Waveform Component Portability for DSP Processing Platforms

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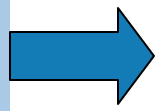
Computer Systems, Inc. MERCURY Challenges Drive Innovation™

Introduction

- **Portable waveforms that can work on any hardware**
- **Re-use existing components by using different parameters**
- **Maximum portability → standardize every aspect of the architecture**
  - Waveform Control
  - Data movement
  - Software Architecture
  - Security
  - etc..
- **Standards tend to create "Performance Bottlenecks"**
- **Not all of the standards are commoditized**
  - E.g. There is no "unique" way of communicating with non-GPP elements (DSPs, FPGAs)

Agenda

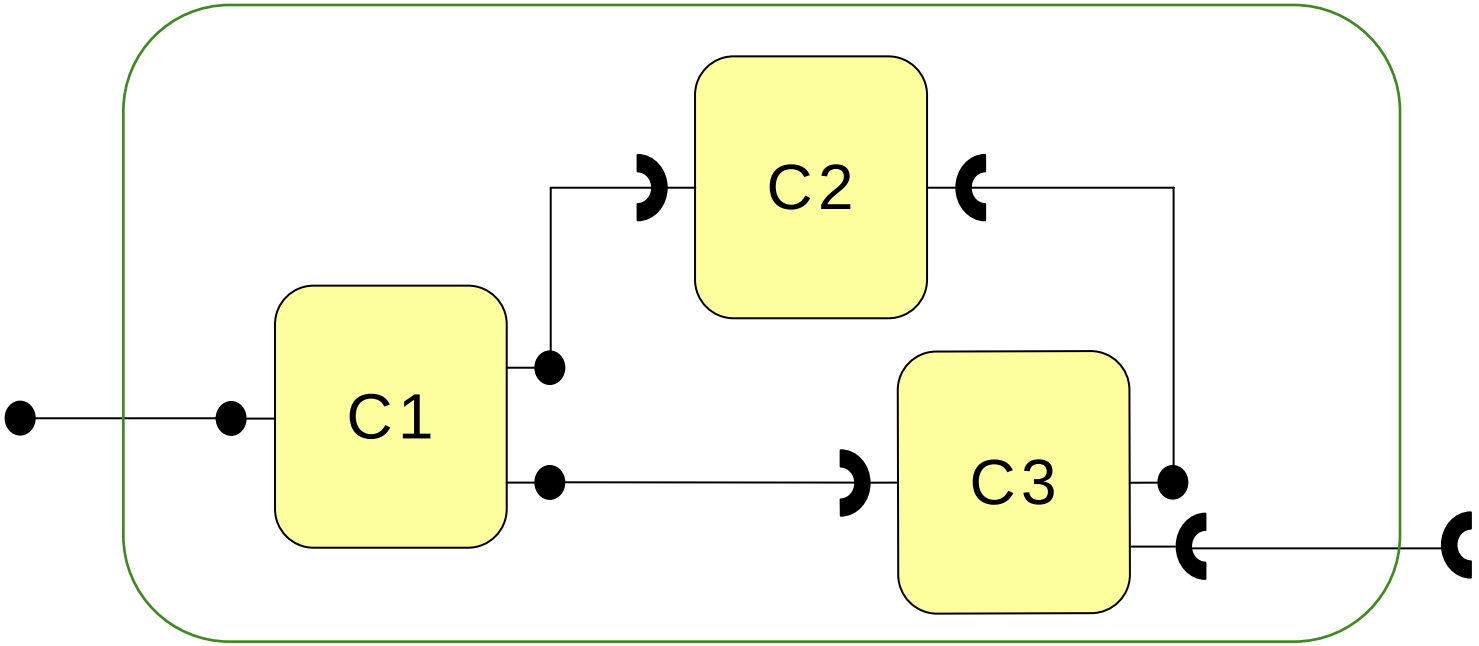


- Component Based Programming
- Development Environment
- Deployment Engine
- Run-time
- Component model

Component Based Programming

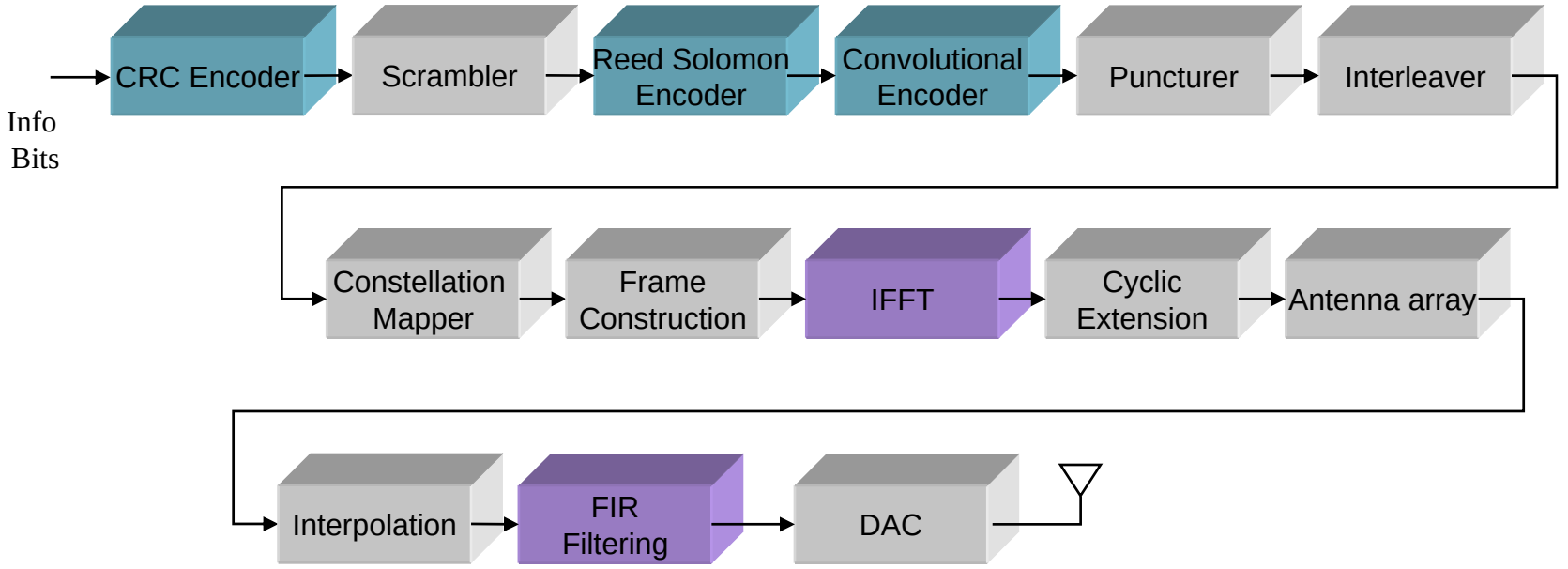
Why use components?

- If we build the parts of our system to well-defined specifications, then it should be easy to assemble these pieces to create a system
- It should also be relatively easy to replace one part of a system with another part that meets the same specification, *after the system is built*



Third Party Development

- Create an ecosystem
- Enables third party development of components
- Components can be tested and verified before integration



Supplied by Company A

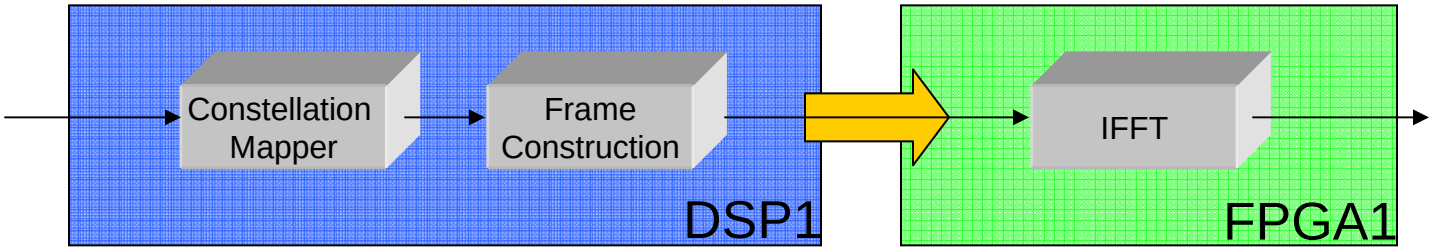
Supplied by Company B

Internal Development

Example Use Case

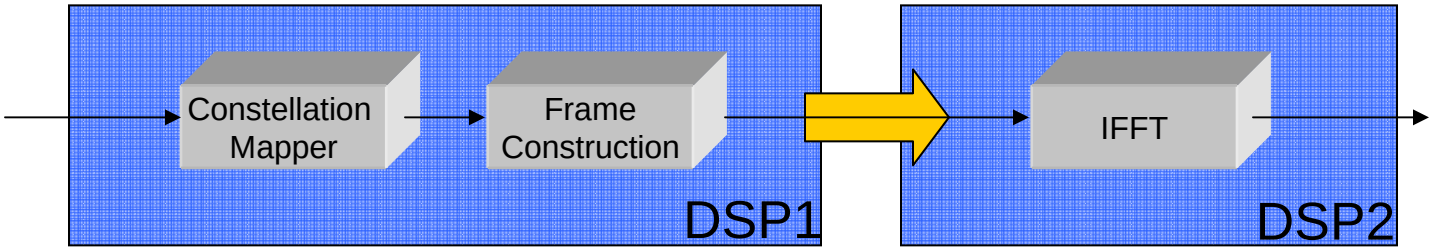
C1: Constellation Mapper
C2: Frame Construction
C3: IFFT

Deployment 1: C1, C2 to DSP1; C3 to FPGA1



•FPGA malfunction → switch to deployment plan 2…

Deployment 2: C1, C2 to DSP1; C3 to DSP2*



*Two different implementations required for C3 (I3a and I3b)

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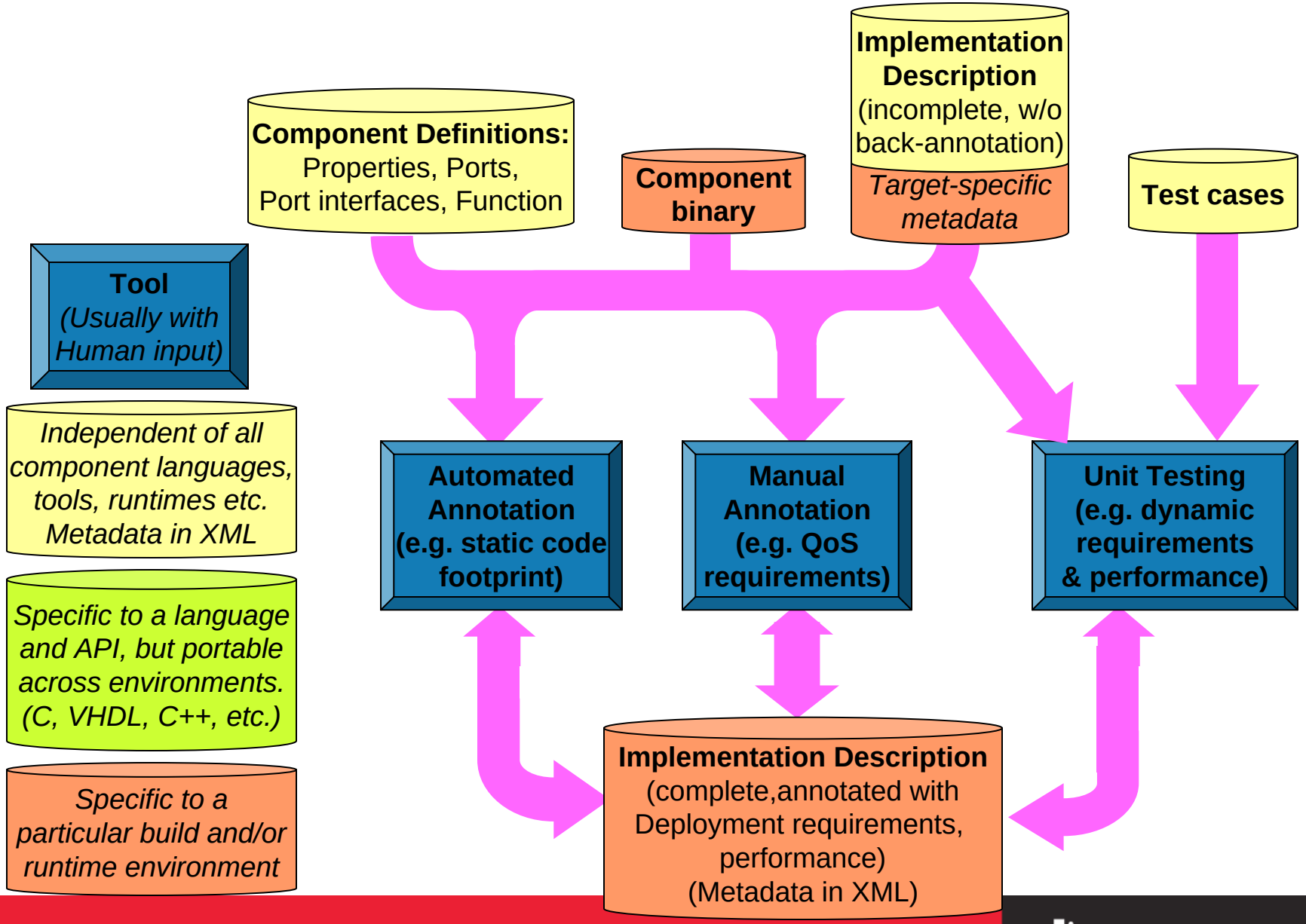
Development Environment

1. Specify components and assemblies using a tool
2. Generate metadata (XML) and portable code (headers , declarations, and skeleton for executable code)
3. Enter target specific information and generate target specific code (wrapper code, project files, build scripts, makefiles etc)
4. Implement signal processing logic

Component Characterization: annotating implementations (describe how to deploy components)



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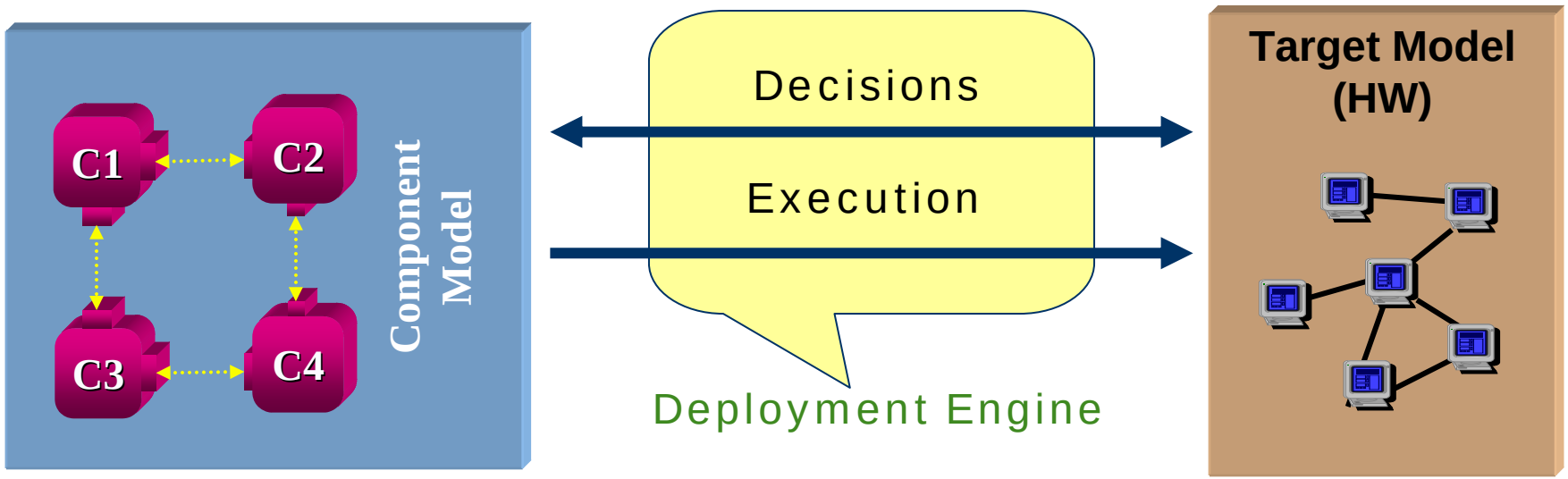
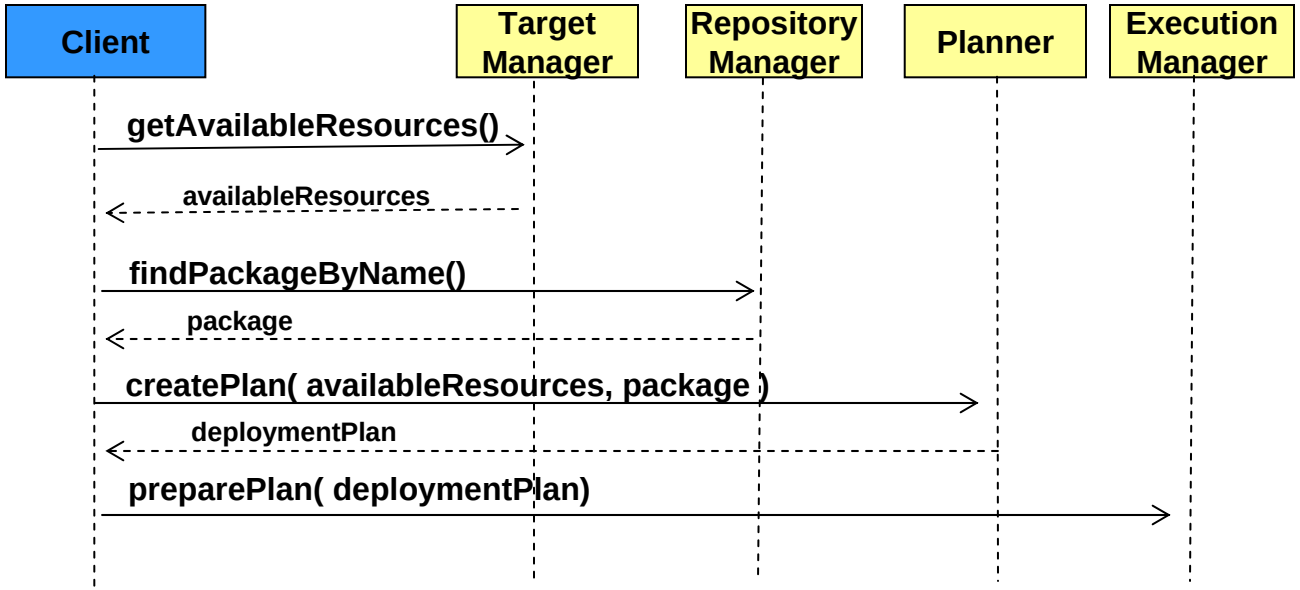
Deployment Engine

- Deployment engine automatically deploys the software modules to the available hardware, and runs the application
- Input is an XML file (specified by OMG)
- Monolithic implementation does not use CORBA
- Distributed implementation also available

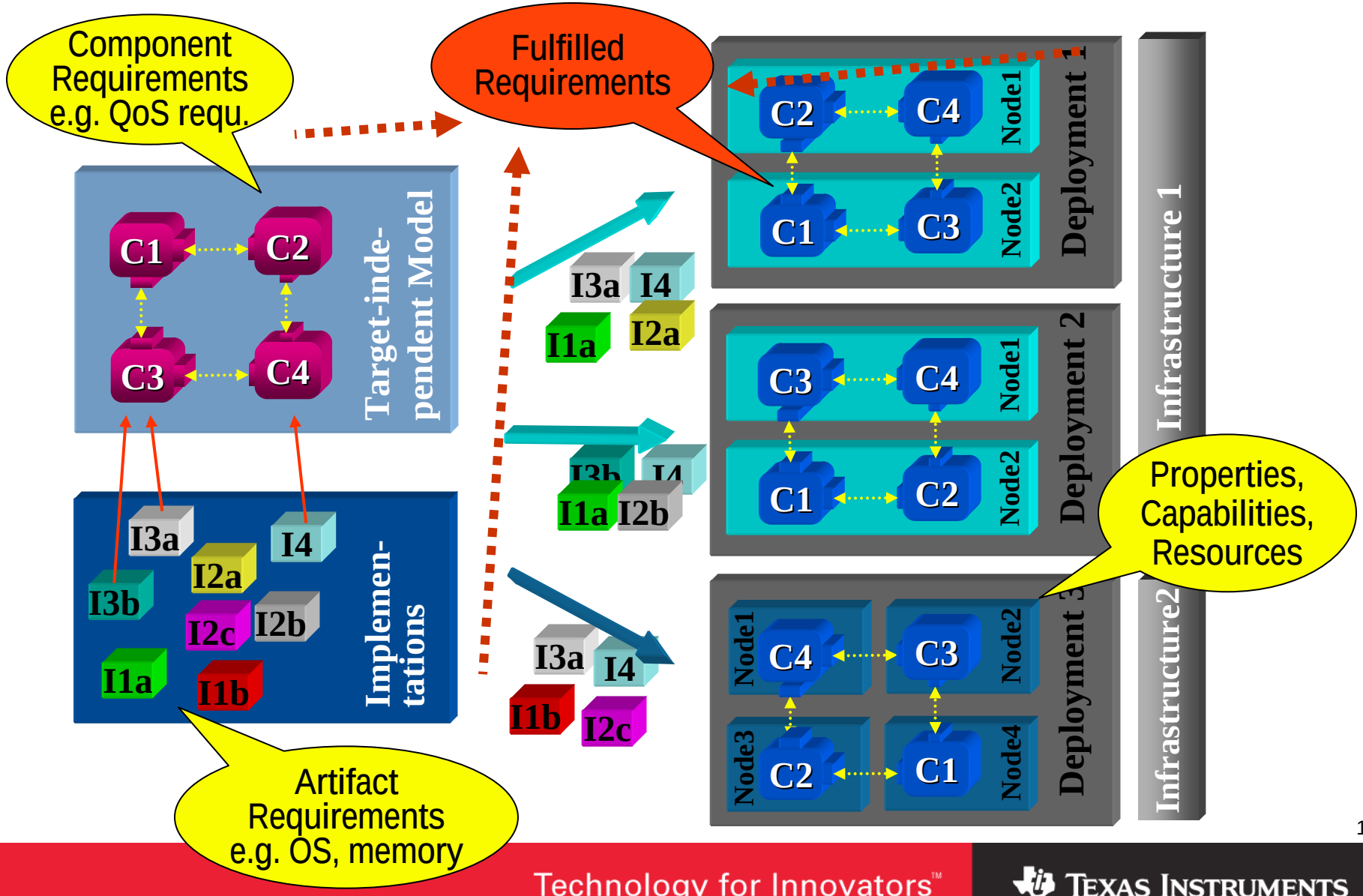


Planning the Deployment

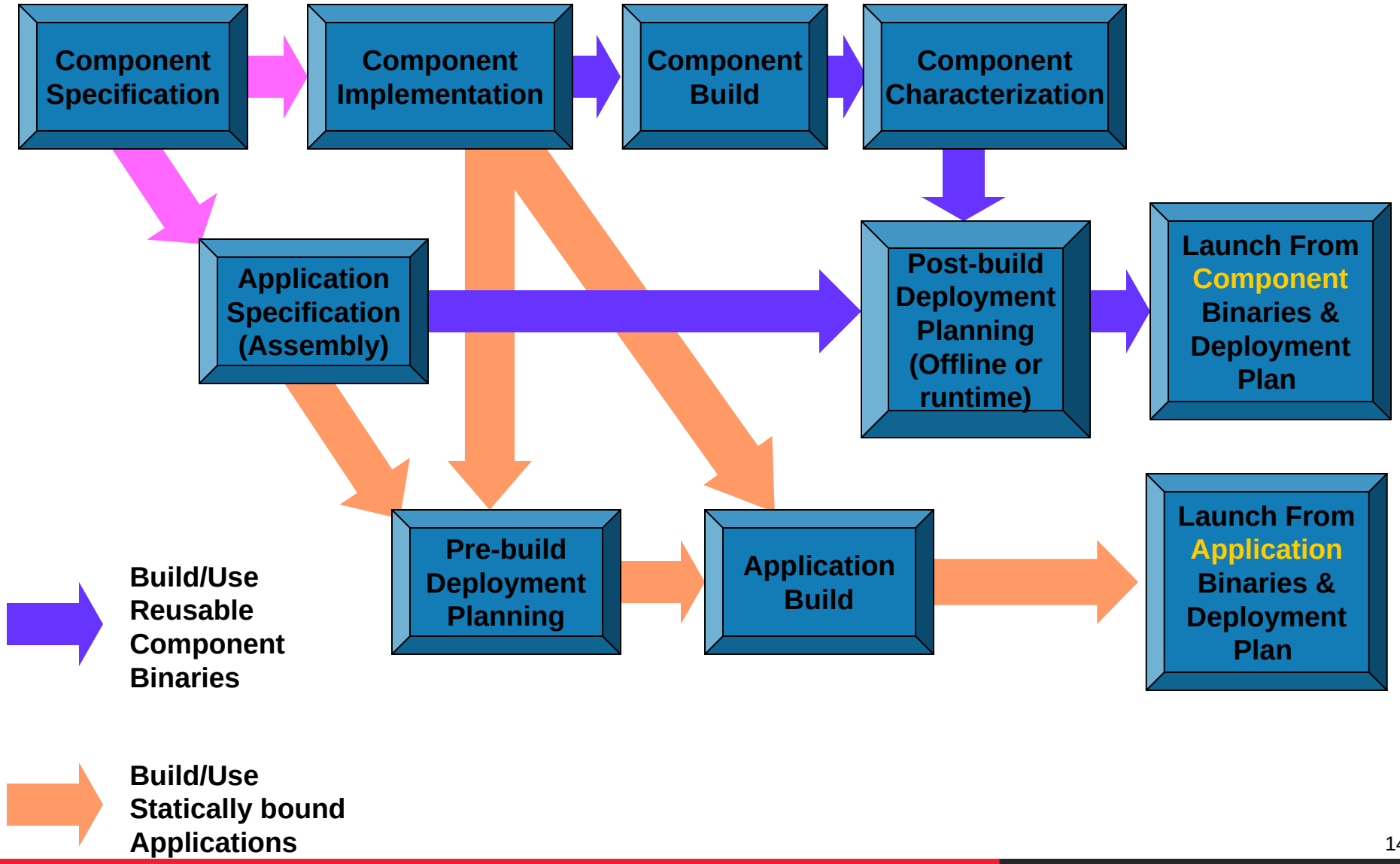
- "Planner" creates the Execution Model (Deployment Plan)
- Can be Online or Offline (Dynamic or Static)
- Generated Automatically
- Pluggable Deployment Algorithms
- Various Scenarios for Different Configurations



Fulfilling Requirements



Component-based application flows



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Run-time Monitoring

- Provided by the deployment engine
- Specific to implementation
- Start/Stop components using the control plane
- No interruption to the data plane

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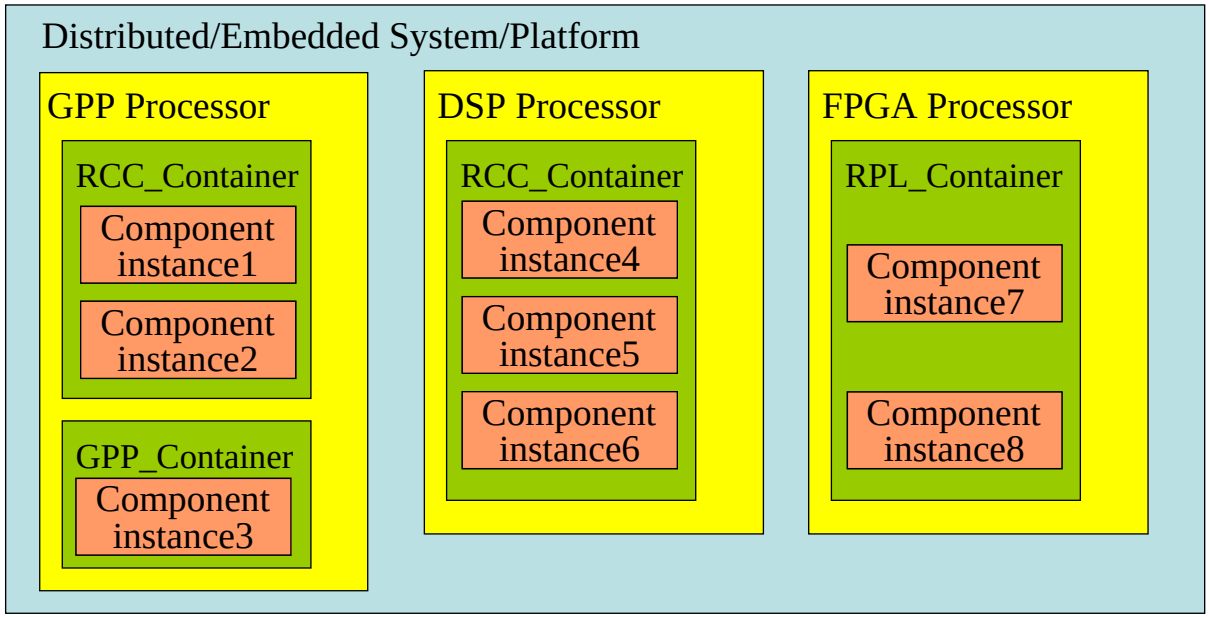
Goals

- **Overall:**
  - Waveform portability by integrating GPP, DSP and FPGA technologies into component models for embedded/distributed systems
- **Specific goals:**
  - Portability of components at source level
  - Replace-ability across technologies
  - Separation of concerns between platform provider and component author
  - Resource efficiency and performance
  - Minimal impact/changes required on existing component models

Component Portability Specification

- Works with Deployment Engine, without needing an SCA CF
- Does not have CORBA overhead
- Developed by Mercury under contract from JTRS Program Office
- Officially submitted as Change Proposal 289 to SCA
- Minimal effect to existing SCA implementations

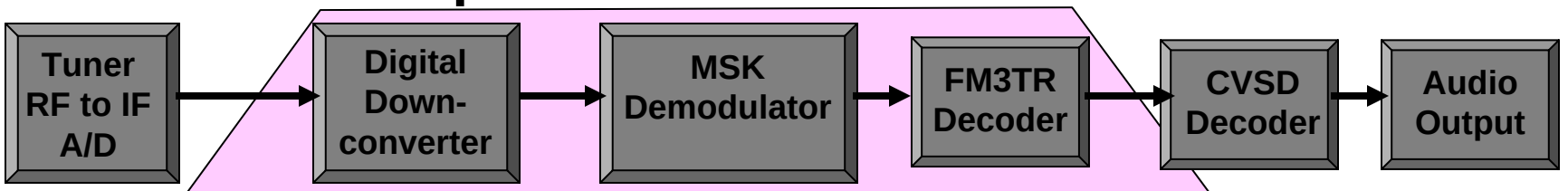
Component Model Concepts



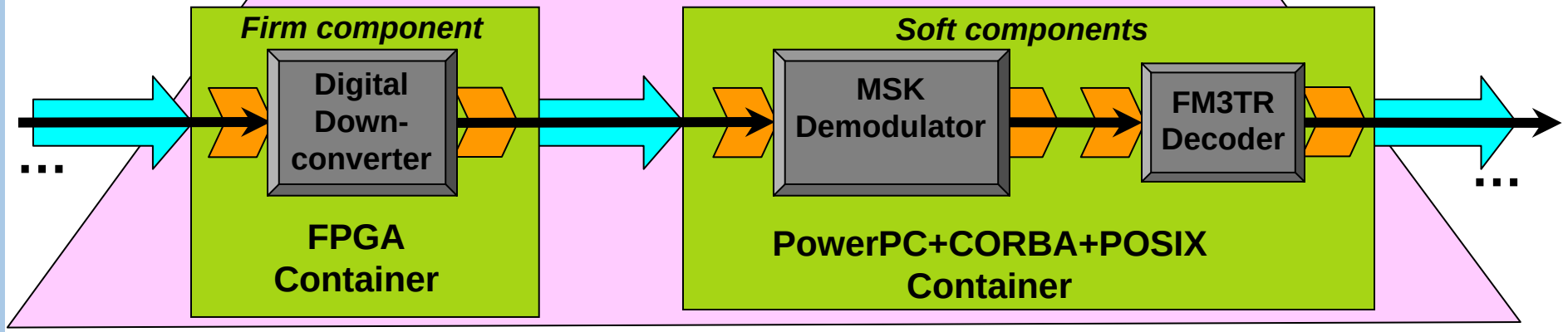
- **Worker: (Component implementation)**
  - Interacts with containers for data transmission
  - Developed for containers which provide portability of worker code
- **Container:**
  - the *immediate* runtime environment in which a component instance executes
  - Provided by platform provider
- **Class (a.k.a. which Component Implementation Framework):**
  - A particular language/API model to which components are written

FM3TR Voice Receiver

Simple FM3TR Receiver



Component implementations in Containers



Components talk to their containers. Important interface for portability of components. APIs used by component authors.

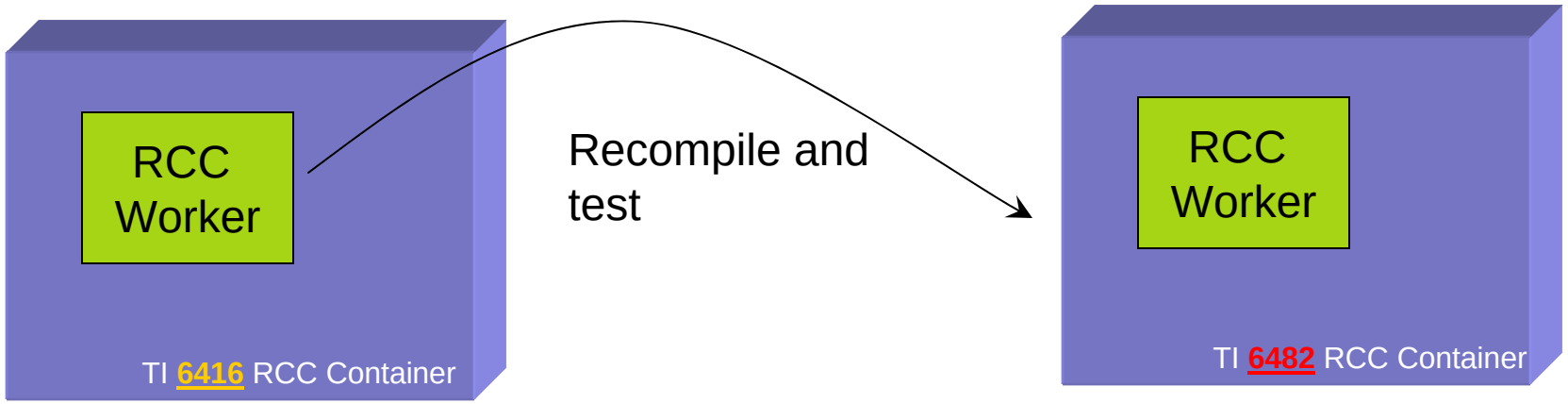
Containers talk to containers. Important interface for interoperability/plug&play of containers (e.g. boards). Protocols/networks/busses.

Communication between components, conveyed by their containers

RCC: Resource-Constrained C Environments

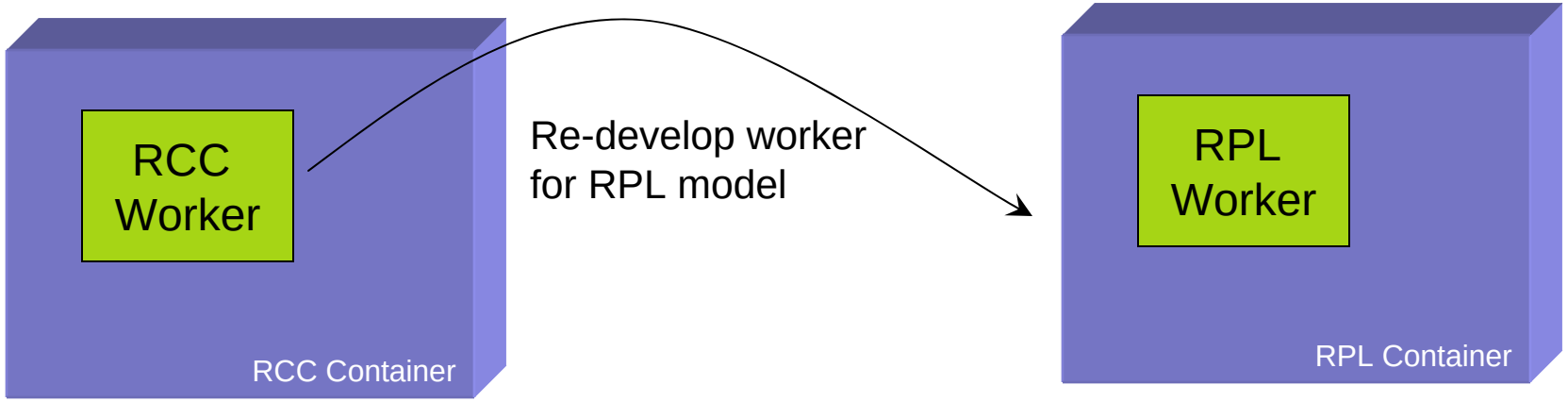
- **Component Model for DSPs**
- **Defines meta-data for the component**
- **All interfaces are ANSI C**
- **Single-threaded and Multi-threaded Profiles**
- **Management interface**
  - Simple component model
  - *Initialize/start/stop/release/configure/test/run*
- **Intercomponent interface**
  - Get/put buffers
  - Can block on combinations of ports
- **Local interfaces**
  - Roughly ANSI C without I/O

Portability



- **A component implementation can move to same class of container ("like for like"), recompiling source**
- **Portable "reference implementations" can be tweaked to use special features (e.g. Viterbi accelerator on DSP)**
- **RCC components easily port and wrap into GPP environments.**

Replace-ability



- **Enables changes in technology/processor class with no impact on the rest of the application**
- **Enables addition of component implementations to existing components**
  - Multiple implementations in a component package are possible
  - Allow adding FPGA implementation to component with GPP implementation without impacting application
- **Implies opaque interoperability between all classes of component implementations**

Resource Efficiency and Performance

- **Minimize "tax" for portability and interoperability**
- **Low memory footprint**
- **Enable full performance usage of inter-processor hardware interconnections**
  - busses, networks, fabrics, NICs
- **Enable full performance for collocated component instances**
- **Enable statically pre-combinations of component implementations**
- **Enable zero copy operation**
  - To inter-processor interconnects
  - Between collocated components
  - Between input and output of a component

Status

- **Deployment Engine:**
  - Deployment implementation is complete for online and offline planning
  - Run-time control and monitoring infrastructure can launch applications
- **Component model:**
  - Container and components are implemented for TMS320C6482, TMS320C6416 DSPs, as well as Intel Pentium and PowerPC GPPs
  - Container implementation in progress for FPGAs
- **Tools:**
  - Metadata, project files, offline deployment planning and skeleton code for DSP components can be generated by Zeligsoft Component Enabler™

Conclusion

- A component environment with support for multiple processor classes
- Highly automated development environment
- Waveforms can be easily ported from one platform or processor to another maximizing re-use
- No added CORBA overhead
- All real, exists today!

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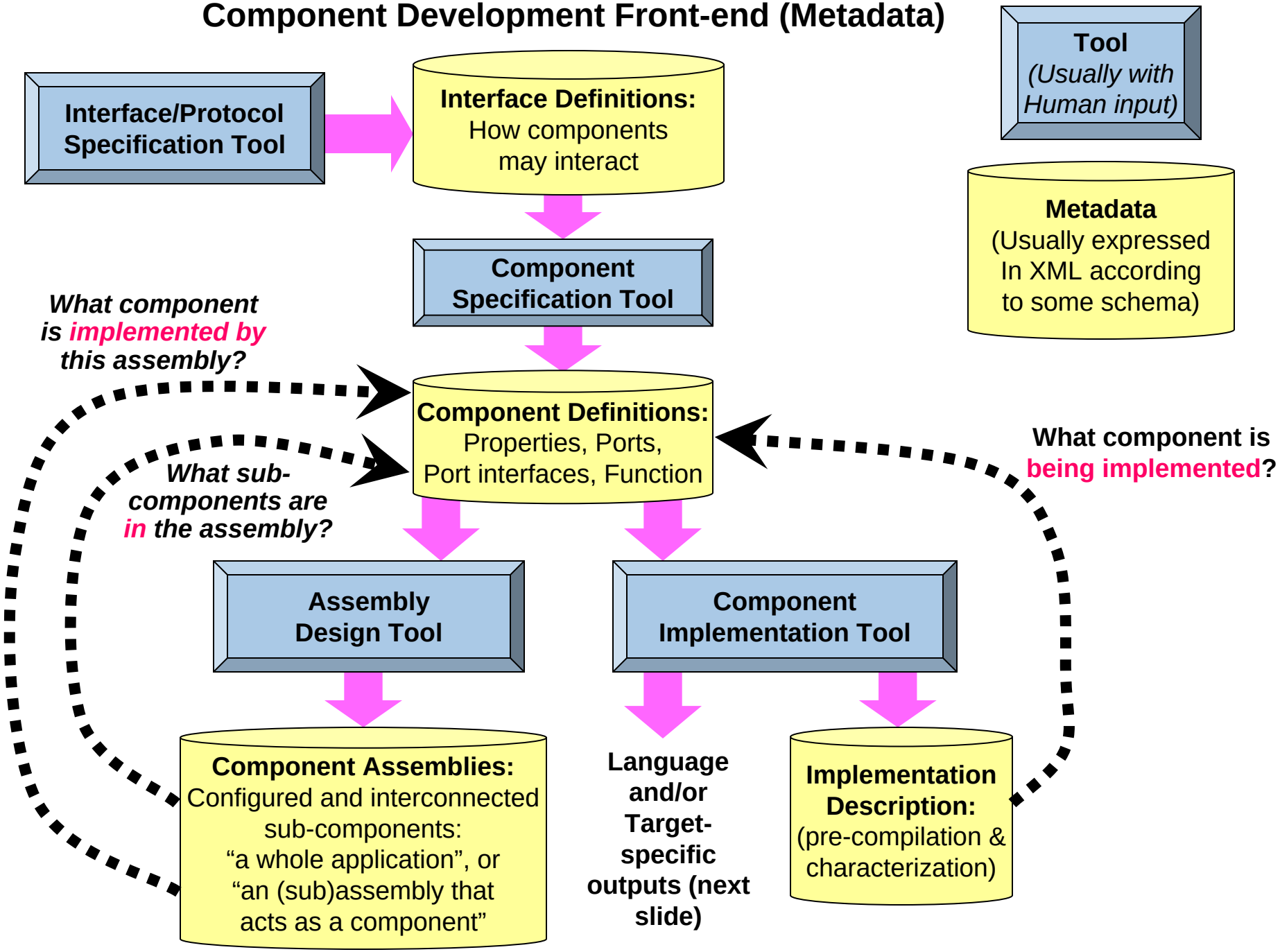
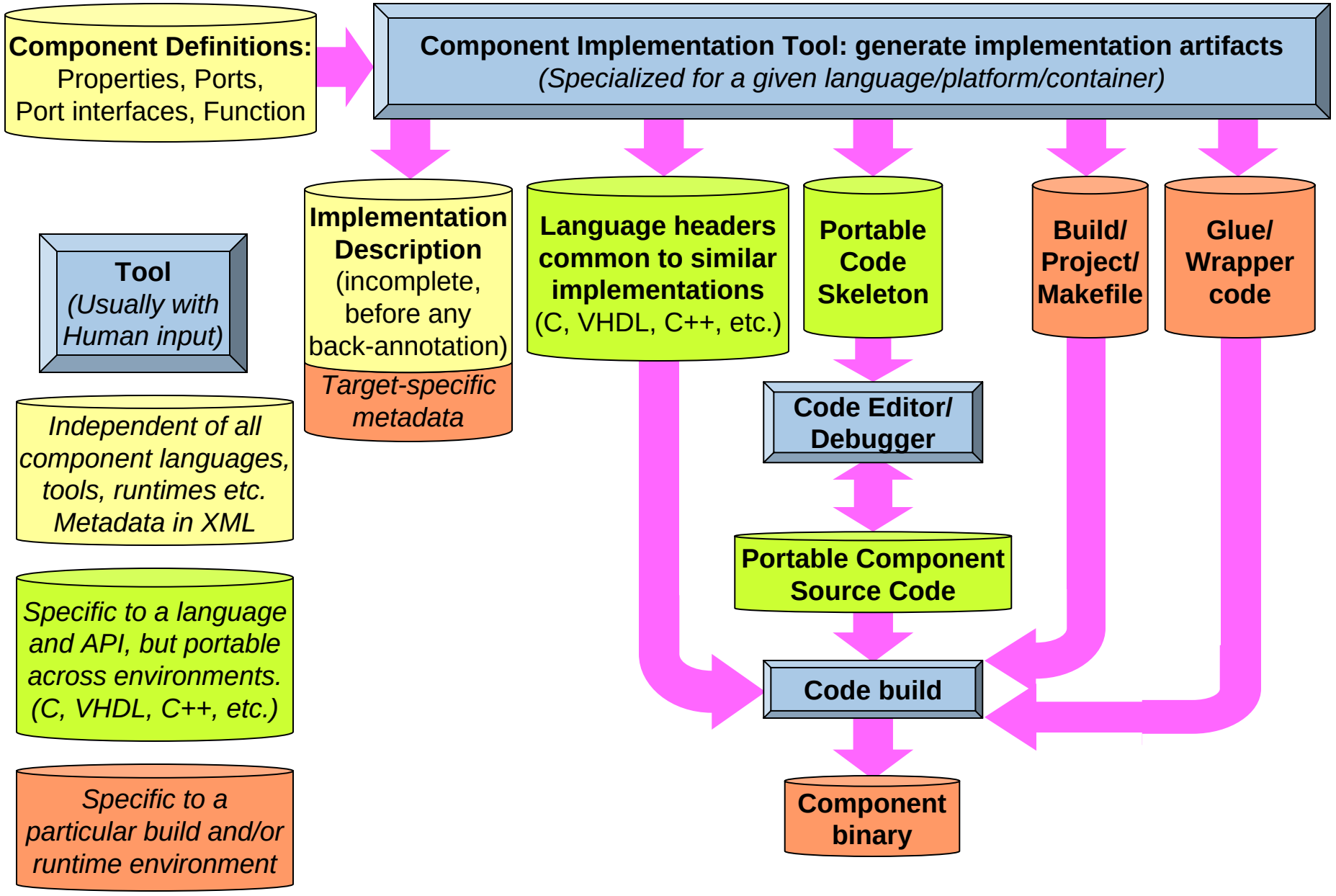
SEE THE FUTURE

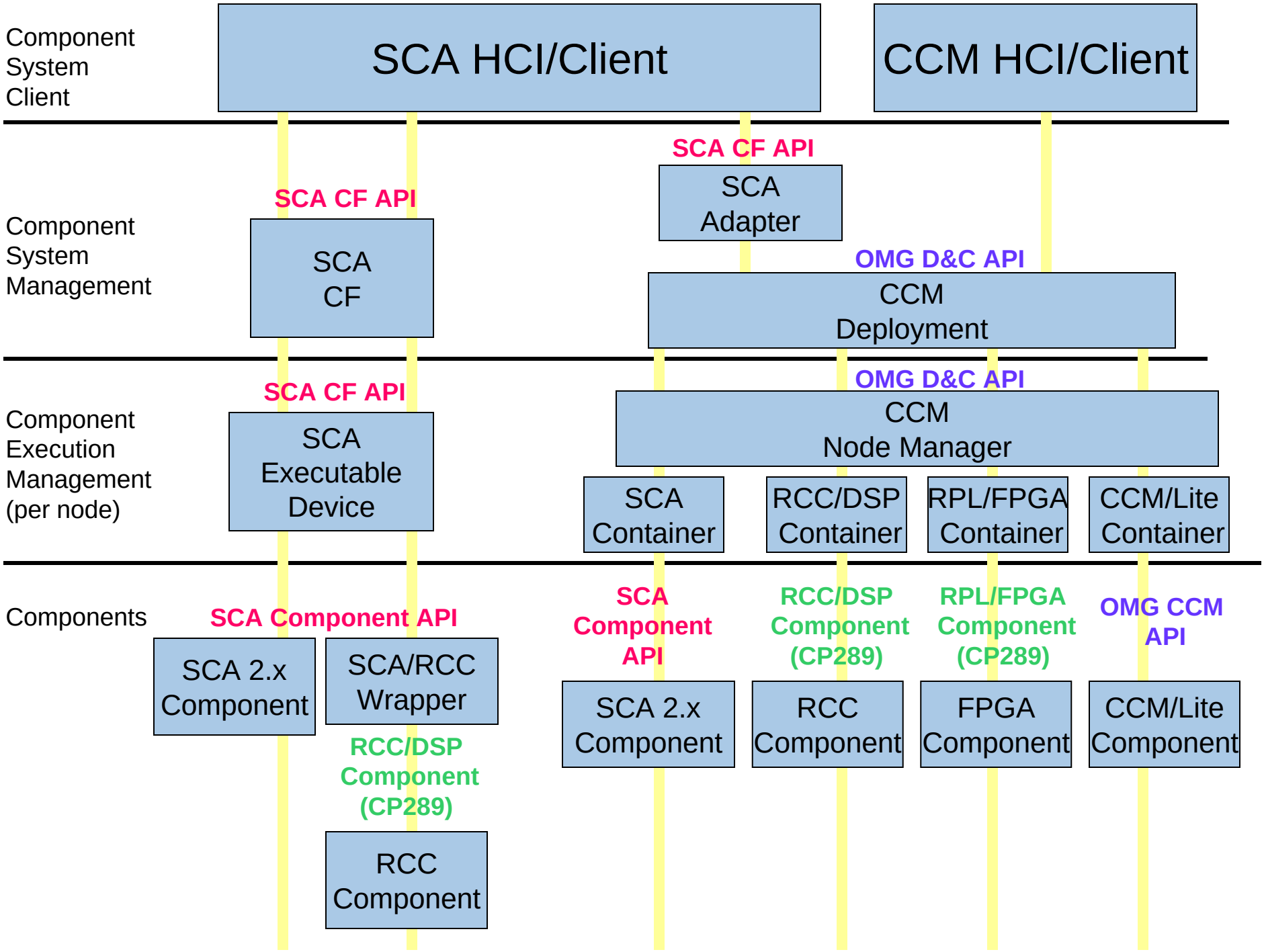
CREATE YOUR OWN

Component Development Front-end (Metadata)



Component Development Back-end: Creating Implementations (deployable binaries for each individual component)




Component System Client
SCA HCI/Client
CCM HCI/Client
SCA CF API
SCA Adapter
Component System Management
SCA CF API
SCA CF
OMG D&C API
CCM Deployment
OMG D&C API
SCA CF API
Component Execution Management (per node)
SCA Executable Device
CCM Node Manager
SCA Container
RCC/DSP Container
RPL/FPGA Container
CCM/Lite Container
Components
SCA Component API
SCA 2.x Component
SCA/RCC Wrapper
RCC/DSP Component (CP289)
RCC Component
SCA Component API
RCC/DSP Component (CP289)
RPL/FPGA Component (CP289)
OMG CCM API
SCA 2.x Component
RCC Component
FPGA Component
CCM/Lite Component