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function x = Tridiag(e, f, q, r)
% Tridiag: Tridiagonal equation solver banded system
   x = Tridiag(e, f, g, r): Tridiagonal system solver.
% input:
% e = subdiagonal vector
% f = diagonal vector
% g = superdiagonal vector
% r = right hand side vector
% output:
% x = solution vector
n=length(f);
% forward elimination
                (n-1)
for k = 2:n
 factor = e(k)/f(k-1);
 f(k) = f(k) - factor*g(k-1); 2
 r(k) = r(k) - factor*r(k-1); 2
end
% back substitution
x(n) = r(n)/f(n);
for k = n-1:-1:1 (n-1)
 x(k) = (r(k)-g(k)*x(k+1))/f(k);
            1+1+1=3
                   5 (n-1)

+ 3 (n-1)

+ 1

8(n-1) +1
                       8 (1-1)+1
```