

Generating Random Logic Programs Using Constraint Programming

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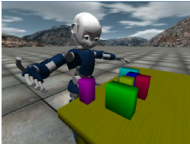
Engineering and
Physical Sciences
Research Council

Probabilistic Logic Programs (PROBLOG)

The Smokers Network (Domingos et al. 2008)

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    person(michelle).
    person(timothy).
    friend(timothy,michelle).
```

Applications



Moldovan et al. 2012

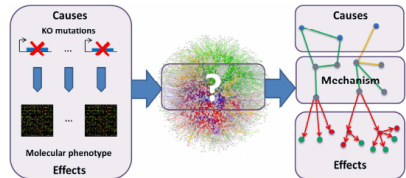
```
is_malignant(Case):-
    biopsyProcedure(Case,usCore),
    changes_Sizeinc(Case,missing),
    feature_shape(Case).
is_malignant(Case):-
    assoFinding(Case,asymmetry),
    breastDensity(Case,scatteredFDensities),
    vacuumAssisted(Case,yes).
is_malignant(Case):-
    needleGauge(Case,9),
    offset(Case,14),
    vacuumAssisted(Case,yes).
```

Côte-Real, Dutra, and Rocha 2017

Q1: In a group of 10 people, 60 percent have brown eyes. Two people are to be selected at random from the group. What is the probability that neither person selected will have brown eyes?

Q2: Mike has a bag of marbles with 4 white, 8 blue, and 6 red marbles. He pulls out one marble from the bag and it is red. What is the probability that the second marble he pulls out of the bag is white?

Dries et al. 2017



De Maeyer et al. 2013

Inference Algorithms and Knowledge Compilation Maps

- NNF negation normal form
- d-DNNF deterministic decomposable negation normal form
- BDD binary decision diagrams
- SDD sentential decision diagrams
- k*-Best ???

Example Diagrams for $C \wedge (A \vee \neg B)$

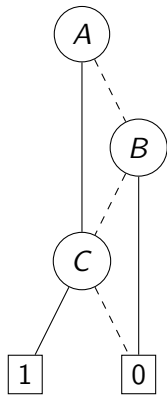


Figure: BDD

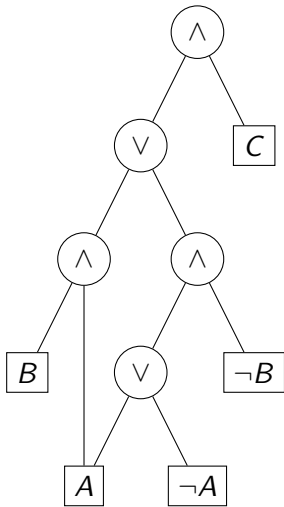


Figure: d-DNNF

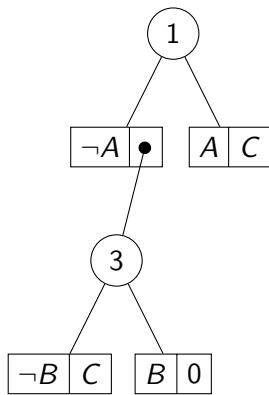


Figure: SDD

How Many Programs Are Used to Test Algorithms?

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Anytime Inference in Probabilistic Logic Programs with T_p -Compilation

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ProbLog Technology for Inference in a Probabilistic First Order Logic

Maurice Bruynooghe and Theodoros Mantas and Angelika Kimmig and Bernd Gutmann
and Joost Vennekens and Gerda Janssens and Luc De Raedt¹

What Characterises a (Probabilistic) Logic Program?

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0.3::cancer_smoke(P):-person(P).
    smokes(X):-stress(X).
    smokes(X):-smokes(Y),influences(Y,X).
    cancer(P):-cancer_spont(P).
    cancer(P):-smokes(P),cancer_smoke(P).
    person(michelle).
    person(timothy).
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```

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`person`(*michelle*).

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- predicates,
arities

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- predicates, arities
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- predicates, arities
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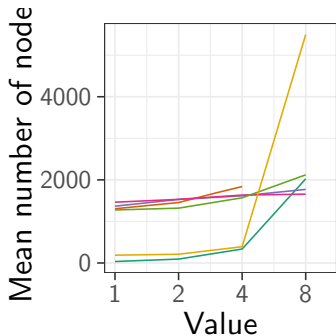
- predicates, arities
- variables
- constants
- probabilities
- length

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- predicates, arities
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- probabilities
- length
- complexity

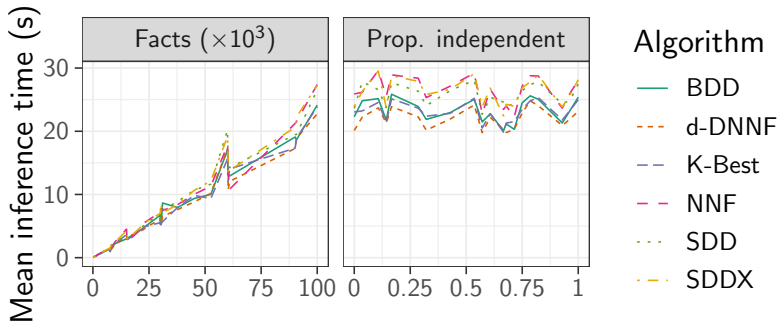
Scalability



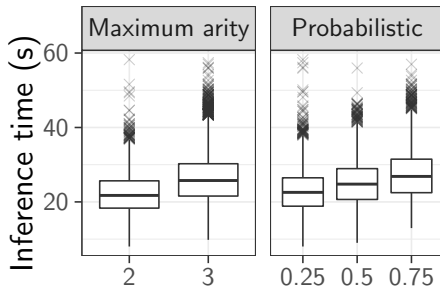
Variable

- The number of predicates
- Maximum arity
- The number of variables
- The number of constants
- The number of additional clauses
- The maximum number of nodes

Properties of Programs vs. Inference Algorithms



Properties of Programs vs. Inference Algorithms



Overview

General parameters

- maximum number of solutions
- `maxNumNodes` (in the tree representation of a clause)
- list of predicates with their variables
- maximum number of clauses
- option to forbid all cycles or just negative cycles
- list of probabilities that are randomly assigned to clauses:
 $\{0.1, 0.2, \dots, 0.9, 1, 1, 1, 1, 1, 1\}$

Decision variables

- `IntVar[] clauseAssignments`: a predicate or disabled
- `Clause[] clauses`

Constraints

Each predicate should get at least one constraint

- numDisabledClauses: defined by a count constraint
- numDistinctValues =
$$\begin{cases} \text{numPredicates} + 1 & \text{if numDisabledValues} > 0 \\ \text{numPredicates} & \text{otherwise.} \end{cases}$$
 - also constrained using the nValues constraint

Miscellaneous

- clauseAssignments are sorted.
- If clauseAssignments[i - 1] = clauseAssignments[i],
 - then clause[i - 1] \preceq clause[i].

Clauses

A clause is defined by...

- `IntVar[] treeStructure`
 - `treeStructure[i] = i`: the i -th node is a root.
 - `treeStructure[i] = j`: the i -th node's parent is node j .
- `IntVar[] treeValues`: \neg , \wedge , \vee , \top , and any predefined predicates with variables.

Auxiliary variables

- `numNodes, numTrees` $\in \{1, \dots, \text{maxNumNodes}\}$

Clause constraints

- `treeStructure` represents `numTrees` trees.
- `treeStructure[0] = 0`
- `numTrees + numNodes = maxNumNodes + 1`
- `treeStructure` is sorted
- For $i = 0, \dots, \text{maxNumNodes} - 1$,
 - If $\text{numNodes} \leq i$,
 - then `treeStructure[i] = i` and `treeValues[i] = \top` ,
 - else `treeStructure[i] < numNodes`.
 - has 0 children $\iff \text{treeValues}[i]$ is a predicate
 - has 1 child $\iff \text{treeValues}[i] = \neg$
 - has > 1 child $\iff \text{treeValues}[i] \in \{\wedge, \vee\}$
 - `treeStructure[i] \neq i \implies treeValues[i] $\neq \top$`
- If the clause should be disabled, `numNodes = 1` and `treeValues[0] = \top` .

Adjacency matrix representation

$A[i][j] = 0 \iff \nexists k : \text{clauseAssignments}[k] = j \text{ and } i \in \text{clauses}[k].\text{treeValues}$

New constraints

- No (negative) cycles
 - No clever propagation, just entailment checking.
- Independence. Propagation:
 - Two types of dependencies: determined and one-undetermined-edge-away-from-being-determined.
 - Look up the dependencies of both predicates. For each pair of matching dependencies:
 - If both are determined, fail.
 - If one is determined, the selected edge of the other must not exist.
- Conditional independence
 - Same propagation, but with a 'filter' that masks out the expression that the independence is conditioned on.