

535.641 Mathematical Methods Assignment 5

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Name_____

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2	/25
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TOTAL	/100

1. Rewrite the n^{th} order differential equation

$$y^{(n)}(t) + a_{n-1}y^{(n-1)}(t) + \dots + a_0y(t) = b_0u(t) + b_1\dot{u}(t)$$

as a dimension- n linear state equation

$$\dot{\mathbf{x}}(t) = A\mathbf{x}(t) + Bu(t)$$

Hint: Let $x_n(t) = y^{(n-1)}(t) - b_1u(t)$

2. Consider the system $\dot{\mathbf{x}} = A\mathbf{x}$. Sketch a phase portrait for each A matrix:

$$\begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix} \quad \begin{bmatrix} -1 & -1 \\ 1 & -1 \end{bmatrix} \quad \begin{bmatrix} -2 & -2 \\ -2 & 1 \end{bmatrix} \quad \begin{bmatrix} -1 & 1 \\ -2 & 1 \end{bmatrix} \quad \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix}$$

3. Consider the linear system:

$$\frac{d\mathbf{x}}{dt} = A\mathbf{x} + Bu, \quad \mathbf{x} \in \mathbb{R}^2, \quad u \in \mathbb{R},$$

where

$$A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}, \quad B = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

Let $K = \begin{bmatrix} k_1 & k_2 \end{bmatrix}$ be a state feedback gain such that a forcing, $u(t)$, is prescribed according to,

$$u(t) = -K\mathbf{x}(t).$$

So that the closed-loop system is:

$$\frac{d\mathbf{x}}{dt} = (A - BK)\mathbf{x}.$$

- (a) Show that the open-loop system (with $u = 0$) is unstable.
- (b) Determine conditions on the feedback gain $K = \begin{bmatrix} k_1 & k_2 \end{bmatrix}$ such that the closed-loop system is stable. *Hint: For a 2×2 matrix, all eigenvalues have negative real parts if and only if the trace is negative and the determinant is positive.*
- (c) Among all such stabilizing gains K , find the one that minimizes the Euclidean norm

$$\min_K \|K\|_2 = \sqrt{k_1^2 + k_2^2}$$

4. Alfvén waves describe the evolution of small amplitude perturbations in an electrically conducting fluid in the presence of a strong background magnetic field and can be modeled using the following equations

$$\begin{aligned}\frac{d\omega}{dt} &= ik j, \\ \frac{dj}{dt} &= ik \omega,\end{aligned}$$

where ω is the vorticity, j is the induced current density, k is the wavenumber of the fluid disturbance, and $i = \sqrt{-1}$.

- (a) Cast the set of equations in the form, $\dot{\mathbf{x}} = A\mathbf{x}$, and clearly identify A and \mathbf{x} .
- (b) Classify the A matrix, (Hermitian/Skew-Hermitian/Unitary)?
- (c) Diagonalize the matrix if possible.
- (d) Obtain the second order ODEs for $\omega(t)$, $j(t)$ from the given first order ODEs. Solve them as an initial value problem to find their solution. The initial conditions are $\omega(t=0) = \omega_0$, $j(t=0) = 0$.
- (e) Confirm your solution in part (d) by expanding the solution vector \mathbf{x} using the eigen solutions of matrix A and initial conditions given in (d).