Generating Random Logic Programs Using Constraint Programming

Paulius Dilkas Vaishak Belle

AIAI Seminar





How Many Programs Are Used to Test Algorithms?

Anytime Inference in Probabilistic Logic Programs with T_P -Compilation

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Anytime Inference in Probabilistic Logic Programs with T_p -Compilation

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Inference and learning in probabilistic logic programs using weighted Boolean formulas

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k-Optimal: a novel approximate inference algorithm for ProbLog

Joris Renkens · Guy Van den Broeck · Siegfried Nijssen

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Inference and learning in probabilistic logic programs using weighted Boolean formulas

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On the Efficient Execution of ProbLog Programs

Angelika Kimmig¹, Vítor Santos Cost ², Ricardo Rocha², Bart Demoen¹, and Luc De Raedt¹

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Inference and learning in probabilistic logic programs using weighted Boolean formulas

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On the Efficient Execution of ProbLog Programs

Angelika Kimmig¹, Vítor Santos Cost², Ricardo Rocha², Bart Demoen¹, and Luc De Raedt¹

On the Implementation of the Probabilistic Logic Programming Language ProbLog

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Vítor Santos Costa and Ricardo Rocha

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Inference and learning in probabilistic logic programs using weighted Boolean formulas

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k-Optimal: a novel approximate inference algorithm for ProbLog ◀

Joris Renkens · Guy Van den Broeck · Siegfried Nijssen

On the Efficient Execution of ProbLog Programs

Angelika Kimmig 1, Vítor Santos Cost 2 , Ricardo Rocha 2, Bart Demoen 1, and Luc De Raedt 1

On the Implementation of the Probabilistic Logic Programming Language ProbLog

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ProbLog Technology for Inference in a Probabilistic First Order Logic

Maurice Bruynooghe and Theofrastos Mantadia and Angelika Kimmig and Bernd Gutmann and Joost Vennekens and Gerda Janssens and Luc De Raedt¹

The Constraint Model

Example Programs

Experimental Results

Conclusions

Probabilistic Logic Programs (PROBLOG)

"Smokers" (Domingos et al. 2008; Fierens et al. 2015)

```
0.2::stress(P):-person(P).
0.3::influences(P_1, P_2):-friend(P_1, P_2).
0.1::cancer_spont(P):-person(P).
0.3::cancer_smoke(P):-person(P).
    smokes(X):-stress(X).
    smokes(X):-smokes(Y), influences(Y, X).
    cancer(P): - cancer\_spont(P).
    cancer(P): - smokes(P), cancer\_smoke(P).
    person(michelle).
    person(timothy).
    friend(timothy, michelle).
```

Applications





Moldovan et al. 2012

```
is_malignant(Case):-
    biopsyProcedure(Case, usCore),
    changes_Sizeinc(Case, missing),
    feature_shape(Case).

is_malignant(Case):-
    assoFinding(Case, asymmetry),
    breastDensity(Case, scatteredFDensities),
    vacuumAssisted(Case, yes).

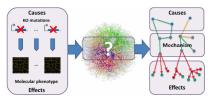
is_malignant(Case):-
    needleGauge(Case,9),
    offset(Case,14),
    vacuumAssisted(Case,yes).
```

Côrte-Real, Dutra, and Rocha 2017

Q1: In a group of 10 people, 60 percent have brown eyes. Two people are to be selected at random from the group. What is the probability that neither person selected will have brown eyes?

Q2: Mike has a bag of marbles with 4 white, 8 blue, and 6 red marbles. He pulls out one marble from the bag and it is red. What is the probability that the second marble he pulls out of the bag is white?

Dries et al. 2017



De Maeyer et al. 2013

```
Let a \oplus b := a + b - ab. Then
Pr[cancer(michelle)] = Pr[cancer_spont(michelle)]
                     ⊕ Pr[smokes(michelle)]
                     × Pr[cancer_smoke(michelle)]
```

```
cancer(P):-cancer\_spont(P).
cancer(P): - smokes(P), cancer\_smoke(P).
```

Let
$$a \oplus b := a + b - ab$$
. Then $Pr[cancer(michelle)] = 0.1 \oplus 0.3 \times Pr[smokes(michelle)]$

```
0.1::cancer_spont(P):-person(P).
0.3::cancer_smoke(P):-person(P).
```

```
Let a \oplus b := a + b - ab. Then
Pr[cancer(michelle)] = 0.1 \oplus 0.3 \times Pr[smokes(michelle)]
Pr[smokes(michelle)] = Pr[stress(michelle)]
                       \oplus \Pr[smokes(timothy)]
                       × Pr[influences(timothy, michelle)]
```

```
smokes(X):-stress(X).
smokes(X):-smokes(Y), influences(Y, X).
```

```
Let a \oplus b := a + b - ab. Then
Pr[cancer(michelle)] = 0.1 \oplus 0.3 \times Pr[smokes(michelle)]
Pr[smokes(michelle)] = 0.2 \oplus 0.3 \times Pr[smokes(timothy)]
```

```
0.2::stress(P):-person(P).
0.3::influences(P_1, P_2):-friend(P_1, P_2).
```

```
Let a \oplus b := a + b - ab. Then
Pr[cancer(michelle)] = 0.1 \oplus 0.3 \times Pr[smokes(michelle)]
Pr[smokes(michelle)] = 0.2 \oplus 0.3 \times Pr[smokes(timothy)]
Pr[smokes(timothy)] = Pr[stress(timothy)] = 0.2
```

```
0.2::stress(P):-person(P).
    smokes(X):-stress(X).
```

```
0.2::stress(P):-person(P).
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    smokes(X):-smokes(Y), influences(Y, X).
    cancer(P):-cancer_spont(P).
    cancer(P): - smokes(P), cancer\_smoke(P).
    person(michelle).
    person(timothy).
    friend(timothy, michelle).
```

```
cancer(michelle) = T
     Pr(world) = 0.2 \times (1 - 0.3) \times 0.1 \times 0.3
0.2: stress(P):-person(P).
0.3::influences(P_1, P_2):=friend(P_1, P_2).
0.1::cancer_spont(P):-person(P).
0.3::cancer_smoke(P):-person(P).
     smokes(X):-stress(X).
     smokes(X):-smokes(Y), influences(Y, X).
     cancer(P): - cancer\_spont(P).
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```

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0.1::cancer_spont(P):-person(P).
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     smokes(X):-stress(X).
     smokes(X):-smokes(Y), influences(Y, X).
     cancer(P): - cancer\_spont(P).
     cancer(P):=smokes(P), cancer\_smoke(P).
     person(michelle).
     person(timothy).
     friend(timothy, michelle).
```

```
cancer(michelle) = \top
  Pr(world) = (1 - 0.2) \times (1 - 0.3) \times 0.1 \times 0.3
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     smokes(X):-smokes(Y), influences(Y, X).
     cancer(P): - cancer\_spont(P).
     cancer(P):=smokes(P), cancer\_smoke(P).
     person(michelle).
     person(timothy).
     friend(timothy, michelle).
```

```
cancer(michelle) = \bot
Pr(world) = (1 - 0.2) \times (1 - 0.3) \times (1 - 0.1) \times (1 - 0.3)
   0.2::stress(P):-person(P).
   0.3::influences(P_1, P_2):-friend(P_1, P_2).
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   0.3::cancer_smoke(P):-person(P).
        smokes(X):-stress(X).
        smokes(X):-smokes(Y), influences(Y, X).
        cancer(P):-cancer_spont(P).
        cancer(P):=smokes(P), cancer\_smoke(P).
        person(michelle).
        person(timothy).
        friend(timothy, michelle).
```

```
NNF negation normal form
```

- BDD binary decision diagrams
- SDD sentential decision diagrams
- k-Best only use the k most probable proofs
- d-DNNF deterministic decomposable negation normal form

```
NNF negation normal form
```

- BDD binary decision diagrams
- SDD sentential decision diagrams
- k-Best only use the k most probable proofs
- d-DNNF deterministic decomposable negation normal form
 - for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
 - for every pair $\alpha \wedge \beta$, no atoms are shared between α and β

```
NNF negation normal form
```

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- BDD binary decision diagrams
- SDD sentential decision diagrams
- k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
- for every pair $\alpha \wedge \beta$, no atoms are shared between α and β
- examples:

$$(A \lor C) \land (A \lor \neg B)$$

```
NNF negation normal form
```

BDD binary decision diagrams

SDD sentential decision diagrams

k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
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- examples:

$$\begin{array}{c} XX & (A \lor C) \land (A \lor \neg B) \\ C \land (A \lor \neg B) \end{array}$$

```
NNF negation normal form
```

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$$(A \lor C) \land (A \lor \neg B)$$

 $(A \lor C) \land (A \lor \neg B)$

```
NNF negation normal form
```

BDD binary decision diagrams

SDD sentential decision diagrams

k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
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- examples:

$$(A \lor C) \land (A \lor \neg B)$$
 $(A \lor A) \lor (A \lor \neg B)$

```
NNF negation normal form
```

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BDD binary decision diagrams

SDD sentential decision diagrams

k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
- for every pair $\alpha \wedge \beta$, no atoms are shared between α and β
- examples:

$$(A \lor C) \land (A \lor \neg B)$$
 $(A \lor A) \lor (A \lor \neg B)$
 $(A \lor A) \lor (A \lor \neg B)$
 $(A \lor A) \lor (A \lor \neg B)$

```
NNF negation normal form
```

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- SDD sentential decision diagrams
- k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
- for every pair $\alpha \wedge \beta$, no atoms are shared between α and β
- examples:

$$(A \lor C) \land (A \lor \neg B)$$
 $(A \lor A) \lor (A \lor \neg B)$

$$\checkmark B \land C \land [(B \land A) \lor \neg B]$$

```
NNF negation normal form
```

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- BDD binary decision diagrams
- SDD sentential decision diagrams
- k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
- for every pair $\alpha \wedge \beta$, no atoms are shared between α and β
- examples:

$$(A \lor C) \land (A \lor \neg B)$$

$$X \sim C \wedge (A \vee \neg B)$$

$$\checkmark$$
 $\land B \land C \land [(B \land A) \lor \neg B]$

```
NNF negation normal form
```

Probabilistic Logic Programming

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- BDD binary decision diagrams
- SDD sentential decision diagrams
- k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
- for every pair $\alpha \wedge \beta$, no atoms are shared between α and β
- examples:

$$(A \lor C) \land (A \lor \neg B)$$

 $(A \lor C) \land (A \lor \neg B)$

$$\checkmark \times B \land C \land [(B \land A) \lor \neg B]$$

 $C \land [(B \land A) \lor \neg B]$

```
NNF negation normal form
```

Probabilistic Logic Programming

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- SDD sentential decision diagrams
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- for every pair $\alpha \wedge \beta$, no atoms are shared between α and β
- examples:

$$(A \lor C) \land (A \lor \neg B)$$

$$X \land C \land (A \lor \neg B)$$

$$\checkmark \times B \land C \land [(B \land A) \lor \neg B]$$

$$\checkmark$$
 $C \wedge [(B \wedge A) \vee \neg B]$

```
NNF negation normal form
```

Probabilistic Logic Programming

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- BDD binary decision diagrams
- SDD sentential decision diagrams
- k-Best only use the k most probable proofs

- for every pair $\alpha \vee \beta$, we have $\alpha \wedge \beta = \bot$
- for every pair $\alpha \wedge \beta$, no atoms are shared between α and β
- examples:

$$(A \lor C) \land (A \lor \neg B)$$
 $(A \lor C) \land (A \lor \neg B)$
 $(A \lor A) \lor \neg B$

Example Diagrams for $C \wedge (A \vee \neg B)$

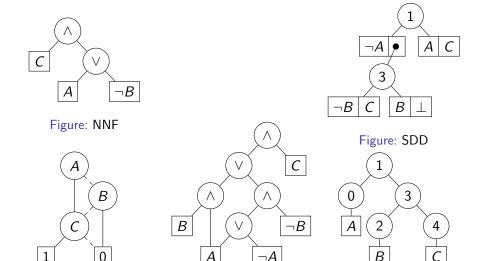


Figure: BDD

Figure: d-DNNF

Figure: vtree

```
0.2::stress(P):-person(P).
0.3: influences(P_1, P_2): -friend(P_1, P_2).
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0.3::cancer_smoke(P):-person(P).
    smokes(X) : - stress(X).
    smokes(X):-smokes(Y), influences(Y, X).
    cancer(P):-cancer_spont(P).
    cancer(P) : -smokes(P), cancer_smoke(P).
    person(michelle).
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0.2:stress(P):-person(P).
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    smokes(X):-stress(X).
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```

predicates, arities

```
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0.3: influences(P_1, P_2): -friend(P_1, P_2).
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    smokes(X):-stress(X).
    smokes(X):-smokes(Y), influences(Y, X).
     cancer(P): - cancer\_spont(P).
     cancer(P): - smokes(P), cancer\_smoke(P).
    person(michelle).
    person(timothy).
    friend(timothy, michelle).
```

- predicates, arities
- variables

```
0.2::stress(P):-person(P).
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0.1::cancer_spont(P):-person(P).
0.3::cancer\_smoke(P):-person(P).
    smokes(X):-stress(X).
    smokes(X):-smokes(Y), influences(Y, X).
    cancer(P):-cancer_spont(P).
    cancer(P): - smokes(P), cancer\_smoke(P).
    person(michelle).
    person(timothy).
    friend(timothy, michelle).
```

- predicates, arities
- variables
- constants

```
0.2::stress(P):-person(P).
0.3::influences(P_1, P_2):-friend(P_1, P_2).
0.1::cancer_spont(P):-person(P).
0.3::cancer_smoke(P):-person(P).
    smokes(X):-stress(X).
    smokes(X):-smokes(Y), influences(Y, X).
    cancer(P): - cancer\_spont(P).
    cancer(P): - smokes(P), cancer\_smoke(P).
    person(michelle).
    person(timothy).
    friend(timothy, michelle).
```

- predicates, arities
- variables
- constants
- probabilities

```
0.2::stress(P):-person(P).
0.3::influences(P_1, P_2):-friend(P_1, P_2).
0.1::cancer_spont(P):-person(P).
0.3::cancer_smoke(P):-person(P).
     smokes(X):-stress(X).
     smokes(X):-smokes(Y), influences(Y, X).
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    person(michelle).
    person(timothy).
     friend(timothy, michelle).
```

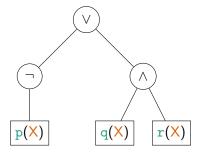
- predicates, arities
- variables
- constants
- probabilities
- length

```
0.2::stress(P):-person(P).
0.3::influences(P_1, P_2):-friend(P_1, P_2).
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     smokes(X):-stress(X).
     smokes(X):-smokes(Y), influences(Y, X).
     cancer(P): - cancer\_spont(P).
     cancer(P):=smokes(P), cancer\_smoke(P).
    person(michelle).
    person(timothy).
     friend(timothy, michelle).
```

- predicates, arities
- variables
- constants
- probabilities
- length
- complexity

$$\neg p(X) \lor (q(X) \land r(X))$$

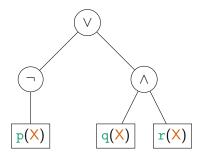




 $\neg p(X) \lor (q(X) \land r(X))$

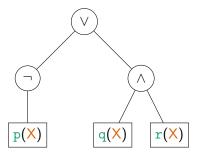
S: **V**:

0	0	0	1	2	2	6
V	٦	\wedge	p(X)	q(X)	r(X)	Т



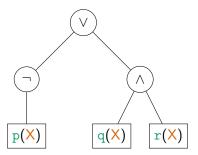
$$\neg p(X) \lor (q(X) \land r(X))$$

0 0 6 S: q(X)r(X)



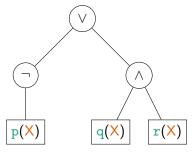
• s is a forest with T=2 trees

$$\neg p(X) \lor (q(X) \land r(X))$$



• s is a forest with T = 2 trees

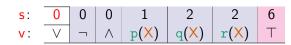
$$\neg p(X) \lor (q(X) \land r(X))$$

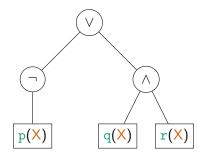


• s is a forest with T = 2 trees

- s is sorted
- $s_i \neq i \implies v_i \neq \top$

$$\neg p(X) \lor (q(X) \land r(X))$$



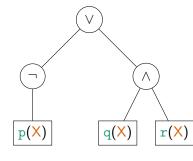


- s is a forest with T=2 trees
- length <u>L</u> = 7
- number of nodes N := L T + 1 = 6
- for i = 1, ..., L 1,
 - if i < N, then $s_i < i$
 - else $s_i = i$ and $v_i = T$

- s is sorted
- $s_i \neq i \implies v_i \neq \top$

$$\neg p(X) \lor (q(X) \land r(X))$$

S:	0	0	0	1	2	2	6
V :	V	Г	\wedge	p(X)	q(X)	r(X)	Т
C:	2	1	2	0	0	0	0



- s is a forest with T=2 trees
- length L = 7
- number of nodes N := L T + 1 = 6
- for i = 1, ..., L 1,
 - if i < N, then $s_i < i$
 - else $s_i = i$ and $v_i = \top$
- $c_i = 0 \iff v_i = T$ or is a predicate
- $c_i = 1 \iff v_i = \neg$
- $c_i > 1 \iff v_i \in \{\land, \lor\}$

- s is sorted
- $s_i \neq i \implies v_i \neq \top$

Variable Symmetry Breaking

```
The Problem
Let \{W, X, Y\} be the set of variables. Then
          smokes(X):-smokes(Y), influences(Y, X)
is equivalent to
          smokes(Y):-smokes(X), influences(X, Y)
and to
         smokes(W):-smokes(X), influences(X, W)
```



Occurrences (channeling)

 $\begin{array}{c} \mathsf{W} \mapsto \emptyset \\ \mathsf{X} \mapsto \{0,3\} \end{array}$

 $Y \mapsto \{1,2\}$

Introductions

 $1 + \min occurrences(v) \text{ or } 0$

 $W \mapsto 0$

 $X \mapsto 1$

 $Y \mapsto 2$

sorted!



Occurrences (channeling)

 $W \mapsto \emptyset$ $X \mapsto \{1, 2\}$ $Y \mapsto \{0, 3\}$

Introductions $1 + \min \operatorname{occurrences}(v)$ or 0

 $W \mapsto 0$

 $X \mapsto 2$

 $\mathsf{Y} \mapsto \mathsf{1}$

not sorted!



Occurrences (channeling)

$$\begin{array}{c} \mathsf{W} \mapsto \{0,3\} \\ \mathsf{X} \mapsto \{1,2\} \end{array}$$

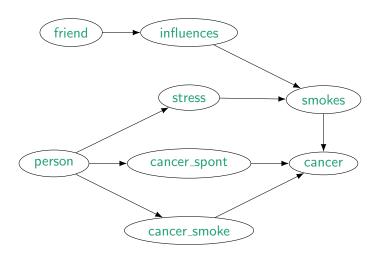
 $Y \mapsto \emptyset$

Introductions $1 + \min \operatorname{occurrences}(v)$ or 0

$$W \mapsto 1$$
$$X \mapsto 2$$
$$Y \mapsto 0$$

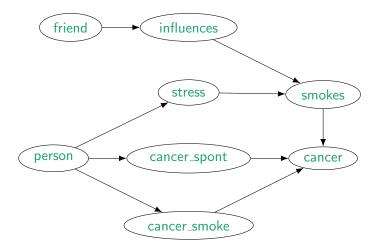
not sorted!

Predicate Dependency Graph



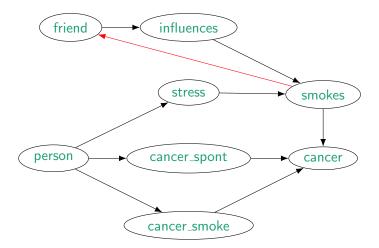
Stratification and Negative Cycles

0.1::friend(X, Y):-\+smokes(Y).

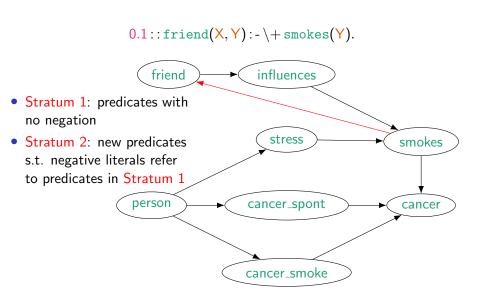


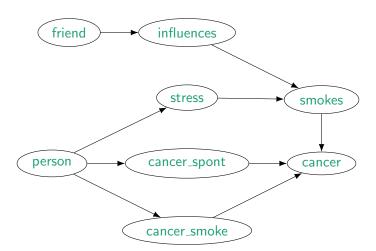
Stratification and Negative Cycles

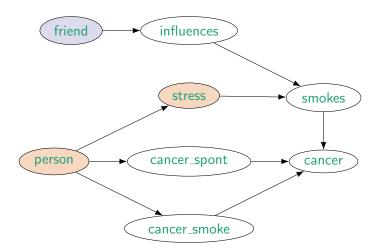
0.1::friend(X, Y):-\+smokes(Y).

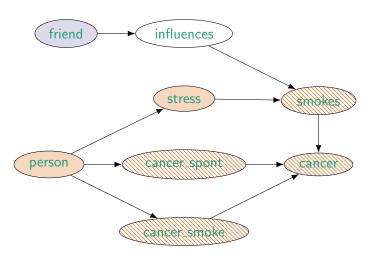


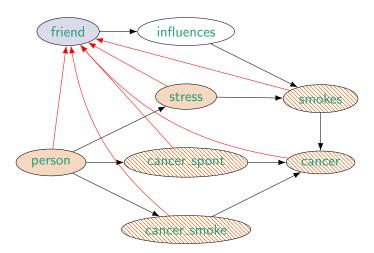
Stratification and Negative Cycles

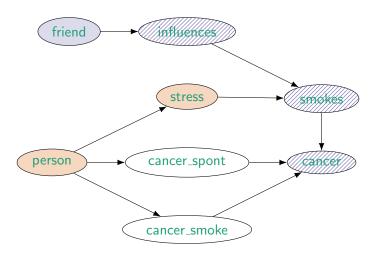


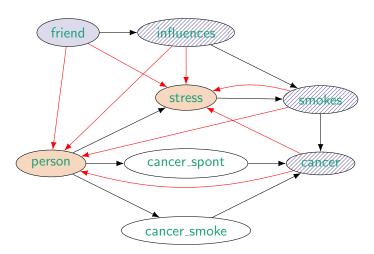












One-Liners

Setup

- predicate p/1
- variable X
- no constants
- 1 clause
- 4 nodes
- no negative cycles

(All) Programs

Example Programs 0000

- p(X).
- 0.7::p(X):-p(X).
- 0.8::p(X):-p(X);p(X).
- 0.7::p(X):-p(X),p(X).
- 0.1::p(X):-p(X);p(X);p(X).
- 0.8::p(X):-p(X),p(X),p(X).

Symmetry Breaking in Action

Setup

- predicate p/3
- variables: X, Y, Z
- no constants
- 1 clause
- 1 node
- no cycles at all

(All) Programs

• 0.8::p(Z,Z,Z).

Example Programs 0000

- p(Y, Y, Z).
- p(Y, Z, Y).
- p(Y, Z, Z).
- 0.1::p(X,Y,Z).

A Larger Example

Setup

- predicates: p/1, q/2, r/3
- variables: X, Y, Z
- constants: a, b, c
- 5 clauses
- 5 nodes
- no negative cycles

A Random Program

r(Y, b, Z).

Example Programs 0000

$$p(b):- +(q(a,b), q(X,Y), q(Z,X)).$$

 $0.4::q(X,X):- +r(Y,Z,a).$
 $q(X,a):-r(Y,Y,Z).$
 $q(X,a):-r(Y,b,Z).$

Examples of Predicate Independence

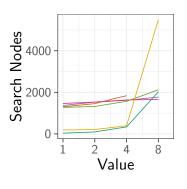
Setup

- predicates: p/1, q/1, r/1
- no variables
- constant a
- 3 clauses
- 3 nodes
- no negative cycles
- p ⊥ q

A Few Random Programs

- 0.5::p(a):-p(a);p(a). 0.2::q(a):-q(a),q(a).
 - 0.4: :r(a): + q(a).
- p(a) : -p(a).
 - 0.5::q(a):-r(a);q(a).
 - r(a) : -r(a) : r(a).
- p(a) : p(a); p(a).
 - 0.6::q(a):-q(a).
 - 0.7: :r(a): + q(a).

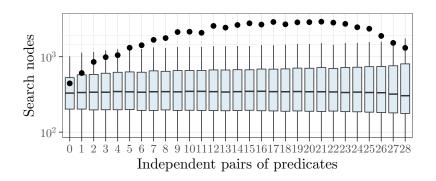
Scalability



Variable

- The number of predicates
- Maximum arity
- The number of variables
- The number of constants
- The number of additional clauses
- The maximum number of nodes

How Predicate Independence Affects Search Complexity



What Programs Should We Generate?

- each program is divided into:
 - rules
 - e.g., 0.2::stress(P):-person(P).
 - facts
 - e.g., friend(timothy, michelle).
- predicates, variables, nodes: 2, 4, 8
- maximum arity: 1, 2, 3
- all possible numbers of pairs of independent predicates
- 10 programs per configuration
 - fully restarting the constraint solver
- probabilities sampled from $\{0.1, 0.2, \dots, 0.9\}$
- query: random unlisted fact

```
0.2::stress(P):-person(P).
```

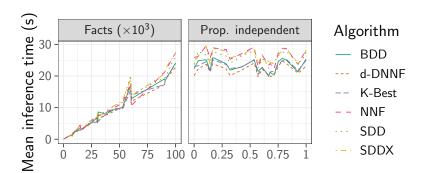
- no constants, no empty bodies
- one rule per predicate
- all rules are probabilistic

Facts

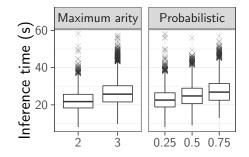
friend(timothy, michelle).

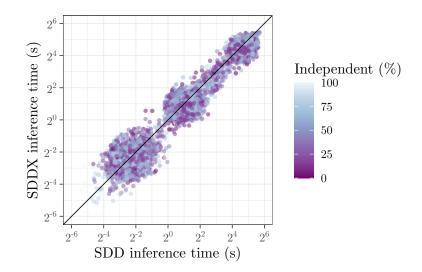
- proportion probabilistic: 25%, 50%, 75%
- constants: 100, 200, 400
- number of facts: 10³, 10⁴, 10⁵
 - but only up to 75% of all possible facts

Properties of Programs vs. Inference Algorithms

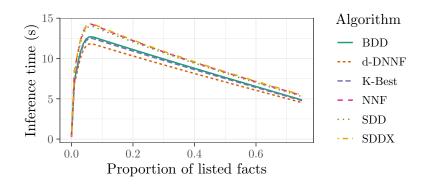


Properties of Programs vs. Inference Algorithms





The Ratio of Listed Facts to Possible Facts



- The model can generate (approximately) realistic instances of reasonable size
- The main performance bottleneck can be addressed by generating programs with a simpler structure
- Open guestions and future work
 - Can the model be used to ensure uniform sampling?
 - What is the reason behind all algorithms behaving similarly?
 - Why does independence have no effect on inference time?
 - Can random program generation be useful in learning?

The implementation of the model is available at

https://github.com/dilkas/random-logic-programs