# Recursive Solutions to First-Order Model Counting

#### 16th March 2022

## 1 Introduction

In a way, we're dividing the idea of domain recursion between the IDR and the Ref nodes, thus also generalising it. [TODO: mention Fig. 1.]

## 2 Preliminaries

### Things I might need to explain.

- atom, (positive/negative) literal, constant, predicate, variable, clause, unit clause, first-order logic
- WMC, w,  $\overline{w}$ .
- two parts: compilation and inference.
- During inference, there is a domain size map  $\sigma \colon \mathcal{D} \to \mathbb{N}_0$ .
- mention which rules are in  $\Gamma$  and which ones are in  $\Delta$  (and why tryCache has to be in  $\Delta$ ). TODO: having notation for  $\Delta$  and  $\Gamma$  isn't that necessary
- My formalisation of constraints is more restrictive than the original (e.g., in the thesis).
- ForcLift
- $\bullet$   $\sqcup$  for both sets and functions

TODO: reorder Section 6 to introduce DR before CR before Ref.

#### Notation.

• We write  $\rightarrow$  for functions,  $\rightarrow$  for partial functions,  $\rightarrow$  for bijections, and  $\hookrightarrow$  for set inclusion. Let id denote the identity function (on any domain). For any function f, let Im f be the image of f.

Most of the definitions here are adaptations/formalisations of [3] and the corresponding code.

**Definition 1.** A domain is a symbol for a finite set.<sup>1</sup>

**Definition 2.** An *(inequality) constraint* is a pair (a, b), where a is a variable, and b is either a variable or a constant.

<sup>&</sup>lt;sup>1</sup>In the context of functions, the domain of a function f retains its usual meaning and is denoted dom(f).

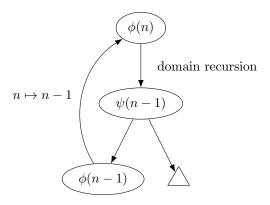


Figure 1: An illustration of the main idea.

**Definition 3.** A clause is a triple  $c = (L, C, \delta_c)$ , where L is a set of literals, C is a set of constraints, and  $\delta_c$  is a function that maps all variables in c to their domains such that (s.t.) if  $(x, y) \in C$  for some variables x and y, then  $\delta_c(x) = \delta_c(y)$ . Note that for convenience sometimes we write  $\delta_c$  for the domain map of c without unpacking c into its three constituents.

Also, let Vars be a function that maps clauses and sets of literals and inequalities to the set of variables contained within. In particular,  $Vars(c) := Vars(L) \cup Vars(C)$ .

A formula is a set of clauses. All variables in a clause are implicitly universally quantified (but note that variables are never shared among clauses), and all clauses in a formula are implicitly linked by conjunction. This way, one can read formulas as defined here as sentences in first-order logic.

TODO: Note: we will reuse this several times.

**Example 1.** Let  $\phi := \{c_1, c_2\}$  be a formula, where

$$c_1 := (\{ \neg p(X,Y), \neg p(X,Z) \}, \{ (Y,Z) \}, \{ X \mapsto a, Y \mapsto b, Z \mapsto b \}), \tag{1}$$

and

$$c_2 := (\{ \neg p(X,Y), \neg p(Z,Y) \}, \{ (X,Z) \}, \{ X \mapsto a, Y \mapsto b, Z \mapsto a \}), \tag{2}$$

for some predicate p, variables X, Y, Z, and domains a and b. Then in first-order logic  $\phi$  could be read as

$$(\forall X \in a. \forall Y \in b. \forall Z \in b. Y \neq Z \implies \neg p(X,Y) \lor \neg p(X,Z)) \land (\forall X \in a. \forall Y \in b. \forall Z \in a. X \neq Z \implies \neg p(X,Y) \lor \neg p(Z,Y)).$$

**Hashing.** We use hash codes to efficiently check whether a recursive relationship between two formulas is plausible. (It is plausible if the formulas are equal up to variables and domains.) The hash code of a clause  $c = (L, C, \delta)$  combines the hash codes of the sets of constants and predicates in c, the numbers of positive and negative literals, the number of inequality constraints |C|, and the number of variables |Vars(c)|. The hash code of a formula  $\phi$  combines the hash codes of all its clauses and is denoted  $\#\phi$ .

Notation for lists. Let  $\langle \rangle$  and  $\langle x \rangle$  denote an empty list and a list with one element x, respectively. We write  $\in$  for (in-order) enumeration, + for concatenation, and  $|\cdot|$  for the length of a list. Let h:t denote a list with first element (a.k.a. head) h and remaining list (a.k.a. tail) t. We also use list comprehensions written equivalently to set comprehensions. For example, let  $L:=\langle 1\rangle$  and  $M:=\langle 2\rangle$  be two lists. Then  $M=\langle 2x\mid x\in L\rangle$ ,  $L+M=1:\langle 2\rangle$ , and |M|=1.

# 3 Generalising Circuits to Labelled Graphs

A first-order deterministic decomposable negation normal form computational graph (FCG) is a (weakly connected) directed graph with a a single source, vertex labels, and ordered outgoing edges.<sup>2</sup> We denote an FCG as  $G = (V, s, N^+, \tau)$ , where V is the set of vertices, and  $s \in V$  is the unique source. Also,  $N^+$  is the direct successor function that maps each vertex in V to a list that contains either other vertices in V or a special symbol  $\star$ . This symbol means that the target of the edge is yet to be determined.

Vertex labels consist of two parts: the type and the parameters. For the main definition, we leave the parameters implicit and let  $\tau: V \to \mathcal{T}$  denote the vertex-labelling function that maps each vertex in V to its type in  $\mathcal{T}$ . Most of our list of types  $\mathcal{T} := \{\bigcirc, \bigcirc, \bigcirc, \bigcirc, \bigcirc, \bigcirc, \bigcirc, CR, DR, IE, REF\}$  is as described in previous work [2, 3] as well as the source code of FORCLIFT<sup>3</sup> but with one new type CR and two revamped types DR and REF. For each vertex  $v \in V$ , the length of the list  $N^+(v)$  (i.e., the out-degree of v) is determined by its type  $\tau(v)$ .

TODO: conjunctions and disjunctions should be different from set-conjunctions and set-disjunctions.

As in previous work [3], to describe individual vertices and small (sub)-FCGs, we also use notation of the form, e.g.,  $\text{Ref}_{\rho}(v)$ . Here, the type of the vertex (e.g., Ref) is 'applied' to its direct successors (e.g., v) using either function or infix notation and provided with its parameter(s) (e.g.,  $\rho$ ) in the subscript. We say that 'G is an FCG for formula  $\phi$ ' if two conditions are satisfied. First, the image of  $N^+$  contains no  $\star$ 's. Second, G encodes a function that maps the sizes of the domains in  $\phi$  to the WMC of  $\phi$  (more on this in Section 7).

#### TODO.

- provide a short explanation of the types (emphasising which ones are new/updated).
- have an example of a simple FCG. Maybe describe the figure from later and move it here.

# 4 Compilation as Search

**Definition 4.** A state (of the search for an FCG for a given formula) is a tuple (G, C, L), where:

- G is an FCG (or null),
- C is a compilation cache that maps integers to sets of pairs  $(\phi, v)$ , where  $\phi$  is a formula, and v is a vertex of G (which is used to identify opportunities for recursion),
- and L is a list of formulas (that are yet to be compiled). (Note that the order is crucial!)

**Definition 5.** A (compilation) *rule* is a function that takes a formula and returns a set of (G, L) pairs, where G is a (potentially null) FCG, and L is a list of formulas.

TODO: Take the example from the AIAI talk.

We assume that if there is a pair (null, L) in the set returned by a rule, then |L| = 1, i.e., the rule transformed the formula without creating any vertices.

TODO: explain the 'tail' part of the algorithm, i.e., that the first formula is replaced by some vertices and some formulas. And explain why we don't want to have REF vertices in the cache.

Note: At the end, mergeFcgs will never return null because there is going to be at least one  $\star$  in G and the function will find it.

## Algorithm 1: The (main part of the) search algorithm

```
Input: a formula \phi_0
   Output: all found FCGs for \phi_0 are in the set solutions
 1 solutions \leftarrow \emptyset;
 2 C_0 \leftarrow \emptyset;
 \mathbf{3}\ (G_0,C_0,L_0) \leftarrow \mathsf{applyGreedyRules}(\phi_0,C_0);
 4 if L_0 = \langle \rangle then solutions \leftarrow \{G_0\};
 6
        q \leftarrow an empty queue of states;
        q.put((G_0, C_0, L_0));
 7
        while not q.empty() do
 8
             foreach state (G, C, L) \in \text{applyAllRules}(q.\text{get}()) do
                  if L = \langle \rangle then solutions \leftarrow solutions \cup \{G\};
10
11
                  else q.put((G,C,L));
```

# 5 In-Between Compilation and Inference: Smoothing

[Insert motivation for smoothing from Section 3.4. of the ForcLift paper.] Originally, smoothing was (and still is) a two-step process. First, atoms that are still accounted for in the circuit are propagated upwards. Then, at vertices of certain types, missing atoms are detected and additional sinks are created to account for them. If left unchanged, the first step of this process would result in an infinite loop whenever a cycle is encountered. Algorithm 4 outlines how the first step can be adapted to an arbitrary directed graph.

# 6 New Compilation Rules

Let  $\mathcal{D}$  be the set of all domains. Note that this set expands during the compilation.

## 6.1 Identifying Possibilities for Recursion

#### 6.1.1 Notation

Let Doms be a function that maps any clause or formula to the set of domains used within. Specifically,  $\operatorname{Doms}(c) := \operatorname{Im} \delta_c$  for any clause c, and  $\operatorname{Doms}(\phi) := \bigcup_{c \in \phi} \operatorname{Doms}(c)$  for any formula  $\phi$ .

For partial functions  $\alpha, \beta \colon A \to B$  s.t.  $\alpha|_{\operatorname{dom}(\alpha) \cap \operatorname{dom}(\beta)} = \beta|_{\operatorname{dom}(\alpha) \cap \operatorname{dom}(\beta)}$ , we write  $\alpha \cup \beta$  for the unique partial function s.t.  $\alpha \cup \beta|_{\operatorname{dom}(\alpha)} = \alpha$ , and  $\alpha \cup \beta|_{\operatorname{dom}(\beta)} = \beta$ .

For any clause  $c = (L, C, \delta_c)$ , bijection  $\beta$ : Vars $(c) \rightarrow V$  (for some set of variables V), and function  $\gamma$ : Doms $(c) \rightarrow \mathcal{D}$ , let  $c[\beta, \gamma] = d$  be the clause c with all occurrences of any variable  $v \in \text{Vars}(c)$  in L and C replaced with  $\beta(v)$  (so Vars(d) = V) and  $\delta_d : V \rightarrow \mathcal{D}$  defined as  $\delta_d := \gamma \circ \delta_c \circ \beta^{-1}$ . In other words,  $\delta_d$  is the unique function that makes

$$\operatorname{Vars}(c) \stackrel{\beta}{\rightarrowtail} V = \operatorname{Vars}(d)$$

$$\delta_c \downarrow \qquad \qquad \downarrow \exists ! \delta_d$$

$$\operatorname{Doms}(c) \stackrel{\gamma}{\longrightarrow} \mathcal{D}$$

<sup>&</sup>lt;sup>2</sup>Note that imposing an ordering on outgoing edges is just a limited version of edge labelling.

<sup>3</sup>https://dtai.cs.kuleuven.be/drupal/wfomc

```
Algorithm 2: Functions used in Algorithm 1 for applying compilation rules
    Data: a set of greedy rules \Gamma
    Data: a set of non-greedy rules \Delta
 1 Function applyGreedyRules(\phi, C):
         foreach rule \ r \in \Gamma \ do
 2
             if r(\phi) \neq \emptyset then
 3
                  (G, L) \leftarrow \text{any element of } r(\phi);
 4
                  if G = \text{null then return applyGreedyRules} (the only element of L, C);
 5
 6
                       (V, s, N^+, \tau) \leftarrow G;
 7
                       C \leftarrow \text{updateCache}(C, \phi, G);
 8
                       return applyGreedyRulesToAllFormulas(G, C, L);
        return (null, C, \langle \phi \rangle);
10
    Function applyGreedyRulesToAllFormulas((V, s, N^+, \tau), C, L):
         if L = \langle \rangle then return ((V, s, N^+, \tau), C, L);
12
         N^+(s) \leftarrow \langle \rangle;
13
         L' \leftarrow \langle \rangle;
14
         foreach formula \phi \in L do
15
              (G', C, L'') \leftarrow \text{applyGreedyRules}(\phi, C);
16
             L' \leftarrow L' + L'';
17
             if G' = \text{null then } N^+(s) \leftarrow N^+(s) + \langle \star \rangle;
18
19
                  (V', s', N', \tau') \leftarrow G';
20
                  V \leftarrow V \sqcup V':
21
                  N^+ \leftarrow N^+ \sqcup N';
22
                  N^+(s) \leftarrow N^+(s) \# \langle s' \rangle;
23
24
        return ((V, s, N^+, \tau), C, L');
    Function applyAllRules(s):
26
         (G, C, L) \leftarrow s;
27
         \phi: T \leftarrow L;
28
         (G', C', L') \leftarrow \text{a copy of } s;
29
         newStates \leftarrow \langle \rangle;
30
         foreach rule \ r \in \Delta \ do
31
             foreach (G'', L'') \in r(\phi) do
32
                  if G'' = \text{null then newStates} \leftarrow \text{newStates} + \text{applyAllRules}((G', C', L''));
33
                  else
34
                       (V, s, N^+, \tau) \leftarrow G'';
35
                       C' \leftarrow \text{updateCache}(C', \phi, G'');
36
                       (G'', C', L'') \leftarrow \text{applyGreedyRulesToAllFormulas}(G'', C', L'');
37
                       if G' = \text{null then newStates} \leftarrow \text{newStates} + \langle (G'', C', L'' + T) \rangle;
38
                       \mathbf{else}\ \mathsf{newStates} \leftarrow \mathsf{newStates} + \langle (\mathsf{mergeFcgs}(G',\,G''),C',L''+T) \rangle;
39
             (G',C',L') \leftarrow a \text{ copy of } s;
40
         return newStates;
41
```

## **Algorithm 3:** Helper functions used by Algorithm 2

```
1 Function updateCache(C, \phi, (V, s, N^+, \tau)):
        if \tau(s) = \text{Ref then return } C;
        if \#\phi \not\in \text{dom}(C) then return C \cup \{ \#\phi \mapsto (\phi, s) \};
 3
        if there is no (\phi', v) \in C(\#\phi) s.t. v = s then C(\#\phi) \leftarrow (\phi, s) \# C(\#\phi);
 4
       return C;
 6 Function mergeFcgs (G = (V, s, N^+, \tau), G' = (V', s', N', \tau'), r = s):
        if \tau(r) = \text{Ref then return null};
        foreach t \in N^+(r) do
 8
            if t = \star then
 9
                replace t with s' in N^+(r);
10
                return (V \sqcup V', s, N^+ \sqcup N', \tau \sqcup \tau');
11
            G'' \leftarrow \texttt{mergeFcgs}(G, G', t);
12
            if G'' \neq \text{null then return } G'';
13
       return null;
14
```

## Algorithm 4: Propagating atoms for smoothing across the FCG in a way that avoids infinite loops

```
Input: FCG (V, s, N^+, \tau)
  Input: function \iota that maps vertex types in \mathcal{T} to sets of atoms
  Input: functions \{f_t\}_{t\in\mathcal{T}} that take a list of sets of atoms and return a set of atoms
  Output: function S that maps vertices in V to sets of atoms
1 S \leftarrow \{v \mapsto \iota(\tau(v)) \mid v \in V\};
2 changed ← true;
3 while changed do
4
       changed \leftarrow false;
       foreach vertex \ v \in V do
\mathbf{5}
           S' \leftarrow f_{\tau(v)}(\langle S(w) \mid w \in N^+(v) \rangle);
6
           if S' \neq S(v) then
               changed \leftarrow true;
               S(v) \leftarrow S';
```

### **Algorithm 5:** The compilation rule for Ref

```
Input: formula \phi
    Output: either a singleton with the new Ref vertex or \emptyset
 1 foreach (\psi, v) \in \text{compilationCache}(\#\phi) do
          \rho \leftarrow \text{identifyRecursion}(\phi, \psi);
         if \rho \neq \text{null then return } \{ (\text{Ref}_{\rho}(v), \emptyset) \};
 4 return ∅;
 5 Function identifyRecursion(\phi, \psi, \rho = \emptyset):
         if |\phi| \neq |\psi| or \#\phi \neq \#\psi then return null;
          if \phi = \emptyset then return \rho;
          foreach clause c \in \phi do
 8
               foreach clause d \in \psi s.t. \#d = \#c do
                    foreach (\beta, \gamma) \in \text{generateMaps}(c, d, \rho) \text{ s.t. } c[\beta, \gamma] = d \text{ do}
10
                         \rho' \leftarrow \text{identifyRecursion}(\phi \setminus \{c\}, \psi \setminus \{d\}, \rho \cup \gamma);
11
                         if \rho' \neq \text{null then return } \rho';
12
               return null;
13
    Function generateMaps (c, d, \rho):
14
          foreach bijection \beta: Vars(c) \rightarrow \text{Vars}(d) do
15
16
               \gamma \leftarrow \text{constructDomainMap}(\text{Vars}(c), \delta_c, \delta_d, \beta, \rho);
              if \gamma \neq \text{null then yield } (\beta, \gamma);
17
18 Function constructDomainMap(V, \delta_c, \delta_d, \beta, \rho):
          \gamma \leftarrow \emptyset;
19
          foreach v \in V do
20
               if \delta_c(v) \in \text{dom}(\rho) and \rho(\delta_c(v)) \neq \delta_d(\beta(v)) then return null;
21
               if \delta_c(v) \notin \text{dom}(\gamma) then \gamma \leftarrow \gamma \cup \{ \delta_c(v) \mapsto \delta_d(\beta(v)) \};
22
               else if \gamma(\delta_c(v)) \neq \delta_d(\beta(v)) then return null;
23
         return \gamma;
24
```

commute. For example, if clause  $c_1$  is as in Example 1, then

$$c_{1}[\{X \mapsto A, Y \mapsto B, Z \mapsto C\}, \{a \mapsto b, b \mapsto c\}] = (\{\neg p(A, B), \neg p(A, C)\}, \{(B, C)\}, \{A \mapsto b, B \mapsto c, C \mapsto c\}).$$

#### 6.1.2 Everything Else

## **TODO**

- introduce/describe Algorithm 5 and describe the cache that's being used.
- explain why  $\rho \cup \gamma$  is possible
- explain what the second return statement is about and why a third one is not necessary
- explain the yield keyword
- in the example below: write down both formula using the ForcLift format

The algorithm could be improved in two ways:

• by constructing a domain map first and then using it to reduce the number of viable variable bijections.

• by similarly using the domain map  $\rho$ .

However, it is not clear that this would result in an overall performance improvement, since the number of variables in instances of interest never exceeds three and the identity bijection is typically the right one.

Diagramatically, constructDomainMap attempts to find  $\gamma \colon \text{Doms}(c) \to \text{Doms}(d)$  s.t.

$$\begin{array}{ccc}
\operatorname{Vars}(c) & \stackrel{\beta}{\longleftarrow} & \operatorname{Vars}(d) \\
\delta_c \downarrow & & \downarrow \delta_d \\
\operatorname{Doms}(c) & \stackrel{\gamma}{\longleftarrow} & \operatorname{Doms}(d) \\
\downarrow & & \downarrow \\
\mathcal{D} & \stackrel{\rho}{\longrightarrow} & \mathcal{D}.
\end{array} \tag{3}$$

commutes (and returns null if such a function does not exist).

TODO: update this example. Fix references.

**Example 2.** Let  $\phi$  be the formula from Example 1 and  $\psi := \phi[\operatorname{id}, \{a \mapsto a', b \mapsto b^{\perp}\}]$  (i.e.,  $\phi$  with both of its domains replaced). Since  $\#\phi = \#\psi$ , and both formulas are non-empty, the algorithm proceeds with the for-loops on Lines 8 to 10. Suppose c in the algorithm refers to Eq. (1), and d to ??. Since both clauses have three variables, in the worst case, function <code>generateMaps</code> would have 3! = 6 bijections to check. Suppose the identity bijection is picked first. Then <code>constructDomainMap</code> is called with the following parameters:

- $V = \{ X, Y, Z \},$
- $\delta_c = \{ X \mapsto a, Y \mapsto b, Z \mapsto b \},$
- $\delta_d = \{ X \mapsto a', Y \mapsto b^{\perp}, Z \mapsto b^{\perp} \},$
- $\beta = \{ X \mapsto X, Y \mapsto Y, Z \mapsto Z \},$
- $\bullet$   $\rho = \emptyset$ .

Since  $\delta_i(Y) = \delta_i(Z)$  for  $i \in \{c, d\}$ , constructDomainMap returns  $\gamma = \{a \mapsto a', b \mapsto b^{\perp}\}$ . Thus, generateMaps yields its first pair of maps  $(\beta, \gamma)$  to Line 10. Furthermore, the pair satisfies  $c[\beta, \gamma] = d$ .

Since  $\pi(a') = a$ , and  $a' \in \mathcal{C}$ , traceAncestors(a, a') returns true, which sets foundConstraintRemoval' to true as well. When e = b, however, traceAncestors $(b, b^{\perp})$  returns false since  $b^{\perp}$  is a descendant of b but not created by the constraint removal compilation rule. On Line 11, a recursive call to identifyRecursion $(\phi', \psi', \gamma, \text{ true})$  is made, where  $\phi'$  and  $\psi'$  are new formulas with one clause each: Eq. (2) and ??, respectively.

Again we have two non-empty formulas with equal hash codes, so generateMaps is called with c set to Eq. (2), d set to ??, and  $\rho = \{a \mapsto a', b \mapsto b^{\perp}\}$ . Suppose Line 15 picks the identity bijection first again. Then constructDomainMap is called with the following parameters:

- $V = \{ X, Y, Z \},$
- $\delta_c = \{ X \mapsto a, Y \mapsto b, Z \mapsto a \},$
- $\delta_d = \{ X \mapsto a', Y \mapsto b^{\perp}, Z \mapsto a' \},$
- $\beta = \{ X \mapsto X, Y \mapsto Y, Z \mapsto Z \},$
- $\rho = \{ a \mapsto a', b \mapsto b^{\perp} \}.$

Since  $\beta$  and  $\rho$  commute (as in Eq. (3)), and there are no new domains in  $\mathrm{Doms}(c)$  and  $\mathrm{Doms}(d)$ ,  $\gamma$  exists and is equal to  $\rho$ . Again, the returned pair  $(\beta,\gamma)$  satisfies  $c[\beta,\gamma]=d$ . Line 11 calls  $\mathrm{identifyRecursion}(\emptyset,\ \emptyset,\ \rho$ , true), which immediately returns  $\rho=\{a\mapsto a',b\mapsto b^\perp\}$  as the final answer. This means that one can indeed use an FCG for  $\mathrm{WMC}(\phi)$  to compute  $\mathrm{WMC}(\psi)$  by replacing every mention of a with a' and every mention of b with  $b^\perp$ .

## Algorithm 6: The compilation rule for CR

```
Input: formula \phi, set of domains \mathcal{D}
    Output: set S
 1 S \leftarrow \emptyset;
 2 foreach domain d \in \mathcal{D} and element e \in d s.t. e does not occur in any literal of any clause of \phi and
      for each clause c = (L, C, \delta_c) \in \phi and variable v \in Vars(c), either \delta_c(v) \neq d or (v, e) \in C do
         add a new domain d' to \mathcal{D};
          \phi' \leftarrow \emptyset:
 4
         foreach clause (L, C, \delta) \in \phi do
 5
               C' \leftarrow \{ (x, y) \in C \mid y \neq e \};
 6
 7
               foreach variable\ v \in Vars(L) \cup Vars(C')\ \mathbf{do}
 8
                    if \delta(v) = d then \delta' \leftarrow \delta' \cup \{v \mapsto d'\};
 9
                 else \delta' \leftarrow \delta' \cup \{v \mapsto \delta(v)\};
10
            \phi' \leftarrow \phi' \cup \{ (L, C', \delta') \};
11
         S \leftarrow S \cup \{ \operatorname{CR}_{d \mapsto d'}, \phi' \};
12
```

#### 6.1.3 Evaluation

 $\mathrm{WMC}(\mathrm{Ref}_{\rho}(v);\sigma) = \mathrm{WMC}(v;\sigma')$  (n is the target vertex), where  $\sigma'$  is defined as

$$\sigma'(x) = \begin{cases} \sigma(\rho(x)) & \text{if } x \in \text{dom}(\rho) \\ \sigma(x) & \text{otherwise} \end{cases}$$

for all  $x \in \mathcal{D}$ .

### 6.2 Constraint Removal

TODO: describe Algorithm 6 and rewrite the example below.

**Example 3.** Let  $\phi = \{c_1, c_2, c_e\}$  be a formula with clauses (constants lowercase, variables uppercase)

$$c_{1} = (\emptyset, \{ (Y, X) \}, \{ X \mapsto b^{\top}, Y \mapsto b^{\top} \}),$$

$$c_{2} = (\{ \neg p(X, Y), \neg p(X, Z) \}, \{ (X, x), (Y, Z) \}, \{ X \mapsto a, Y \mapsto b^{\perp}, Z \mapsto b^{\perp} \}),$$

$$c_{3} = (\{ \neg p(X, Y), \neg p(Z, Y) \}, \{ (X, x), (Z, X), (Z, x) \}, \{ X \mapsto a, Y \mapsto b^{\perp}, Z \mapsto a \}).$$

Domain a and with its element  $x \in a$  satisfy the preconditions for constraint removal. The operator introduces a new domain a' and transforms  $\phi$  to  $\phi' = (c'_1, c'_2, c'_3)$ , where

$$\begin{aligned} c_1' &= c_1 \\ c_2' &= (\{ \neg p(X,Y), \neg p(X,Z) \}, \{ (Y,Z) \}, \{ X \mapsto a', Y \mapsto b^{\perp}, Z \mapsto b^{\perp} \}) \\ c_3' &= (\{ \neg p(X,Y), \neg p(Z,Y) \}, \{ (Z,X) \}, \{ X \mapsto a', Y \mapsto b^{\perp}, Z \mapsto a' \}). \end{aligned}$$

Evaluation.

$$WMC(CR_{d\mapsto d'}(n); \sigma) = \begin{cases} WMC(n; \sigma \cup \{d' \mapsto \sigma(d) - 1\}) & \text{if } \sigma(d) > 0 \\ 0 & \text{otherwise.} \end{cases}$$

## **Algorithm 7:** The compilation rule for DR

```
Input: formula \phi
  Output: set S
1 S \leftarrow \emptyset;
2 foreach domain d \in \mathcal{D} s.t. there is a clause c \in \phi and a variable v \in \text{Vars}(L_c) s.t. \delta_c(v) = d do
        x \leftarrow a new constant associated with domain d;
       foreach clause c = (L, C, \delta) \in \phi do
5
             V \leftarrow \{ v \in \text{Vars}(L) \mid \delta(v) = d \};
6
             foreach subset W \subseteq V s.t. W^2 \cap C = \emptyset and
              W \cap \{v \in Vars(C) \mid (v, y) \in C \text{ for some constant } y\} = \emptyset \text{ do}
                 /* Here, \delta' is the restriction of \delta to the new set of variables
                                                                                                                                                */
              \phi' \leftarrow \phi' \cup \{ (L[x/W], C[x/W] \cup \{ (v, x) \mid (v \in V \setminus W) \}, \delta') \};
8
       S \leftarrow S \cup \{ (\mathrm{DR}_{d \leftarrow d \setminus \{x\}}, \phi') \};
```

### 6.3 A Generalisation of Domain Recursion

The algorithm uses this notation for substitution. Let S be a set of constraints or literals, V a set of variables, and x either a variable or a constant. Then we write S[x/V] to denote S with all occurrences of all variables in V replaced with x.

TODO: Compare with the original [2].

The reason for this precondtion is the same as in the initial version of domain recursion: there must be a variable with that domain featured among the literals because it needs to be replaced by a constant. TODO: expand this.

TODO: describe Algorithm 7.

**Example 4.** Let  $\phi = \{c_1, c_2\}$  be a formula, where

$$c_1 = (\{ \neg p(X,Y), \neg p(X,Z) \}, \{ (Z,Y) \}, \{ X \mapsto a, Y \mapsto b, Z \mapsto b \}),$$
  
$$c_2 = (\{ \neg p(X,Y), \neg p(Z,Y) \}, \{ (Z,X) \}, \{ X \mapsto a, Y \mapsto b, Z \mapsto a \}).$$

While domain recursion is possible on both domains, here we illustrate how it works on a.

Suppose Line 5 picks  $c = c_1$  first. Then  $V = \{X\}$ . Both subsets of V satisfy the conditions on Line 7 and generate new clauses

$$(\{\,\neg p(X,Y),\neg p(X,Z)\,\},\{\,(Z,Y),(X,x)\,\},\{X\mapsto a,Y\mapsto b,Z\mapsto b\}),$$

(from  $W = \emptyset$ ) and

$$(\{ \neg p(x, Y), \neg p(x, Z) \}, \{ (Z, Y) \}, \{ Y \mapsto b, Z \mapsto b \})$$

(from W = V).

When  $c = c_2$ , then  $V = \{X, Z\}$ . The subset W = V fails to satisfy the first condition because of the  $Z \neq X$  constraint; without this condition, the resulting clause would have an unsatisfiable constraint  $x \neq x$ . The other three subsets of V all generate clauses for  $\phi'$ :

$$(\{\neg p(X,Y), \neg p(Z,Y)\}, \{(Z,X), (X,x), (Z,x)\}, \{X \mapsto a, Y \mapsto b, Z \mapsto a\})$$

(from  $W = \emptyset$ ),

$$(\{ \neg p(x,Y), \neg p(Z,Y) \}, \{ (Z,x) \}, \{ Y \mapsto b, Z \mapsto a \})$$

<sup>&</sup>lt;sup>4</sup>Note that if (v, w) is a two-variable constraint, substituting a constant c for v would result in (c, w), which would have to be rewritten as (w, c) to fit the definition of a constraint.

(from 
$$W=\{X\}$$
), and 
$$\big( \big\{ \neg p(X,Y), \neg p(x,Y) \big\}, \big\{ (X,x) \big\}, \big\{ X \mapsto a, Y \mapsto b, \big\} \big)$$
 (from  $W=\{Z\}$ ).

Evaluation.

$$\mathrm{WMC}(\mathrm{DR}_{d \leftarrow d \setminus \{x\}}(n); \sigma) = \begin{cases} \mathrm{WMC}(n; \sigma) & \text{if } \sigma(d) > 0 \\ 1 & \text{otherwise.} \end{cases}$$

One is picked as the multiplicative identity.

# 7 How to Evaluate an FCG

Along with the three vertex types described above, here are all the other ones. This section is mostly just taken from [3] but with some changes in notation.

**Definition 6.** Let  $\operatorname{gr}(\cdot;\sigma)$  be the function (parameterised by the domain size function  $\sigma$ ) that takes a clause  $c = (L, C, \delta)$  and returns the number of ways the variables in c can be replaced by elements of their respective domains in a way that satisfies the inequality constraints.<sup>5</sup> Formally, for each variable  $v \in \operatorname{Vars}(c)$ , let  $C_v = \{w \mid (u, w) \in C \setminus \operatorname{Vars}(c)^2, u \neq v\}$  be the set of (explicitly named) constants that v is permitted to be equal to. Then

$$\operatorname{gr}(c;\sigma) \coloneqq \left| \left\{ (e_v)_{v \in \operatorname{Vars}(c)} \in \prod_{v \in \operatorname{Vars}(c)} C_v \sqcup [\sigma(\delta(v)) - |C_v|] \middle| e_u \neq e_w \text{ for all } (u,w) \in C \cap \operatorname{Vars}(c)^2 \right\} \right|$$

for any clause c. (Here,  $[n] := \{1, 2, \dots, n\}$  for any non-negative integer n.)

TODO: how does the algorithm prevent the number in  $[\cdot]$  from being negative?

TODO: explain that x, y, z refer to vertices, c refers to a clause, and describe each vertex type in a bit more detail.

tautology WMC( $\cap$ ;  $\sigma$ ) = 1

contradiction  $\text{WMC}(\bigcirc c; \sigma) = 0^{\text{gr}(c;\sigma)}$ 

unit clause

$$\mathrm{WMC}(\mathbb{D}c;\sigma) = \begin{cases} \mathrm{w}(p)^{\mathrm{gr}(c;\sigma)} & \text{if the literal is positive} \\ \overline{\mathrm{w}}(p)^{\mathrm{gr}(c;\sigma)} & \text{otherwise,} \end{cases}$$

where p is the predicate of the literal.

**smoothing** WMC( $\bigcirc c; \sigma) = (w(p) + \overline{w}(p))^{\operatorname{gr}(c;\sigma)}$ , where p is the predicate of the literal.

**decomposable conjunction**  $\text{WMC}(x \bigcirc y; \sigma) = \text{WMC}(x; \sigma) \times \text{WMC}(y; \sigma)$ 

deterministic disjunction  $WMC(x \bigcirc y; \sigma) = WMC(x; \sigma) + WMC(y; \sigma)$ 

decomposable set-conjunction  $\text{WMC}(\triangle_D x; \sigma) = \text{WMC}(x; \sigma)^{\sigma(D)}$ 

deterministic set-disjunction  $\text{WMC}(\bigotimes_{D\subseteq S} x; \sigma) = \sum_{d=0}^{\sigma(S)} \binom{\sigma(S)}{d} \text{WMC}(x; \sigma \cup \{D \mapsto d\})$ 

inclusion-exclusion  $WMC(IE(x, y, z); \sigma) = WMC(x; \sigma) + WMC(y; \sigma) - WMC(z; \sigma)$ 

Function Class			Asymptotic Complexity of Counting		
Partial	Endo	Class	Best Known	With Circuits	With Graphs
<b>√</b> / <b>X</b>	<b>√</b> / <b>X</b>	Functions	$\log m$	m	m
X	X	Surjections	$n \log m $ [1]	?	?
X	✓		$n \log m$ [1]	?	?
✓	X		Same as injections from $b$ to $a$		
✓	✓		Same as endo-injections		
X	X	Injections	$\log m$	-	mn
X	✓		$\log m$	-	$m^3$
✓	X		$\min\{m,n\}^2$	-	$n^2$
✓	✓		$m^2$	-	-
X	X	Bijections	$\log m$	-	m
X	✓		Same as (partial) (endo-)injections		
✓	<b>√</b> / <b>X</b>				

Table 1: Here, m is the size of a, and n is the size of b. All asymptotic complexities are in  $\Theta(\cdot)$ . This is for unweighted counting. A hyphen means that no solution was found. Assuming all arithmetic operations to take constant time. Maybe a better solution could be found with more search. TODO: explain assumptions for the counts to not be zero. TODO: double check. TODO: maybe combine more rows/columns. TODO: transfer the citations to text.

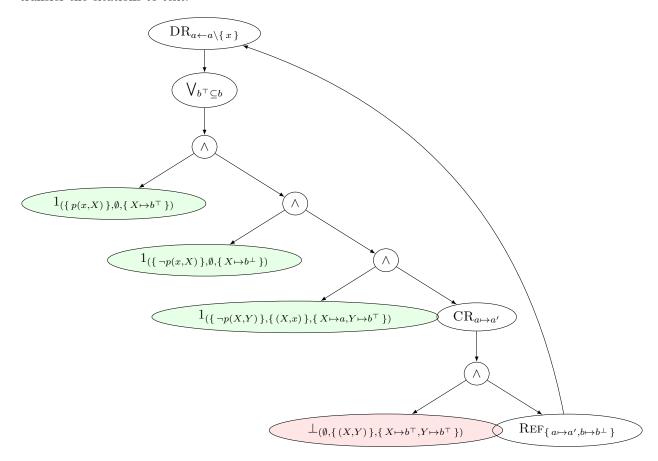


Figure 2: A graphical representation of an FCG for injections and partial injections between two domains. TODO: add a reference to a formula?

# 8 Examples of Newly Domain-Liftable Formulas

### TODO.

- Describe Fig. 2 and connect it to the algebraic formula.
- Explain the algebraic notation that I'm using here (e.g., that f is always the main function)
- Explain the importance of comparing domain sizes to 2. FCGs that compare the size of a domain to an integer can be constructed automatically using compilation rules, although n is upper bounded by the maximum number of variables in any clause of the input formula since there is no rule that would introduce new variables.
- Mention that it only takes a few seconds to find these solutions. Going beyond depth 6 (or sometimes even completing depth 6) is computationally infeasible with the current implementation, but depth at most 5 can be searched within at most a few seconds.
- Combine the tikz and the algebraic notation into one, so I don't need to have two versions. But how? Maybe associate a symbol with each type and only to the types that I use?
- the exponential solutions can be computed in quadratic time with dynamic programming!
- Can't explain how formulas are translated into (my definition of) clauses without explaining Skolemization, which is out of scope.
- Note that in some cases different descriptions of the same problem lead to different solutions (with different complexities).
- Maybe we are actually guaranteed that the solution is always polynomial-time. Except... running time could be infinite?

Let p be a predicate of arity two s.t. the first argument is associated with domain a, and the second argument is associated with domain b (i.e., p represents a relation between sets a and b). Then, to restrict all relations representable by p to just functions from a to b, in first-order logic one might write

$$\forall X \in a. \forall Y \in b. \forall Z \in b. p(X,Y) \land p(X,Z) \implies Y = Z \tag{4}$$

$$\forall X \in a. \exists Y \in b. p(X, Y). \tag{5}$$

The former says that one element of a can map to at most one element of b, and the latter says that each element of a must map to at least one element of b. One might add

$$\forall W \in a. \forall X \in a. \forall Y \in b. p(W, Y) \land p(X, Y) \implies W = X \tag{6}$$

to restrict p to injections or

$$\forall Y \in b. \exists X \in a.p(X,Y) \tag{7}$$

to ensure surjectivity or remove Eq. (5) to consider partial functions. Lastly, one can replace all occurrences of b with a so as to model endofunctions instead.

#### Notes.

- FORCLIFT fails on all of these.
- Functions, surjections, and their partial counterparts are/were already liftable. It seems like lifting injectivity (which is a fairly general property) is the main accomplishment. (But this is just the one I noticed. There may be many others as well.)
- Here,  $[\cdot]$  is the Iverson bracket.

<sup>&</sup>lt;sup>5</sup>Note that the literals of the clause have no effect on gr.

#### Results.

• 1d bijections and 1d injections (note that it's the same problem). Depth 3 solution:

$$f(n) = \sum_{m=0}^{n} \binom{n}{m} (-1)^{n-m} g(n, m)$$
$$g(n, m) = \sum_{l=0}^{n} \binom{n}{l} [l < 2] g(n - l, m - 1)$$
$$= g(n, m - 1) + ng(n - 1, m - 1),$$

which works with base case g(n,0) = 1.

- 1d partial injections. 2 solutions at depth 6, but they're too complicated to check by hand. A contradiction with  $X \neq x$  constraints makes things complicated.
- 2d bijections. Depth 3:

$$f(m,n) = \sum_{l=0}^{m} {m \choose l} [l < 2] (1 - [l < 1]) f(m-l, n-1)$$
  
=  $m f(m-1, n-1)$ ,

which works with base cases f(0,0) = 1, f(0,n) = 0, f(m,0) = 0.

• 2d injections. Depth 2:

$$f(m,n) = \sum_{l=0}^{m} {m \choose l} [l < 2] f(m-l, n-1)$$
$$= f(m, n-1) + m f(m-1, n-1),$$

which works with base cases f(0,0) = 1 and f(m,0) = 0.

• 2d partial injections, depth 2. Exactly the same circuit as above but with base case f(m,0)=1.

## 9 Discussion

- new rules that don't create vertices (e.g., duplicate removal, unconditional contradiction detection, etc.)
- some notes on halting
  - Search is infinite. Some rules increase the size of the formula(s), but most reduce it.
  - Inference is guaranteed to terminate if at least one domain shrinks by at least one. But note that allowing recursive calls with the same domain sizes (e.g., f(n) = f(n) + ...) could be useful because these problematic terms might cancel out.
  - It's impossible for  $n \leftarrow n-1$  and for  $n \in \dots$  to combine in a way that results in an infinite loop.
- care should be taken when cloning to preserve the validity of the cache and avoid infinite cycles (we use a separate (node  $\rightarrow$  node) cache for this)

## 10 Conclusions and Future Work

#### Conclusions and observations.

• CR must be separate from DR because initially the requirement to not have the newly introduced constant in the literals is not satisfied.

#### Future work.

- Transform FCGs to definitions of (possibly recursive) functions on integers. Use a computer algebra system to simplify them.
- Design an algorithm to infer the necessary base cases. (Note that there can be an infinite amount of them when functions have more than one parameter.)
- Observation: -1 (and powers thereof) appear in every solution to a formula if and only if the formula has existential quantification. That's not very smart! By putting unit propagation into  $\Gamma$ , these powers are pushed to the outer layers of the solution (i.e., 'early' in the FCG). It's likely that removing this restriction would enable the algorithm to find asymptotically optimal solutions.

## References

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