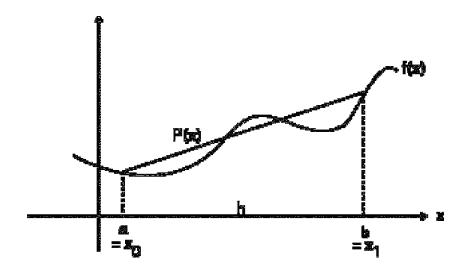
COMPUTER SCIENCE 349A Handout Number 26

NEWTON-COTES CLOSED QUADRATURE FORMULAS

The case n = 1 (Section 21.1 of the textbook):



Here h = b - a. The (linear) interpolating polynomial is

$$P(x) = \frac{x - x_1}{x_0 - x_1} f(x_0) + \frac{x - x_0}{x_1 - x_0} f(x_1) .$$

The quadrature formula for approximating $\int_a^b f(x)dx$ is obtained by integrating P(x):

$$\int_{a}^{b} f(x)dx \approx \int_{x_{0}}^{x_{1}} P(x)dx$$

$$= \left[\int_{x_{0}}^{x_{1}} \frac{x - x_{1}}{x_{0} - x_{1}} f(x_{0})dx \right] + \left[\int_{x_{0}}^{x_{1}} \frac{x - x_{0}}{x_{1} - x_{0}} f(x_{1})dx \right]$$

$$= \frac{f(x_{0})}{x_{0} - x_{1}} \left[\frac{x^{2}}{2} - x_{1}x \right]_{x_{0}}^{x_{1}} + \frac{f(x_{1})}{x_{1} - x_{0}} \left[\frac{x^{2}}{2} - x_{0}x \right]_{x_{0}}^{x_{1}}$$

$$= \frac{x_{1} - x_{0}}{2} f(x_{0}) + \frac{x_{1} - x_{0}}{2} f(x_{1})$$

$$= \frac{h}{2} [f(x_{0}) + f(x_{1})], \text{ since } h = x_{1} - x_{0}.$$

This is the **trapezoidal rule**. Its error term can be obtained by integrating the error term of the Lagrange form of the interpolating polynomial, which for n = 1 is

$$f(x) - P(x) = \frac{f''(\xi(x))}{2}(x - x_0)(x - x_1).$$

Note that ξ does depend on x; for each value of x in [a, b], there is a different value ξ for which the above expression gives the value of f(x) - P(x). Integrating this gives

$$\int_{a}^{b} f(x)dx - \int_{x_{0}}^{x_{1}} P(x)dx = \int_{a}^{b} f(x)dx - \frac{h}{2}[f(x_{0}) + f(x_{1})]$$

$$= \int_{a}^{b} \frac{f''(\xi(x))}{2}(x - x_{0})(x - x_{1})dx$$

$$= \frac{f''(\eta)}{2} \int_{a}^{b} (x - x_{0})(x - x_{1})dx, \text{ for some constant}$$

$$\eta \text{ between } a \text{ and } b, \text{ by themean - value}$$
theorem for integrals
$$= \frac{f''(\eta)}{2} \int_{0}^{1} h^{2}t(t - 1)(hdt), \text{ with the change of}$$
variable $x = x_{0} + th$, so that $x - x_{0} = th$
and $x - x_{1} = (t - 1)h$

$$= h^{3} \frac{f''(\eta)}{2} \int_{0}^{1} t(t - 1)dt$$

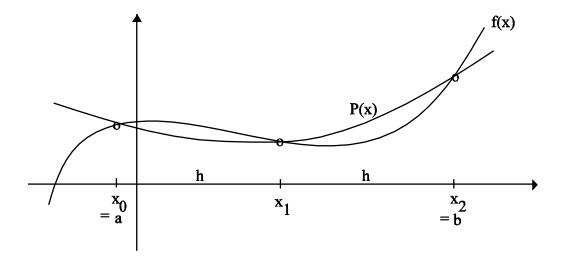
$$= -\frac{h^{3}}{12} f'''(\eta), \text{ for some value } \eta \text{ between } a \text{ and } b.$$

See (21.6) on page 605 of the 6th ed. or page 607 of the 7th ed., where h = b - a. This error term is the **truncation error** when $\int_{a}^{b} f(x)dx$ is approximated by $\int_{a}^{b} P(x)dx$.

The case n = 2 (Section 21.2.1 on page 613 of the 6th ed. or page 615 of the 7th ed.):

The quadratic interpolating polynomial is

$$P(x) = \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} f(x_0) + \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} f(x_1) + \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} f(x_2) .$$



As in the case n = 1, the quadrature formula for approximating $\int_{a}^{b} f(x)dx$ is obtained by integrating P(x): $\int_{a}^{b} f(x)dx \approx \int_{x_{0}}^{x_{2}} P(x)dx$

This gives

$$\int_{a}^{b} f(x)dx \approx \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2)),$$

where now $h = \frac{b-a}{2}$. This is called **Simpson's rule** (or as in the textbook, Simpson's 1/3 rule), and its **truncation error** is given by

$$\int_{a}^{b} f(x)dx - \int_{x_{0}}^{x_{2}} P(x)dx = -\frac{h^{5}}{90} f^{(4)}(\xi), \text{ for some value } \xi \in [a, b].$$

See pages 614-615 of the 6^{th} ed. or pages 616-617 of the 7^{th} ed.

The Newton-Cotes closed quadrature formula for n = 3, in which f(x) is approximated by a cubic polynomial that interpolates it at four equally-spaced points, is

$$\int_{a}^{b} f(x)dx \approx \frac{3h}{8} (f(x_0) + 3f(x_1) + 3f(x_2) + f(x_3)), \text{ where } h = \frac{b - a}{3},$$

which is called the **Simpson's 3/8 rule**. See Section 21.2.3 on page 618 of the 6^{th} ed. or page 620 of the 7^{th} ed.