

# Physics 410 - Homework 3

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## 1 Problem 1

### 1.1

$$\begin{aligned}l &= \vec{r} \times \vec{p} \\&= rmv \sin \phi \\ \phi &= 90^\circ \\&= rmv \\ \omega &= \frac{v}{r}, v = \omega r \\&= r^2 m \omega\end{aligned}\tag{1}$$

### 1.2

$$\begin{aligned}\frac{d}{dt}\left(\frac{dA}{dt}\right) &= 0 = \text{Kepler's Second Law} \\ \frac{dA}{dt} &= \frac{1}{2}\omega r^2 \\ \frac{dA}{dt} &= \frac{1}{2}\frac{v}{r}r^2 \\ \frac{dA}{dt} &= \frac{1}{2}vr \\ \frac{d}{dt}\left(\frac{dA}{dt}\right) &= \left(\frac{1}{2}vr\right)\frac{d}{dt} \\ &= \frac{1}{2}(v\dot{r} + r\dot{v}) \\ &= \frac{1}{2}(0 + 0) \\ \frac{d}{dt}\left(\frac{dA}{dt}\right) &= 0\end{aligned}\tag{2}$$

## 2 Problem 2

### 2.1

Prove  $\dot{l} = 0$

Since the force is always being applied parallel to  $\vec{r}$ , the momentum never changes

$$\begin{aligned}
\dot{l} &= \Gamma^{ext} \\
\Gamma^{ext} &= \vec{F} \times \vec{r} \\
\Gamma^{ext} &= 0 = \dot{l}
\end{aligned} \tag{3}$$

This is true since the force is being applied parallel to the radius at all points. Therefore their cross product is 0 and there is no change in angular momentum.

## 2.2

$$\begin{aligned}
I &= mr^2 \\
l_{final} &= I_{final}\omega_{final} \\
l_{initial} &= I_{initial}\omega_{initial}
\end{aligned}$$

Since angular momentum,  $l$ , is constant in the system, we can set the  $l_{initial} = l_{final}$ , and solve for  $\omega_{final}$

$$\begin{aligned}
l_{initial} &= l_{final} \\
mr_{initial}^2\omega_{initial} &= mr_{final}^2\omega_{final} \\
r_{initial}^2\omega_{initial} &= r_{final}^2\omega_{final} \\
\omega_{final} &= \frac{r_{initial}^2\omega_{initial}}{r_{final}^2}
\end{aligned} \tag{4}$$

## 2.3

$$KE = \frac{1}{2}I\omega^2$$

We can calculate the kinetic energy before and after pulling the string to calculate the work done.

$$\begin{aligned}
KE_{initial} &= \frac{1}{2}mr_{initial}^2\omega_{initial}^2 \\
KE_{final} &= \frac{1}{2}mr_{final}^2\omega_{final}^2 \\
KE_{initial} + W &= KE_{final} \\
\frac{1}{2}mr_{initial}^2\omega_{initial}^2 + W &= \frac{1}{2}mr_{final}^2\omega_{final}^2 \\
\frac{1}{2}mr_{initial}^2\omega_{initial}^2 + W &= \frac{1}{2}mr_{final}^2\left(\frac{r_{initial}^2\omega_{initial}^2}{r_{final}^2}\right) \\
W &= \frac{1}{2}mr_{final}^2\left(\frac{r_{initial}^4\omega_{initial}^2}{r_{final}^4}\right) - \frac{1}{2}mr_{initial}^2\omega_{initial}^2 \\
&= \frac{1}{2}mr_{initial}^2\omega_{initial}^2\left(\frac{r_{initial}^2}{r_{final}^2} - 1\right)
\end{aligned} \tag{5}$$

Since the work is non-zero and  $(\frac{r_{initial}^2}{r_{final}^2} - 1)$  will be a positive, we know that work is positive and therefore  $KE_{final} > KE_{initial}$

### 3 Problem 3

$$W = \int_0^P F \cdot dr = \int_0^P (F_x dx + F_y dy)$$

$$F = (x^2, 2xy)$$

#### 3.1

$$\int_0^P (F_x dx + F_y dy) = \int_0^Q (F_x dx) + \int_0^P (F_y dy)$$

Since x and y both go from 0 to 1, we can replace the bounds of integration

$$\begin{aligned} &= \int_0^1 (x^2 dx) + \int_0^1 (2xy dy) \\ &= \frac{x^3}{3} \Big|_0^1 + \int_0^1 (21y dy) \\ &= \frac{1}{3} + 2 \int_0^1 (\frac{y^2}{2} dy) \\ &= \frac{1}{3} + 2 \left[ \frac{y^2}{2} \Big|_0^1 \right] \\ &= \frac{1}{3} + 1 \\ &= \frac{4}{3} \end{aligned} \tag{6}$$

#### 3.2

$$\begin{aligned} \int_0^P (F_x dx + F_y dy) &= \int_0^Q (F_x dx) + \int_0^P (F_y dy) \\ &= \int_0^Q (x^2 dx) + \int_0^P (2xy dy) \\ &= \int_0^Q (x^2 dx) + \int_0^P (2x^3 2x dx) \\ &= \int_0^1 (x^2 dx) + \int_0^1 (2x^3 2x dx) \\ &= \frac{1}{3} + \frac{4}{5} \\ &= \frac{17}{15} \end{aligned} \tag{7}$$

### 3.3

$$0 \leq t \leq 1$$

$$F = (t^6, 2t^5)$$

$$\begin{aligned} \int_0^Q (F_x dx) + \int_0^P (F_y dy) &= \int_0^1 t^6 3t^2 dt + \int_0^1 2t^5 2t dt \\ &= 3 \int_0^1 t^8 dt + 4 \int_0^1 t^6 dt \\ &= (3 * \frac{1}{9}) + (4 * \frac{1}{7}) \\ &= \frac{1}{3} + \frac{4}{7} \\ &= \frac{19}{21} \end{aligned} \tag{8}$$

## 4 Problem 4

$$E = U + T$$

$$U = mgR \cos \phi \tag{9}$$

$$E_0 = mgR \tag{10}$$

$$E_f = mgR \cos \phi + \frac{mv^2}{2} \tag{11}$$

Using conservation of energy we know the  $E_0 = E_f$

$$E_0 = E_f$$

$$mgR = mgR \cos \phi + \frac{mv^2}{2}$$

$$gR - gR \cos \phi = \frac{v^2}{2} \tag{12}$$

$$2gR(1 - \cos \phi) = v^2$$

$$v = \sqrt{2gR(1 - \cos \phi)}$$

The puck will leave the sphere when the normal force is 0.

$$m\dot{v} = -F_N + F_g$$

$$m \frac{v^2}{r} = -F_N + mg \cos \phi \tag{13}$$

$$F_N = -m \frac{v^2}{r} + mg \cos \phi$$

Solving for when  $F_N = 0$  and plugging in our value for the velocity in terms of  $\phi$

$$\begin{aligned}
F_N &= -m \frac{v^2}{R} + mg \cos \phi \\
0 &= -m \frac{(\sqrt{2gR(1 - \cos \phi)})^2}{R} + mg \cos \phi \\
m \frac{(\sqrt{2gR(1 - \cos \phi)})^2}{R} &= mg \cos \phi \\
2(1 - \cos \phi) &= \cos \phi \\
2 - 2 \cos \phi &= \cos \phi \\
2 &= 3 \cos \phi \\
\frac{2}{3} &= \cos \phi \\
\phi &= 48.18^\circ
\end{aligned} \tag{14}$$

However, it should leave the surface at a max  $45^\circ$  as it does not make physical sense for the puck to gain momentum in the  $-\hat{x}$  which would occur when the puck basically loops around the sphere when  $\phi = 48^\circ$ . For this reason, I calculated the sin as well and got an answer of  $\phi = 41.81^\circ$ , which might be more reasonable.

## 5 Problem 5

**5.1**  $f(x, y, z) = ax^2 + bxy + cy^2$

$$\begin{aligned}
\frac{\partial}{\partial x}(ax^2 + bxy + cy^2) \\
&= \frac{\partial}{\partial x}ax^2 + \frac{\partial}{\partial x}bxy + 0 \\
&= 2ax + by
\end{aligned} \tag{15}$$

$$\begin{aligned}
\frac{\partial}{\partial y}(ax^2 + bxy + cy^2) \\
&= ax^2 + \frac{\partial}{\partial y}(bxy) + \frac{\partial}{\partial y}(cy^2) \\
&= 0 + bx + 2cy \\
&= bx + 2cy
\end{aligned} \tag{16}$$

$$\begin{aligned}
\frac{\partial}{\partial z}(ax^2 + bxy + cy^2) \\
&= 0
\end{aligned} \tag{17}$$

**5.2**  $g(x, y, z) = \sin(axyz^2)$

$$\begin{aligned}
\frac{\partial}{\partial x}(\sin(axyz^2)) \\
&= \frac{\partial}{\partial x}(\sin(axyz^2)) * \frac{\partial}{\partial x}(axyz^2) \\
&= \cos(axyz^2)(ayz^2)
\end{aligned} \tag{18}$$

$$\begin{aligned}
\frac{\partial}{\partial y}(\sin(axyz^2)) &= \frac{\partial}{\partial y}(\sin(axyz^2)) * \frac{\partial}{\partial y}(axyz^2) \\
&= \cos(axyz^2)(xz^2)
\end{aligned} \tag{19}$$

$$\begin{aligned}
\frac{\partial}{\partial z}(\sin(axyz^2)) &= \frac{\partial}{\partial z}(\sin(axyz^2)) * \frac{\partial}{\partial z}(axyz^2) \\
&= \cos(axyz^2)(2axyz)
\end{aligned} \tag{20}$$

**5.3**  $h(x, y, z) = ae^{\frac{xy}{z^2}}$

$$\begin{aligned}
\frac{\partial}{\partial x}(ae^{\frac{xy}{z^2}}) &= a \frac{\partial}{\partial x}(e^{\frac{xy}{z^2}}) * \frac{\partial}{\partial x}(\frac{xy}{z^2}) \\
&= a(e^{\frac{xy}{z^2}})(\frac{y}{z^2})
\end{aligned} \tag{21}$$

$$\begin{aligned}
\frac{\partial}{\partial y}(ae^{\frac{xy}{z^2}}) &= a \frac{\partial}{\partial y}(e^{\frac{xy}{z^2}}) * \frac{\partial}{\partial y}(\frac{xy}{z^2}) \\
&= a(e^{\frac{xy}{z^2}})(\frac{x}{z^2})
\end{aligned} \tag{22}$$

$$\begin{aligned}
\frac{\partial}{\partial z}(ae^{\frac{xy}{z^2}}) &= a \frac{\partial}{\partial z}(e^{\frac{xy}{z^2}}) * \frac{\partial}{\partial z}(\frac{xy}{z^2}) \\
&= a(e^{\frac{xy}{z^2}})(-\frac{2xy}{z^3})
\end{aligned} \tag{23}$$

## 6 Problem 6

$$\begin{aligned}
U(r) &= k(x^2 + y^2 + z^2) \\
\vec{F} \cdot d\vec{r} &= W = -U
\end{aligned}$$

$$\begin{aligned}
\vec{F} \cdot d\vec{r} &= -U \\
\vec{F} \cdot d\vec{r} &= -[k(x^2 + y^2 + z^2)] \\
\vec{F} &= -\frac{d}{dr}k(x^2 + y^2 + z^2) \\
&= -k \frac{d}{dr}r^2 \\
&= -k2r \\
&= -2k(\sqrt{x^2 + y^2 + z^2})
\end{aligned} \tag{24}$$

## 7 Problem 7

$$\nabla \times F = 0$$

**7.1**  $F = k(x, 2y, 3z)$

$$\begin{aligned}\nabla \times F &= \left( \left[ \frac{\partial}{\partial y} k3z \right] - \left[ \frac{\partial}{\partial z} k2y \right] \right) \hat{i} + \left( \left[ \frac{\partial}{\partial z} kx \right] - \left[ \frac{\partial}{\partial x} k3z \right] \right) \hat{j} + \left( \left[ \frac{\partial}{\partial x} k2y \right] - \left[ \frac{\partial}{\partial y} kx \right] \right) \hat{k} \\ &= 0\hat{i} + 0\hat{j} + 0\hat{k} \\ &= 0\end{aligned}\tag{25}$$

F is conservative

$$\begin{aligned}U &= - \int \vec{F} \cdot d\vec{r} \\ &= - \left[ \int F_x dx + \int F_y dy + \int F_z dz \right] \\ &= - \left[ k \int x dx + 2k \int y dy + 3k \int z dz \right] \\ &= -k \left[ \left( \frac{x^2}{2} + c_1 \right) + 2 \left( \frac{y^2}{2} + c_2 \right) + 3 \left( \frac{z^2}{2} + c_3 \right) \right]\end{aligned}\tag{26}$$

Now we can verify  $F = -\nabla U$

$$\begin{aligned}F &= -\nabla U \\ &= \left[ \frac{\partial}{\partial x} \left( -\frac{kx^2}{2} - kc_1 \right) + \frac{\partial}{\partial y} \left( -\frac{2ky^2}{2} - 2kc_2 \right) + \frac{\partial}{\partial z} \left( -\frac{3kz^2}{2} - 3kc_3 \right) \right] \\ &= [kx + k2y + k3z] \\ &= k(x, 2y, 3z)\end{aligned}\tag{27}$$

**7.2**  $F = k(y, x, 0)$

$$\begin{aligned}\nabla \times F &= \left( \left[ \frac{\partial}{\partial y} 0 \right] - \left[ \frac{\partial}{\partial z} kx \right] \right) \hat{i} + \left( \left[ \frac{\partial}{\partial z} ky \right] - \left[ \frac{\partial}{\partial x} 0 \right] \right) \hat{j} + \left( \left[ \frac{\partial}{\partial x} kx \right] - \left[ \frac{\partial}{\partial y} ky \right] \right) \hat{k} \\ &= 0\hat{i} + 0\hat{j} + k[1 - 1]\hat{k} \\ &= 0\end{aligned}\tag{28}$$

F is conservative

$$\begin{aligned}U &= - \int \vec{F} \cdot d\vec{r} \\ &= - \left[ \int F_x dx + \int F_y dy + \int F_z dz \right] \\ &= - \left[ ky \int dx + kx \int dy + \int 0 dz \right] \\ &= -[ky(x + c_1) + kx(y + c_2)]\end{aligned}\tag{29}$$

Now we can verify  $F = -\nabla U$

$$\begin{aligned}
F &= -\nabla U \\
&= \left[ \frac{\partial}{\partial x}(k y x + k y c_1) + \frac{\partial}{\partial y}(k x y + k x c_2) + \frac{\partial}{\partial z}(0) \right] \\
&= -[k y + k x + 0] \\
&= k(y, x, 0)
\end{aligned} \tag{30}$$

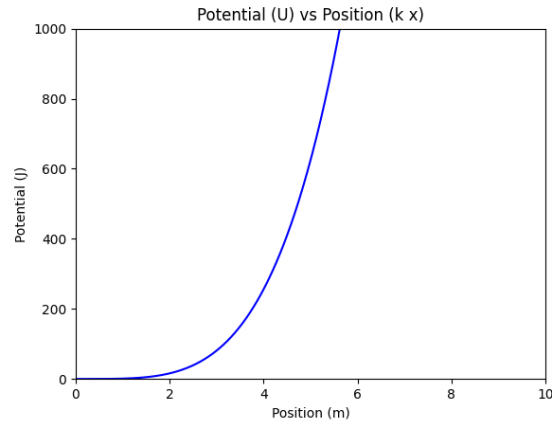
**7.3**  $F = k(-y, x, 0)$

$$\begin{aligned}
\nabla \times F &= \left( \left[ \frac{\partial}{\partial y} 0 \right] - \left[ \frac{\partial}{\partial z} x \right] \right) \hat{i} + \left( \left[ \frac{\partial}{\partial z} y \right] - \left[ \frac{\partial}{\partial x} 0 \right] \right) \hat{j} + \left( \left[ \frac{\partial}{\partial x} x \right] - \left[ -\frac{\partial}{\partial y} y \right] \right) \hat{k} \\
&= 0\hat{i} + 0\hat{j} + [1 + 1]\hat{k} \\
&= 2\hat{k}
\end{aligned} \tag{31}$$

F is not conservative

## 8 Problem 8

### 8.1



### 8.2

$$\begin{aligned}
t &= \int_{x_0}^x \frac{x'}{\dot{x}(x')} \\
&= \sqrt{\frac{m}{2}} \int_{x_0}^x \frac{dx'}{\sqrt{E - U(x')}} \\
U &= kx^4 \\
x_{max} &= A
\end{aligned}$$

At  $x_{max}$ ,  $KE = 0$  therefore  $E = U(A^4)$



$$\begin{aligned}
t_{max} &= \sqrt{\frac{m}{2}} \int_0^A \frac{dx'}{\sqrt{E - U(x')}} \\
&= \sqrt{\frac{m}{2}} \int_0^A \frac{dx'}{\sqrt{kA^4 - kx'^4}} \\
&= \sqrt{\frac{m}{2}} \int_0^A \frac{dx'}{\sqrt{k(A^4 - x'^4)}}
\end{aligned} \tag{32}$$

8.3

$$\begin{aligned}
t_{max} &= \sqrt{\frac{m}{2}} \int_0^A \frac{dx'}{\sqrt{k(A^4 - x'^4)}} \\
&= \sqrt{\frac{m}{2}} \int_0^A \frac{dx'}{\sqrt{kA^4} \sqrt{1 - \frac{x'^4}{A^4}}} \\
&= \sqrt{\frac{m}{2}} \frac{1}{\sqrt{kA^4}} \int_0^A \frac{dx'}{\sqrt{1 - \frac{x'^4}{A^4}}} \\
&= \sqrt{\frac{m}{2}} \frac{1}{A^2 \sqrt{k}} \int_0^A \frac{dx'}{\sqrt{1 - \frac{x'^4}{A^4}}}
\end{aligned} \tag{33}$$

$$y = \frac{x}{A}, \quad dy = \frac{1}{A} dx$$

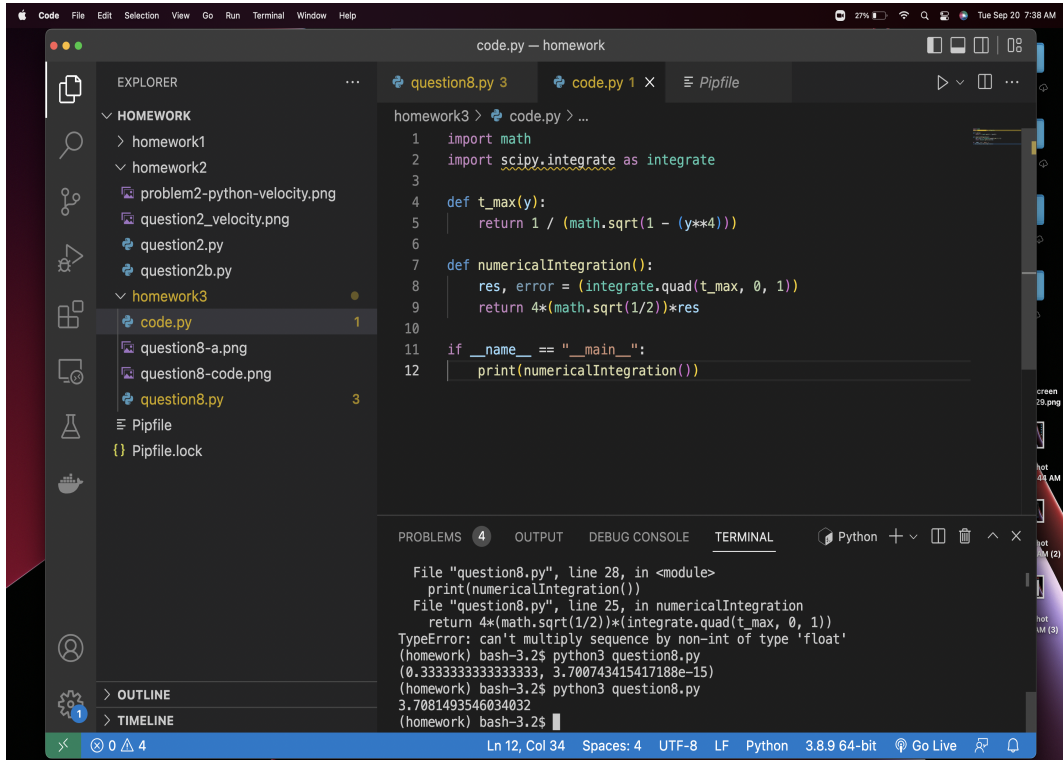
$$\begin{aligned}
&= \sqrt{\frac{m}{2}} \frac{1}{A^2 \sqrt{k}} \int_0^A \frac{1}{\sqrt{(1 - y^4)} dy} A \\
&= \sqrt{\frac{m}{2k}} \frac{1}{A} \int_0^A \frac{1}{\sqrt{(1 - y^4)} dy}
\end{aligned}$$

Multiply by 4 to get full period

$$= 4 \sqrt{\frac{m}{2k}} \frac{1}{A} \int_0^A \frac{1}{\sqrt{(1 - y^4)} dy}$$

8.4

$$\begin{aligned}
t_{max} &= 4 \sqrt{\frac{1}{2}} \int_0^1 \frac{1}{\sqrt{(1 - y^4)} dy} \\
&= 3.708s
\end{aligned} \tag{34}$$



## 9 Problem 9

$$U(\phi) = mgl(1 - \cos \phi)$$

$$4t = \tau$$

$$T = \frac{1}{2}m(l\dot{\phi})^2$$

$$\begin{aligned} E(\phi) &= U(\phi) + T(\phi) \\ &= mgl(1 - \cos \phi) + \frac{1}{2}m(l\dot{\phi})^2 \end{aligned} \quad (35)$$

Using this equation for energy we can solve for  $\dot{\phi}$  in terms of  $\phi$

$$\begin{aligned} E(\phi) &= U(\phi) + T(\phi) \\ E(\phi) &= mgl(1 - \cos \phi) + \frac{1}{2}m(l\dot{\phi})^2 \\ \frac{E(\phi)}{ml^2} - \frac{mgl(1 - \cos \phi)}{l^2} &= \dot{\phi}^2 \\ \sqrt{\frac{E(\phi)}{ml^2} - \frac{g(1 - \cos \phi)}{l}} &= \dot{\phi} \end{aligned} \quad (36)$$

Since this is a conservative system, we know there is no change in energy and therefore  $\delta E = 0$

$$\begin{aligned}
 U(\phi) &= mg(1 - \cos \phi) \\
 \frac{U}{mg} &= (1 - \cos \phi) \\
 \phi &= \cos^{-1} \left( 1 - \frac{U}{mg} \right)
 \end{aligned} \tag{37}$$

$$\begin{aligned}
 U(\phi) &= KE \\
 mgl(1 - \cos \phi) &= \frac{1}{2}m(l\dot{\phi})^2 \\
 2g(1 - \cos \phi) &= \dot{\phi}^2 \\
 \dot{\phi} &= \sqrt{2g(1 - \cos \phi)}
 \end{aligned} \tag{38}$$

$$t = \int_0^{\Phi} \frac{d\phi}{\sqrt{2g(1 - \cos \phi)}} \tag{39}$$

## 10 Problem 10

### 10.1

$$\begin{aligned}
 \tau &= \tau_0 = 2\pi\sqrt{\frac{l}{g}} \\
 \tau &= \frac{2}{\pi} \int_0^1 \frac{du}{\sqrt{1 - u^2}} \\
 &= \tau_0 \frac{2}{\pi} * \left( \frac{\pi}{2} \right) \\
 \tau &= \tau_0
 \end{aligned} \tag{40}$$

$$\begin{aligned}
 \tau &= \tau_0 \frac{2}{\pi} \int_0^1 \frac{1}{\sqrt{1 - u^2}} \left( 1 + \frac{1}{2}A^2u^2 \right) du \\
 &= \tau_0 \left[ 1 + \frac{1}{4} \sin^2 \left( \frac{\Phi}{2} \right) \right]
 \end{aligned} \tag{41}$$