

# Weighted Model Counting Without Parameter Variables

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## 1 Introduction

**Notation.** For any propositional formula  $\phi$  and  $p, q \in \mathbb{R}$ , let  $[\phi]_q^p: 2^X \rightarrow \mathbb{R}$  be a pseudo-Boolean function defined as

$$[\phi]_q^p(Y) := \begin{cases} p & \text{if } Y \models \phi \\ q & \text{otherwise} \end{cases}$$

for any  $Y \subseteq X$ .

**Lemma 1.** *An ADD with  $n$  variables has  $\mathcal{O}(2^n)$  nodes.*

*Proof.* An ADD with  $n$  variables can be, at most, a complete binary tree of height  $n + 1$  (as measured by the number of vertices). It would then have  $2^0 + 2^1 + \dots + 2^n = 2^{n+1} - 1 = \mathcal{O}(2^n)$  nodes.  $\square$

**Lemma 2.** *Let  $\phi$  be a conjunction of  $n$  literals. Then the ADD representation of  $[\phi]_q^p$  can be constructed in  $\mathcal{O}(2^n)$  time for any  $p, q \in \mathbb{R}$  such that  $p \neq q$ .*

*Proof.* The ADD representation of  $\phi$  itself can be constructed with a sequence of  $n - 1$  calls to **apply** with one of the two operands in each call always a literal. The number of variables in the other operand then follows the sequence  $1, 2, 3, \dots, n - 1$ . By Lemma 1, the numbers of nodes in the ADD representations of these operands is then  $\mathcal{O}(2^1), \mathcal{O}(2^2), \dots, \mathcal{O}(2^{n-1})$ . Since one of the operands is of constant size, the overall time complexity of all calls to **apply** is then

$$\mathcal{O}(2^1) + \mathcal{O}(2^2) + \dots + \mathcal{O}(2^{n-1}) = \mathcal{O}(2^n).$$

Let  $\alpha$  be the ADD representation of  $\phi$ . Then the ADD representation of  $[\phi]_q^p$  is  $(p - q)\alpha + q$ . As scalar operations can obviously be implemented in linear time, the overall complexity remains  $\mathcal{O}(2^n)$ .  $\square$

## References.

- Related work without publicly available implementations:
  - direct compilation to SDDs [2]
  - direct compilation to PSDDs, also eliminating parameter variables (a thesis)
  - maybe two more papers

## Notes.

- Apparently, the DPMC paper already shows that taking the first offered decomposition tree is best.
- It is already well-known that WMC is FPT.

## 2 Parameter Variable Elimination

Notes.

- Let  $X_P$  be the set of parameter variable and  $X_I$  be the set of indicator variables.
- Parameter variables are either taken from the LMAP file (for encodings produced by Ace) or assumed to be the variables that have both weights equal to 1.
- If a parameter variable in a clause is ‘negated’, we can ignore the clause. We assume that there are no clauses with more than one instance of parameter variables.
- The second **foreach** loop can be performed in constant time by representing  $\phi'$  as a list and assuming that the two ‘clauses’ are adjacent in that list (and incorporating it into the first loop).
- The  $d$  map is constructed in  $\mathcal{O}(|X_P| \log |X_P|)$  time (we want to use a data structure based on binary search trees rather than hashing).
- **rename** can be implemented in  $\mathcal{O}(\log |X_P|)$  time.
- This may look like preprocessing, but all the transformations are local and thus can be incorporated into an encoding algorithm with no slowdown. In fact, if anything, the resulting algorithm would be slightly faster, as it would have less data to output.

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### Algorithm 1: WMC instance transformation

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**Data:** an (old-format) WMC instance  $(\phi, X_I, X_P, W)$

**Result:** a (new-format) WMC instance  $(\phi', \omega)$

$\phi' \leftarrow \emptyset;$

$\omega \leftarrow 1;$

let  $d: X_P \rightarrow \mathbb{N}$  be defined as  $v \mapsto |\{u \in X_P \mid u \leq v\}|;$

**foreach** clause  $c \in \phi$  **do**

**if**  $c \cap X_P = \{v\}$  for some  $v$  **and**  $W(v) \neq 1$  **then**

**if**  $|c| = 1$  **then**

$\omega \leftarrow \omega \times W(v);$

**else**

$\phi' \leftarrow \phi' \cup \left\{ \left[ \bigwedge_{l \in c \setminus \{v\}} \neg l \right]_1^{W(v)} \right\};$

**else if**  $\{v \mid \neg v \in c\} \cap X_P = \emptyset$  **then**

$\phi' \leftarrow \phi' \cup \{[c]_0^1\};$

**foreach** indicator variable  $v \in X_I$  **do**

**if**  $\{[v]_1^p, [\neg v]_1^q\} \subseteq \phi'$  for some  $p$  and  $q$  **then**

$\phi' \leftarrow \phi' \setminus \{[v]_1^p, [\neg v]_1^q\} \cup \{[v]_q^p\};$

replace every variable  $v$  in  $\phi'$  with **rename**( $v$ );

**return**  $(\phi', \omega);$

**Function** **rename**( $v$ ):

$S \leftarrow \{u \in X_P \mid u \leq v\};$

**if**  $S = \emptyset$  **then return**  $v;$

**return**  $v - d(\max S);$

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### 3 Parameterised Complexity of DPMC

Notes.

- Summary of results
  - We establish DPMC inference as fixed-parameter tractable.
  - We experimentally show that cw+DPMC is best on low-to-moderate treewidth instances, and cd06+c2d overtakes cw+DPMC on higher treewidth instances.
- By DPMC, we always mean DMC+lg.

TODO

- do a literature search focused around these papers
- use mathcal on  $V$ ,  $L$ ,  $E$  (and introduce them)
- maybe use texttt for DPMC?
- do I need to formally consider extending a pseudo-Boolean function to a bigger domain?
- Define:
  - an ADD as a DAG.
  - What does it mean for an ADD to ‘have’ variables? Maybe refer to pseudo-Boolean function sensitivity.
  - Formal definition of a previous WMC instance (CNF, literal weight function) and the new definition (set of  $2^X \rightarrow \mathbb{R}_{\geq 0}$  pseudo-Boolean functions and a constant). Note that the constant idea is borrowed from `bk1m16`.
  - Boolean formula in CNF (perhaps this is too trivial to define),
  - primal graph of a CNF formula (a.k.a. Gaifman/(variable) interaction/connectivity/clique/representing graph),
  - Bayesian network (I already have a definition of these last two),
  - moralisation of a Bayesian network (or of any DAG),

**Theorem 1** ([4], rephrased). *BN Inference (for all algorithms that accept arbitrary instances) has a lower bound that’s linear in the size of the BN and exponential in the treewidth of its moralisation (provide the exact formula).*

**Definition 1** ([3], verbatim but with one change). Let  $X$  be a set of Boolean variables and  $\phi$  be a CNF formula over  $X$ . A *project-join tree* (PJT) of  $\phi$  is a tuple  $(T, r, \gamma, \pi)$  where:

- $T$  is a tree with root  $r \in \mathcal{V}(T)$ ,
- $\gamma: \mathcal{L}(T) \rightarrow \mathbb{R}^{2^X}$  maps leaves of  $T$  to pseudo-Boolean functions, and
- $\pi: \mathcal{V}(T) \setminus \mathcal{L}(T) \rightarrow 2^X$  is a labelling function on internal nodes.

Moreover,  $(T, r, \gamma, \pi)$  must satisfy the following two properties:

1.  $\{\pi(n) : n \in \mathcal{V}(T) \setminus \mathcal{L}(T)\}$  is a partition of  $X$ , and
2. for each internal node  $n \in \mathcal{V}(T) \setminus \mathcal{L}(T)$ , variable  $x \in \pi(n)$ , and clause  $c \in \phi$  such that  $x$  appears in  $c$ , the leaf node  $\gamma^{-1}(c)$  must be a descendant of  $n$  in  $T$ .

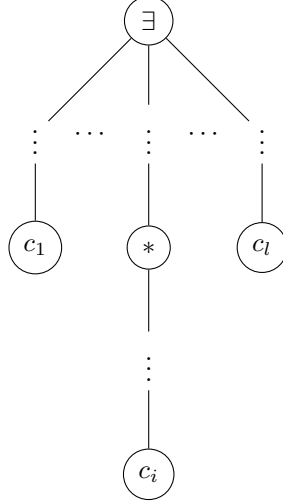


Figure 1: An example PJT with clauses  $c_1, \dots, c_i, \dots, c_l$  that all contain the same variable, its projection node  $\exists$ , and a node under consideration  $*$ .

Note that while Dudek et al. [3] define  $\gamma$  to be a bijection between leaves of a PJT and clauses, our definition is more general.

**Definition 2** ([3]).

$$\mathbf{Vars}(n) := \begin{cases} \mathbf{Vars}(\gamma(n)) & \text{if } n \in \mathcal{L}(T) \\ \left( \bigcup_{o \in \mathcal{C}(n)} \mathbf{Vars}(o) \right) \setminus \pi(n) & \text{if } n \notin \mathcal{L}(T). \end{cases}$$

$$\mathbf{size}(n) := \begin{cases} |\mathbf{Vars}(n)| & \text{if } n \in \mathcal{L}(T) \\ |\mathbf{Vars}(n) \cup \pi(n)| & \text{if } n \notin \mathcal{L}(T). \end{cases}$$

(Note that  $\mathbf{size}(n)$  is the number of variables that can appear during the computation of  $\delta(n)$  (excluding recursive calls).) The *width* of a PJT  $(T, r, \gamma, \pi)$  is  $\mathbf{width}(T) := \max_{n \in \mathcal{V}(T)} \mathbf{size}(n)$ .

**Theorem 2** ([3], rephrased, ‘ADD width is equal to the treewidth of the primal graph’). *Given a CNF formula  $\phi$  with a tree decomposition of its primal graph of width  $w$ , Algorithm 2 (from [3]) returns a PJT of  $\phi$  of width at most  $w + 1$ .*

**Definition 3** ([5], rephrased). A *tree decomposition* of a graph  $G$  is a pair  $(T, \chi)$ , where  $T$  is a tree and  $\chi: V(T) \rightarrow 2^{V(G)}$  is a labelling function, with the following properties:

- $\bigcup_{t \in V(T)} \chi(t) = V(G)$ ;
- for every edge  $e \in E(G)$ , there exists  $t \in V(T)$  such that  $e$  has both endpoints in  $\chi(t)$ ;
- for all  $t, t', t'' \in V(T)$ , if  $t'$  is on the path between  $t$  and  $t''$ , then  $\chi(t) \cap \chi(t'') \subseteq \chi(t')$ .

The *width* of tree decomposition  $(T, \chi)$  is  $\max_{t \in V(T)} |\chi(t)| - 1$ . The *treewidth* of graph  $G$  is the smallest  $w$  such that  $G$  has a tree decomposition of width  $w$ .

**Definition 4.** Let  $f, g: 2^X \rightarrow \mathbb{R}$  be pseudo-Boolean functions. Operations such as addition and multiplication are defined pointwise as

$$(f + g)(Y) := f(Y) + g(Y),$$

and

$$(fg)(Y) := f(Y)g(Y)$$

for all  $Y \subseteq X$ .

**Definition 5.** Let  $f: 2^X \rightarrow \mathbb{R}$  be a pseudo-Boolean function, and  $x \in X$ . Then  $f|_{x=0}, f|_{x=1}: 2^X \rightarrow \mathbb{R}$  are restrictions of  $f$  defined as

$$f|_{x=0}(Y) := f(Y \setminus \{x\}),$$

and

$$f|_{x=1}(Y) := f(Y \cup \{x\})$$

for all  $Y \subseteq X$ .

**Definition 6.** Let  $X$  be a set. For any  $x \in X$ , projection  $\exists_x$  is an endomorphism  $\exists_x: \mathbb{R}^{2^X} \rightarrow \mathbb{R}^{2^X}$  defined as

$$\exists_x f = f|_{x=1} + f|_{x=0}$$

for any  $f: 2^X \rightarrow \mathbb{R}$ .

**Lemma 3.** Let  $f, g: 2^X \rightarrow \mathbb{R}$  be pseudo-Boolean functions represented by ADDs with  $n$  and  $m$  nodes, respectively, and  $x \in X$ . Then  $f + g$  and  $fg$  can be computed in  $\mathcal{O}(mn)$  time, and  $\exists_x f$  can be computed in  $\mathcal{O}(n^2)$  time.

*Proof.* Addition and multiplication are implemented by `apply` algorithm which takes  $\mathcal{O}(mn)$  time [1]. Projection consists of two restrictions and an addition by Definition 6. The computational complexity of restriction is dominated by the reduction operation that transforms a decision diagram into a minimal canonical form [1]. While the original reduction algorithm had a  $\mathcal{O}(n \log n)$  complexity, caching can reduce it to  $\mathcal{O}(n)$  [6]. Either way, the complexity of projection is still  $\mathcal{O}(n^2)$ .  $\square$

**Definition 7.** Let  $(T, r, \gamma, \pi)$  be a PJT, and  $X$  be the set of variables. The functionality of DPMC execution can be represented by  $\delta(r)$ , where  $\delta: \mathcal{V}(T) \rightarrow \mathbb{R}^{2^X}$  is a recursive function defined as

$$\delta(t) = \begin{cases} \gamma(t) & \text{if } t \in \mathcal{L}(T) \\ \exists_{\pi(t)} \prod_{u \in \mathcal{C}(t)} \delta(u) & \text{otherwise.} \end{cases} \quad (1)$$

The range of  $\delta(r)$  then contains a single real number, i.e., the answer.

**Theorem 3** (Theorem 4 in [3], almost verbatim). Let  $\phi$  be a CNF formula over a set  $X$  of variables and  $(S, \chi)$  be a tree decomposition of the primal graph of  $\phi$  of width  $w$ . Then Algorithm 2 returns a PJT of  $\phi$  of width at most  $w + 1$ .

**Theorem 4.** Let  $(T, r, \gamma, \pi)$  be a PJT of width  $k$ . Then DPMC execution is fixed-parameter tractable with respect to the  $k$ . Specifically, DPMC execution time complexity is  $\mathcal{O}(4^k m(n + k))$ , where  $n = |\mathcal{L}(T)|$  is the number of clauses/leaves, and  $m$  is the number of variables.

*Proof.* • Let us consider the overall complexity of all multiplications and projections throughout the recursive calls of  $\delta$  in Definition 7. Clearly, the overall complexity is the sum of the complexity of operations performed within each call to  $\delta$ .

- Let  $t \in \mathcal{V}(T)$  be an arbitrary vertex of  $T$ . If  $t$  is a leaf,
- The total time taken by the DPMC execution stage is the sum of the time taken ‘inside’ each PJT node. The number of such nodes is upper bounded by  $m$ , so the total time complexity of DPMC is  $\mathcal{O}(4^k m(n + k))$ .

- Multiplying  $m$  ADDs can then take up to  $(m-1)(2^{k+1}-1)^2 = \mathcal{O}(m4^k)$  (since one multiplication takes up to  $(2^{k+1}-1)^2$  time and the result will have up to  $2^{k+1}-1$  nodes because the domain stays the same).
- Then, by Lemma 3, projecting  $m$  variables will take  $\mathcal{O}(4^k m)$  time.
- In total, operations on a PJT node with  $m$  children,  $k$  variables,  $n$  of which are projected takes  $\mathcal{O}(4^k(m+n))$  time.

□

## References

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