

# TP 1 Inverse Problem

## Gibbs Sampler

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## 1 Introduction

The objective is to find the sparse signal  $s \in \mathbb{R}^D$  from the observations  $x \in \mathbb{R}^N$  with the following model of added Gaussian noise.  $A \in \mathbb{R}^{N \times D}$  ( $N \ll D$ ).

$$x = As + n$$

To impose sparsity we define  $s$  as a Bernoulli-Gaussian using the binary sequence  $q = [q_1 \dots q_D]^T$  and  $L = \sum_{d=1}^D q_d$ . Thus, the amplitudes  $s_i$  are assumed iid zero-mean Gaussians as:

$$s|q \sim N(0, \sigma_s^2 \text{diag}(q))$$

$$P(q) = \lambda^L (1 - \lambda)^{D-L}$$

We then look to estimate  $\Theta = s, q, \lambda, \sigma_n^2, \sigma_s^2$  from the observations  $x$  with  $\lambda$  following a Beta distribution.

According to the Monte Carlo principle we can estimate  $\Theta$  as seen below, so that the samples converge asymptotically to the probability given below.

$$\hat{\Theta} = \frac{1}{I - J} \sum_{k=J+1}^I \Theta_k$$

$$P(\Theta|x) \propto g(x - As, \sigma_n^2 I_N) P(q, \lambda) g(s, \sigma_s^2 \text{diag}(q)) P(\sigma_n^2) P(\sigma_s^2) P(\lambda)^1 \quad (1)$$

<sup>1</sup>Here  $g(\mu, R)$  is the Gaussian distribution

## 2 Algorithm implementation

### 2.1 Conditional probability

We aim to find the conditional probabilities needed in the Gibbs sampler. Firstly, (1) is derived from the assumptions,

$$P(\Theta|x) \propto \frac{1}{(2\pi\sigma_n^2)^{N/2}} \exp[-\frac{1}{2\sigma_n^2}||x-As||^2] \lambda^{\sum q_d} (1-\lambda)^{D-\sum q_d} \frac{1}{((2\pi)^D |\sigma_s^2 \text{diag}(q)|)^{1/2}} \exp[-\frac{1}{2\sigma_s^2} s^T \text{diag}(q) s] \quad (2)$$

Then, to find the probability of  $q_d$  we consider that it can only take the values 0, 1 and we take the joint probability with  $s_d$ . Given that  $s_d|_{q_d=0} = 0$  we can write the distribution as a Dirac  $\delta(s_d)$ . That way, integrating over  $s_d$  becomes trivial. This yield the expression for  $q_d$  conditioned to  $\Theta \setminus \{q_d, s_d\}$  and the observations.

$$P(q_d = 0, s_d|x, \Theta \setminus \{q_d, s_d\}) \propto (1-\lambda) \exp[\frac{-1}{2\sigma_n^2} ||x-As||^2] \delta(s_d)$$

$$P(q_d = 0|x, \Theta \setminus \{q_d, s_d\}) \propto (1-\lambda) \exp[\frac{-1}{2\sigma_n^2} ||x-A_{-d}s_{-d}||^2]$$

We note the matrix  $A_{-m}$  as the matrix without the m-th column. For  $q_d = 1$  we get that the conditioned probability  $s_d|_{q_d=1}$  is equal to a centred normal with variance  $\sigma_s^2$ .

$$P(q_d = 1, s_d|x, \Theta \setminus \{q_d, s_d\}) \propto \lambda \exp[\frac{-1}{2\sigma_n^2} ||x-As||^2] \frac{1}{(2\pi\sigma_s^2)^{1/2}} \exp[-\frac{s_d^2}{2\sigma_s^2}]$$

We can then marginalize this probability, given that  $s_d \sim N(\mu_d, \sigma_d^2)$ ,

$$P(q_d = 1|x, \Theta \setminus \{q_d, s_d\}) \propto \lambda \exp[\frac{-1}{2\sigma_n^2} ||x-A_{-d}s_{-d}||^2] \frac{\sigma_n}{\sigma_s^2} \exp[-\frac{\mu_d^2}{2\sigma_d^2}]$$

With  $\mu_d = \frac{\sigma_d^2}{\sigma_n^2} A_n^T (x - A_{-d}s_{-d})$  and  $\sigma_d^2 = \frac{\sigma_n^2 \sigma_s^2}{\sigma_n^2 + \sigma_s^2 ||A_n||^2}$ .

Then, if we define  $\gamma_d = \lambda \frac{\sigma_n}{\sigma_s^2} \exp[-\frac{\mu_d^2}{2\sigma_d^2}]$  we find that the conditional probability of  $q$  follows the Bernoulli distribution.

$$q_n | \Theta \setminus \{q_d, s_q\}, x \sim B(\frac{\gamma_d}{\gamma_d + 1 - \lambda})$$

As said before,  $s_d$  is equal to 0 if  $q_d = 0$  or it follows a Normal distribution, thus we have the probability,

$$s_d | \Theta \setminus \{s_q\}, x : \begin{cases} 0 & \text{if } q_d = 0 \\ N(\mu_d, \sigma_d^2) & \text{if } q_d = 1 \end{cases}$$

In the case of  $\lambda$ , we observe from the definition that it comes a Beta distribution whose parameters depend on L and D.

$$\lambda | \Theta \setminus \{\lambda\}, x \propto \lambda^{\sum q_d} (1-\lambda)^{D-\sum q_d}$$

$$\lambda | \Theta \setminus \{\lambda\}, x \sim \text{Beta}(1+L, 1+D-L)$$

## 2.2 Algorithm

The algorithm was implemented in Matlab following the given pseudocode. The implementation is in Annex I.

## 3 Results

### 3.1 Data

The results are based on the active dipoles problem, where the vector  $s$  represents the sources from all points and  $x$  the measured points in the brain. The objective is to find the correct source configuration for an epileptic strike. In all cases 100 iterations of the algorithm are performed. For this problem we have  $N = 91$  and  $D = 19626$ .

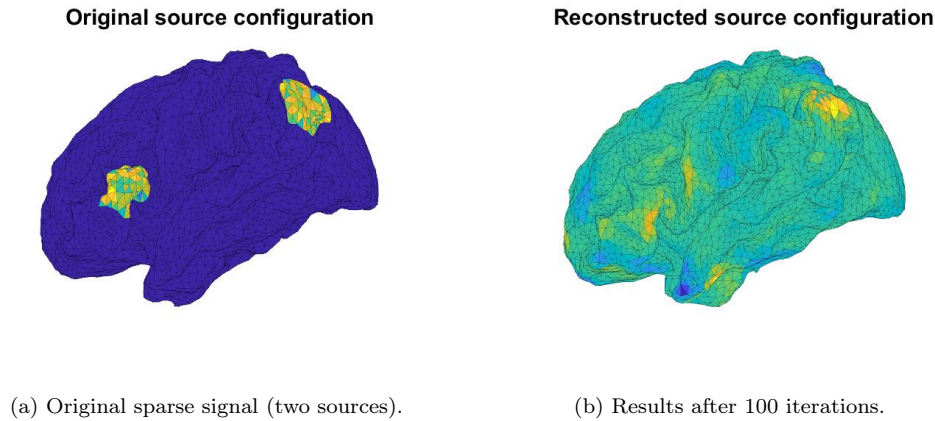


Figure 1: Results obtained for SNR=1.

We observe that the solution is good, since the solution is sparse and concentrates most of its energy around the sources. Notably, the algorithm took a long time to execute, this is most likely due to one of the dimensions being so large.

### 3.2 SNR variation

Now the SNR is changed from 0.1 to 10 in order to see the effects on the results. We observe from the following figure that when the noise is high (low SNR) the result is less sparse and more noisy. As the SNR goes up we get a solution that approaches the real problem sources. As expected, we see most of the energy of the signal around the two sources.

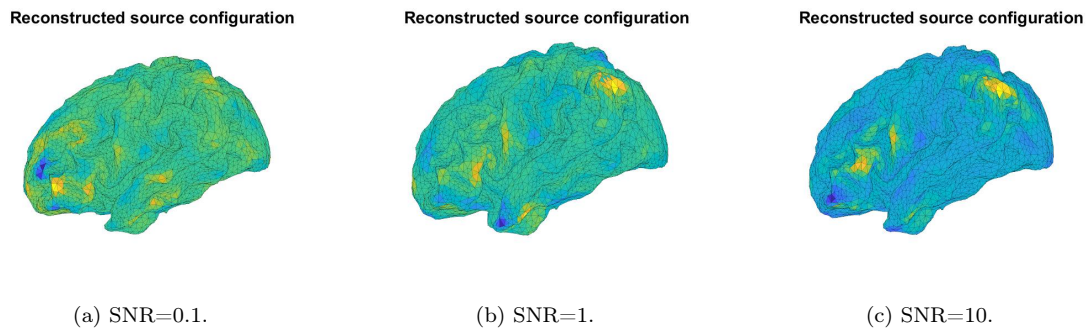


Figure 2: Results for different values of SNR.

## 4 Conclusion

The Gibbs sampling algorithm, which works by making hypothesis on the data to ensure an sparse solution was analyzed and implemented in Matlab. A practical example was shown in the case of a brain signal for an epileptic strike. We observe that when the SNR is not too small (bigger than 1), the results are quite close and both sources are found. Also, the execution times are quite long.

## 5 Annex I. Code

```

1  function [SOut,LambdaOut]=Gibbs_sampler(X,A,sigma2)
2
3  %number of iterations
4  Niter=100;
5  Nsearch = Niter/2;
6
7  %get number of sensors and number of dipoles
8  [N,D]=size(A);
9
10 % constants
11 nA = sum(A.^2,1);
12
13 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
14 % implement the Gibbs sampler here according to the pseudocode
15 % store vectors q and s of each iteration in matrices Q and S (D x niter)
16 % use variables sigma_n2 and sigma_s2 for the variances of noise and s
17 Q = zeros(D,Niter);
18 S = zeros(D,Niter);
19 lambda = betarnd(1,1);
20 sigma_n2 = sigma2;
21 sigma_s2 = sigma2;
22 for k = 1:Niter
23     fprintf('Iteration: %d \n',k);
24     e = X - A * S(:,k);
25     for i = 1:D
26         e_i = e + A(:,i)*S(i,k);
27         sigma_i2 = sigma_n2 * sigma_s2 / (sigma_n2 + sigma_s2 * nA(i));
28         mu_i = (sigma_i2 / sigma_n2) * A(:,i)' * e_i;
29         v_i = lambda * sqrt(sigma_i2 / sigma_s2) * exp(mu_i^2 / (2*sigma_i2));
30         if v_i > 1e10
31             lambda_i = 1;
32         else
33             lambda_i = v_i / (v_i + 1 - lambda);
34         end
35         Q(i,k) = binornd(1,lambda_i, 1, 1);
36         S(i,k) = Q(i,k) .* normrnd(mu_i, sqrt(sigma_i2)); %((randn(1,1) * sqrt(
37             sigma_i2) + mu_i));
38         e = e_i - A(:,i)*S(i,k);
39     end
40     L = sum(Q(:,k));
41     lambda = betarnd(1+L,1+D-L);
42 end
43 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
44 % Make the estimation from Q and S using the MAP criterium
45 %Q(:,Niter/2:Niter)
46 cout = zeros(Nsearch,1);
47 for j = 1:Nsearch
48     q = Q(:,Niter-Nsearch+j);
49     idx = find(q==1);

```

```
50     R = (A(:,idx)'*A(:,idx))/sigma_n2 + eye(length(idx))/sigma_s2;
51     S_opt = (R\ (A(:,idx)'*X))/sigma_n2;
52     cout(j) = - S_opt'*R*S_opt/sigma_n2;
53 end
54
55 [~, OptIdx] = min(cout);
56 q = Q(:,Niter/2+OptIdx);
57 idx = find(q==1);
58 R = (A(:,idx)'*A(:,idx))/sigma_n2 + eye(length(idx))/sigma_s2;
59 SOut = zeros(D,1);
60 SOut(idx) = (R\ (A(:,idx)'*X))/sigma_n2;
61 LambdaOut = length(idx)/D;
```