

CSC349A Numerical Analysis

Lecture 5

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Truncation Errors

Truncation errors occur when some exact mathematical procedure is replaced by a finite approximation. Examples:

- Approximation of a function by a finite number of terms:

$$e^x \approx 1 + x + \frac{x^2}{2} + \frac{x^3}{6}$$

- Approximation of a derivative by a finite difference:

$$\left. \frac{dv}{dt} \right|_{t=t_i} \approx \frac{v(t_{i+1}) - v(t_i)}{t_{i+1} - t_i}$$

- Approximation of a definite integral by a finite sum:

$$\int_a^b f(x) dx \approx \frac{b-a}{2} [f(a) + f(b)]$$

Taylor's Theorem is the fundamental tool for deriving and analyzing numerical approximation formulas in this course.

- It states that any “smooth” function (one with a sufficient number of derivatives) can be approximated by a polynomial, and it includes an error (remainder) term that indicates how accurate the polynomial approximation is.
- Taylor's theorem also provides a means to estimate the value of a function $f(x)$ at some point x_{i+1} using the values of $f(x)$ and its derivatives at some nearby point x_i .

Taylor's theorem definition

Definition

Let $n \geq 0$ and let a be any constant. If $f(x)$ and its first $n + 1$ derivatives are continuous on interval containing x and a , then:

$$f(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \frac{f'''(a)}{3!}(x - a)^3 + \cdots + \frac{f^n(a)}{n!}(x - a)^n + R_n$$

where R_n is the *remainder* term.

Taylor polynomial

$$P_n(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \frac{f'''(a)}{3!}(x - a)^3 + \cdots + \frac{f^n(a)}{n!}(x - a)^n$$

is a polynomial of degree n in x , and is called the **Taylor polynomial approximation of degree n** for $f(x)$ expanded about a .

Truncation error

The remainder term, R_n , is the **truncation error** of the Taylor polynomial approximation to $f(x)$.

$$R_n = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - a)^{n+1}$$

where ξ is some value between x and a .

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Example 1

Determine the Taylor polynomial approximation of order $n = 3$ for $f(x) = \ln(x + 1)$ expanded about $a = 0$ (McLaurin series when $a = 0$). How accurate is it?

Truncation error on interval

Rather than just using the Taylor polynomial approximation to estimate the value of a function at one specified point, it is more common to use the polynomial approximation **for an entire interval of values x** . In such a case, it is also desirable to be able to determine the accuracy (that is an upper bound for the error).

Take a closer look

What are we doing here?

- We know $f(a)$, $f'(a)$, $f''(a)$, etc.
- We approximate some neighbouring $f(x)$.
- That is, if we know the value of a function and its derivatives at some point, we can predict its value at some other (nearby) point.
- What does this describe?

An iterative process for approximating a function

Let $x_{i+1} = x_i + h$ so that $h = x_{i+1} - x_i$. Then Taylor's theorem for $f(x)$ expanded about x_i , and evaluated at $x = x_{i+1}$ is:

$$f(x_{i+1}) = f(x_i) + f'(x_i)h + \frac{f''(x_i)}{2!}h^2 + \frac{f'''(x_i)}{3!}h^3 + \dots + \frac{f^n(x_i)}{n!}h^n + R_n$$

Approximating first derivative

This gives the first derivative approximation

$$f'(x_i) \approx \frac{f(x_{i+1}) - f(x_i)}{h}$$

that was used in Chapter 1; it also gives the truncation error of this finite difference approximation to the derivative, namely $-\frac{R_1}{h} = -\frac{f''(\xi)}{2}h$. As this is some constant times h , we say that this truncation error is $O(h)$.

Example 3

The Taylor polynomial approximation for $f(x) = e^x$ expanded about $a = 0$ is

$$e^x \approx 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots + \frac{x^n}{n!}$$

It is clear from:

$$R_n = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - a)^{n+1}$$

Example 3

The truncation error of any Taylor polynomial approximation is small when x is close to a (note that $R_n = 0$ when $x = a$) and will increase as x gets further away from a . Also, as n increases, the Taylor polynomial approximations become better and better approximations to $f(x)$, provided of course that $f^{(n+1)}(x)$ is bounded on some interval containing x and a .

Alternative form of remainder

Alternative form for the remainder R_n which can also be defined as:

$$R_n = \int_a^x \frac{(x-t)^n}{n!} f^{(n+1)}(t) dt \quad (1)$$

The derivation is based on the first theorem of mean for integrals which states that if a function f is continuous and integrable on an interval containing α and x , then there exists a point ξ between α and x such that:

$$\int_{\alpha}^x g(t)dt = g(\xi)(x - \alpha) \quad (2)$$