

```

from collections import defaultdict

class Graph:
    ...def.__init__(self,vertices):
    .....self.V==.vertices
    .....self.graph==.defaultdict(list)
    ...def.addEdge(self,u,v):
    .....self.graph[u].append(v)
    ...def.DLS(self,source,target,maxDepth):
    .....if.source==.target::return.True
    .....if.maxDepth.<=.0::return.False
    .....#.recursively.traversing.the.graph.while.searching
    .....for.i.in.self.graph[source]:
    .....if(self.DLS(i,target,maxDepth-1)):
    .....return.True
    .....return.False
g=.Graph(9)#.creating.the.graph
g.addEdge(0,.1)
g.addEdge(0,.2)
g.addEdge(1,.3)
g.addEdge(1,.4)
g.addEdge(2,.5)
g.addEdge(2,.6)
g.addEdge(3,7)
g.addEdge(3,8)
target==.3
maxDepth==.3
source==.0

if.g.DLS(source,target,maxDepth)==.True:
    ...print(f"Target.{target}.is.reachable.from.source.{source}.within.max.d
else:
    ...print(f"Target.{target}.is.NOT.reachable.from.source.{source}.within.m

☞ Target 3 is reachable from source 0 within max depth 3

```

[Colab paid products](#) - [Cancel contracts here](#)

✓ 0s completed at 9:18 AM

