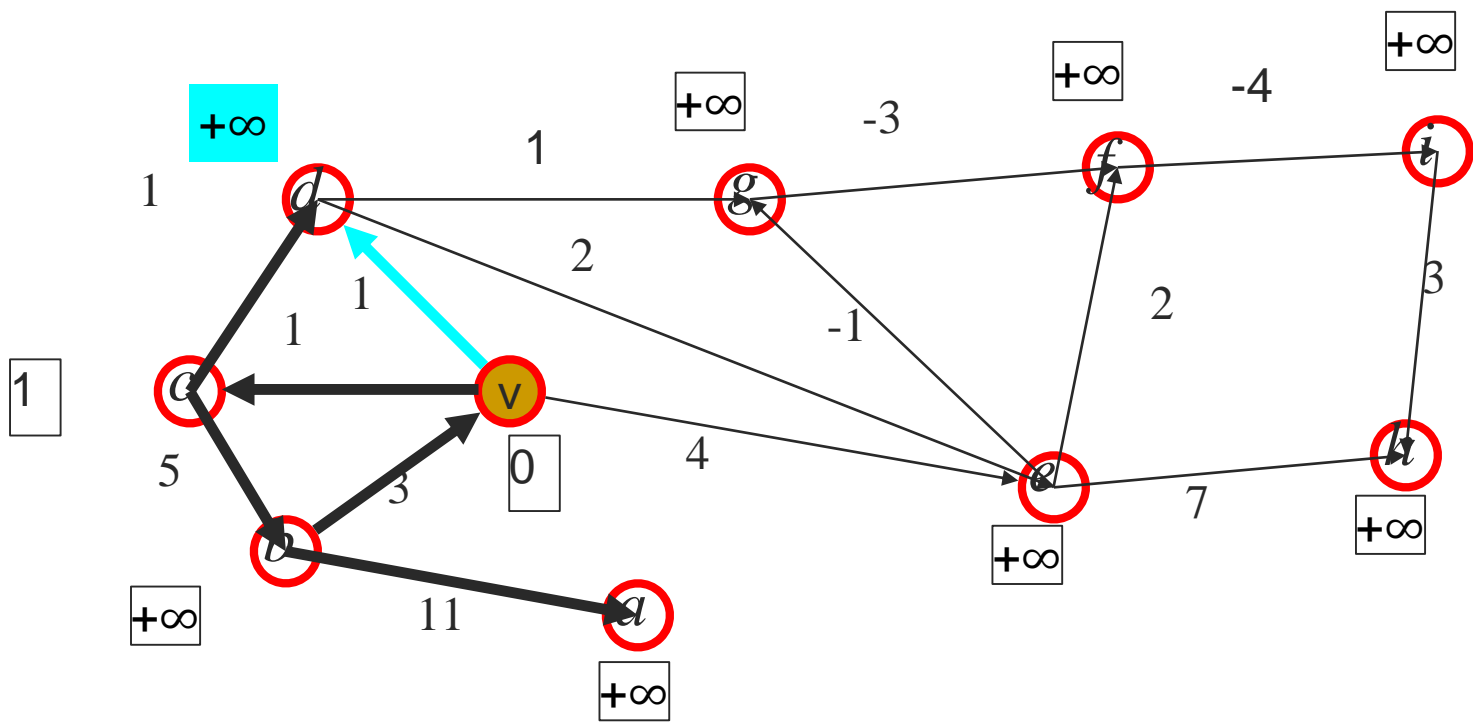


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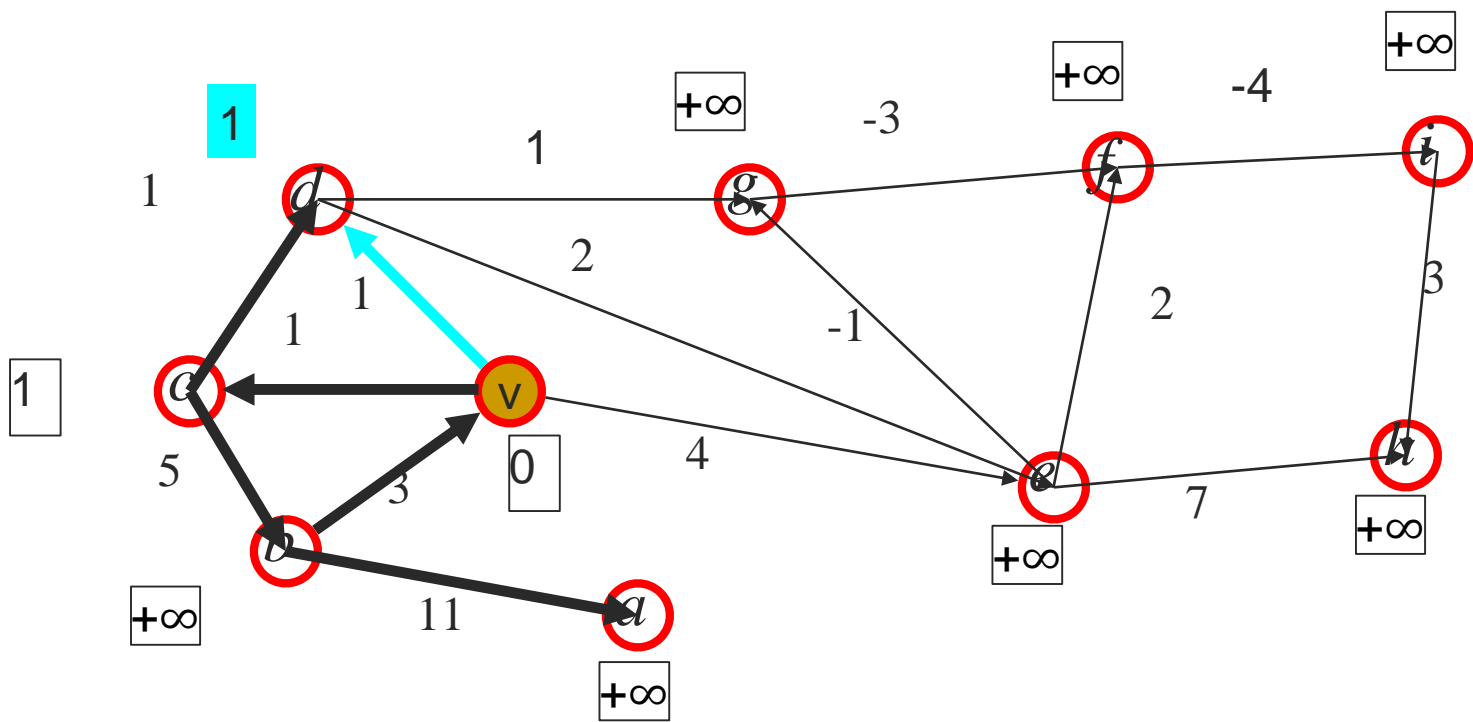
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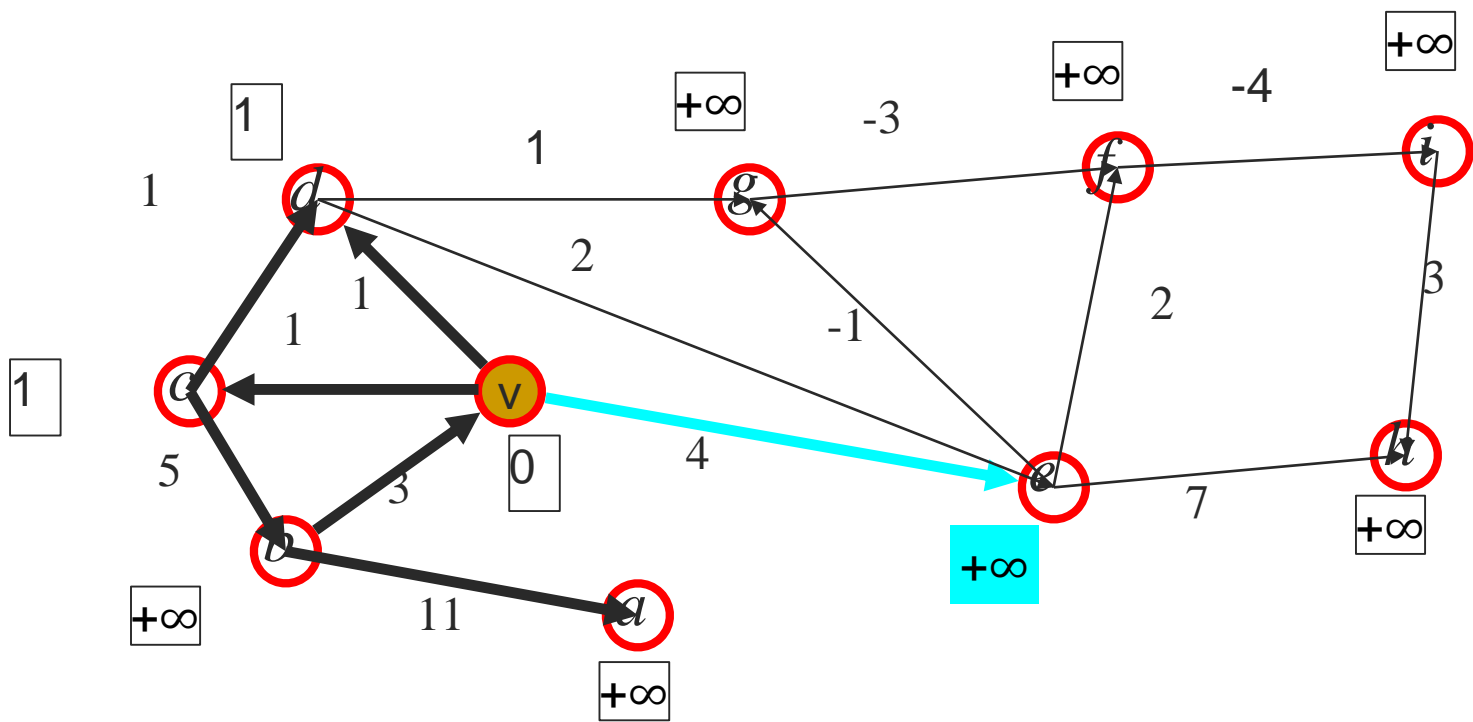
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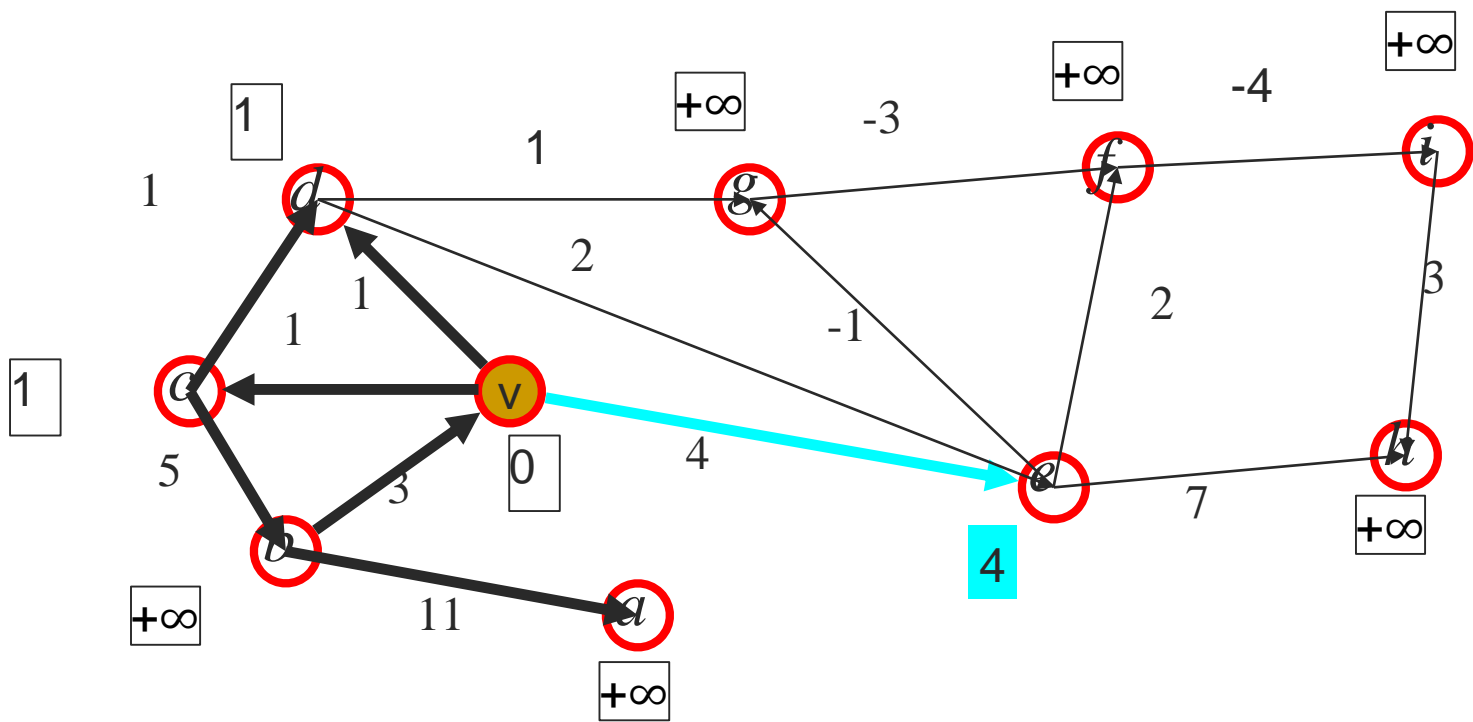
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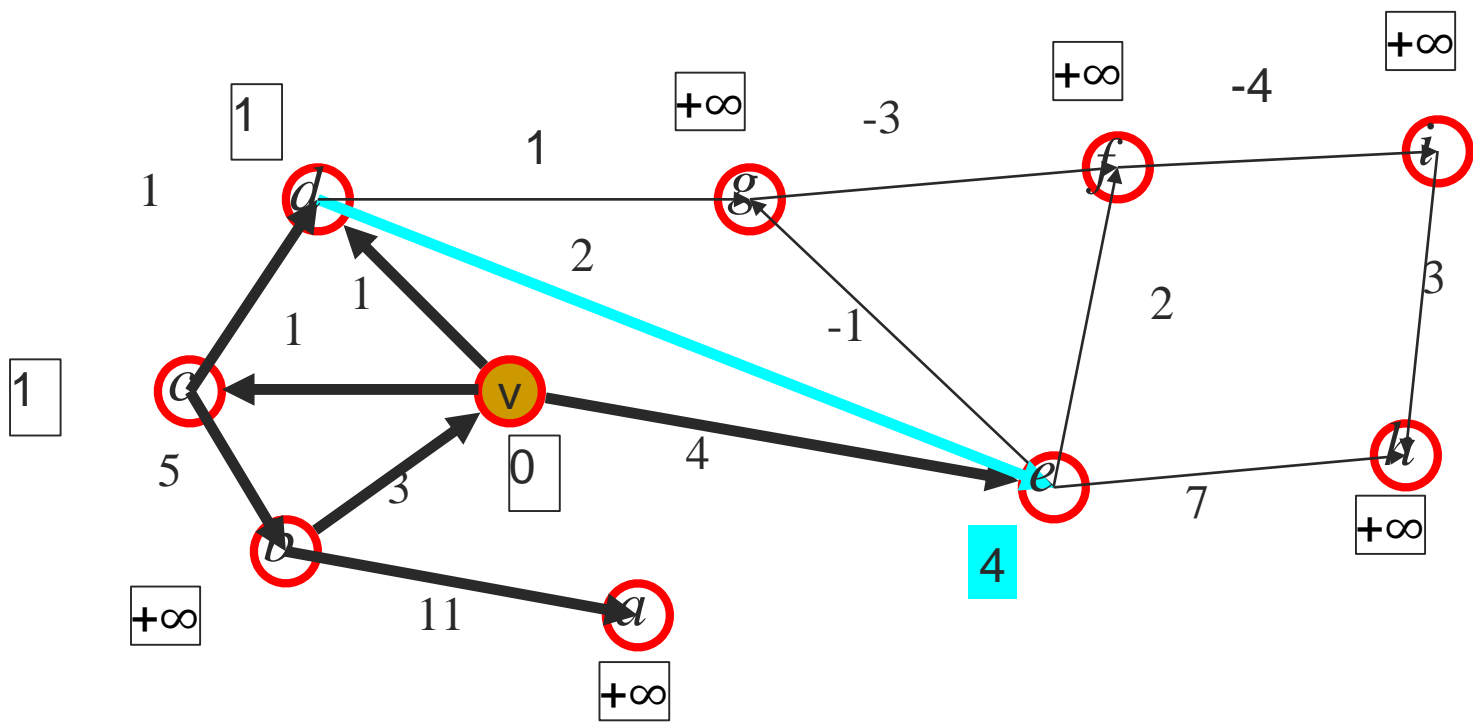
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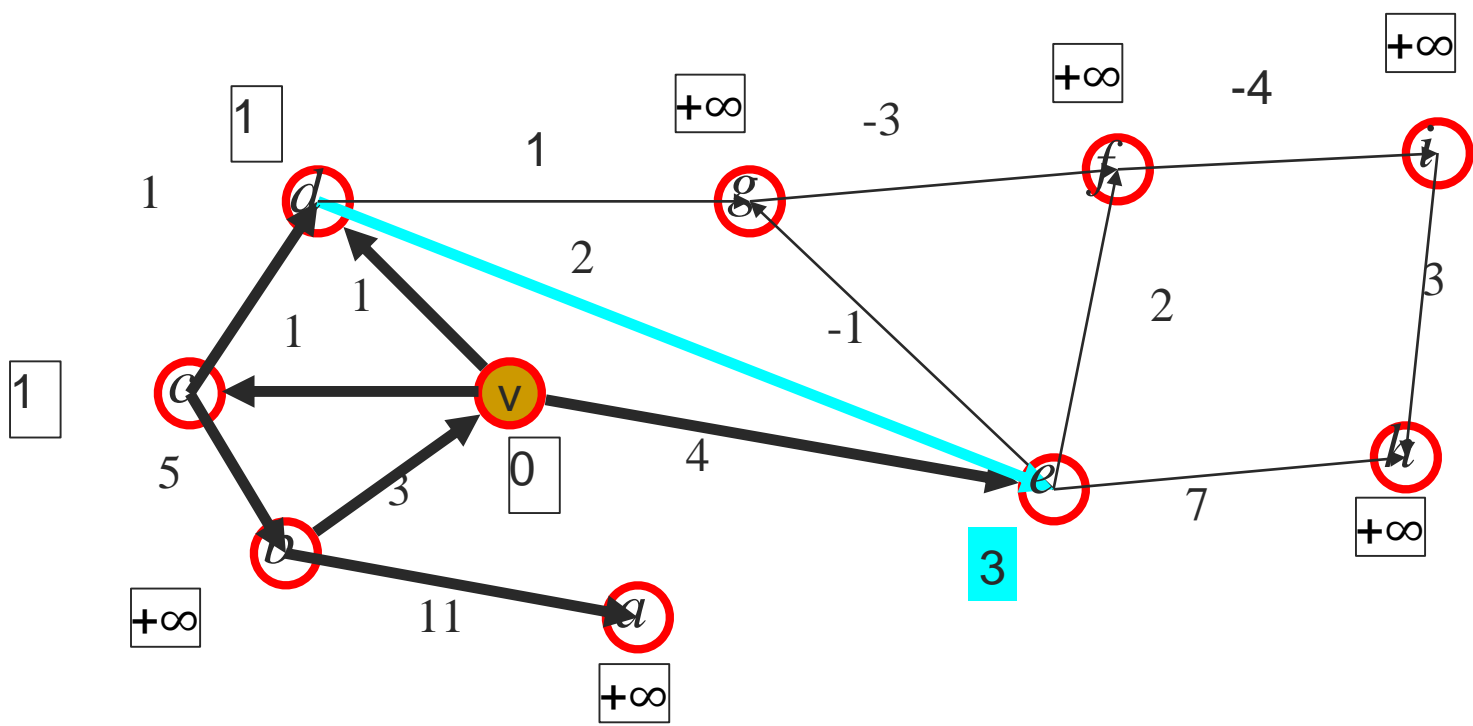
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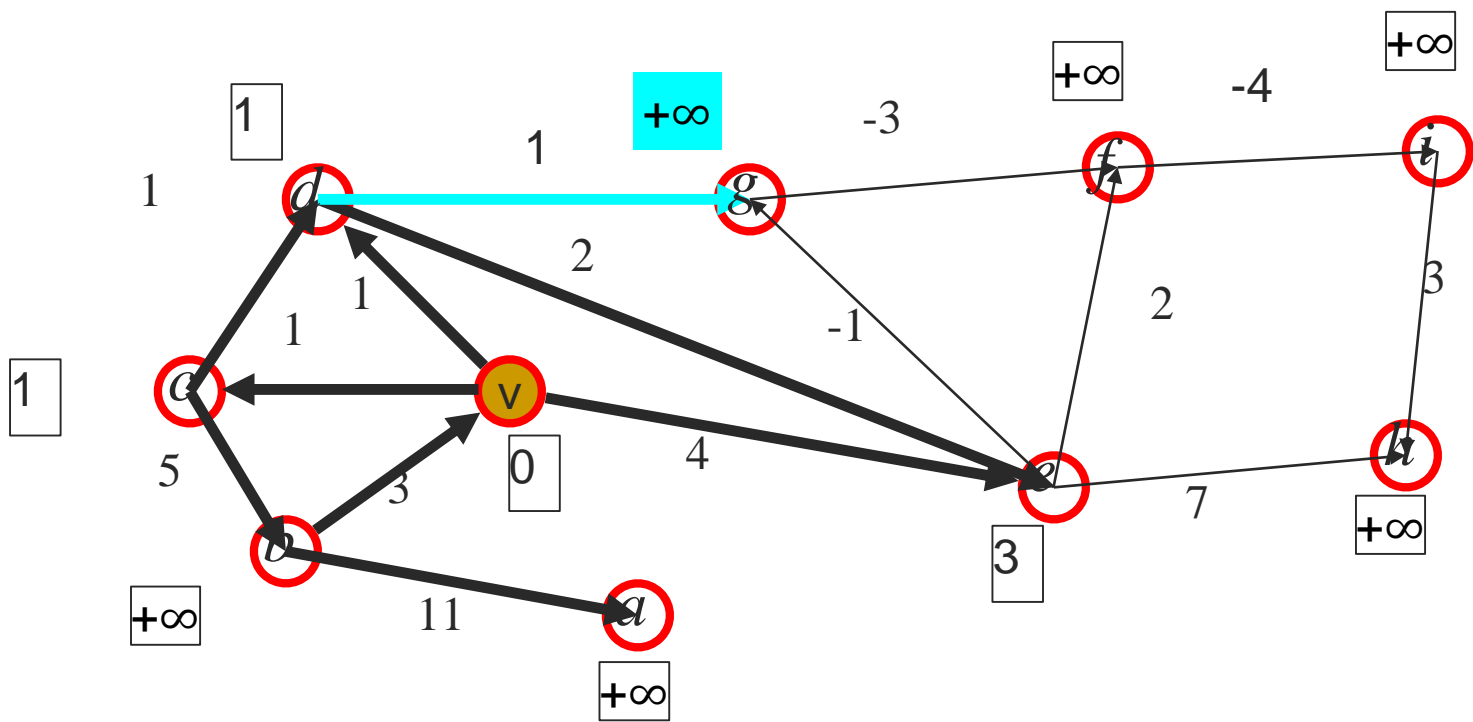


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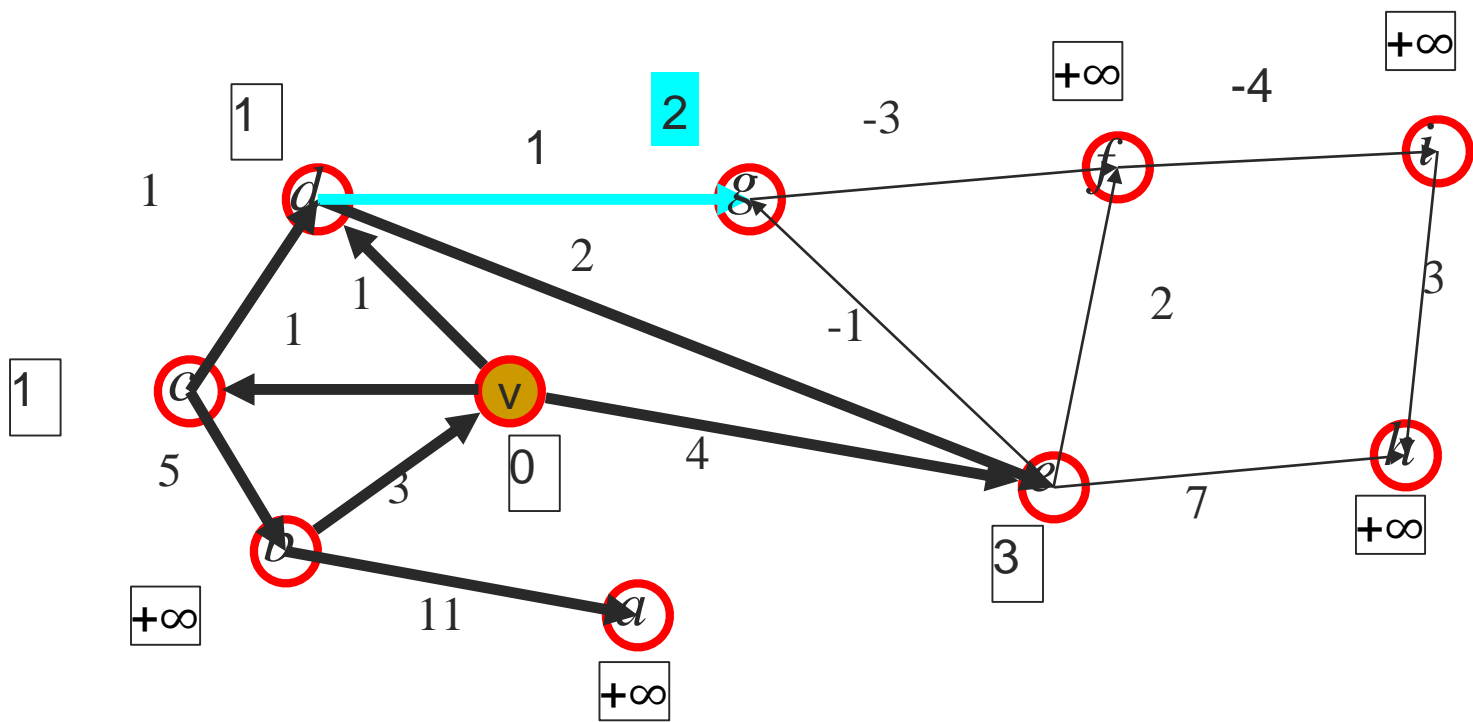




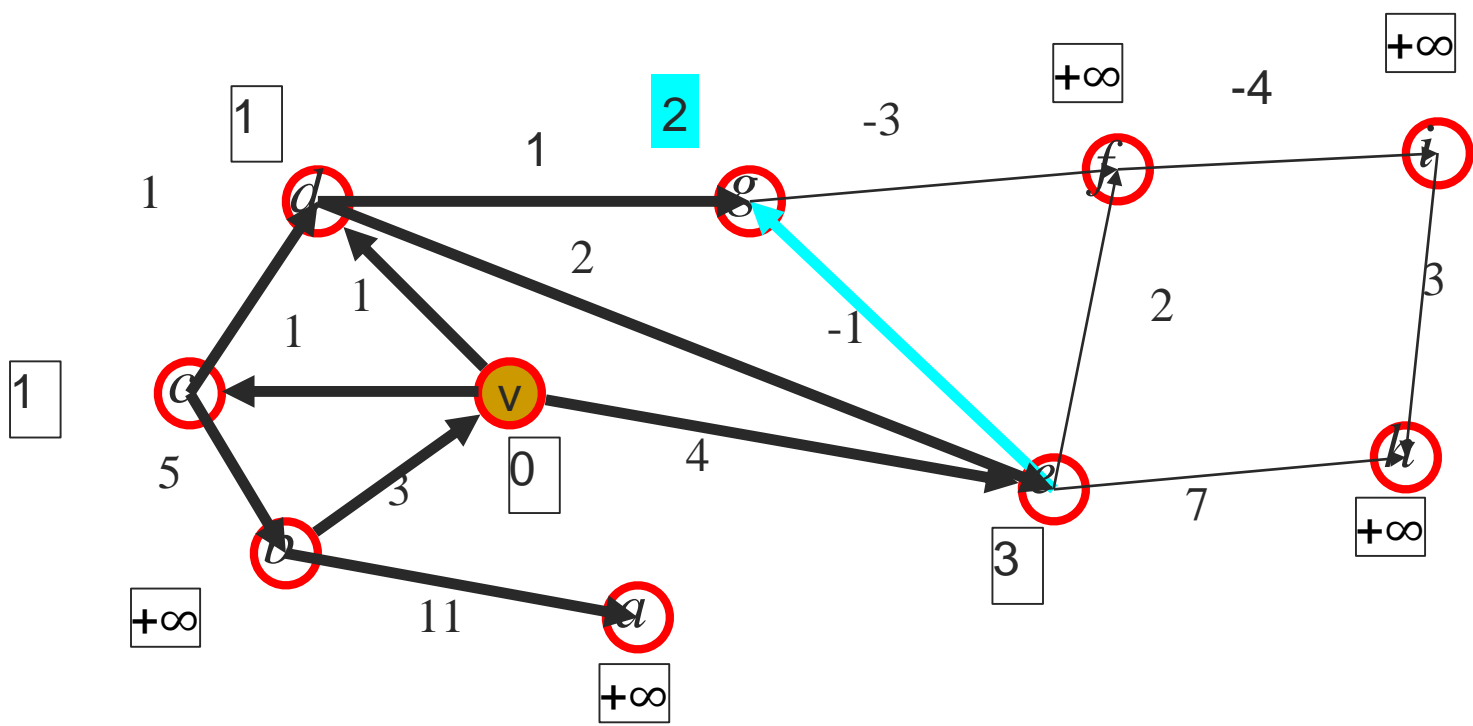
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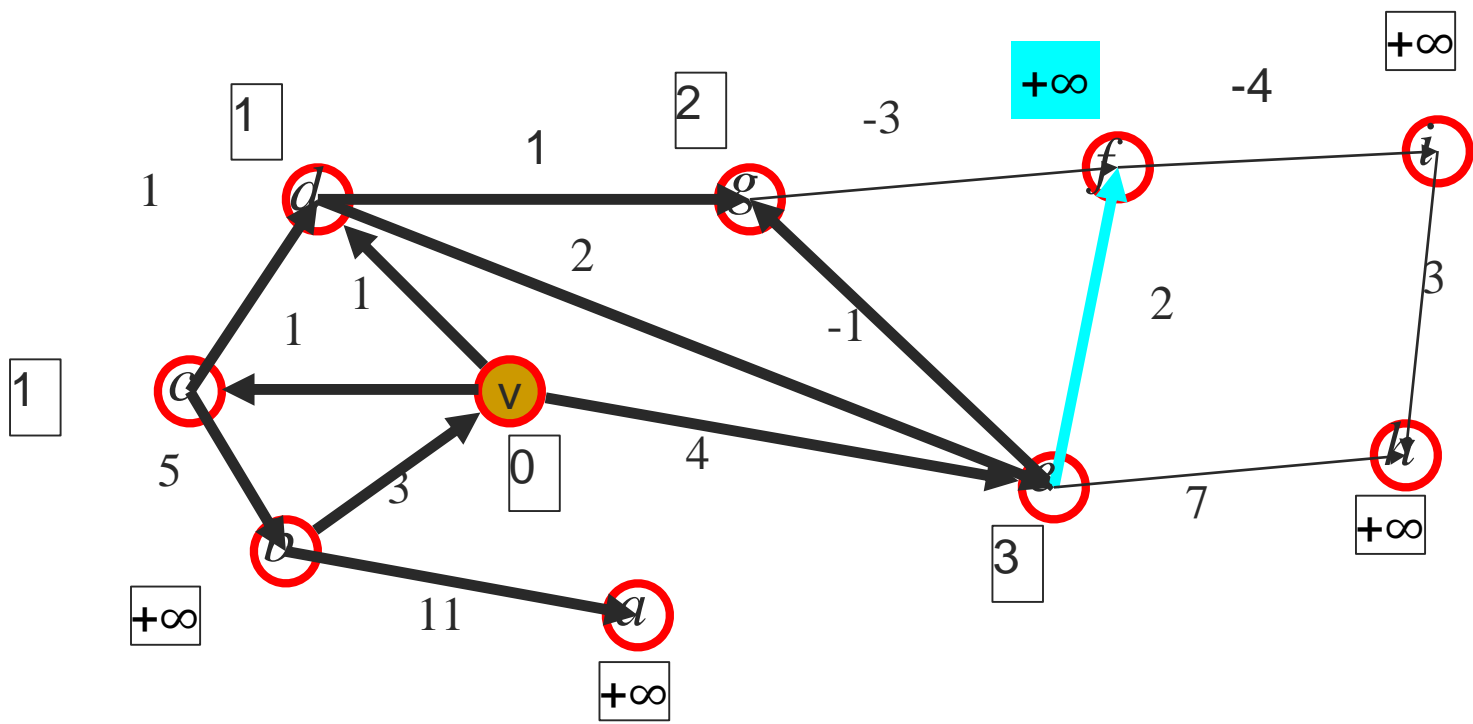
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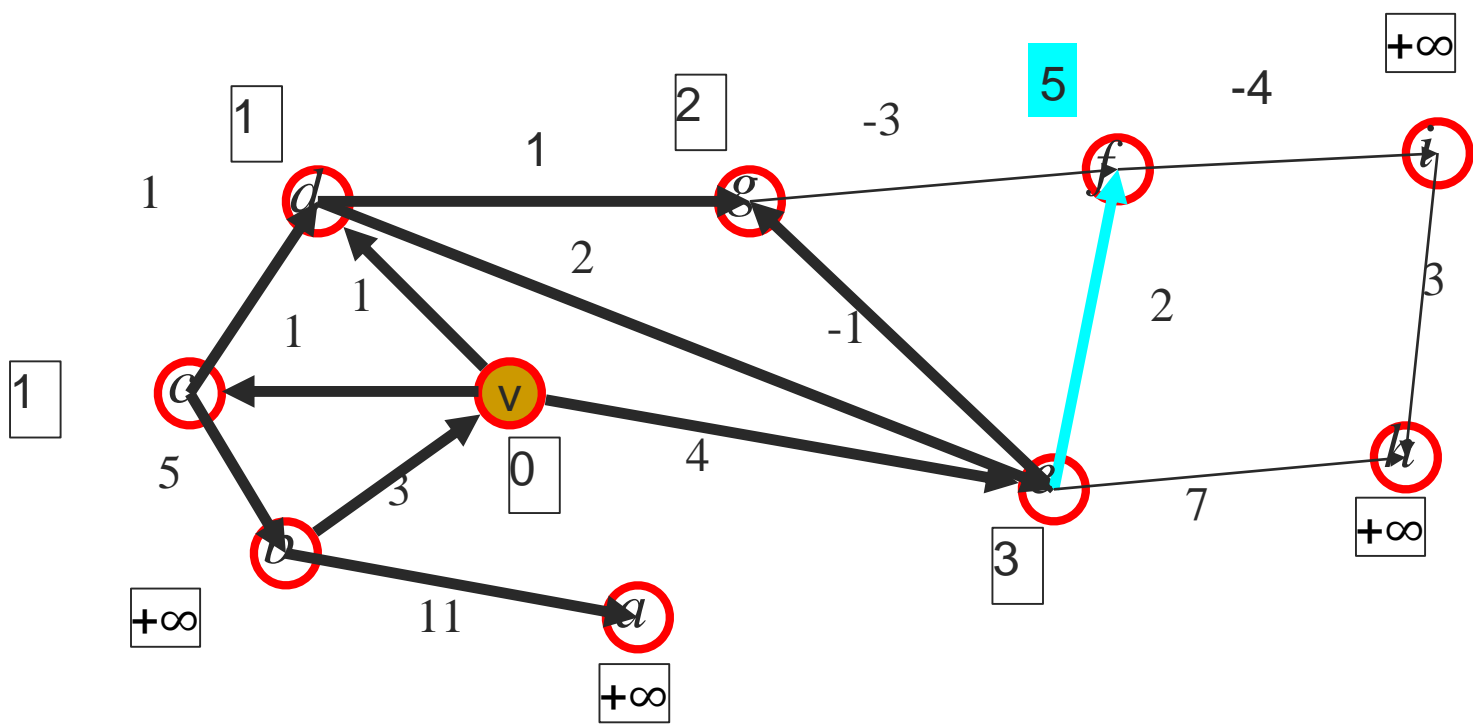
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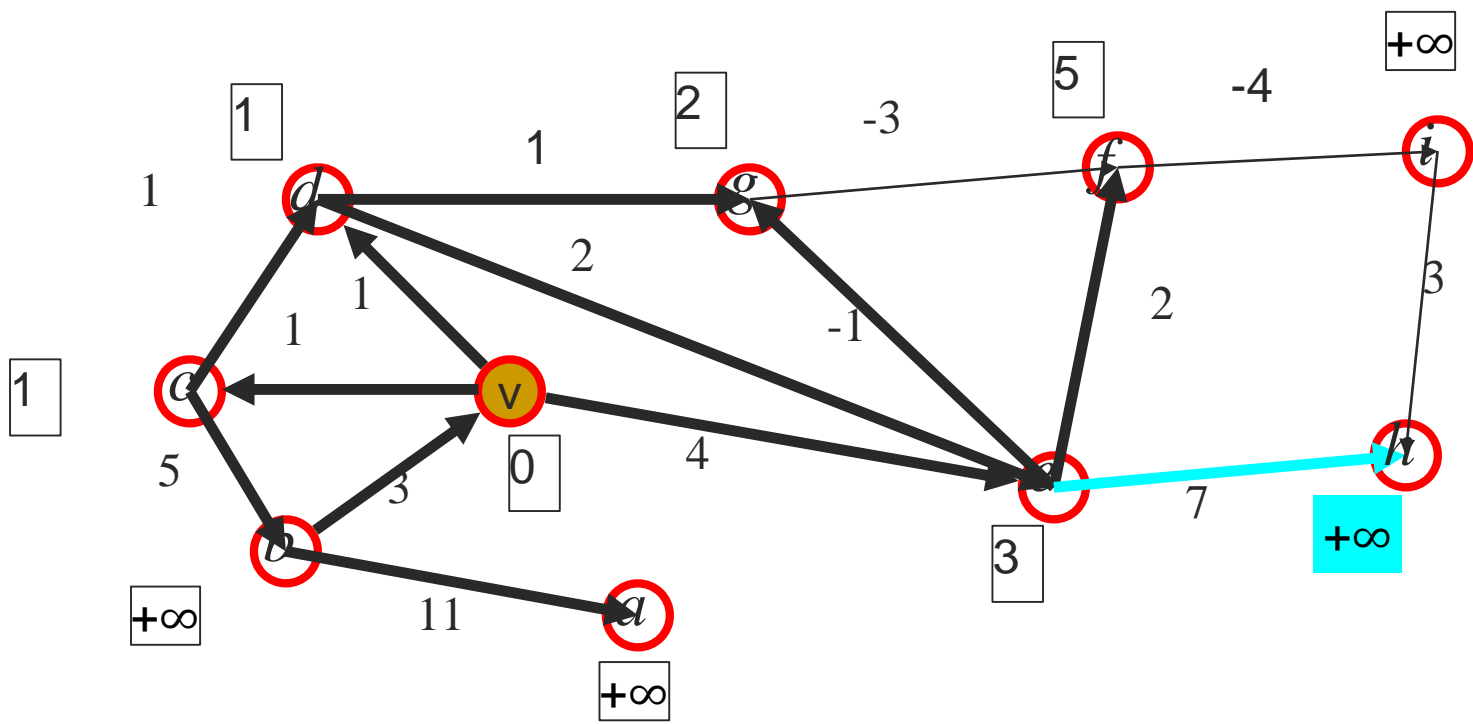
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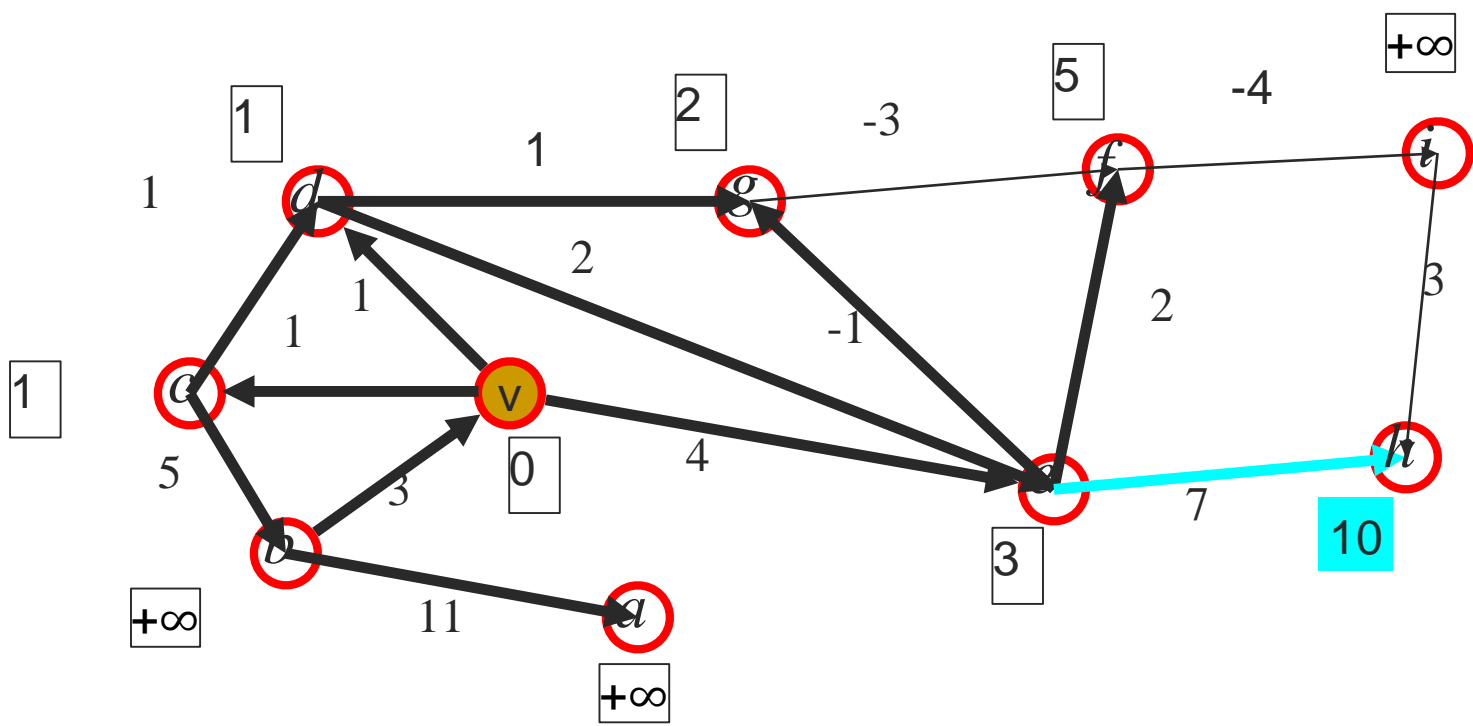
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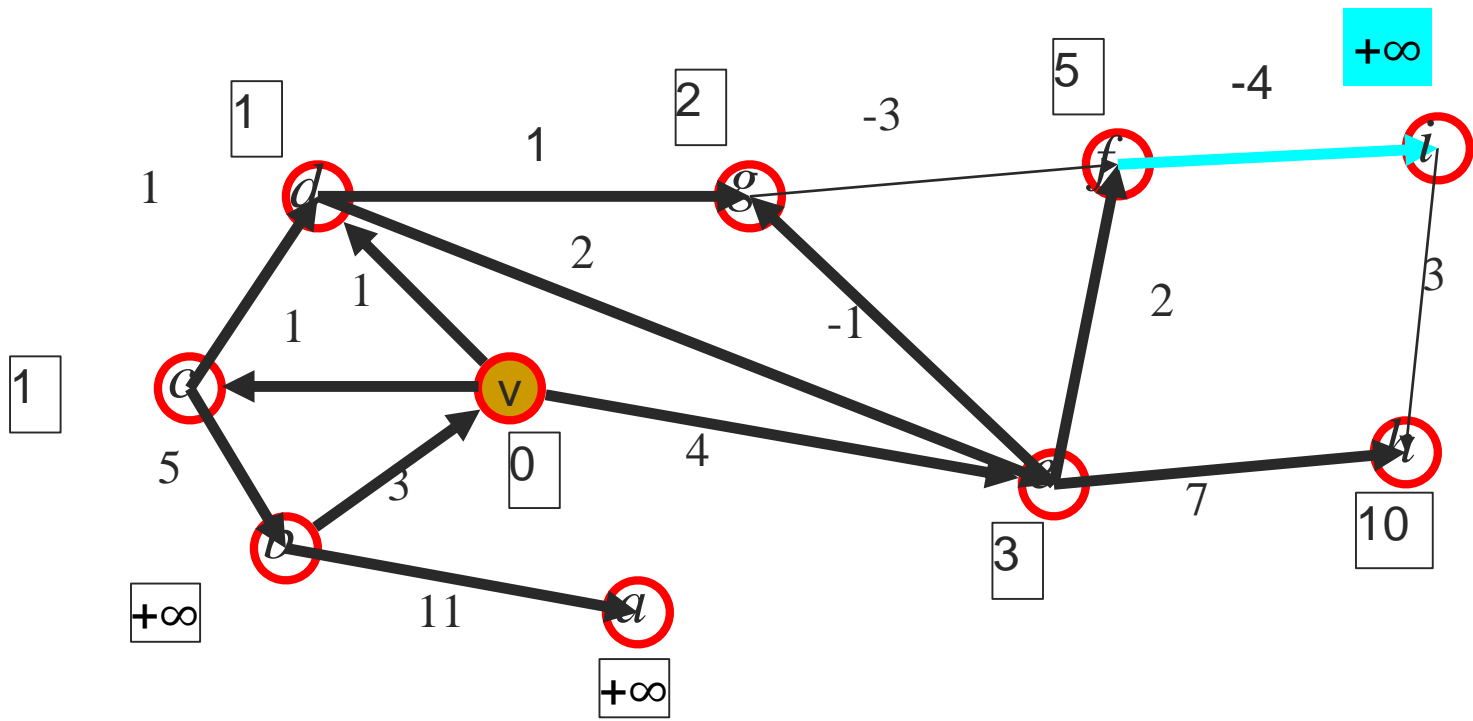
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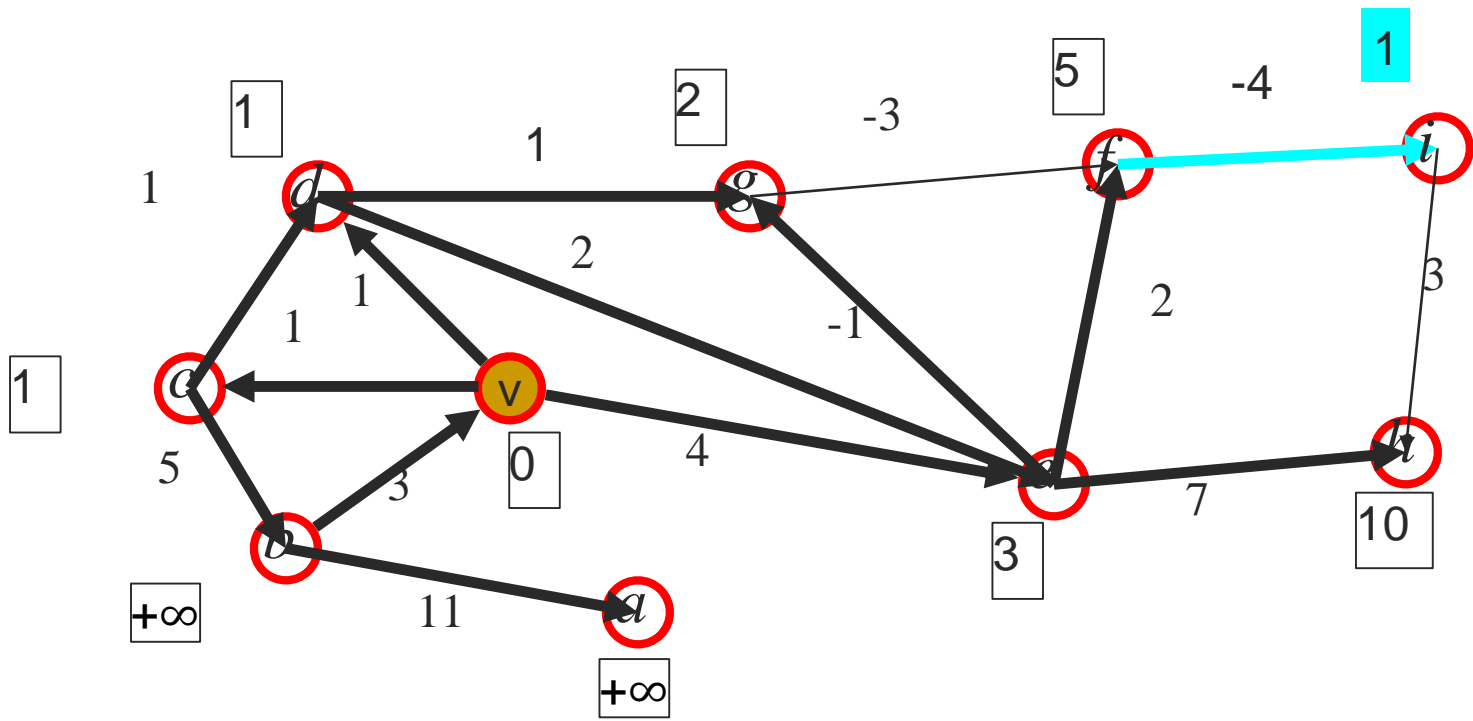


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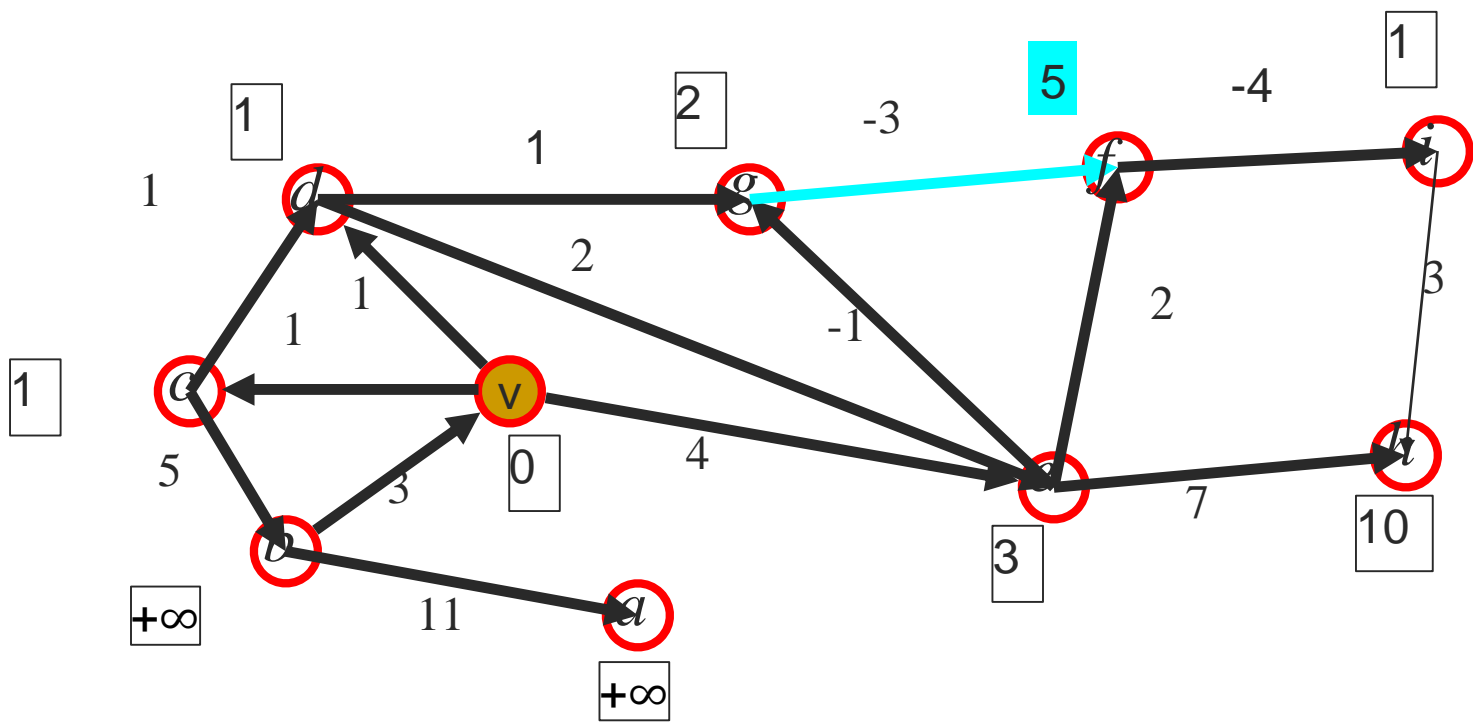




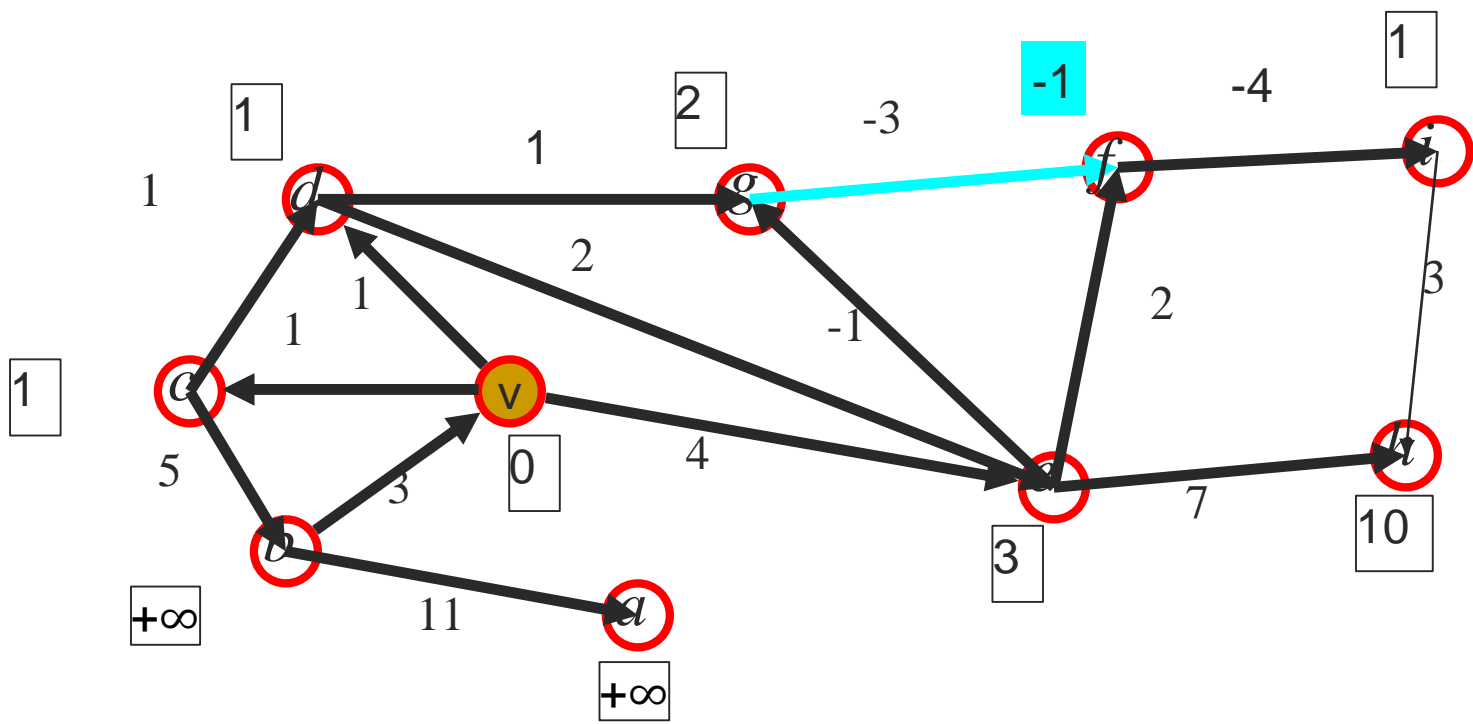
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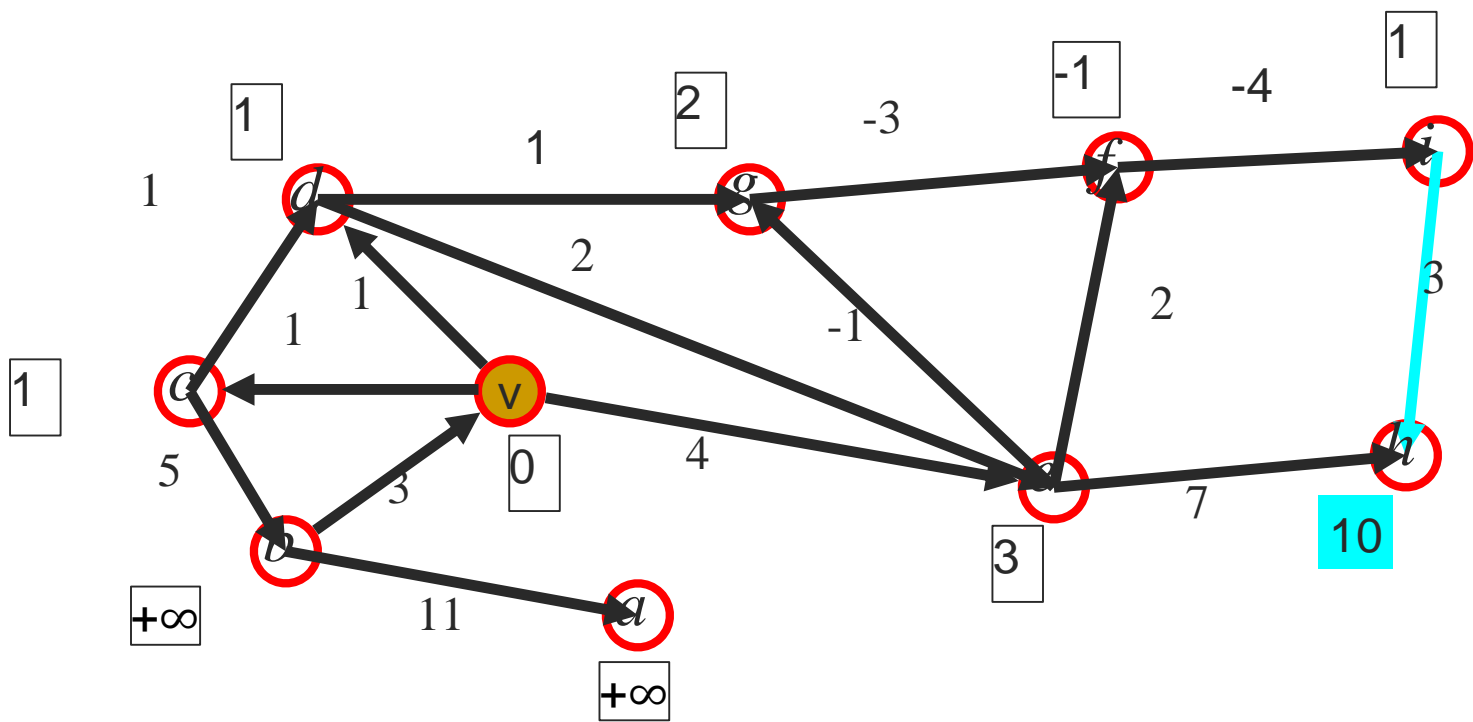
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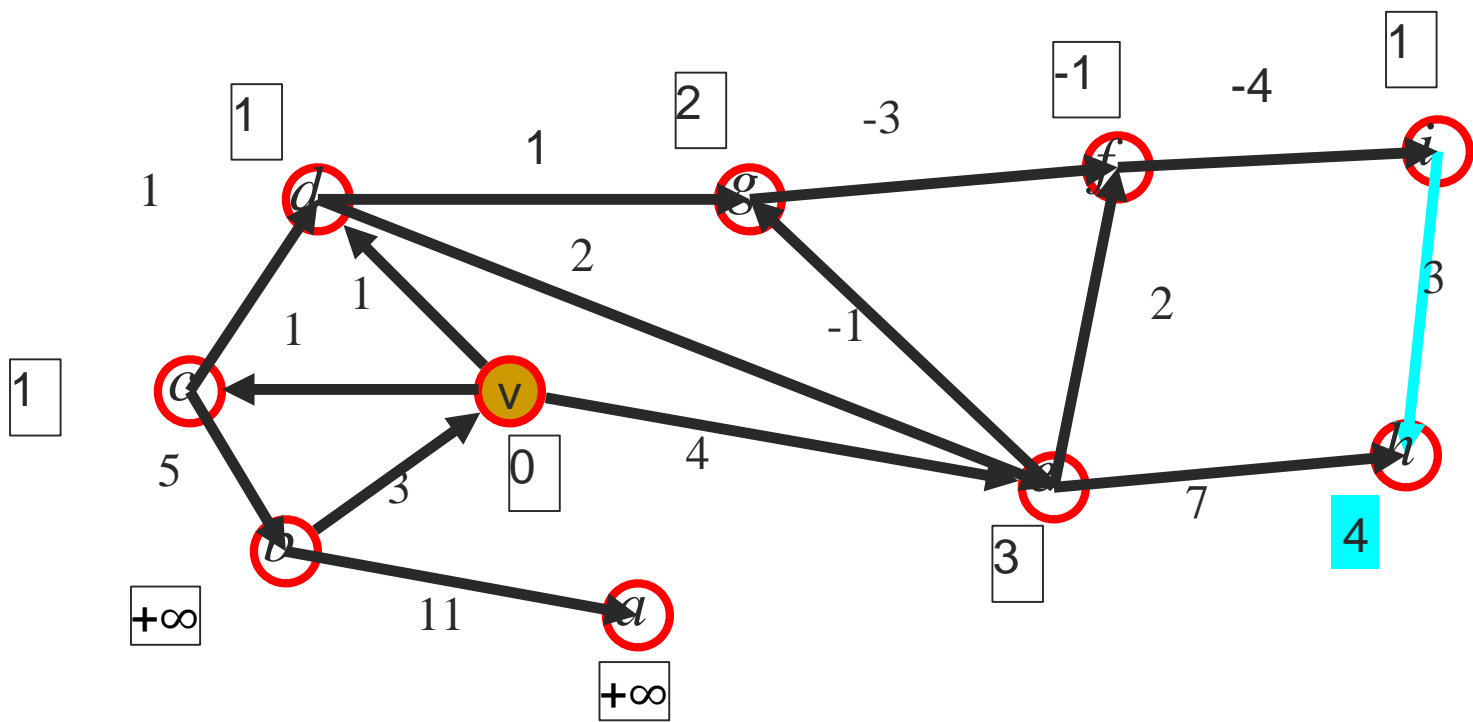
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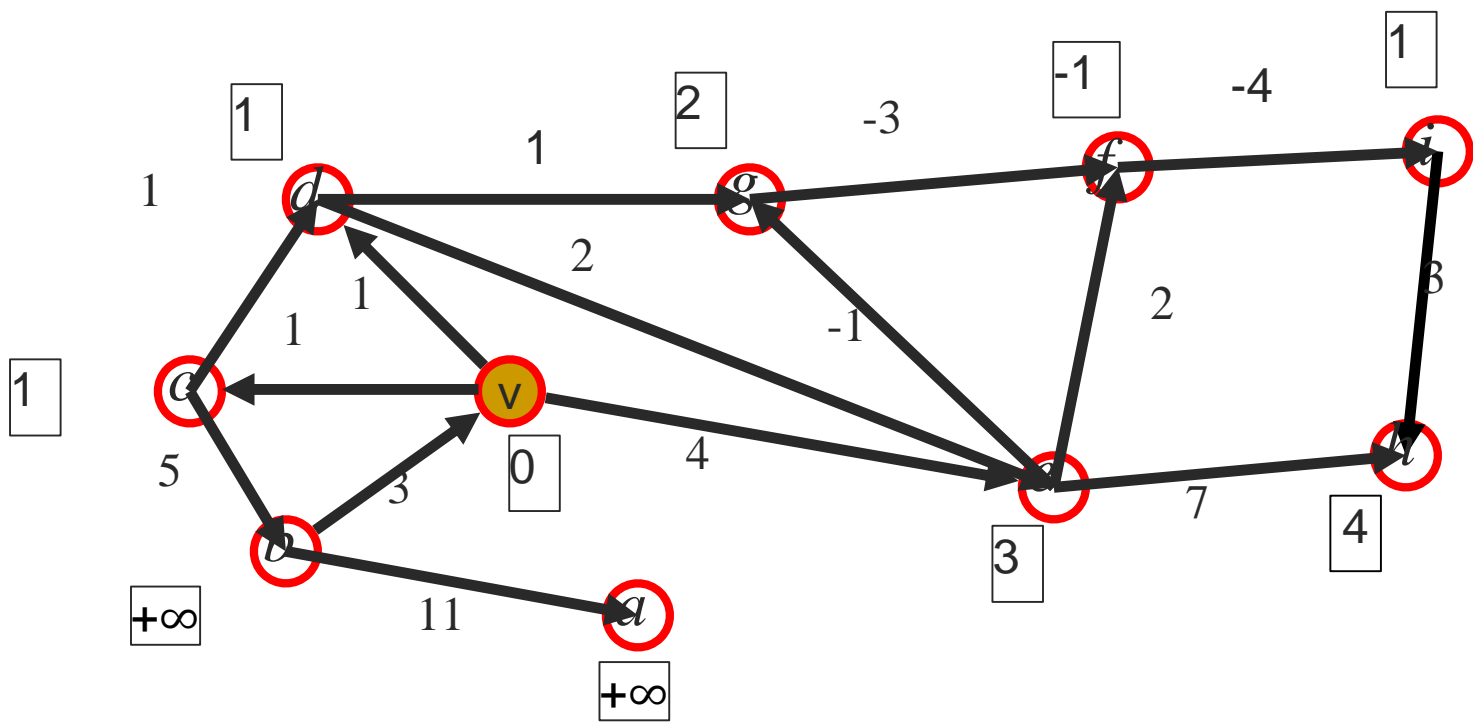
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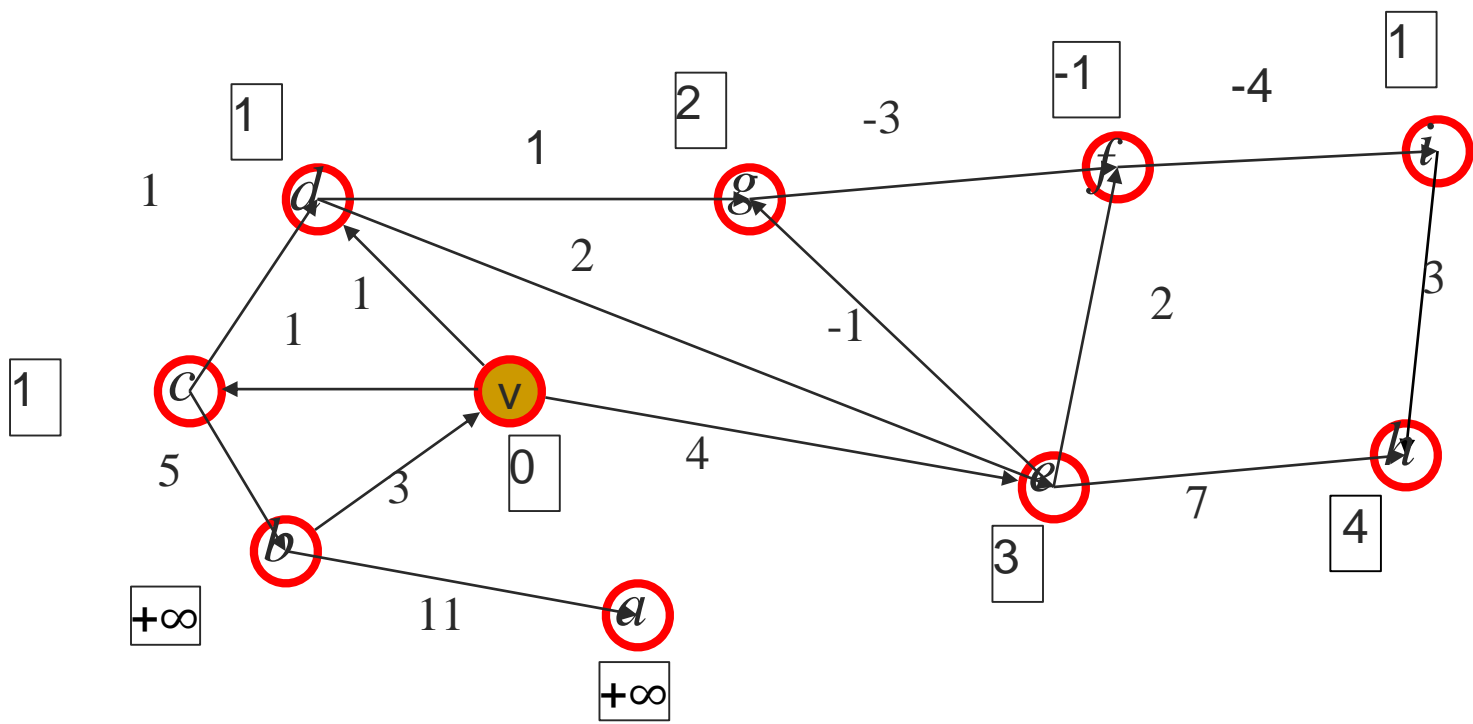
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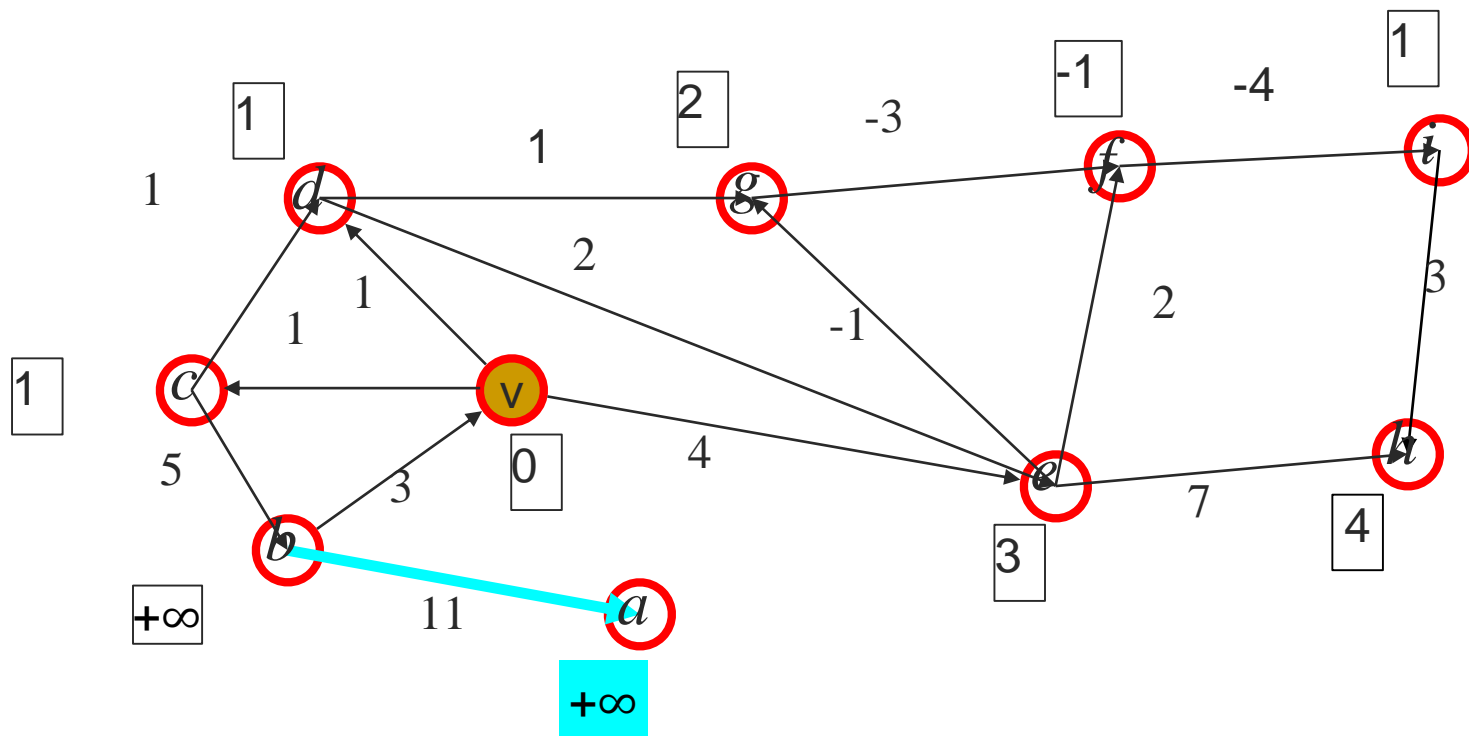
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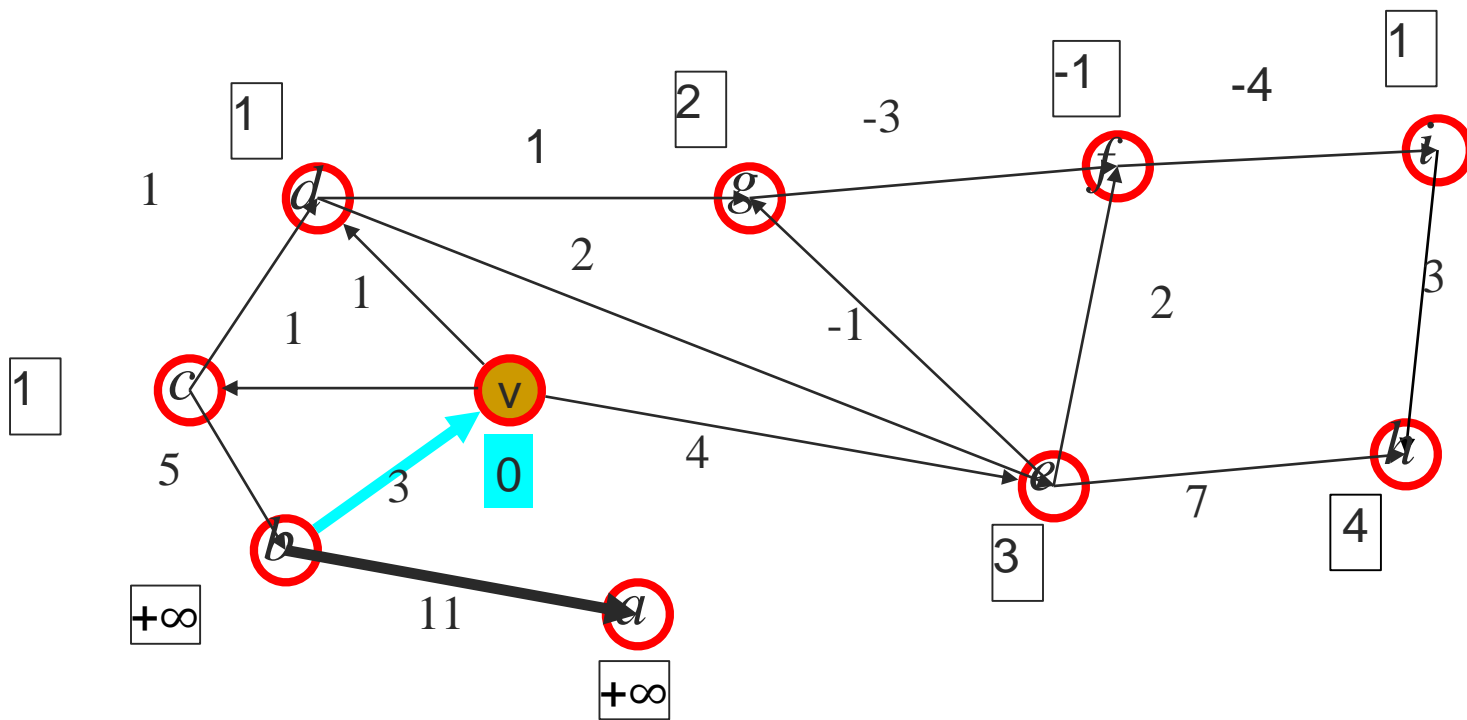


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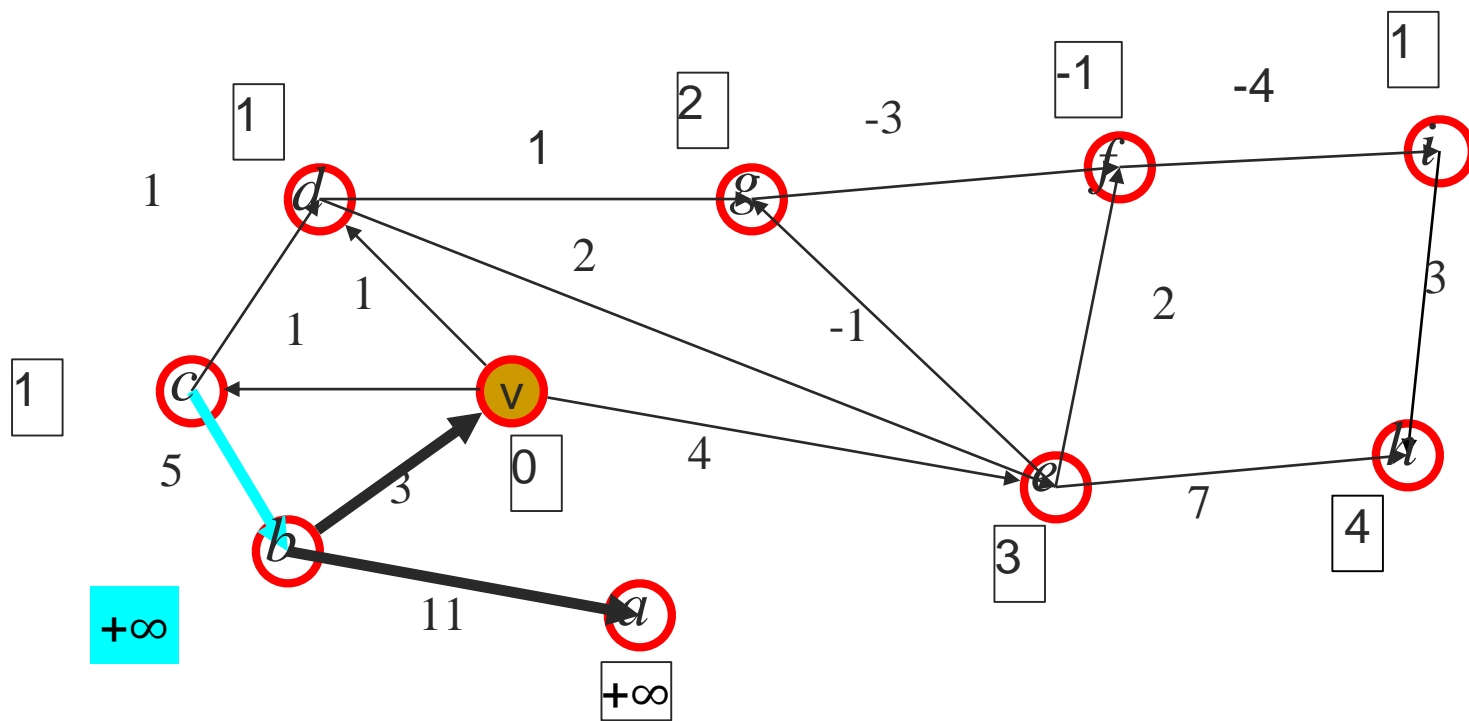




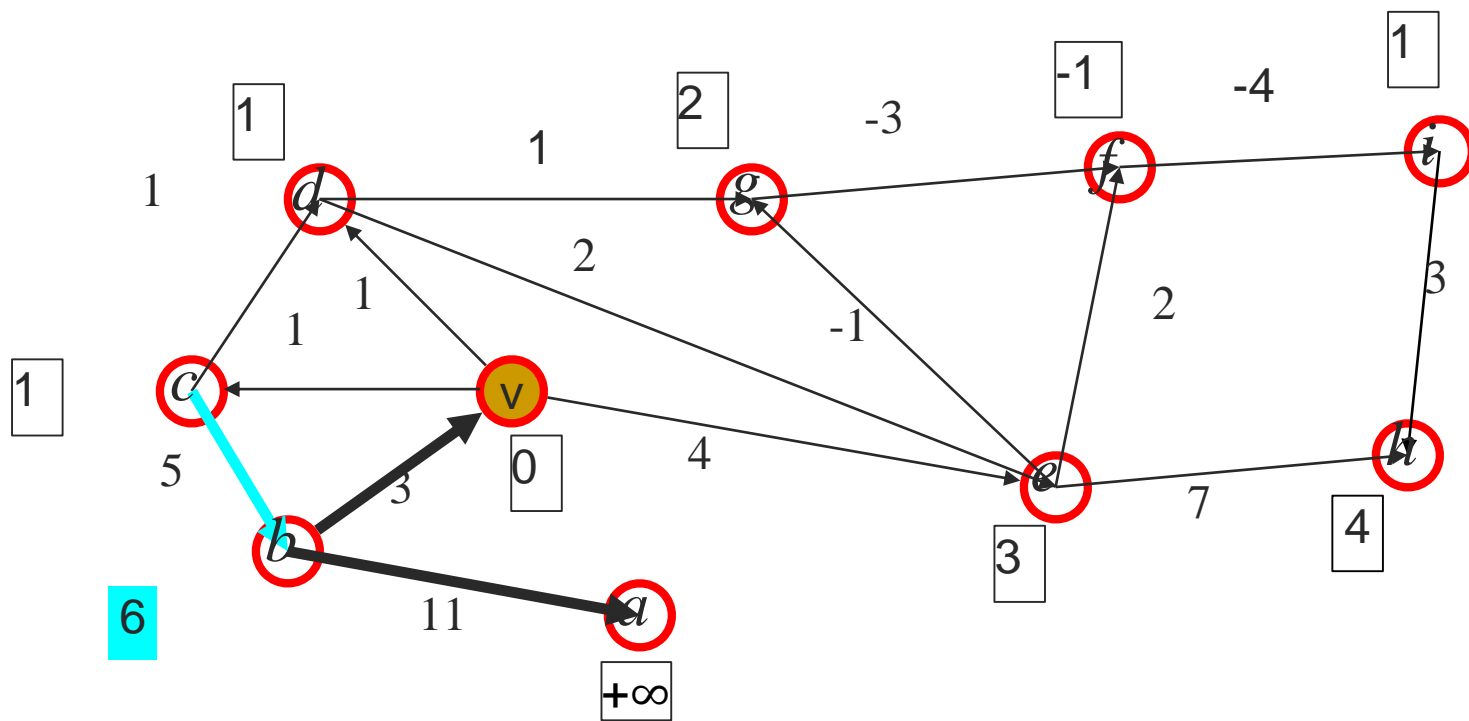
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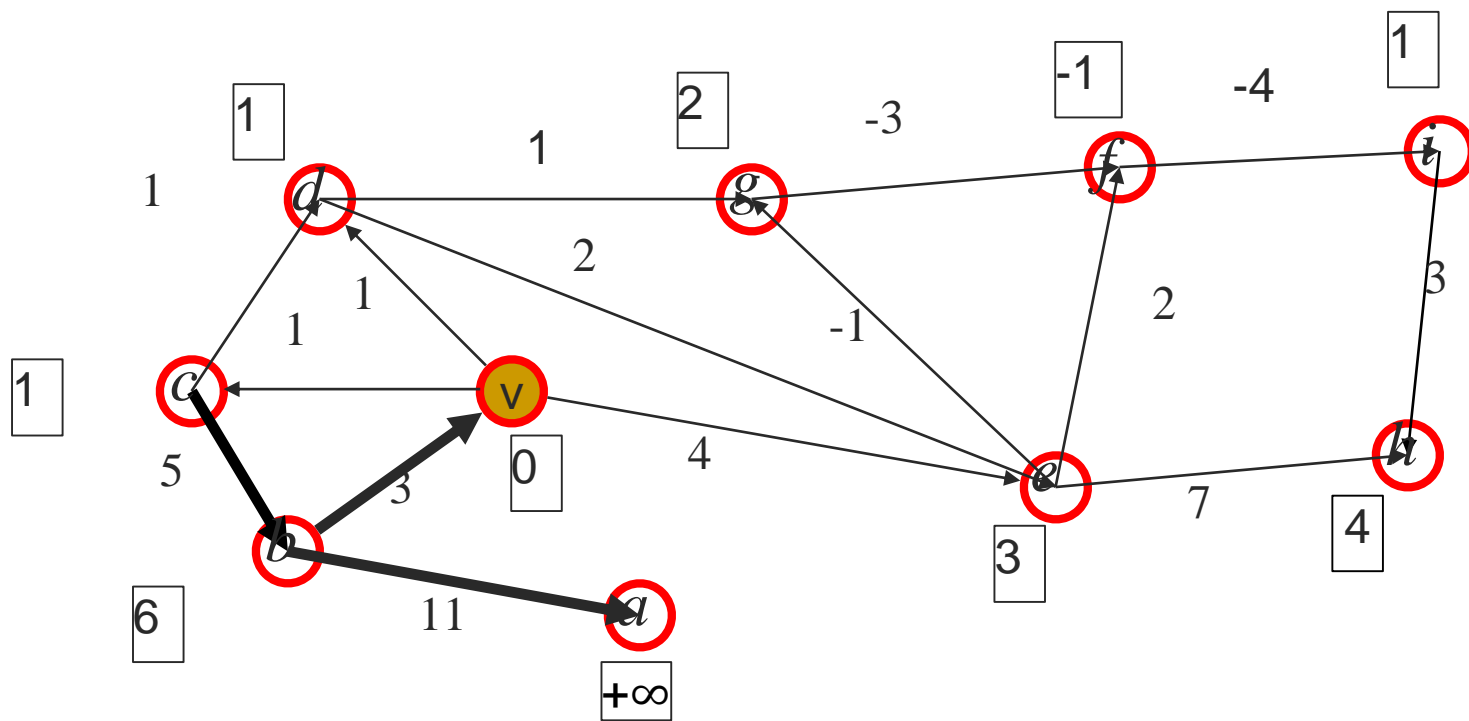
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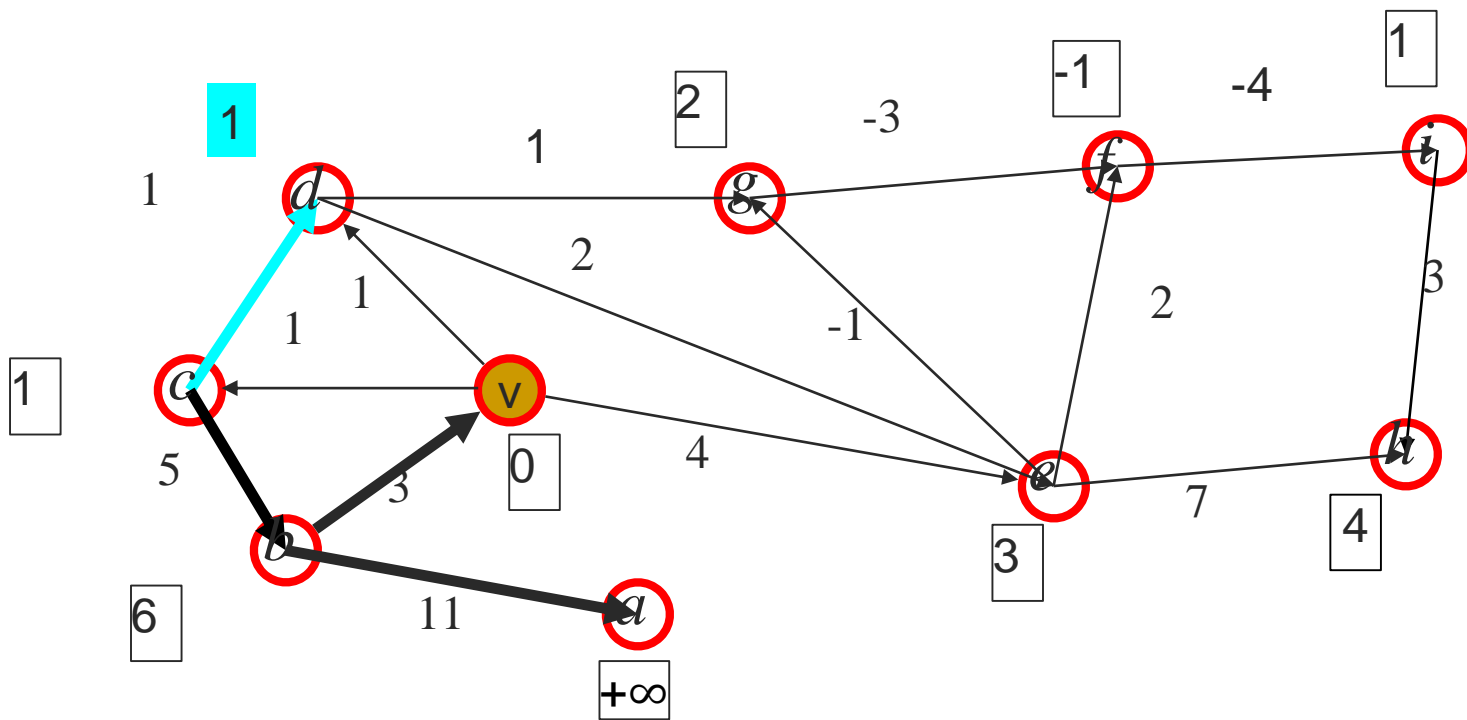
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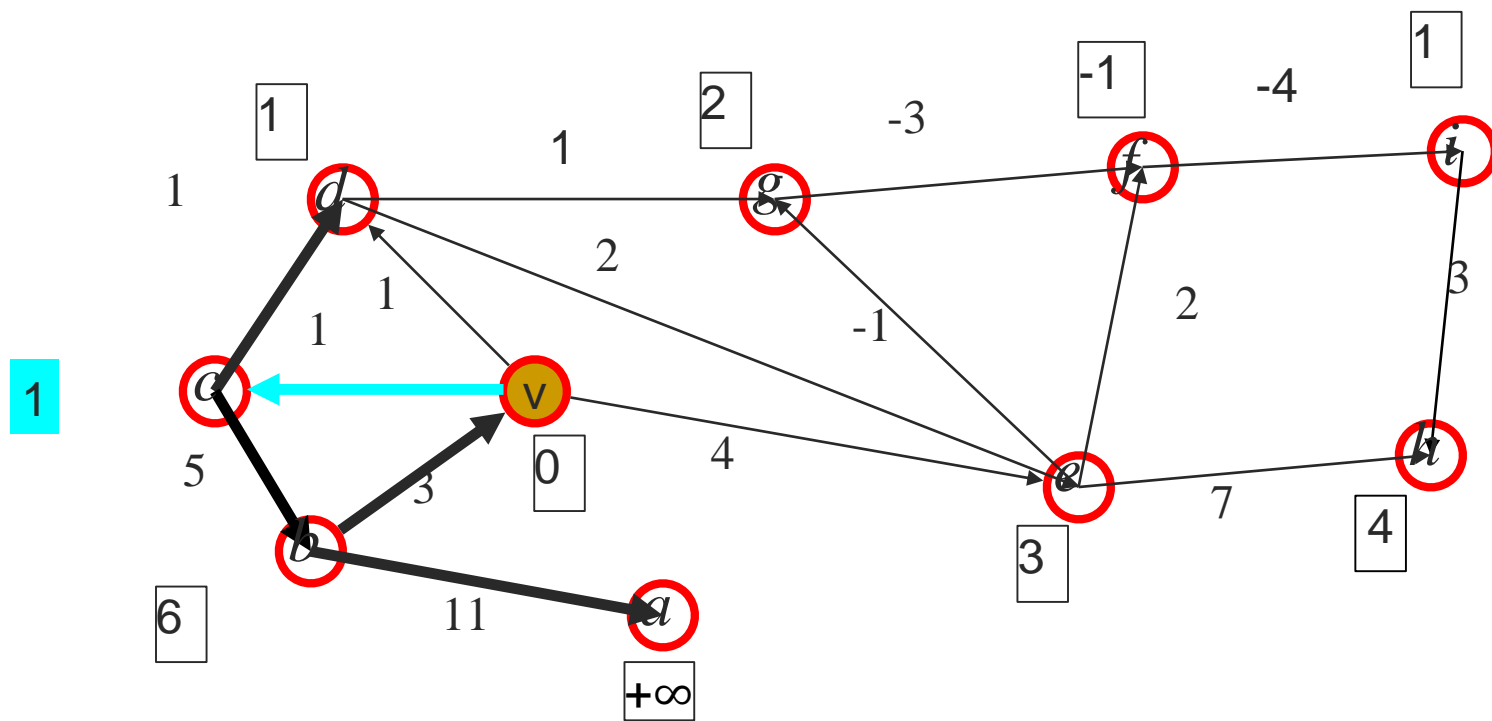
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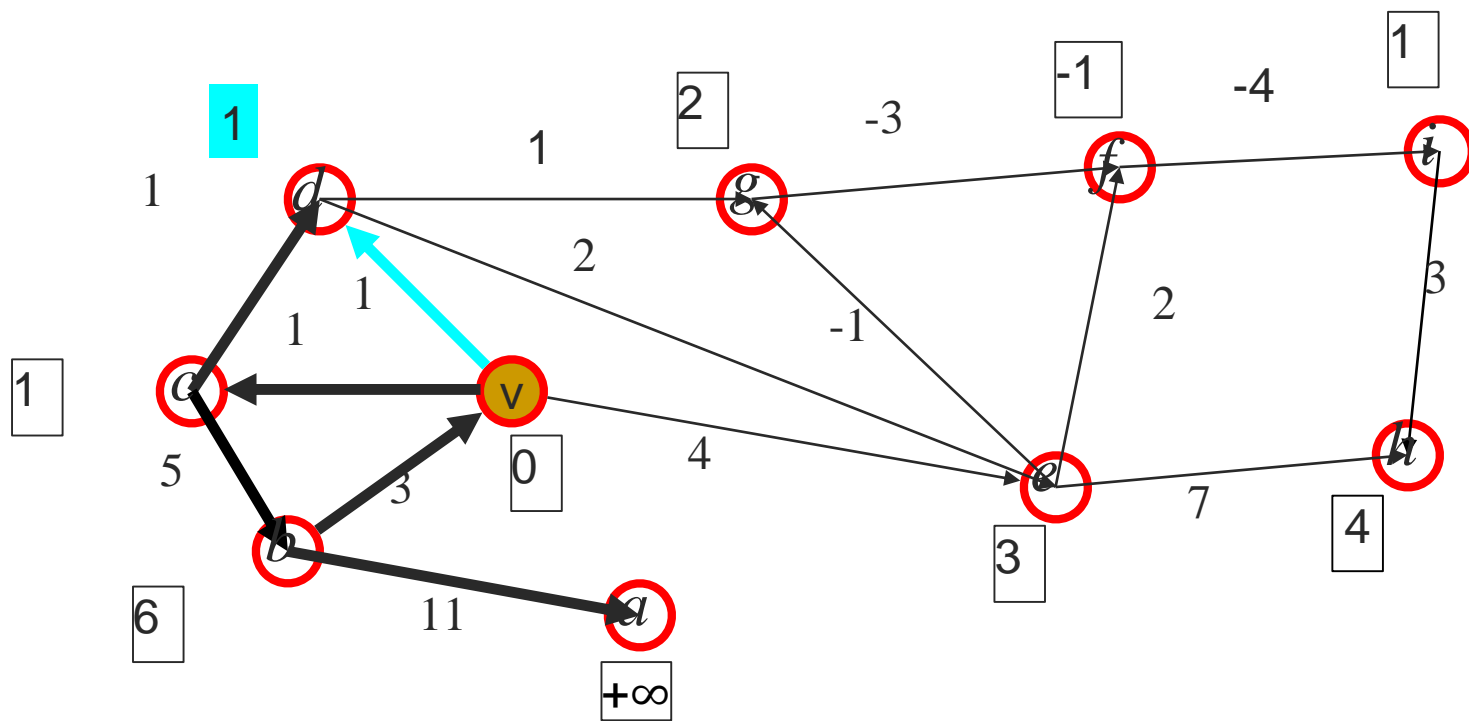
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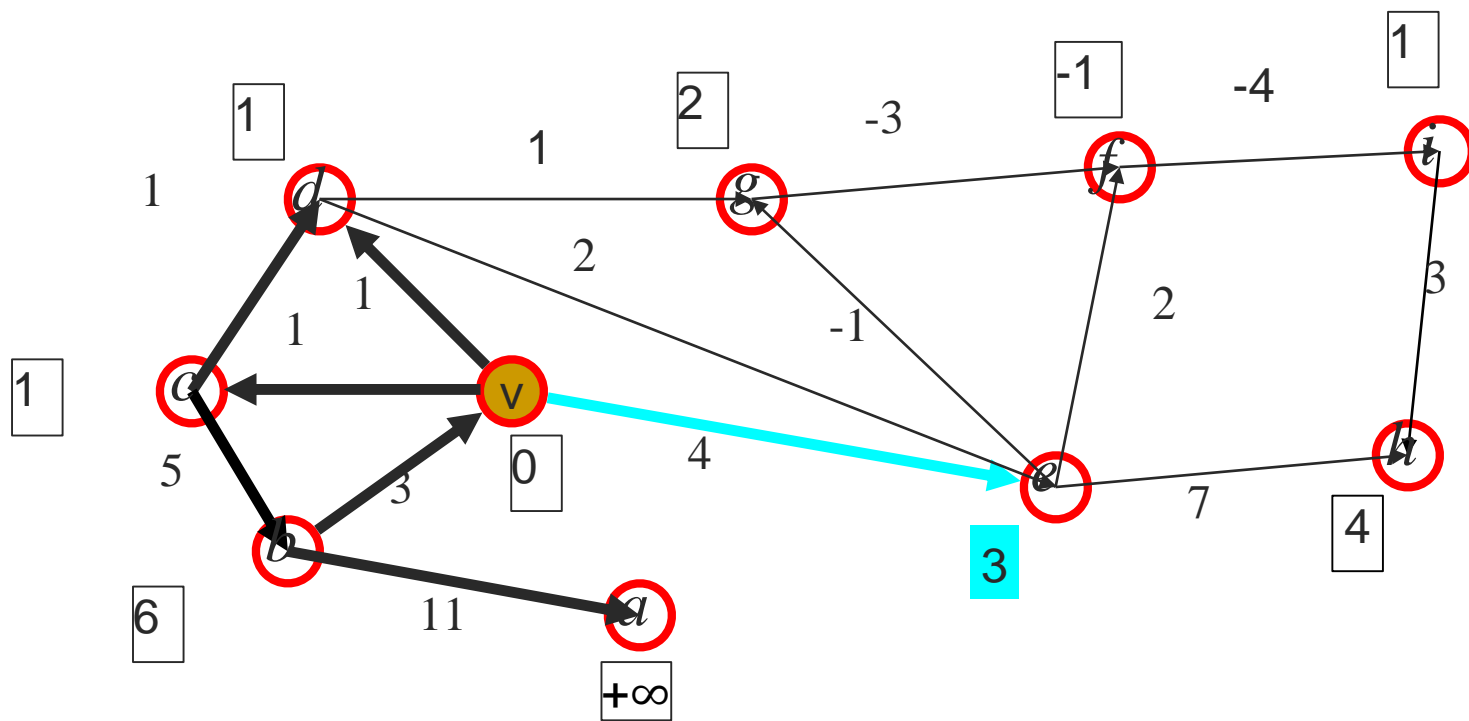
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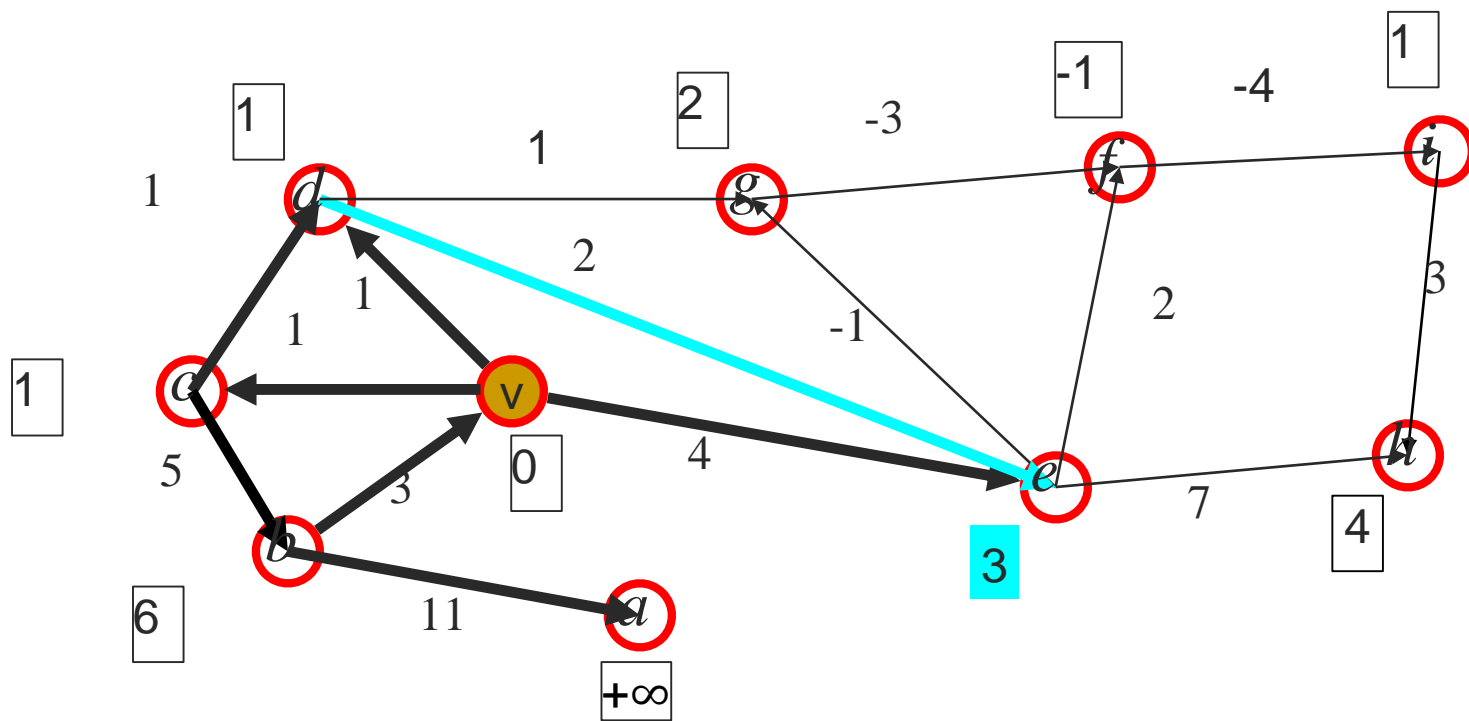


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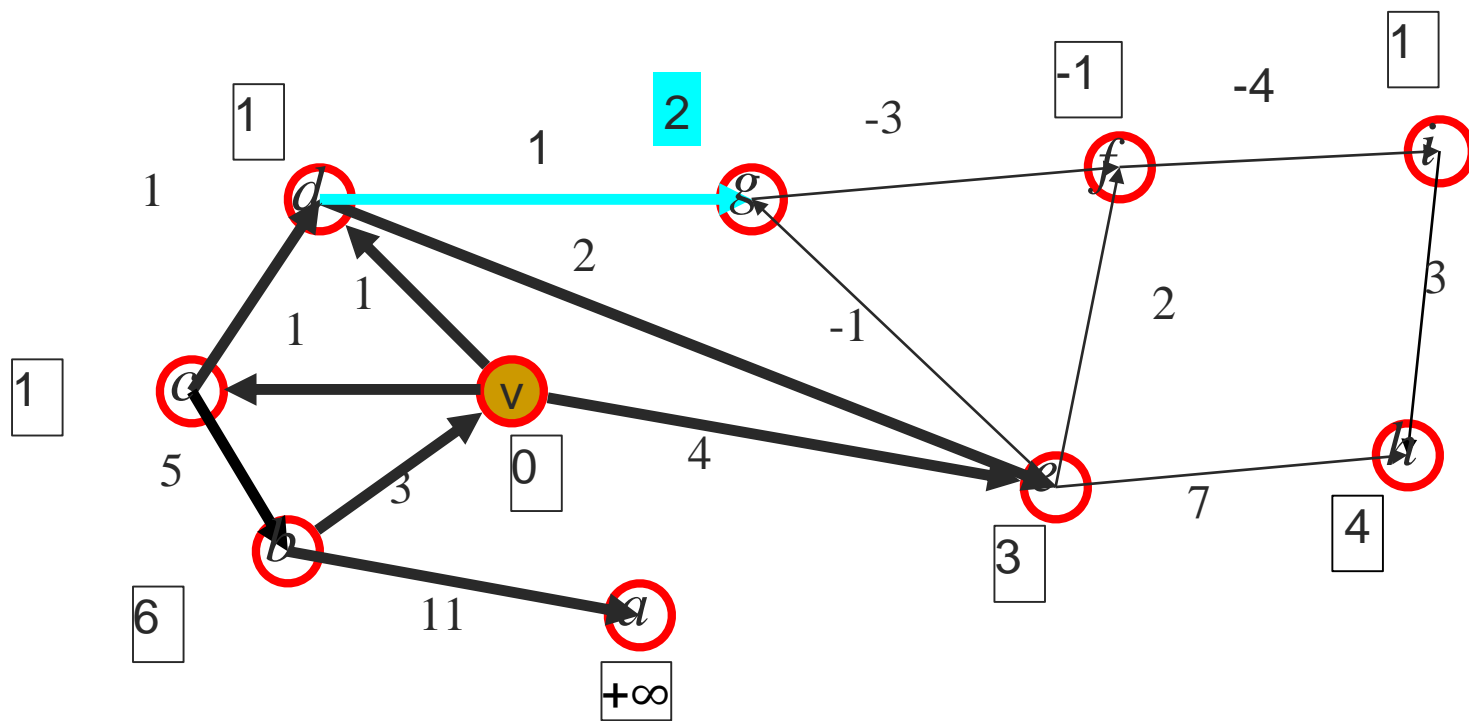




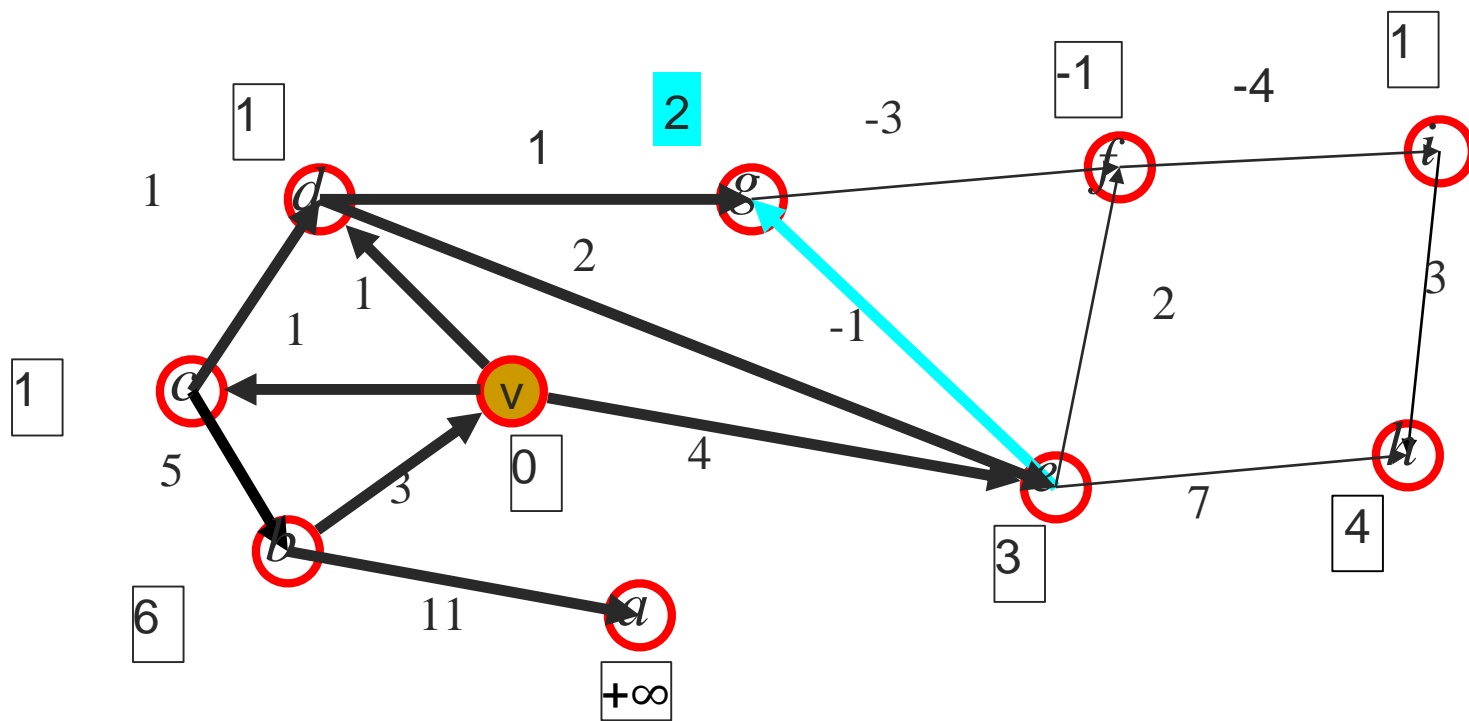
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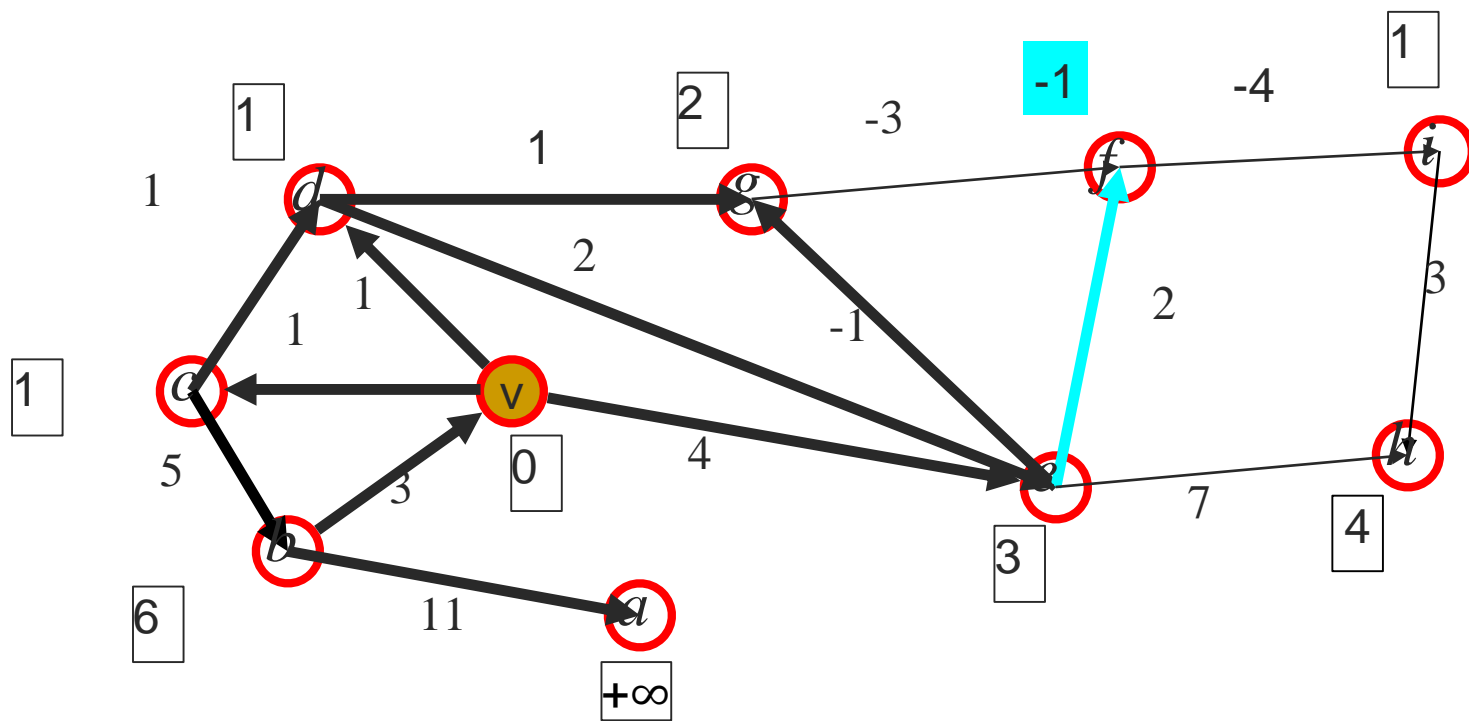
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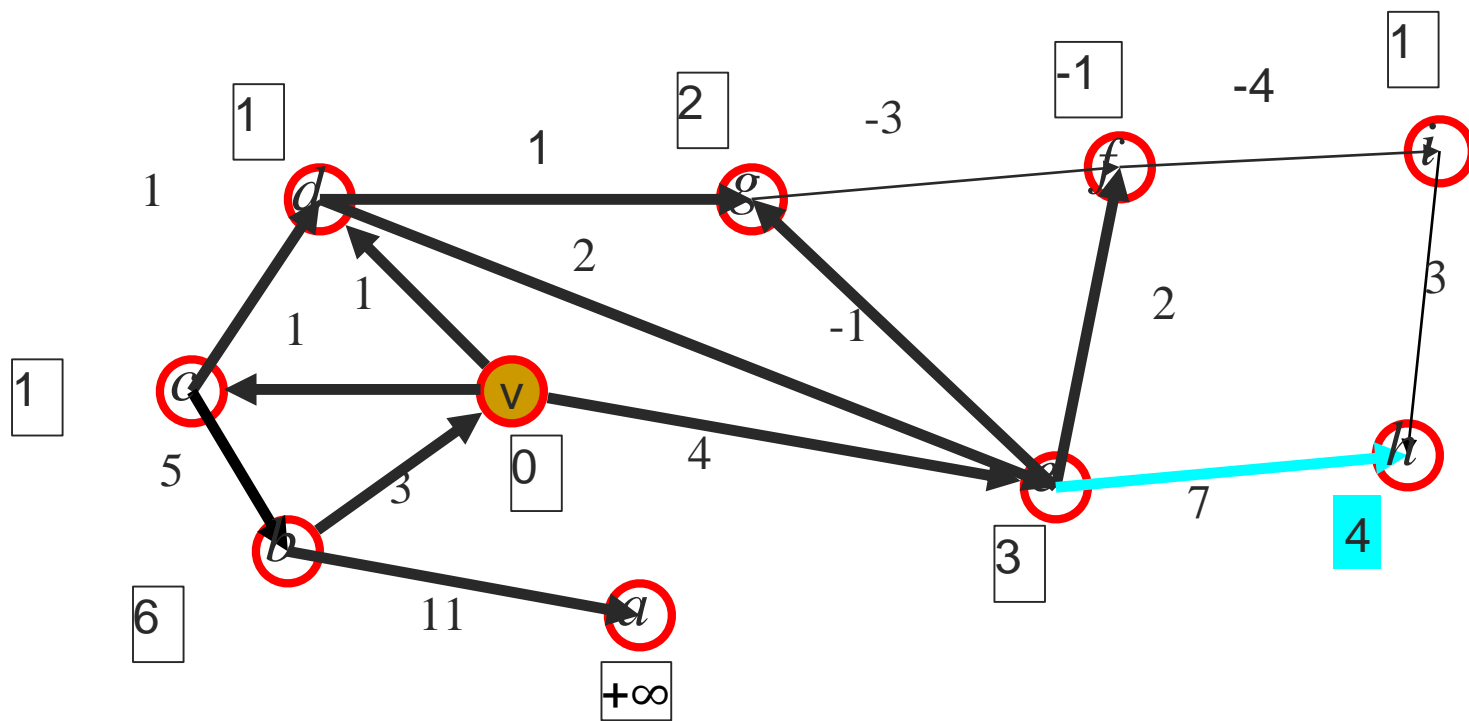
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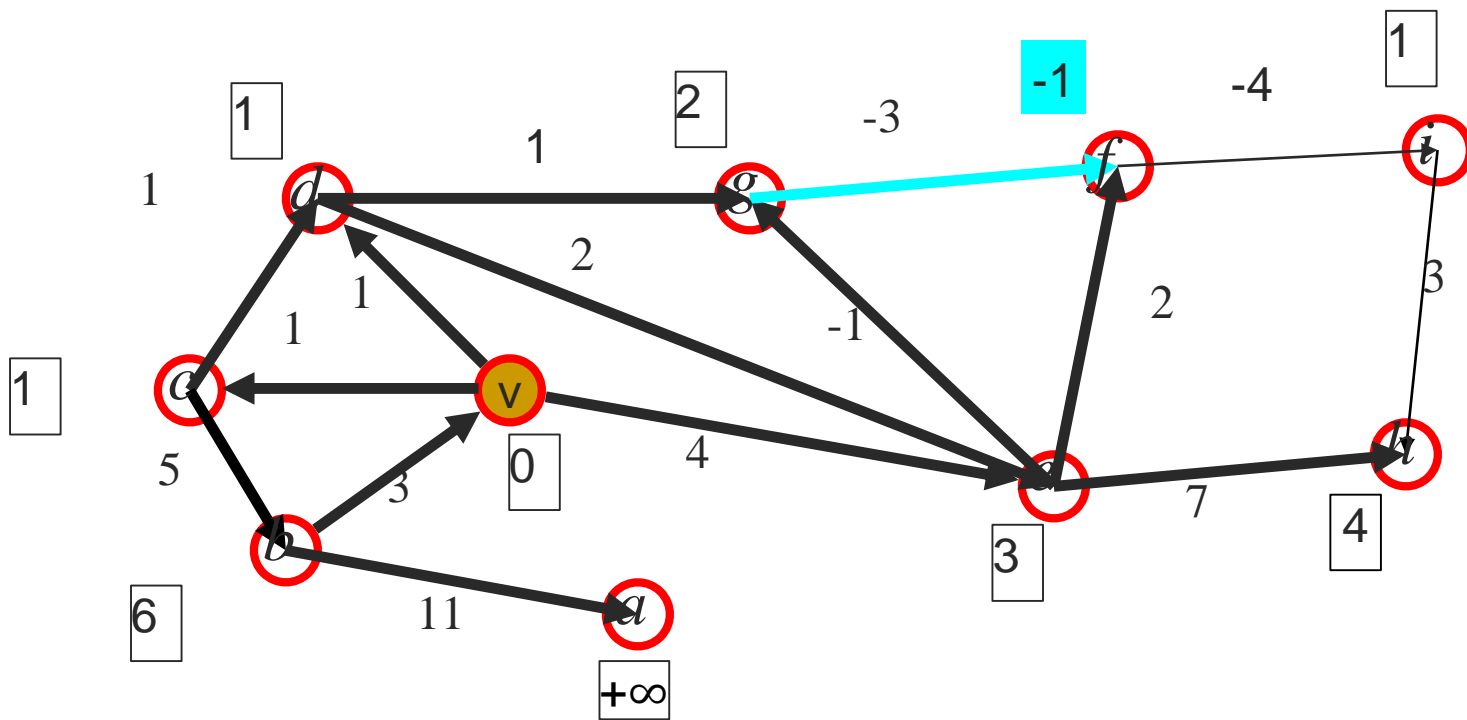
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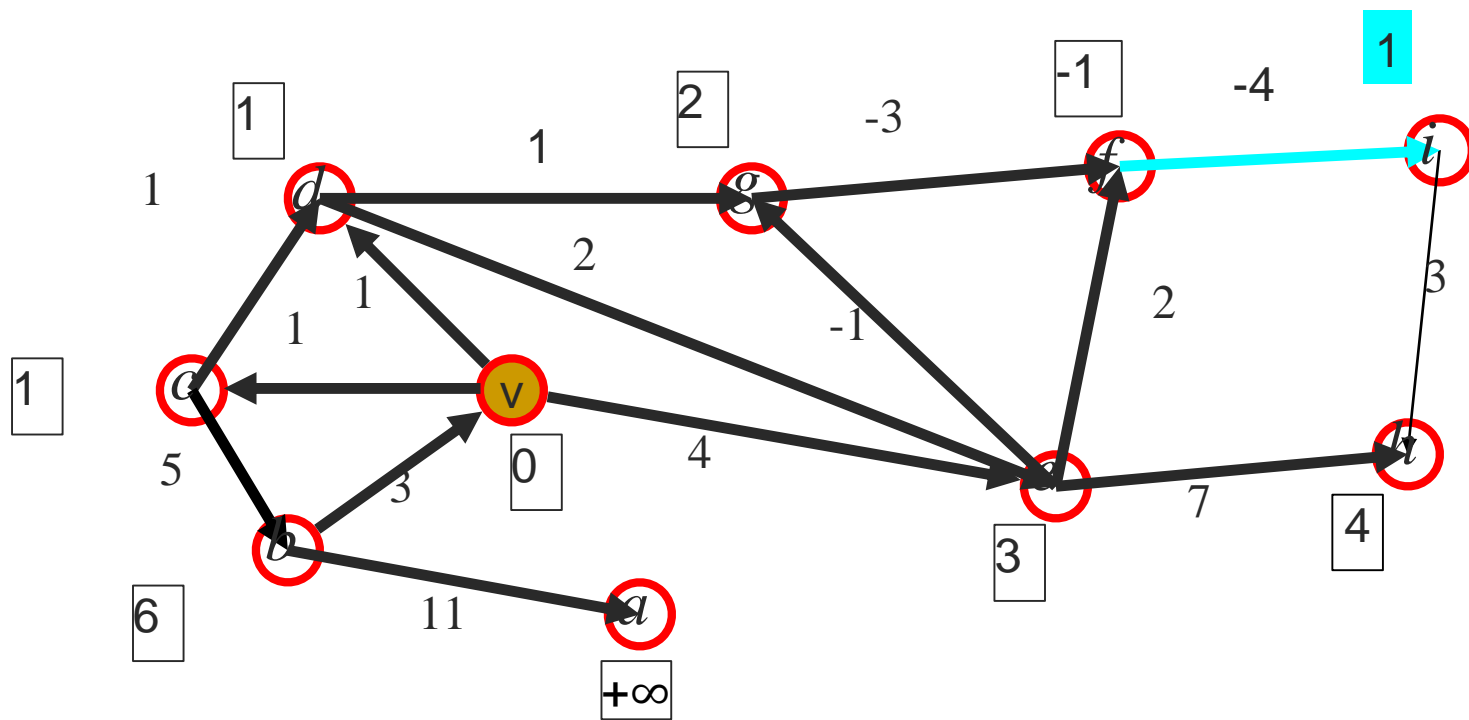
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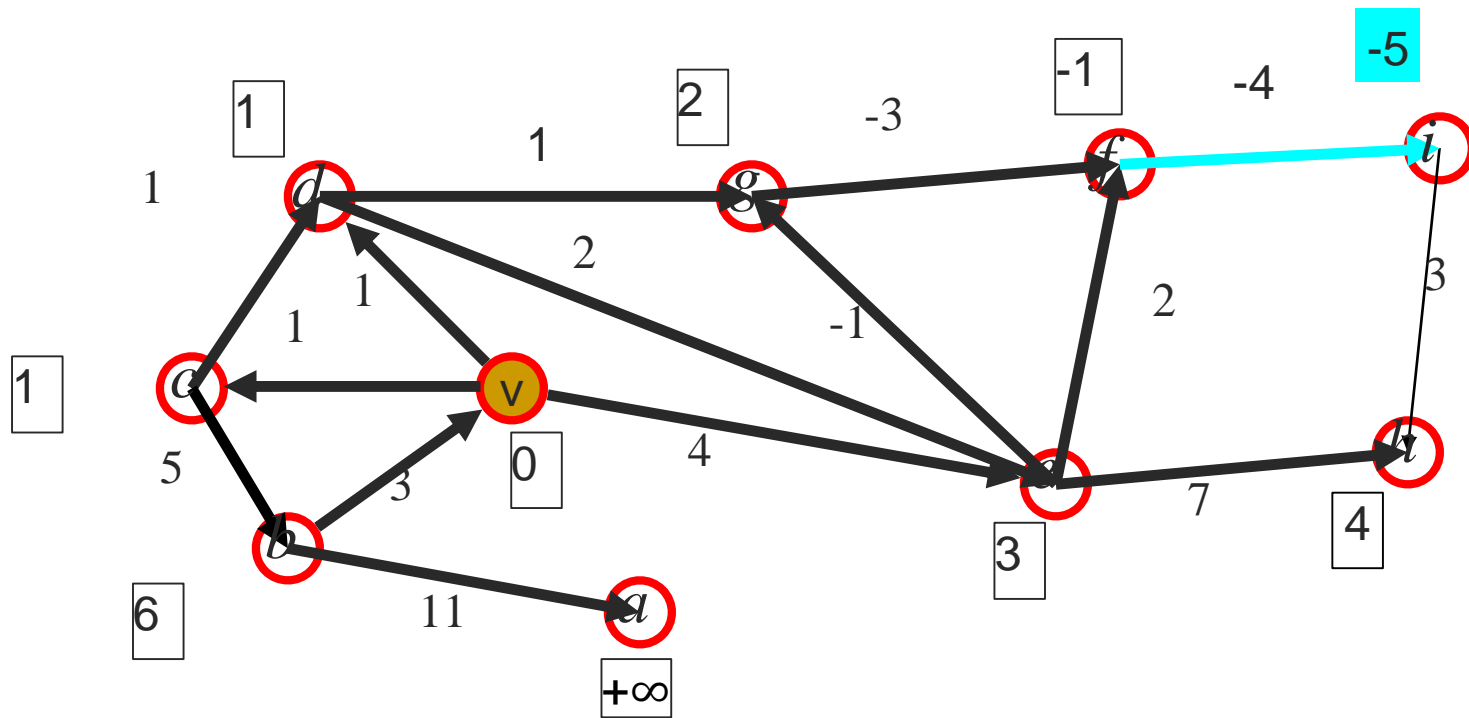
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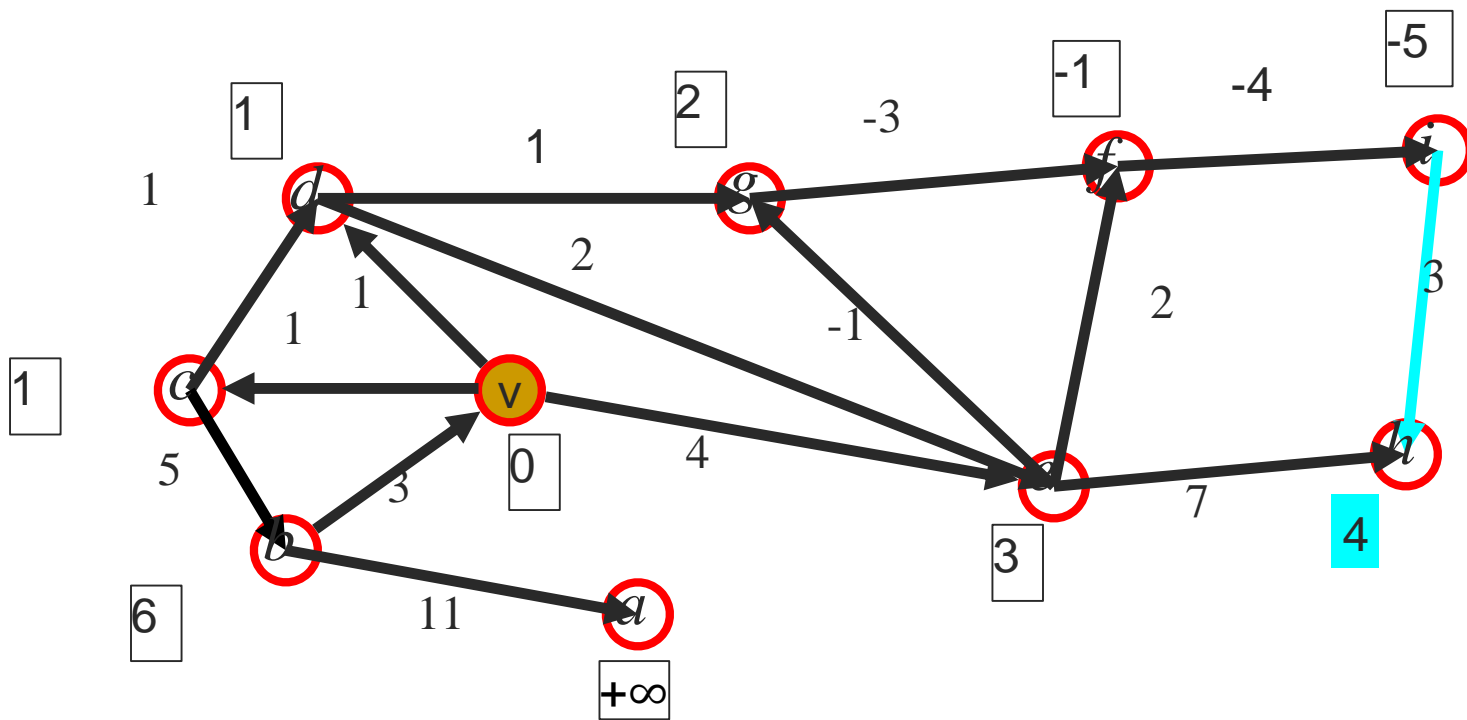


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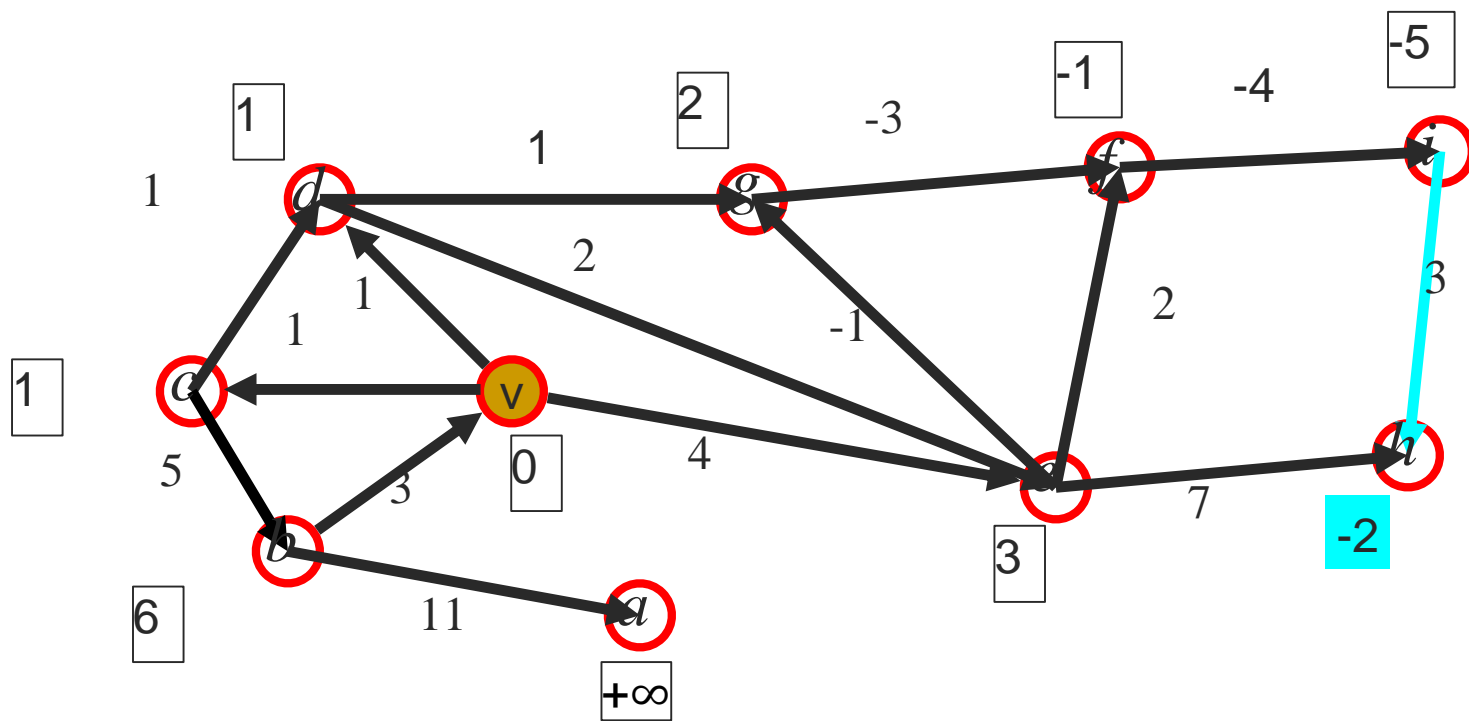




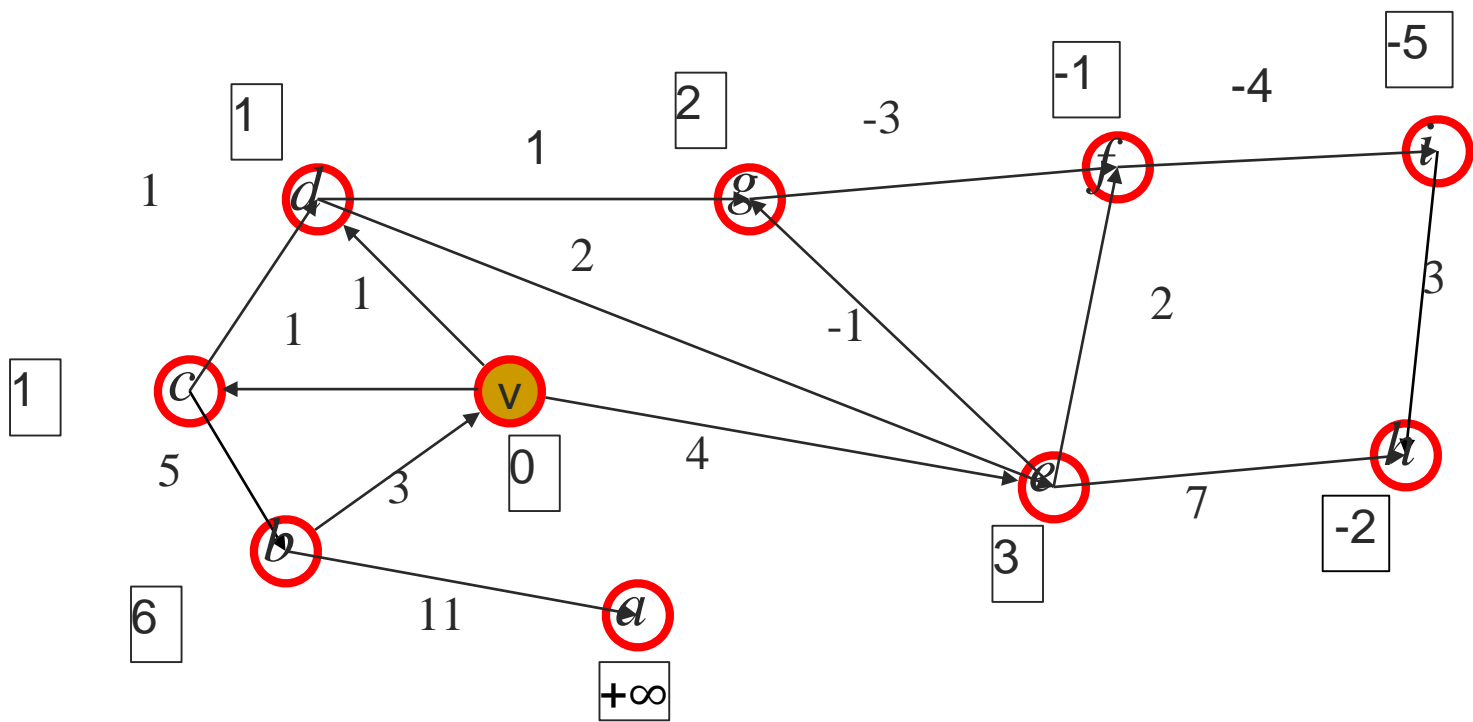
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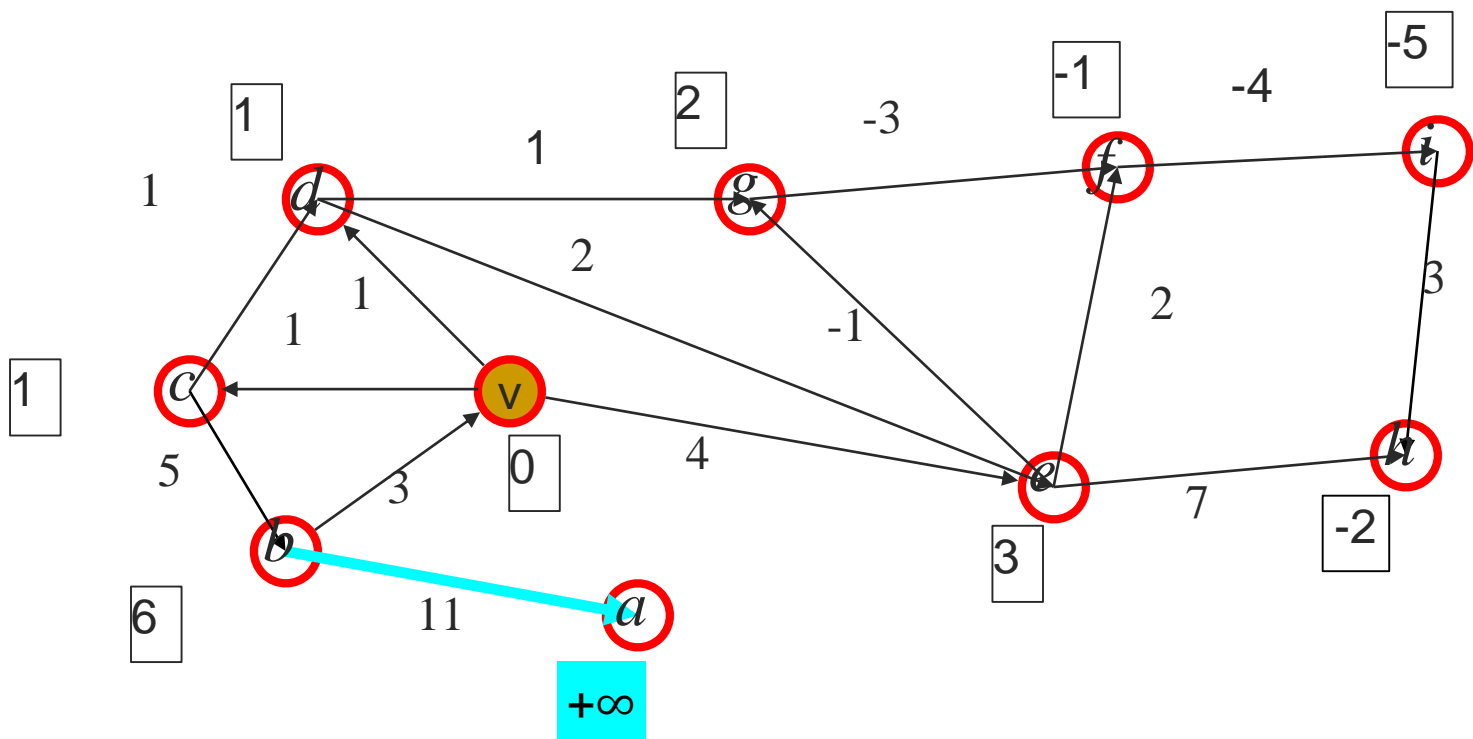
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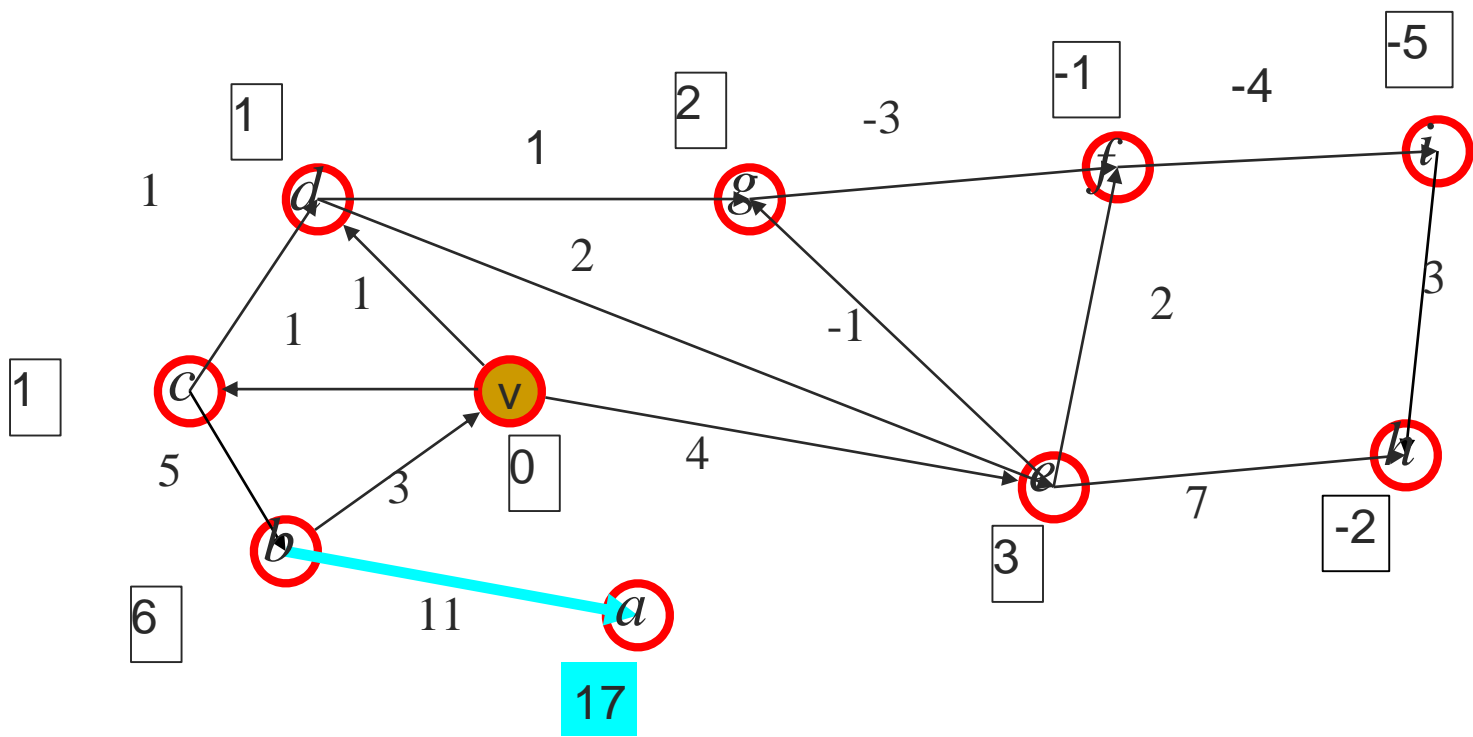
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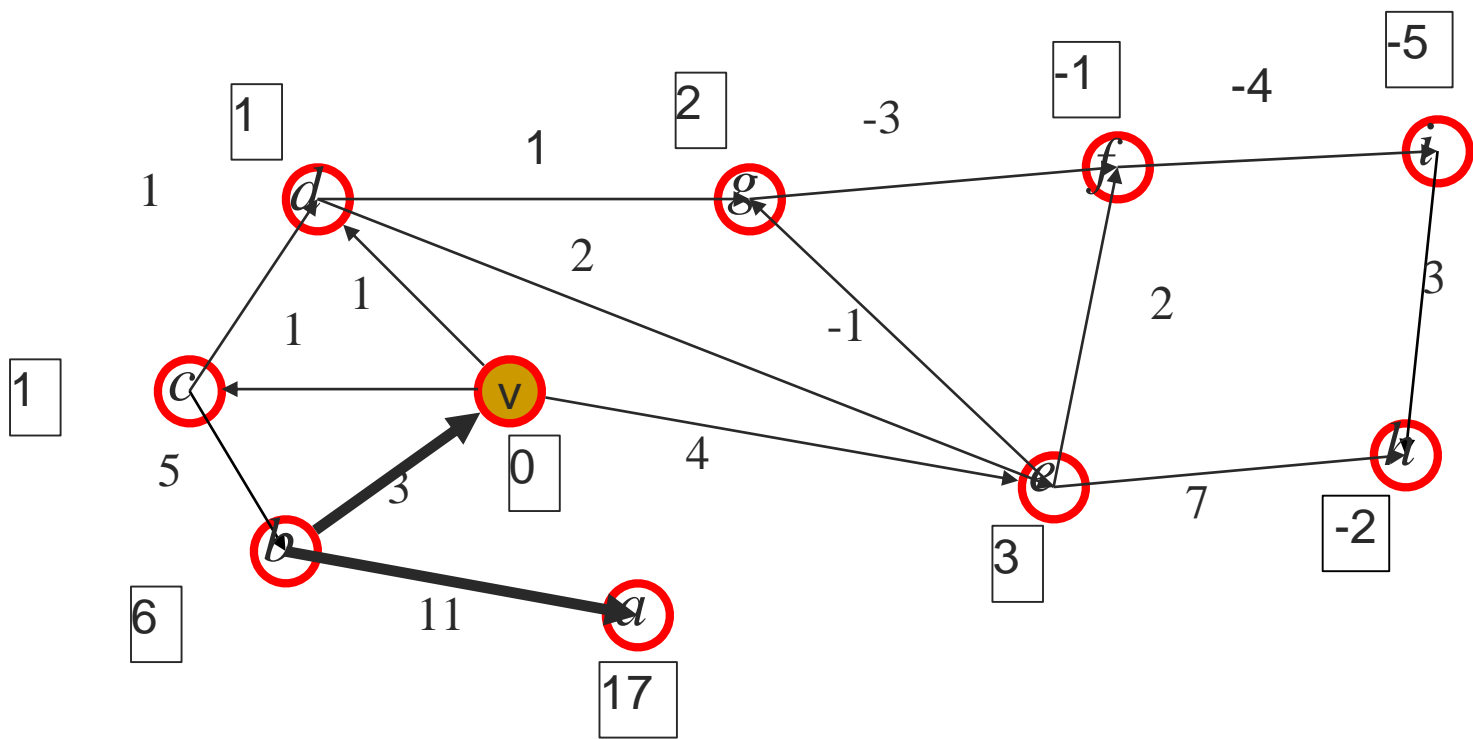
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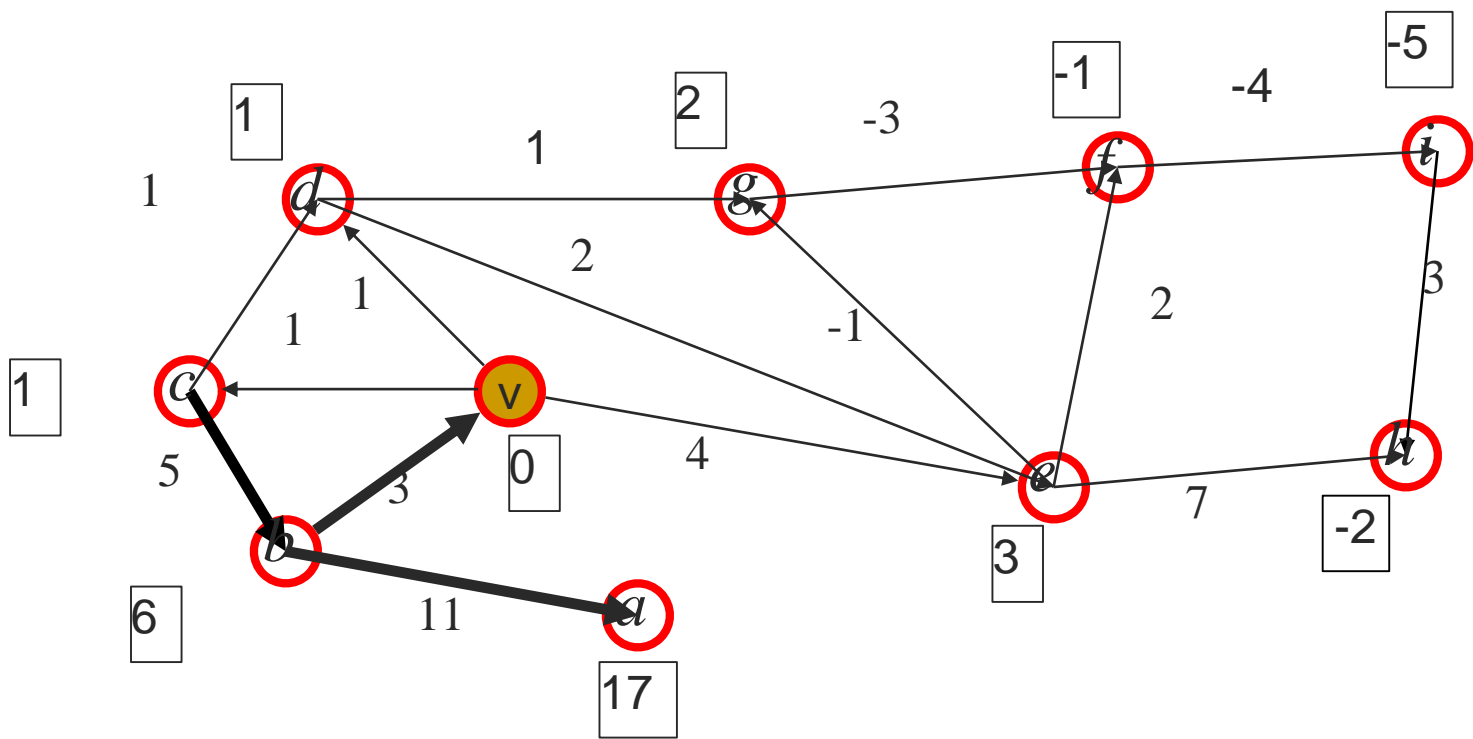
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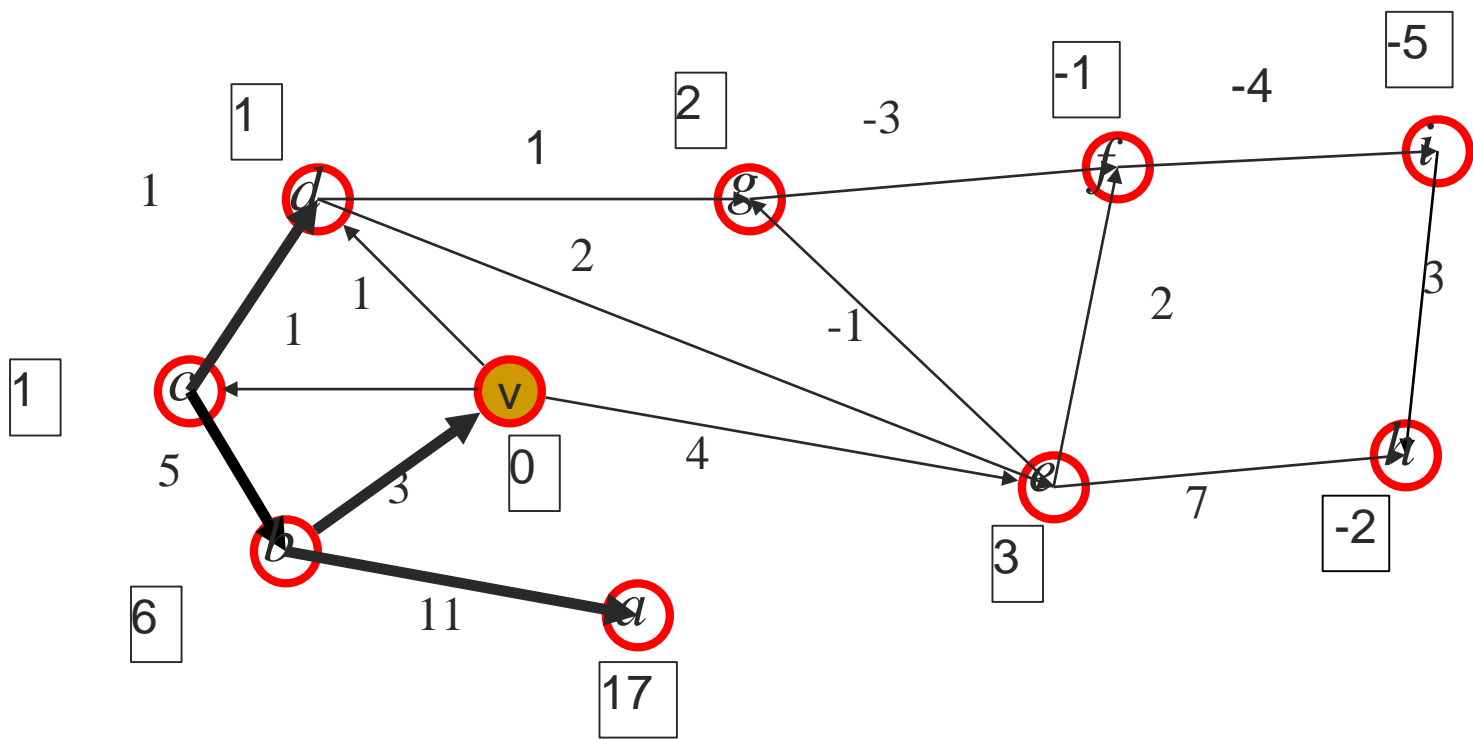
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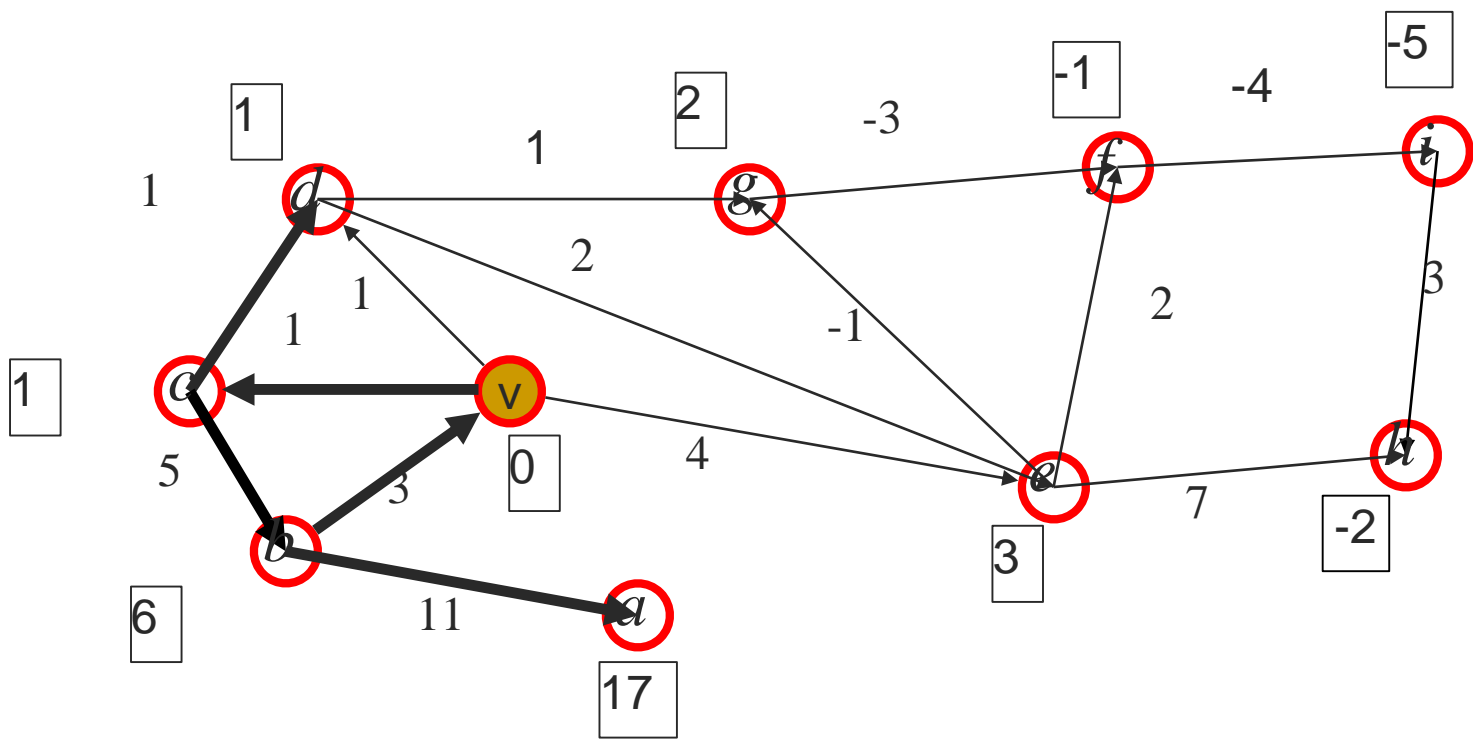


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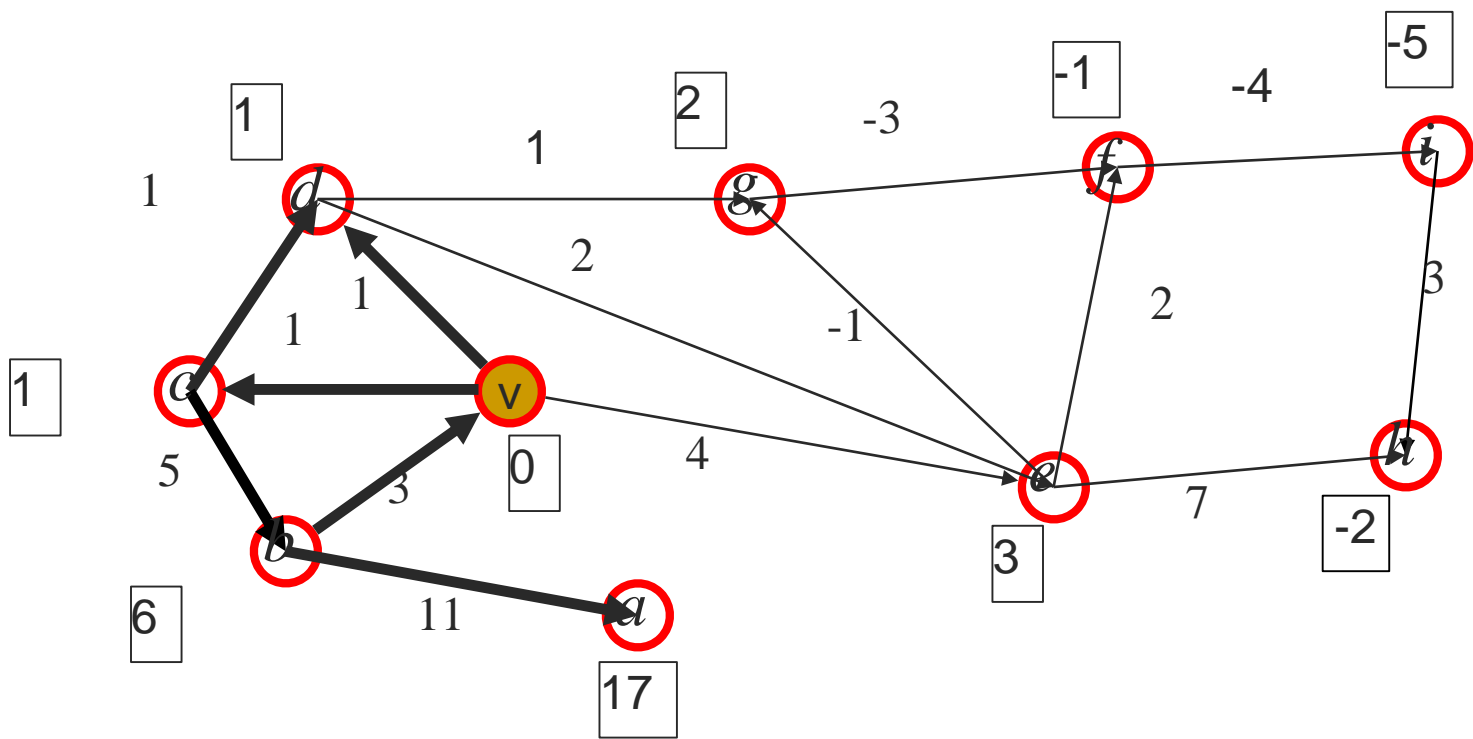




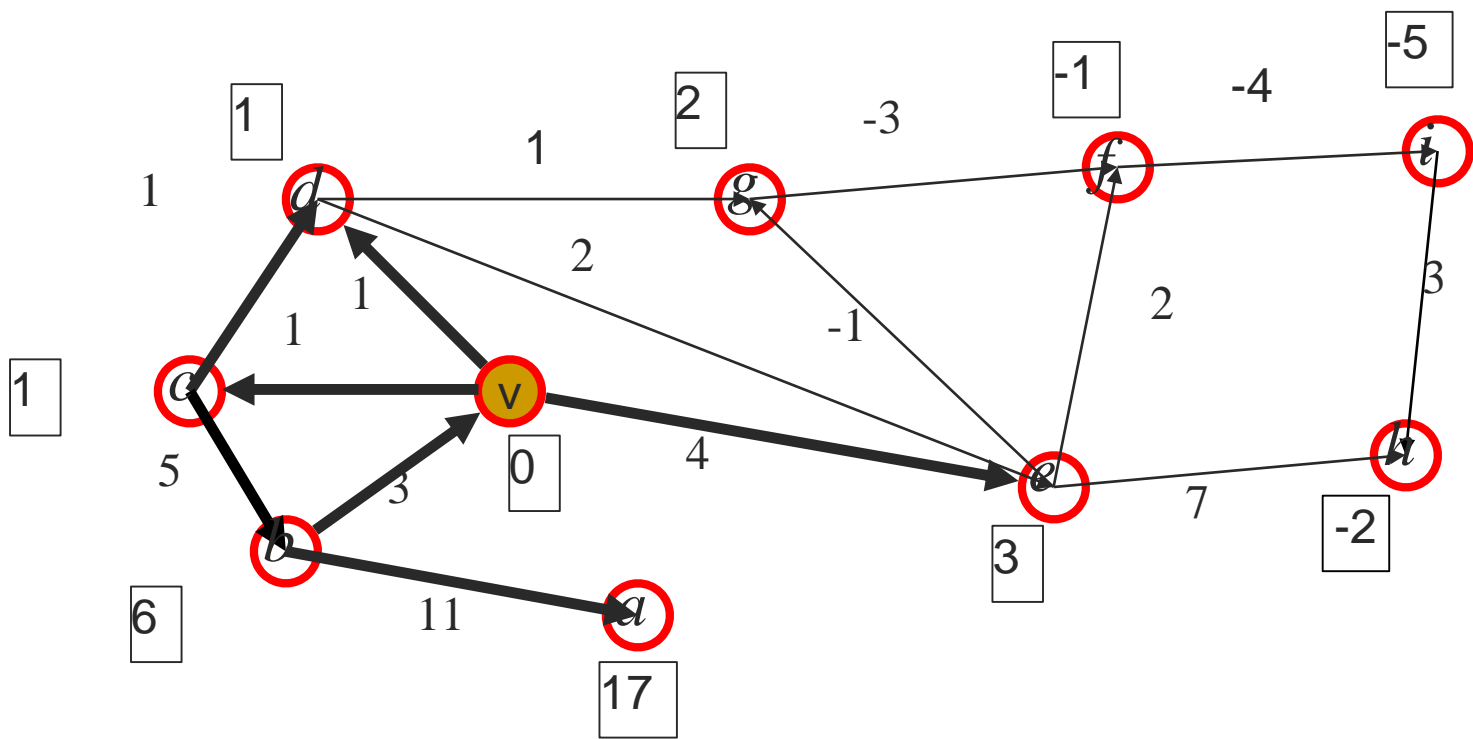
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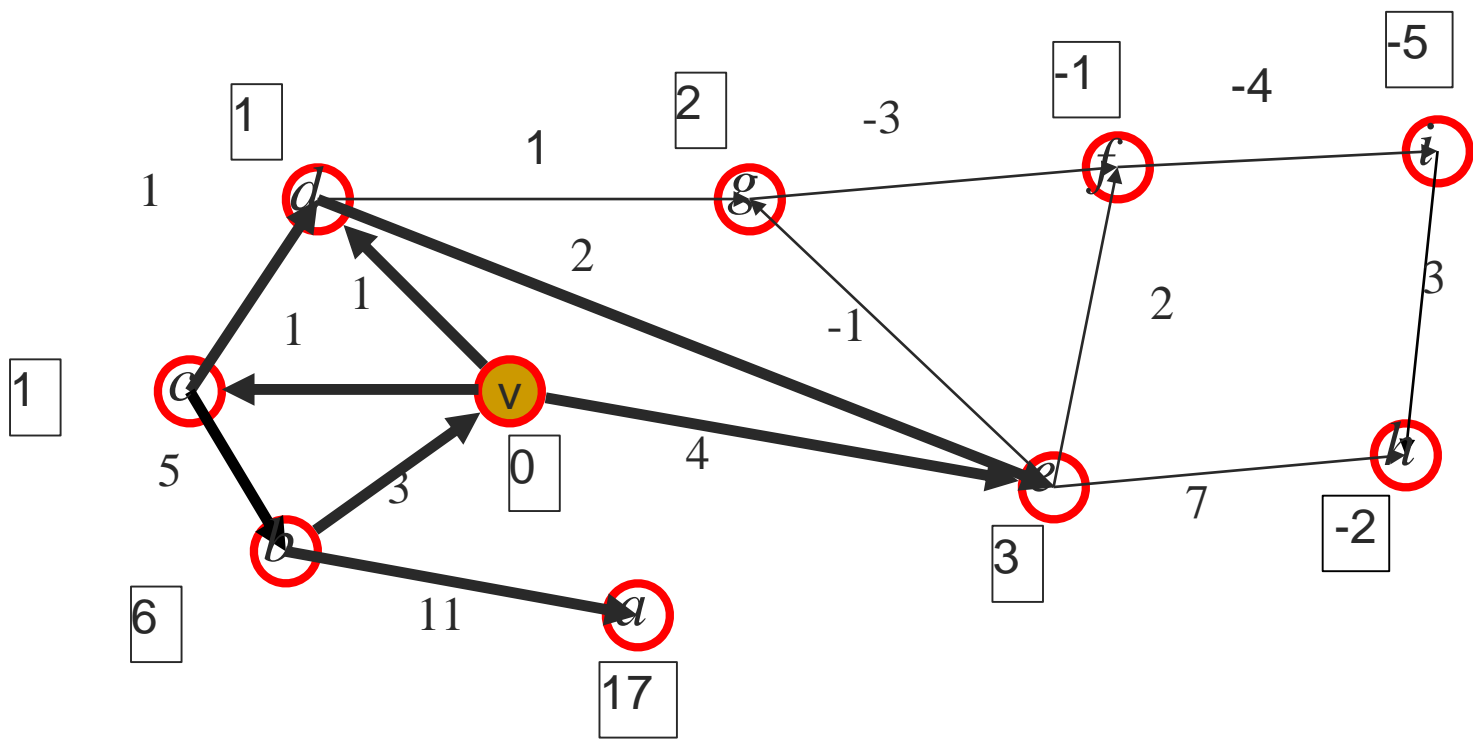
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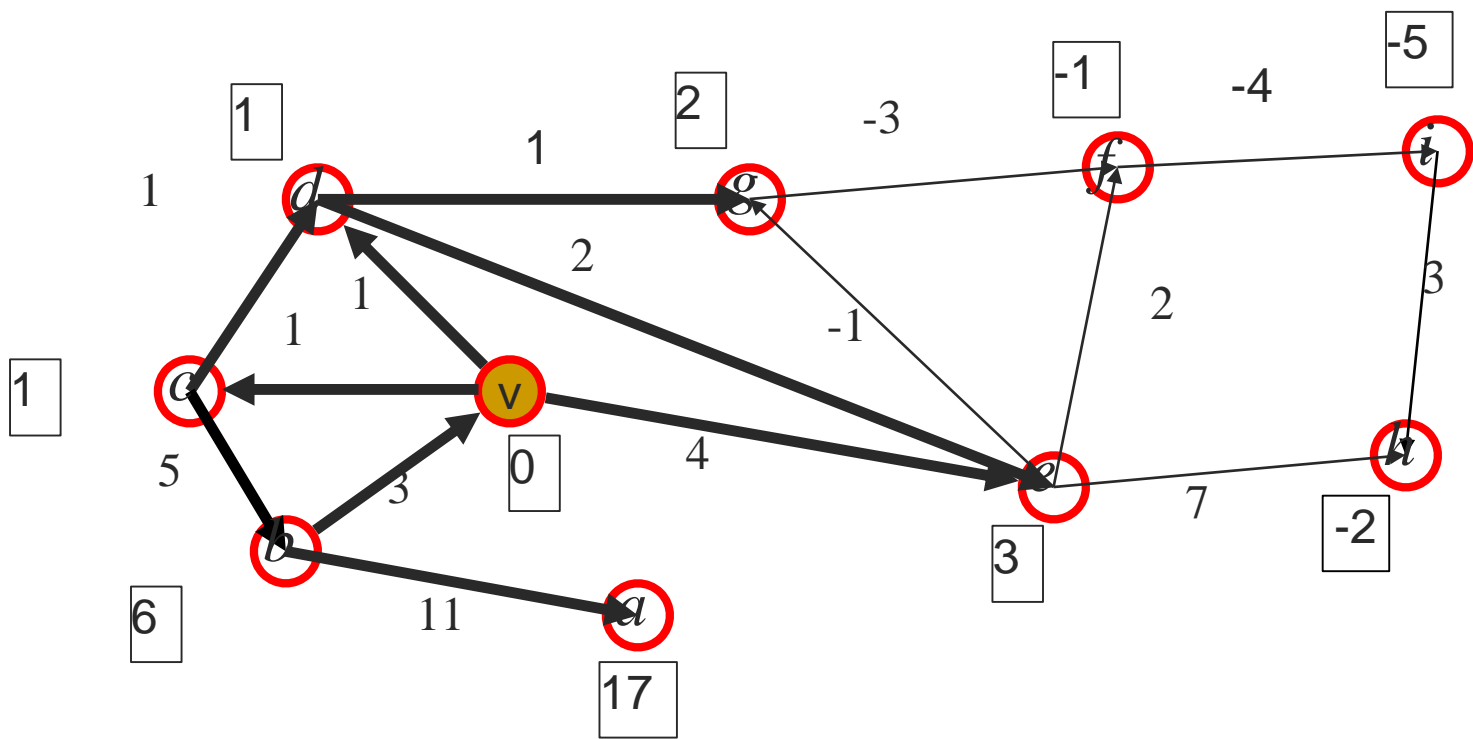
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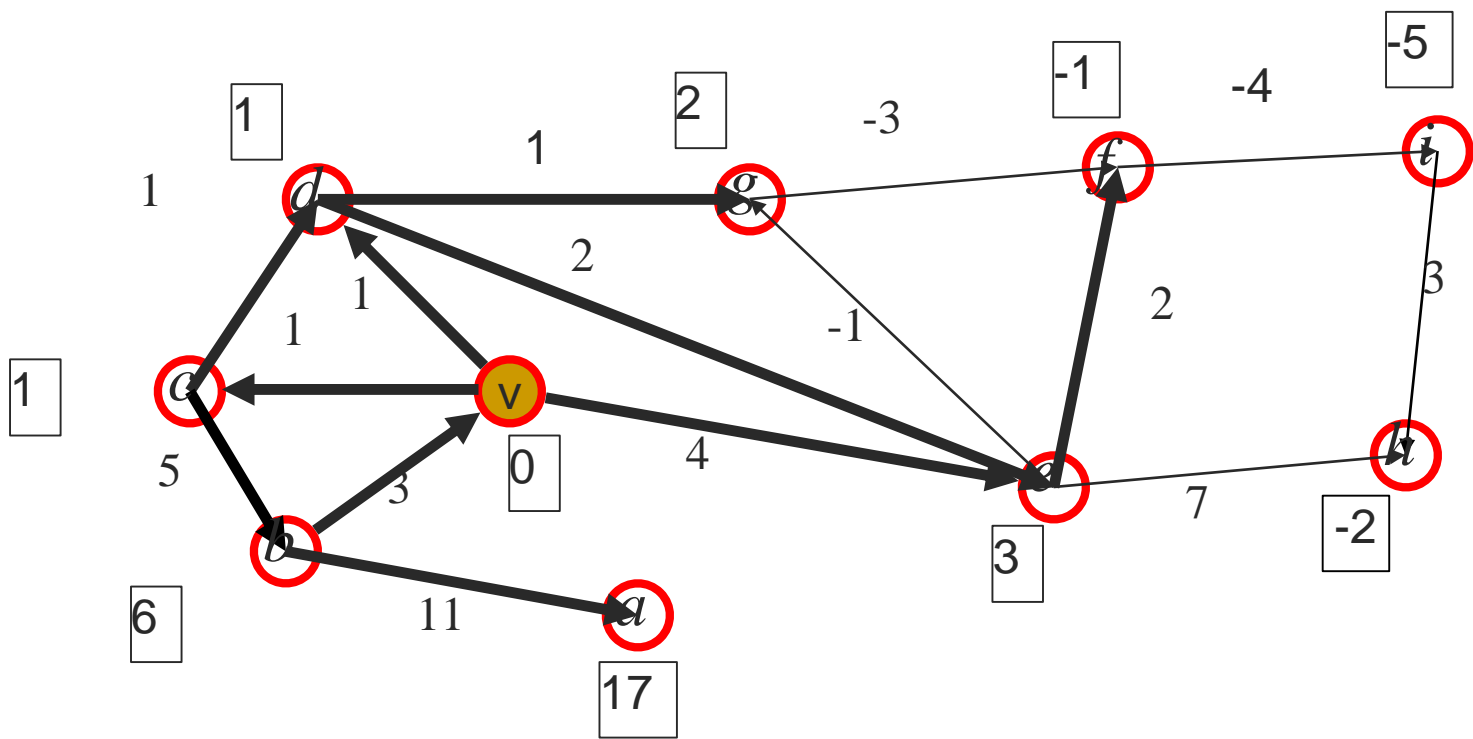
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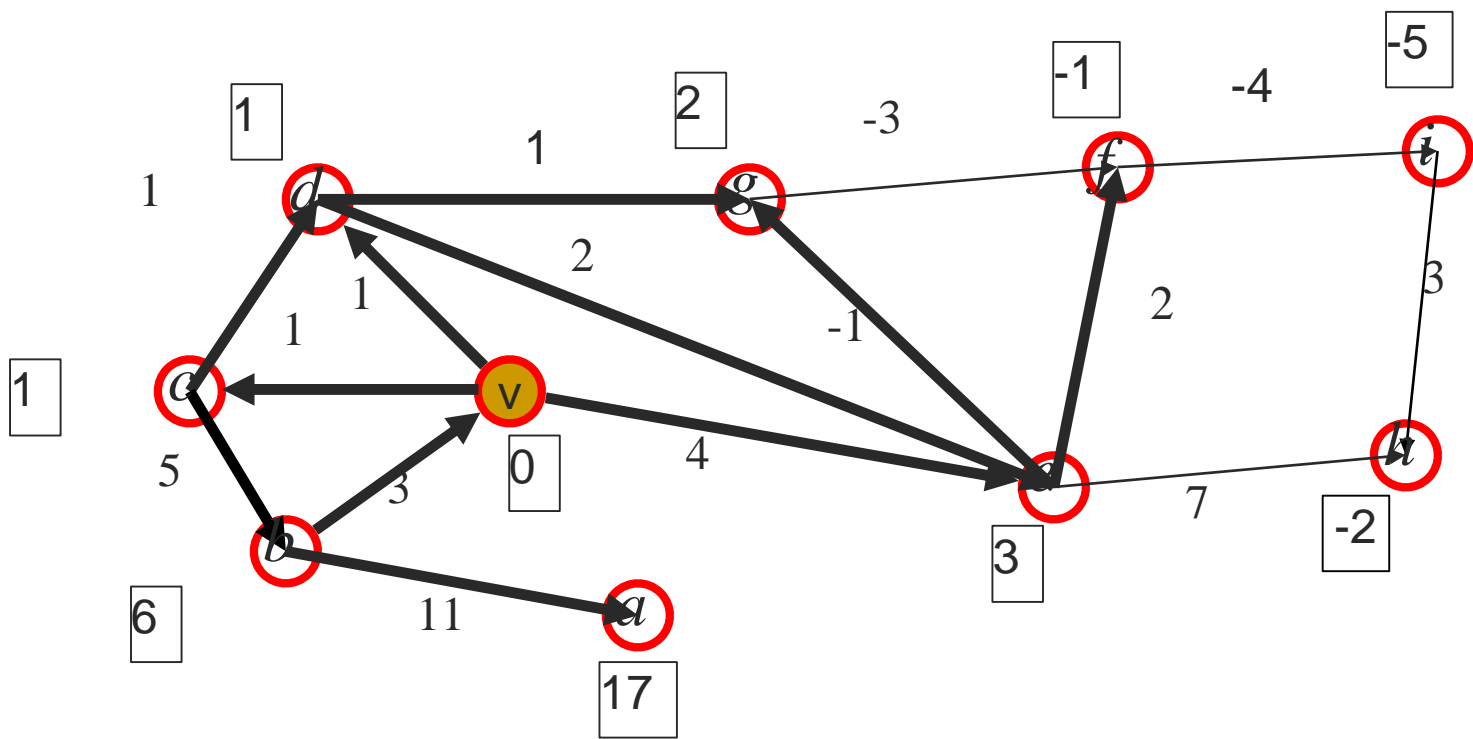
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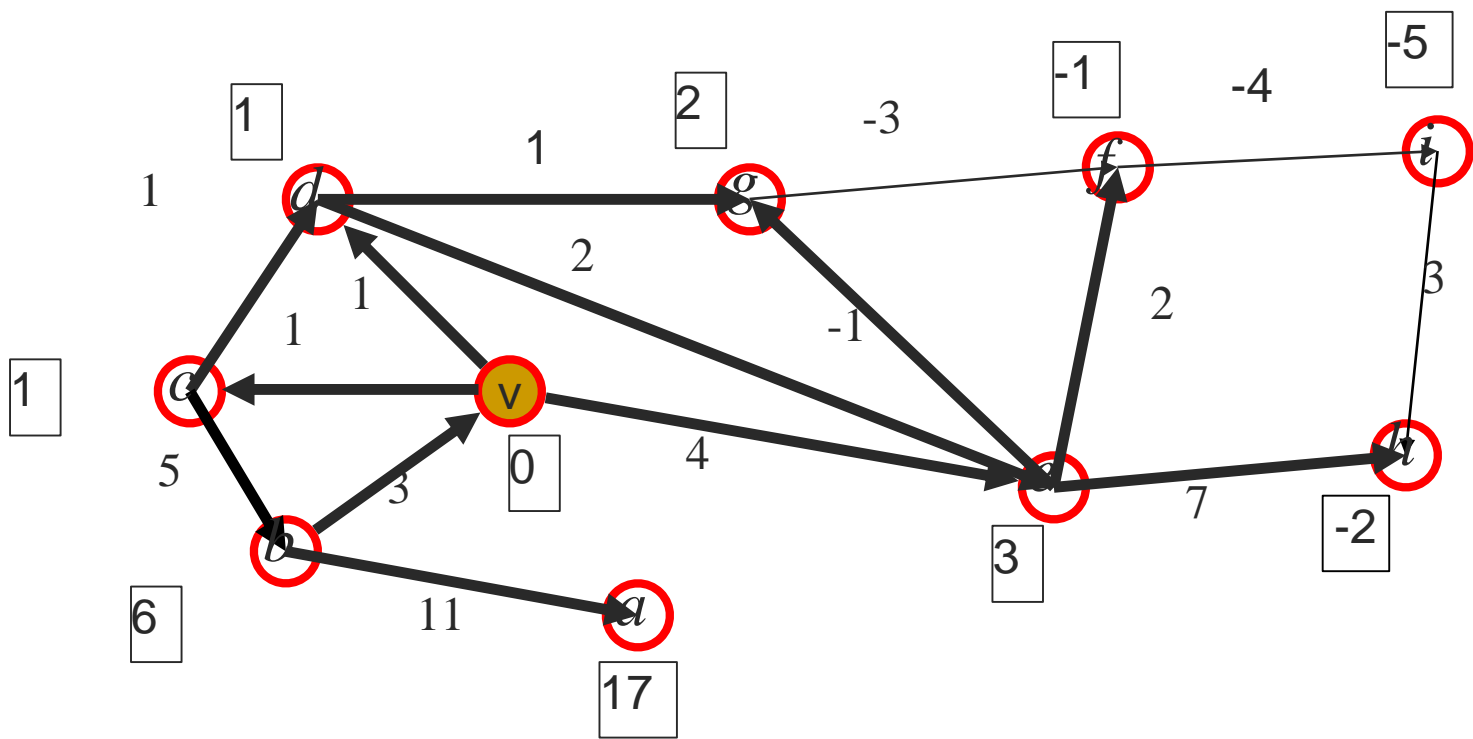
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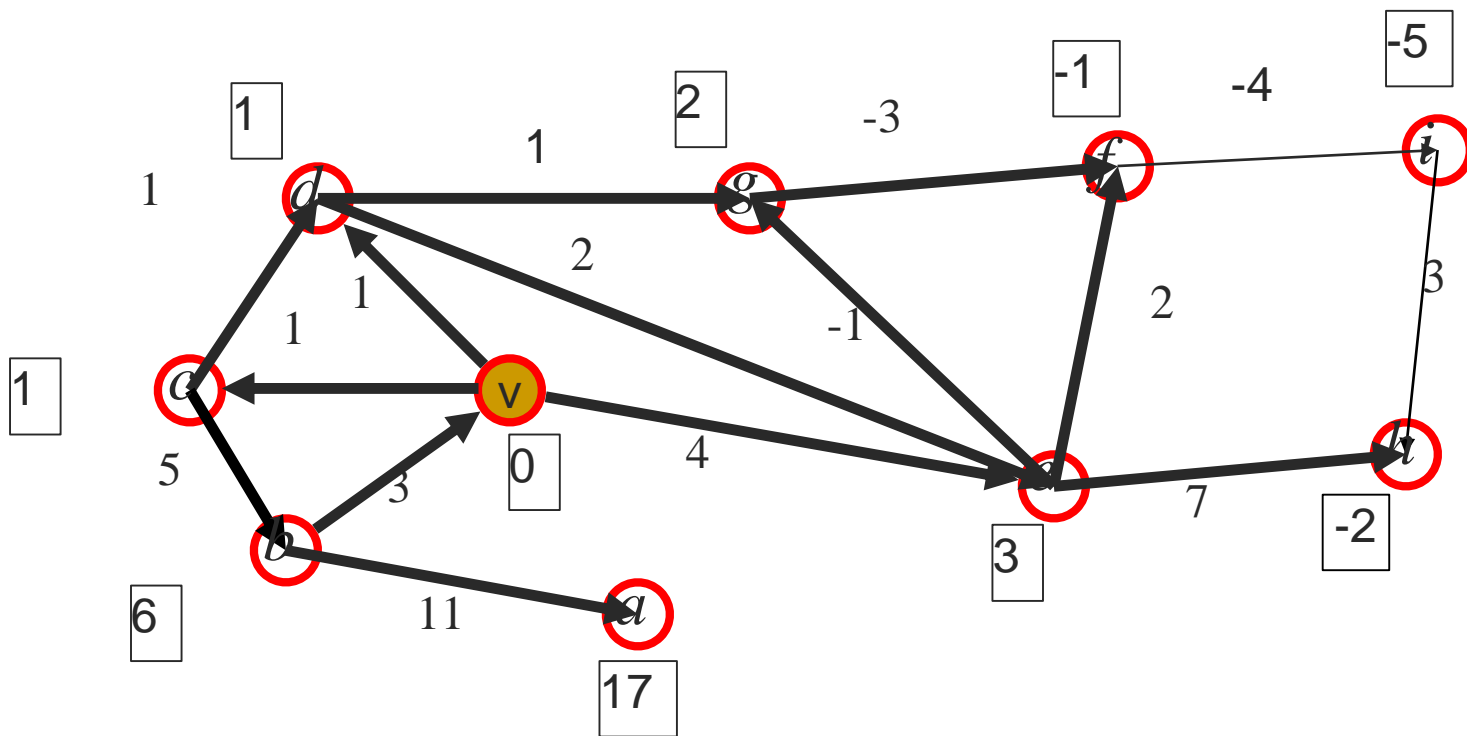


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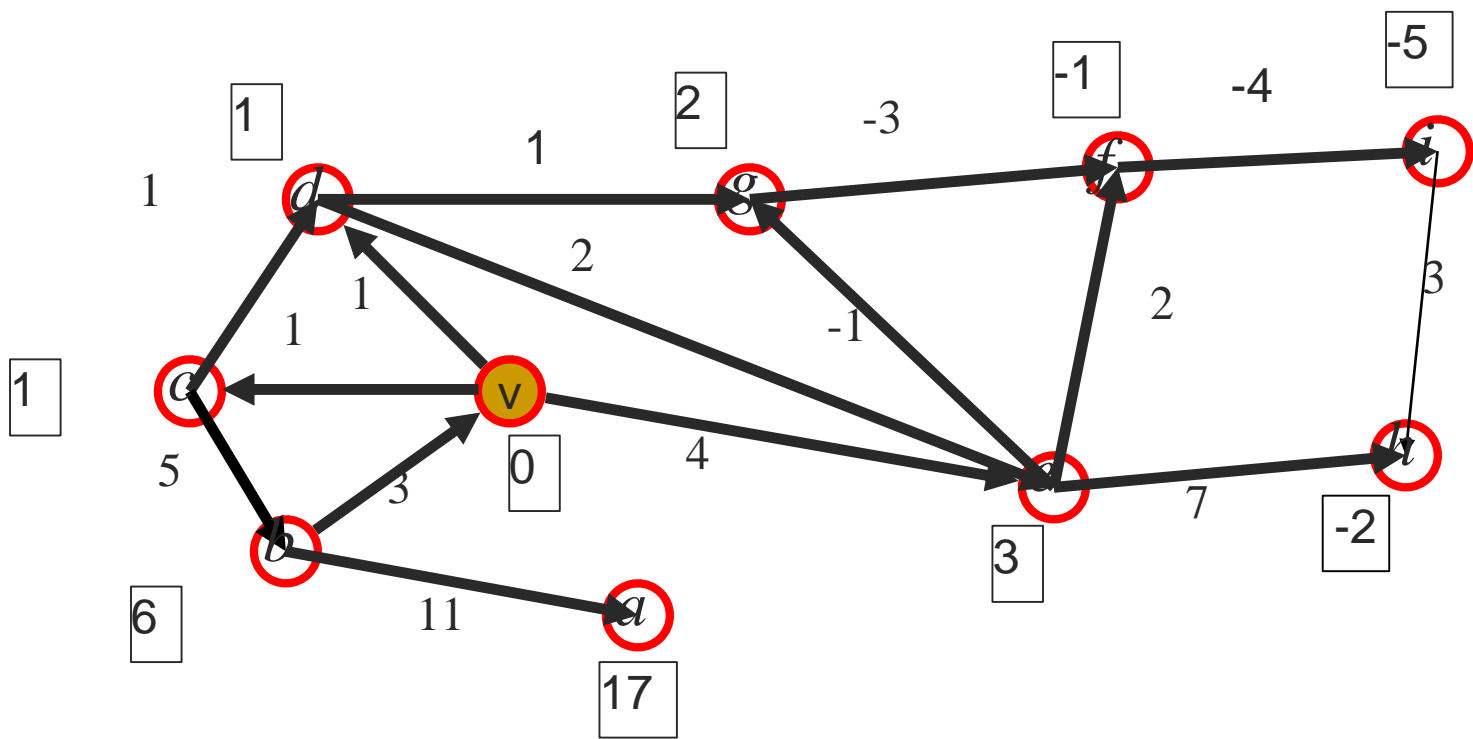




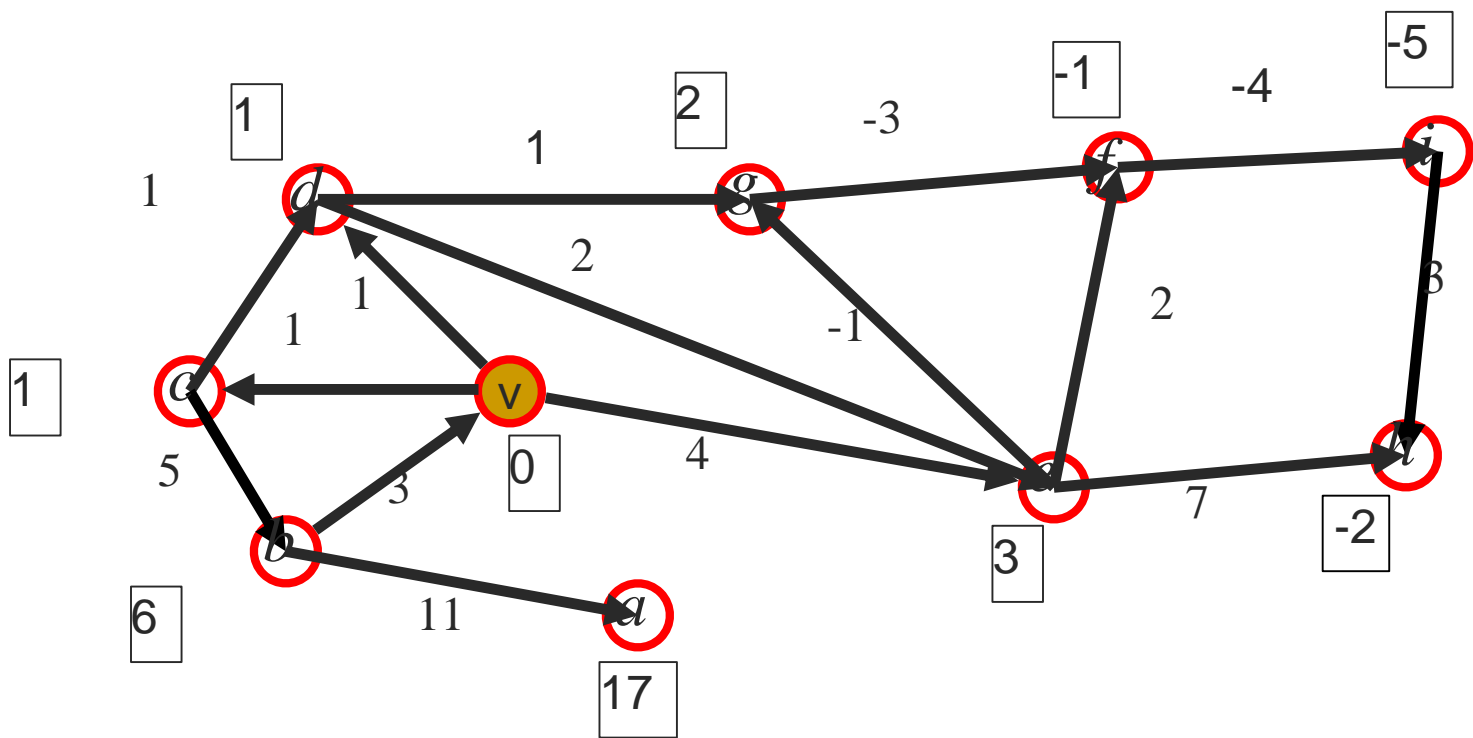
i=3



i=3



i=3



# Algorithm continues until $i=n-1$

- In this example:  $i = 9$ , no more changes starting at  $i = 4$

Running Time

# Algorithm Bellman-Ford( $G, v$ )

```
D[v] ← 0
for each vertex  $u \neq v$  of  $G$  do
    D[u] ←  $+\infty$ 
for  $i \leftarrow 1$  to  $n-1$  do
    for each edge  $(u, z)$  in  $G$  do
        if  $D[u] + w((u, z)) < D[z]$  then
            D[z] ←  $D[u] + w((u, z))$ 
if there are no edges left with potential
relaxation operations then
    return D
else
    return "G contains a negative cycle"
```

performs  $n-1$   
times a  
relaxation of  
every edge  
in the graph

# Running time of Bellman-Ford algorithm

- $O(nm)$

# Shortest Paths in directed acyclic graphs

- Can we do faster than Bellman-Ford?

# All-pairs shortest paths

- For graphs with nonnegative edges
  - Run Dijkstra for each vertex (as a source).
  - $n$  times  $O(m \log n)$  is:  $O(n m \log n)$
- For digraphs with negative edges
  - Run Bellman-Ford for each vertex (as a source).
  - $n$  times  $O(n m)$  is:  $O(n^2 m)$
- Use programming [Dynamic Programming](#)