

Phys273 - Homework 3

Dillon Walton

October 8, 2022

1 Part a

$$\vec{F} = m\ddot{x}$$

$$m\ddot{x}_1 = -k(x_1 - x_2) \tag{1}$$

$$m\ddot{x}_2 = -k(x_2 - x_1) - k(x_2 - x_3) \tag{2}$$

$$m\ddot{x}_3 = -k(x_3 - x_2) \tag{3}$$

2 Part b

Assume solution of:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} e^{i\omega t}$$

2.1 Equations for x_1

$$x_1 = A_1 e^{i\omega t}$$

$$\dot{x}_1 = i\omega A_1 e^{i\omega t}$$

$$\ddot{x}_1 = -\omega^2 A_1 e^{i\omega t}$$

$$-m\omega^2 A_1 = -k(A_1 - A_2)$$

$$-m\omega^2 A_1 + k(A_1 - A_2) = 0$$

$$-m\omega^2 A_1 + kA_1 - kA_2 = 0$$

$$(-m\omega^2 + k)A_1 - kA_2 = 0$$

2.2 Equations for x_2

$$x_2 = A_2 e^{i\omega t}$$

$$\dot{x}_2 = i\omega A_2 e^{i\omega t}$$

$$\ddot{x}_2 = -\omega^2 A_2 e^{i\omega t}$$

$$-m\omega^2 A_2 = -k(A_2 - A_1) - k(A_2 - A_3)$$

$$-m\omega^2 A_2 + k(A_2 - A_1) + k(A_2 - A_3) = 0$$

$$(-m\omega^2 + 2k)A_2 - kA_1 - kA_3 = 0$$

2.3 Equations for x_3

$$\begin{aligned}x_3 &= A_3 e^{i\omega t} \\ \dot{x}_3 &= i\omega A_3 e^{i\omega t} \\ \ddot{x}_3 &= -\omega^2 A_3 e^{i\omega t}\end{aligned}$$

$$\begin{aligned}-m\omega^2 A_3 &= -k(A_3 - A_2) \\ (-m\omega^2 + k)A_3 - kA_2 &= 0\end{aligned}$$

2.4 Final Equations

$$(-m\omega^2 + k)A_1 - kA_2 = 0 \quad (4)$$

$$-kA_1 + (-m\omega^2 + 2k)A_2 - kA_3 = 0 \quad (5)$$

$$-kA_2 + (-m\omega^2 + k)A_3 = 0 \quad (6)$$

2.5 Matrix

$$\begin{bmatrix} (-\omega^2 + \omega_0^2) & -\omega_0^2 & 0 \\ -\omega_0^2 & (-\omega^2 + 2\omega_0^2) & -\omega_0^2 \\ 0 & -\omega_0^2 & (-\omega^2 + \omega_0^2) \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (7)$$

3 Part c

$$\begin{vmatrix} (-\omega^2 + \omega_0^2) & -\omega_0^2 & 0 \\ -\omega_0^2 & (-\omega^2 + 2\omega_0^2) & -\omega_0^2 \\ 0 & -\omega_0^2 & (-\omega^2 + \omega_0^2) \end{vmatrix} = 0 \quad (8)$$

3.1 Determinant

$$\left((-\omega^2 + \omega_0^2) \left[(-\omega^2 + 2\omega_0^2)(-\omega^2 + \omega_0^2) - ((-\omega_0^2)(-\omega_0^2)) \right] \right) - ((-\omega_0^2)(-\omega^2 + \omega_0^2)) + 0 = 0 \quad (9)$$

$$\left[(-\omega^2 + \omega_0^2)(\omega^4 - 3\omega^2\omega_0^2 + \omega_0^4) \right] - (\omega_0^4\omega^2) - \omega_0^6 = 0 \quad (10)$$

$$-\omega^6 - 3\omega^2\omega_0^4 + 4\omega^4\omega_0^2 = 0 \quad (11)$$

$$(\omega^2 - 3\omega_0^2)(\omega^2 - \omega_0^2) = 0 \quad (12)$$

3.2 Normal mode frequencies

$$\omega = \pm\sqrt{3}\omega_0 \quad (13)$$

$$\omega = \pm\omega_0 \quad (14)$$

$$\omega = 0 \quad (15)$$

4 Part d

4.1 $\omega = 0$

$$\begin{bmatrix} (\omega_0^2) & -\omega_0^2 & 0 \\ -\omega_0^2 & (2\omega_0^2) & -\omega_0^2 \\ 0 & -\omega_0^2 & (\omega_0^2) \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (16)$$

$$\begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad (17)$$

4.2 $\omega = \pm\omega_0$

$$\begin{bmatrix} (-\omega_0^2 + \omega_0^2) & -\omega_0^2 & 0 \\ -\omega_0^2 & (-\omega_0^2 + 2\omega_0^2) & -\omega_0^2 \\ 0 & -\omega_0^2 & (-\omega_0^2 + \omega_0^2) \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (18)$$

$$\begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \quad (19)$$

4.3 $\omega = \pm\sqrt{3}\omega_0$

$$\begin{bmatrix} (-3\omega_0^2 + \omega_0^2) & -\omega_0^2 & 0 \\ -\omega_0^2 & (-3\omega_0^2 + 2\omega_0^2) & -\omega_0^2 \\ 0 & -\omega_0^2 & (-3\omega_0^2 + \omega_0^2) \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (20)$$

$$\begin{bmatrix} A_1 \\ A_2 \\ A_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \quad (21)$$

4.4 General Solution

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = A_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cos(\phi_1) + A_2 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \cos(\omega_0 t + \phi_2) + A_3 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cos(\sqrt{3}\omega_0 t + \phi_3) \quad (22)$$