

2.6.1 Pipeline/Timing of Control Register Accesses

As shown in this section, all **MVC** are single-cycle instructions that complete their access of the explicitly named registers in the E1 pipeline phase. This is true whether **MVC** is moving a general register to a control register, or vice versa. In all cases the source register content is read, moved through the .S2 unit, and written to the destination register in the E1 pipeline phase.

Pipeline Stage	E1
Read	<i>src2</i>
Written	<i>dst</i>
Unit in use	.S2

Even though **MVC** modifies the particular target control register in a single cycle, it can take extra clocks to complete modification of the non-explicitly named register. For example, the **MVC** cannot modify bits in the IFR directly. Instead, **MVC** can only write 1's into the ISR or the ICR to specify setting or clearing, respectively, of the IFR bits. **MVC** completes this ISR/ICR write in a single (E1) cycle (as described above) but the modification of the IFR bits themselves occur one clock later. For more information on the manipulation of ISR, ICR, and IFR see these control hardware sections in Chapter 8: section 8.3.2 *Status of, Setting, and Clearing Interrupts*, and section 8.3.3 *Returning from Interrupt Servicing Control Hardware*.

Saturating instructions, such as **SADD**, set the saturation flag bit (SAT) in the Control Status Register (CSR) indirectly. As a result, several of these instructions update the SAT bit one full clock cycle after their primary results are written to the register file. For example, the **SMPY** instruction writes its result at the end of pipeline stage E2; its primary result is available after one delay slot. In contrast, the SAT bit in the CSR is updated one cycle later than the result is written; this update occurs after two delay slots. (For the specific behavior of an instruction, refer to the description of that individual instruction).

The **B IRP** and **B NRP** instructions directly update the GIE and NMIE, respectively. Because these branches directly modify the CSR and IER (Interrupt Enable Register) respectively, there are no delay slots between when the branch is issued and when the control register updates take effect.

2.6.2 Addressing Mode Register (AMR)

For each of the eight registers (A4–A7, B4–B7) that can perform linear or circular addressing, the AMR specifies the addressing mode. A 2-bit field for each register selects the address modification mode: linear (the default) or circular mode. With

circular addressing, the field also specifies which BK (block size) field to use for a circular buffer. In addition, the buffer must be aligned on a byte boundary equal to the block size. The mode select fields and block size fields are shown in Figure 2–5, and the mode select field encoding is shown in Table 2–4.

Figure 2–5. Addressing Mode Register (AMR)

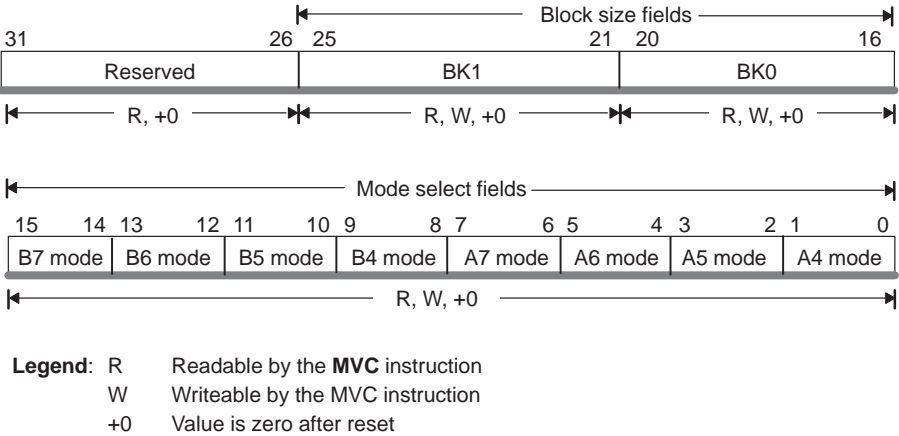


Table 2–4. Addressing Mode Register (AMR) Mode Select Field Encoding

Mode	Description
0 0	Linear modification (default at reset)
0 1	Circular addressing using the BK0 field
1 0	Circular addressing using the BK1 field
1 1	Reserved

The reserved portion of AMR is always 0. The AMR is initialized to 0 at reset.

The block size fields, BK0 and BK1, contain 5-bit values used in calculating block sizes for circular addressing.

$$\text{Block size (in bytes)} = 2^{(N+1)}$$

where N is the 5-bit value in BK0 or BK1

Table 2–5 shows block size calculations for all 32 possibilities.

Table 2–5. Block Size Calculations

N	Block Size	N	Block Size
00000	2	10000	131 072
00001	4	10001	262 144
00010	8	10010	524 288
00011	16	10011	1 048 576
00100	32	10100	2 097 152
00101	64	10101	4 194 304
00110	128	10110	8 388 608
00111	256	10111	16 777 216
01000	512	11000	33 554 432
01001	1 024	11001	67 108 864
01010	2 048	11010	134 217 728
01011	4 096	11011	268 435 456
01100	8 192	11100	536 870 912
01101	16 384	11101	1 073 741 824
01110	32 768	11110	2 147 483 648
01111	65 536	11111	4 294 967 296

Note: When N is 11111, the behavior is identical to linear addressing.