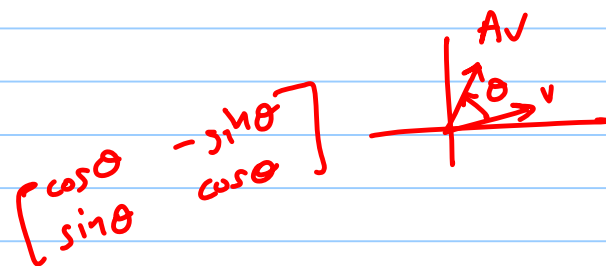


## 3.E ORTHOGONAL MATRICES

A square matrix  $A$  is orthogonal, if its columns form an orthonormal set. This means that each pair of columns is orthogonal and each column is unit.

Theorem: Let  $A$  be a square matrix. TFAE

1.  $A$  is orthogonal
2.  $A^T A = I$  ( $\Leftrightarrow A A^T = I$ )
3.  $A^{-1} = A^T$



Example: Show that the rotation matrix  $A$  is orthogonal. Find  $A^{-1}$ .

Sol<sup>n</sup>  $AA^T = \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & 0 \\ 0 & \cos^2 \theta + \sin^2 \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  so  $A$  is orthogonal.

$A^{-1} = A^T = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$

Example: It's easy to see that  $B = \begin{bmatrix} 2/3 & 1/3 & 2/3 \\ -2/3 & 2/3 & 1/3 \\ 1/3 & 2/3 & -2/3 \end{bmatrix}$  is orthogonal.

Theorem: For  $A$   $n \times n$  TFAE:

1.  $A$  is orthogonal.

2.  $Au \cdot Av = u \cdot v$  for all  $u, v \in \mathbb{R}^n$ . (Preservation of dot product)

3.  $\|Av\| = \|v\|$  for all  $v \in \mathbb{R}^n$ . (Preservation of Lengths)

Remark The matrix transformation  $T(x) = Ax$  with  $A$  orthogonal is also called orthogonal.

The theorem says that orthogonal transformations preserve dot products and lengths and angles. (since  $u \cdot v = \|u\| \|v\| \cos \theta$ )

Theorem: If  $\lambda$  is an EVA of an orthogonal  $A$ , then  $|\lambda|=1$ .

$$\text{Crf } \underbrace{\|v\|}_{\text{EVE}} = \|Av\| = \|\lambda v\| = |\lambda| \underbrace{\|v\|}_{\text{EVE}} \Rightarrow |\lambda|=1 \text{ (since } \|v\| \neq 0 \text{)}$$

This theorem also holds for complex EVAs.

## Eigenvalues of Symmetric Matrices

Theorem: 1. A real symmetric matrix has only real eigenvalues.

2. A real skew-symmetric matrix has only eigenvalues that either pure imaginary or zero.

Example:  $A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{bmatrix}$  has EVAs: 1, 4, -1.  $B = \begin{bmatrix} 0 & 2 & 1 \\ -2 & 0 & 1 \\ -1 & -1 & 0 \end{bmatrix}$  has EVAs: 0,  $\sqrt{6}i$ ,  $-\sqrt{6}i$

$\uparrow$  symmetric       $\uparrow$  real       $\uparrow$  skew-symmetric       $\uparrow$  0 or pure imaginary

## Hermitian and Unitary Matrices

Let  $A$  be a square complex matrix. Then

$A$  is Hermitian, if  $\bar{A}^T = A$  ←

$A$  is skew-Hermitian, if  $\bar{A}^T = -A$  ←

$A$  is unitary, if  $\bar{A}^T = A^{-1}$  ✓ ( $\Leftrightarrow A^T \bar{A} = I$ )

$\bar{A}$  = 'A conjugate'

$$\begin{bmatrix} 3i & 1+i \\ 0 & -5+2i \end{bmatrix} = \begin{bmatrix} -3i & 1-i \\ 0 & -5-2i \end{bmatrix}$$

Example: Show that  $A = \begin{bmatrix} 4 & 2+i \\ 2-i & 0 \end{bmatrix}$  is Hermitian,  $B = \begin{bmatrix} 0 & 2-i \\ -2-i & -4i \end{bmatrix}$  is skew-Hermitian,  $C = \begin{bmatrix} 1/2 & -\sqrt{3}/2 i \\ -\sqrt{3}/2 i & 1/2 \end{bmatrix}$  is unitary.

Sol':  $\bar{A}^T = \begin{bmatrix} 4 & 2+i \\ 2-i & 0 \end{bmatrix}^T = \begin{bmatrix} 4 & 2-i \\ 2+i & 0 \end{bmatrix} = \begin{bmatrix} 4 & 2+i \\ 2-i & 0 \end{bmatrix} = A$ . Likewise,  $\bar{B}^T = -B$  ✓

$$\bar{C}^T C = \begin{bmatrix} 1/2 & -\sqrt{3}/2 i \\ -\sqrt{3}/2 i & 1/2 \end{bmatrix}^T \begin{bmatrix} 1/2 & -\sqrt{3}/2 i \\ -\sqrt{3}/2 i & 1/2 \end{bmatrix} = \begin{bmatrix} 1/2 & \sqrt{3}/2 i \\ \sqrt{3}/2 i & 1/2 \end{bmatrix} \begin{bmatrix} 1/2 & -\sqrt{3}/2 i \\ -\sqrt{3}/2 i & 1/2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I \leftarrow$$

## Remarks

1. A real Hermitian matrix is just a symmetric matrix.  
(skew-) (skew-)
2. A real unitary matrix is just an orthogonal matrix.
3. The main diagonal of a Hermitian matrix consists of real numbers.
4. The main diagonal of a skew-Hermitian matrix consists of 0s or pure imaginary numbers.

Theorem: Let  $A_{n \times n}$  be complex matrix.

1. If  $A$  is Hermitian, then its EVAs are real. ← ↓
2. If  $A$  is skew-Hermitian, then its EVAs are 0 or pure imaginary.
3. If  $A$  is unitary, then its EVAs have absolute value 1. ←