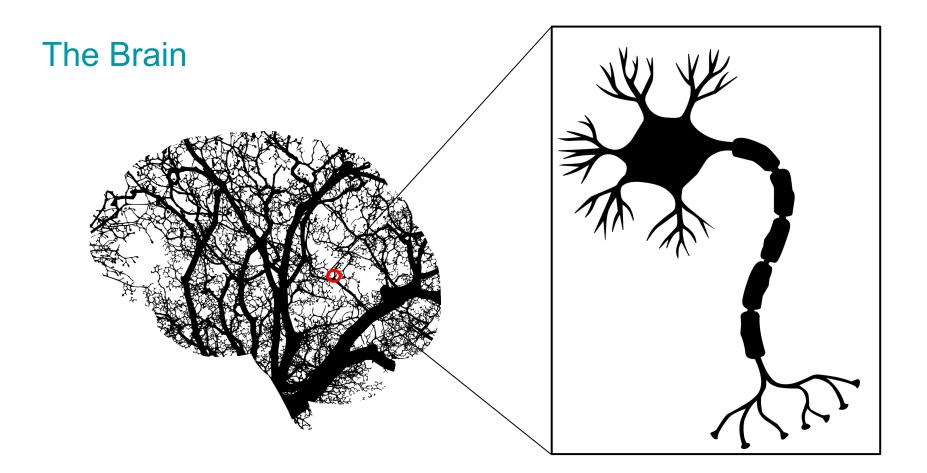
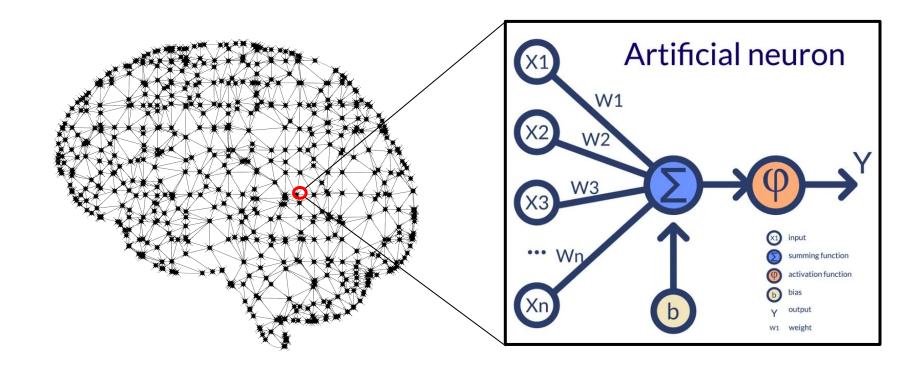
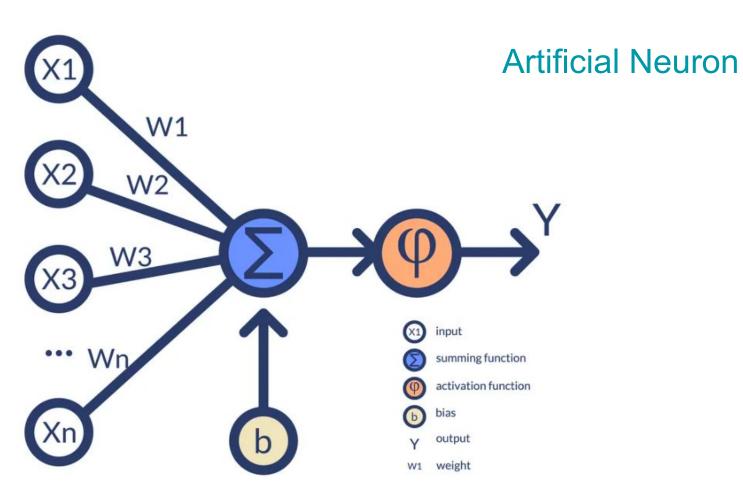
Machine Learning

Lecture 3

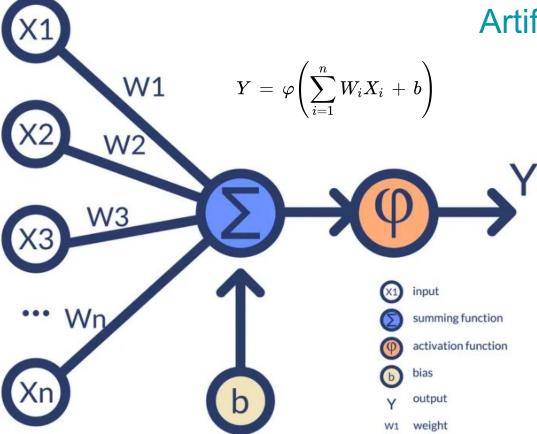


Artificial Neural Network





Artificial Neuron



$Y \,=\, arphi \Biggl(\sum_{i=1}^n W_i X_i \,+\, b \Biggr)$ W1 W2 **W3** input summing function activation function bias output weight

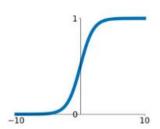
Artificial Neuron

Perceptron

Activation Functions (φ)

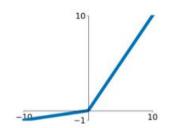
Sigmoid

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



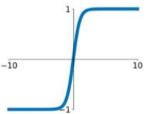
Leaky ReLU

 $\max(0.1x, x)$



tanh

tanh(x)

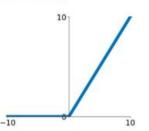


Maxout

 $\max(w_1^T x + b_1, w_2^T x + b_2)$

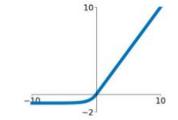
ReLU

 $\max(0, x)$



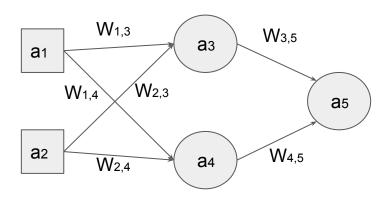
ELU

$$\begin{cases} x & x \ge 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



Feed Forward Neural Network

Single Layer Perceptrons

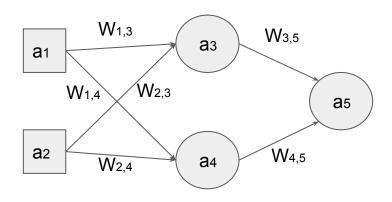


$$egin{aligned} a_5 &= arphi(W_{3,5}, a_3 + W_{4,5}, a_4) \ &= arphi(W_{3,5} \, . \, arphi(W_{1,3}, a_1 + W_{2,3}, a_2) \, + \, W_{4,5}, arphi(W_{1,4}, a_1 + W_{2,4}, a_2)) \end{aligned}$$

- → Feed-forward network = a parameterized family of nonlinear functions
- → Adjusting weights changes the function: do learning this way!

Feed Forward Neural Network

Single Layer Perceptrons



$$egin{aligned} a_5 &= arphi(W_{3,5}.\,a_3 \,+\, W_{4,5}.\,a_4) \,=\, arphi(Net_5) \ &= arphi(W_{3,5}\,.\,arphi(W_{1,3}.\,a_1 \,+\, W_{2,3}.\,a_2) \,+\, W_{4,5}.\,arphi(W_{1,4}.\,a_1 \,+\, W_{2,4}.\,a_2)) \end{aligned}$$

- → Feed-forward network = a parameterized family of nonlinear functions
- → Adjusting weights changes the function: HOW?

Backpropagation

Multilayer Perceptron with a single hidden layer:

$$L(x,y, heta) \,=\, rac{1}{2} (y\,-\,a_5)^2$$

we want to know how much change in W_{3,5} affects the total Loss, AKA the gradient of W_{3,5, i.e. $\rightarrow \frac{\mathrm{d}L}{\mathrm{d}W_{3,5}}$}

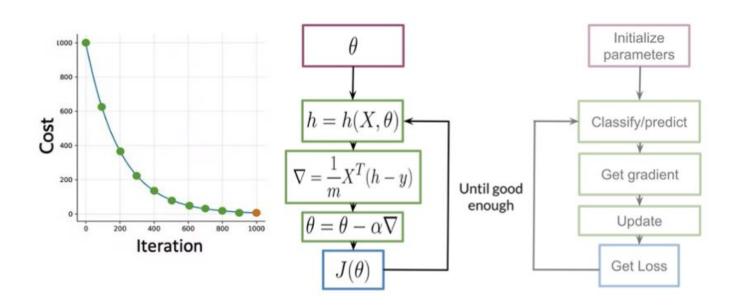
Using chain rule : $\frac{\mathrm{d}L}{\mathrm{d}W_{3,5}}=\frac{\mathrm{d}L}{\mathrm{d}a_5}.\frac{\mathrm{d}a_5}{\mathrm{d}Net_5}.\frac{\mathrm{d}Net_5}{\mathrm{d}W_{3,5}}$

Now,

$$egin{aligned} &\Rightarrow rac{\mathrm{d}L}{\mathrm{d}a_5} = rac{\mathrm{d}\left(rac{1}{2}(y-a_5)^2
ight)}{\mathrm{d}a_5} = -(y-a_5) \ &\Rightarrow rac{\mathrm{d}a_5}{\mathrm{d}Net_5} = rac{\mathrm{d}\left(1+e^{-Net_5}
ight)^{-1}}{\mathrm{d}Net_5} = rac{e^{-Net_5}}{(1+e^{-Net_5})^2} = a_5(1-a_5) \ &\Rightarrow rac{\mathrm{d}Net_5}{\mathrm{d}W_{3.5}} = rac{\mathrm{d}(W_{3,5}a_3+W_{4,5}a_4)}{\mathrm{d}W_{3.5}} = a_3 \end{aligned}$$

Backpropagation

$$\Delta W_{3,5} = -(y-a_5) \cdot a_5(1-a_5) \cdot a_3$$



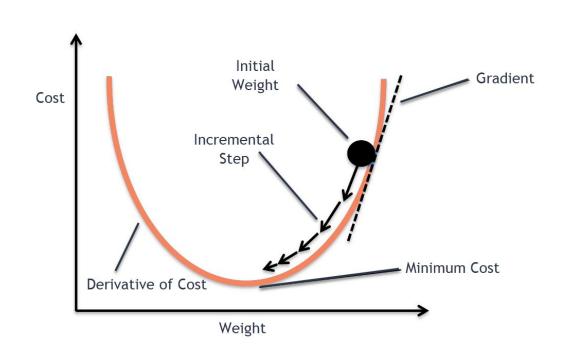
Gradient Descent

$$\min_{\theta} J(\theta)$$

$$\theta \leftarrow \theta - \alpha \frac{\mathrm{d}}{\mathrm{d}\theta} J(\theta)$$

$$rac{\mathrm{d}}{\mathrm{d} heta}J(heta) \,=\, (h(x,\, heta)\,-\,y)\,x$$

$$heta \leftarrow heta \, - \, lpha(h(x, \, heta) \, - \, y)x$$



 $\alpha \rightarrow$ learning rate

Multi-layer Neural Network

Perceptrons

