

Maximum Common Subgraph

Algorithms and Algorithm Portfolios

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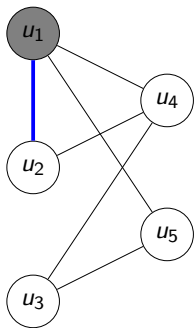
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University of Glasgow

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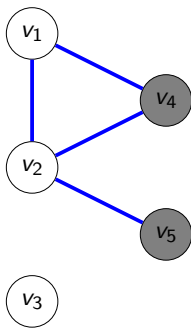
Maximum Common Subgraph

Definition

A *maximum common (induced) subgraph* between graphs G_1 and G_2 is a graph G_3 such that $G_3 = (V_3, E_3)$ is isomorphic to induced subgraphs of both G_1 and G_2 with $|V_3|$ maximised.



G_1



G_2

table here

Algorithm selection

Definition (Bischl et al. 2016)

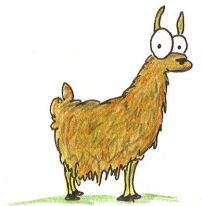
Given a set \mathcal{I} of problem instances, a space of algorithms \mathcal{A} , and a performance measure $m: \mathcal{I} \times \mathcal{A} \rightarrow \mathbb{R}$, the *algorithm selection problem* is to find a mapping $s: \mathcal{I} \rightarrow \mathcal{A}$ that optimises $\mathbb{E}[m(i, s(i))]$.

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LLAMA (Kotthoff 2013)



Algorithms

- MCSPLIT, MCSPLIT \downarrow
 - (McCreesh, Prosser and Trimble 2017)
- clique encoding
 - (McCreesh, Ndiaye et al. 2016)
- $k \downarrow$
 - (Hoffmann, McCreesh and Reilly 2017)

Labelling

Data from Foggia, Sansone and Vento 2001; Santo et al. 2003 (81400 pairs of graphs)

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A *vertex-labelled graph* is a 3-tuple $G = (V, E, \mu)$, where $\mu: V \rightarrow \{0, \dots, N - 1\}$ is a vertex labelling function, for some $N \in \mathbb{N}$.

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A graph $G = (V, E, \mu)$ is said to have a $p\%$ (*vertex*) *labelling* if

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- 3 subproblems
 - no labels
 - vertex labels
 - vertex and edge labels

Features (34 in total)

1–8 are from Kotthoff, McCreesh and Solnon 2016

- ① number of vertices
- ② number of edges
- ③ mean/max degree
- ④ density
- ⑤ mean/max distance between pairs of vertices
- ⑥ number of loops
- ⑦ proportion of vertex pairs with distance $\geq 2, 3, 4$
- ⑧ connectedness

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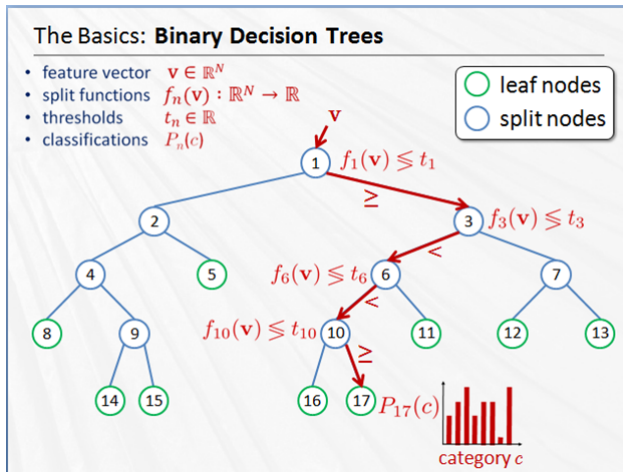
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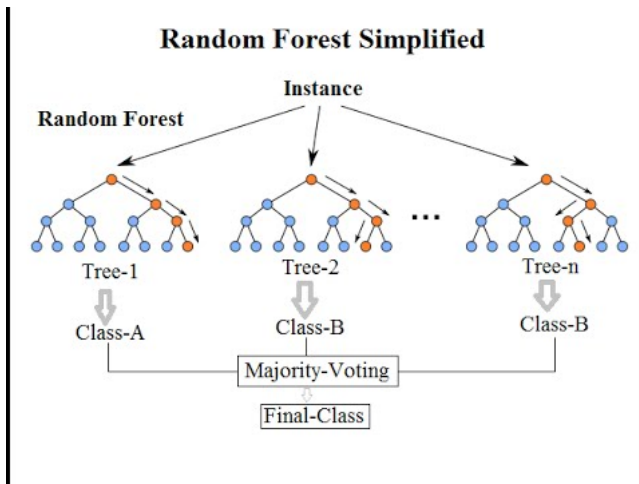
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- ⑪ ratios of features 1–5

Random forests (Breiman 2001)



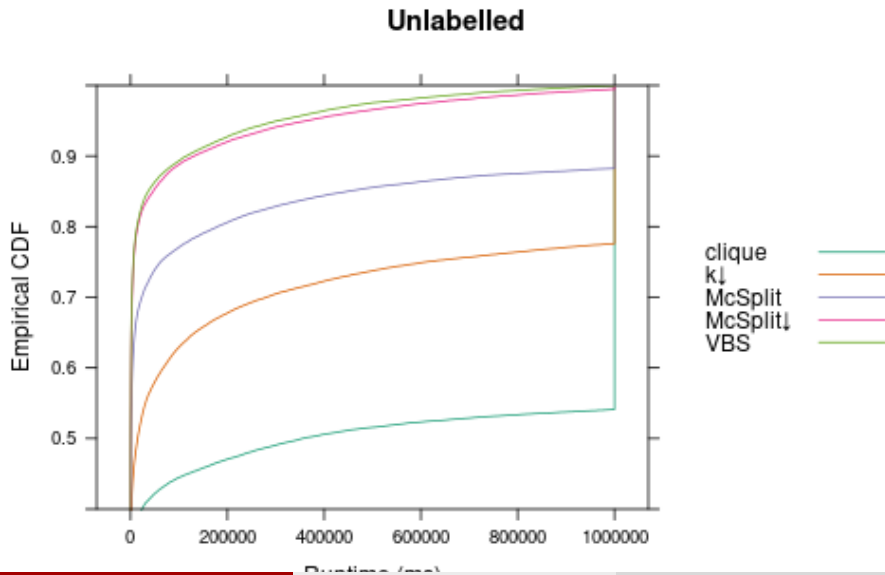
Source: Tae-Kyun Kim & Bjorn Stenger, Intelligent Systems and Networks (ISN) Research Group, Imperial College London

Random forests (Breiman 2001)

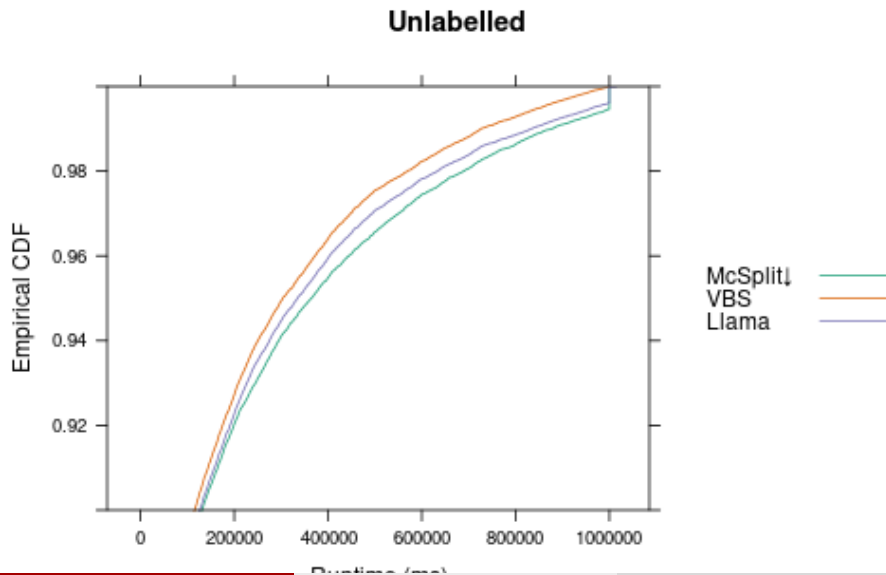


Source: Random Forests(r), Explained, Ilan Reinstein, KDnuggets

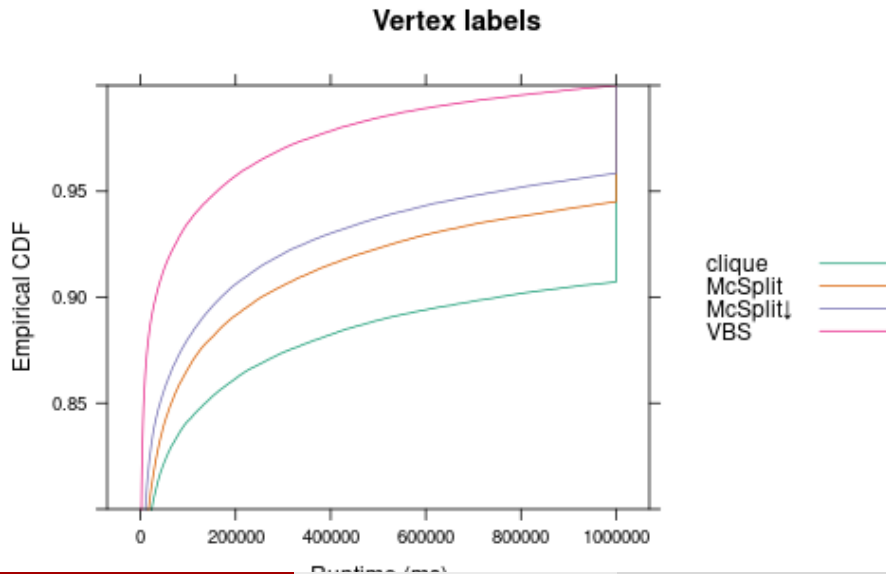
Results



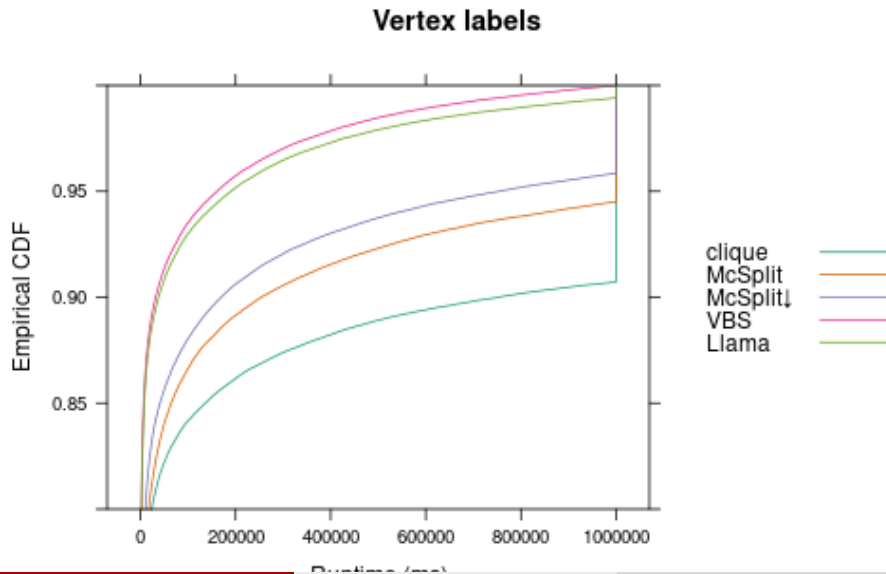
Results (27%)



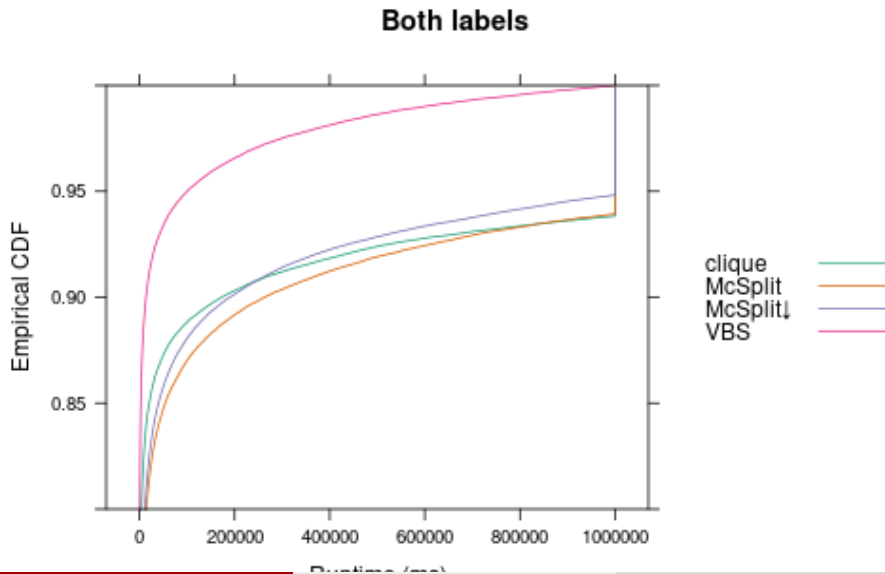
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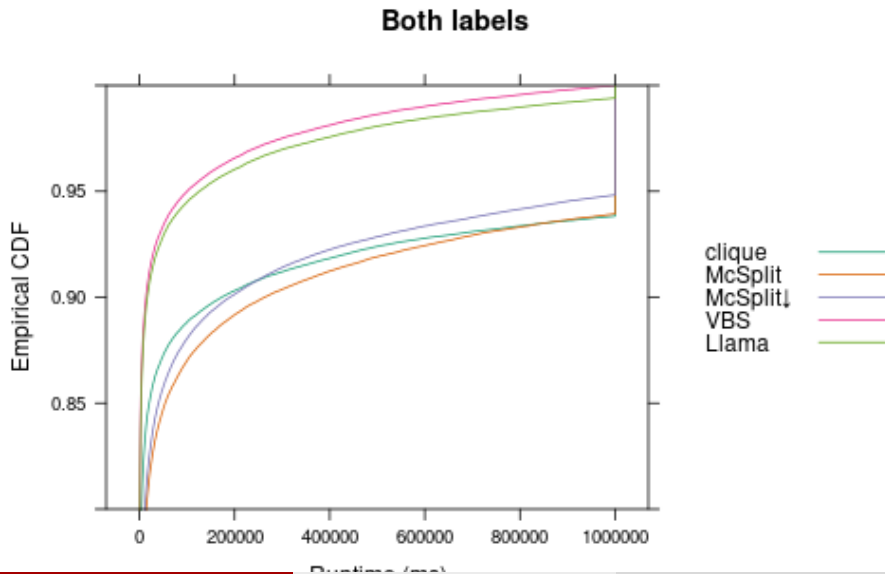
Results (86%)



Results



Results (88%)



Errors

- Out-of-bag error
- For each algorithm
 - $1 - \text{recall}$

Definition

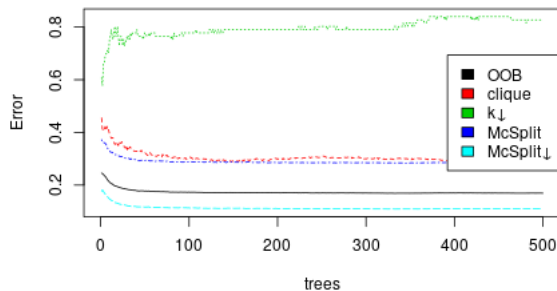
For an algorithm A , *recall* (sensitivity) is

$$\frac{\text{the number of instances that were correctly predicted as } A}{\text{the number of instances where } A \text{ is the correct prediction}}.$$

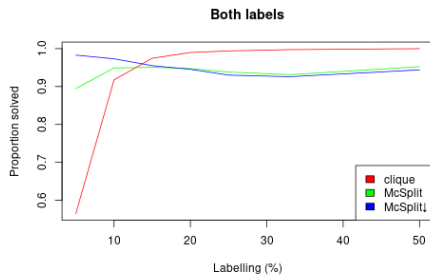
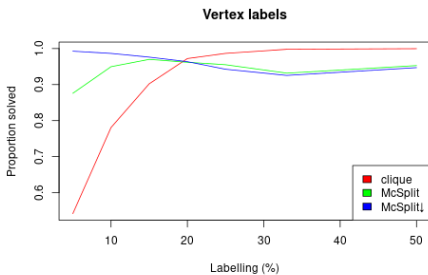
Errors (%)

Error	Labelling		
	no	vertex	both
out-of-bag	17	13	14
clique	30	8	7
McSP _{LIT}	29	22	29
McSP _{LIT} ↓	11	11	11
k ↓	80		

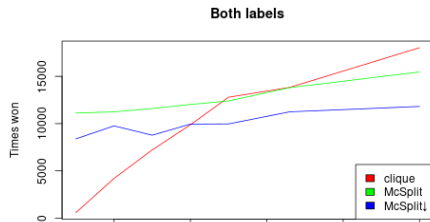
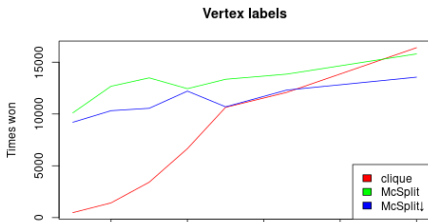
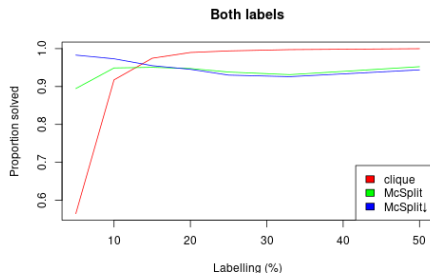
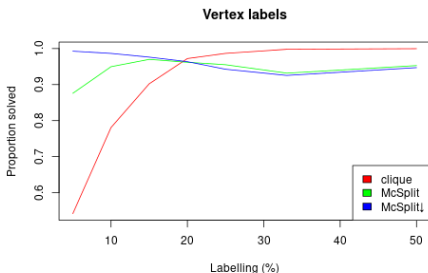
Convergence of errors for unlabelled graphs



What happens when labelling changes?



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Future work

- Relationships between clique algorithm's performance and properties of the association graph
- How the association graph changes after making a decision
- Can $k \downarrow$ and clique work together?