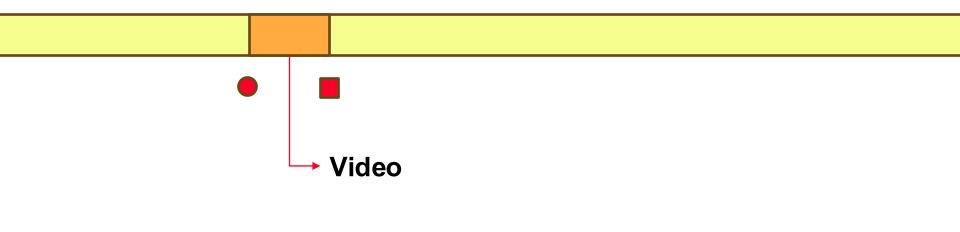


# **Beyond Long Video Understanding**

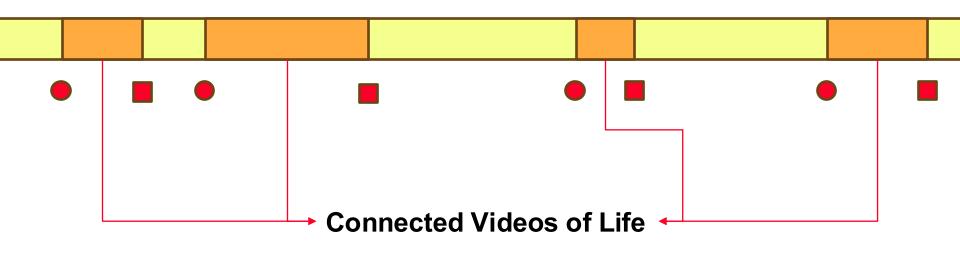


# Previous Video Understanding...





# Upcoming Video Understanding...





# Eventually...

- No current model has the context required for this ...
- Impossible to store and process this influx of data ... But....
- Immense potential ...



#### In this talk...



**Unique Captioning** 



Visual Instruction



Learning from Continuous Street



Out of Sight, Not Out of Mind



HD-EPIC: A Highly-Detailed Egocentric Video Dataset



#### In this talk...



**Unique Captioning** 



**Visual Instructions** 



Learning from Continuous Streams



Out of Sight, Not Out of Mind



HD-EPIC: A Highly-Detailed Egocentric Video Dataset



# It's Just Another Day: Unique Video Captioning by Discriminative Prompting

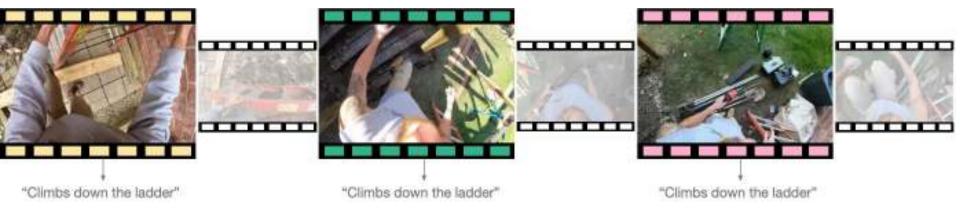
Toby Perrett, Tengda Han, Dima Damen, Andrew Zisserman





Life is repetitive...





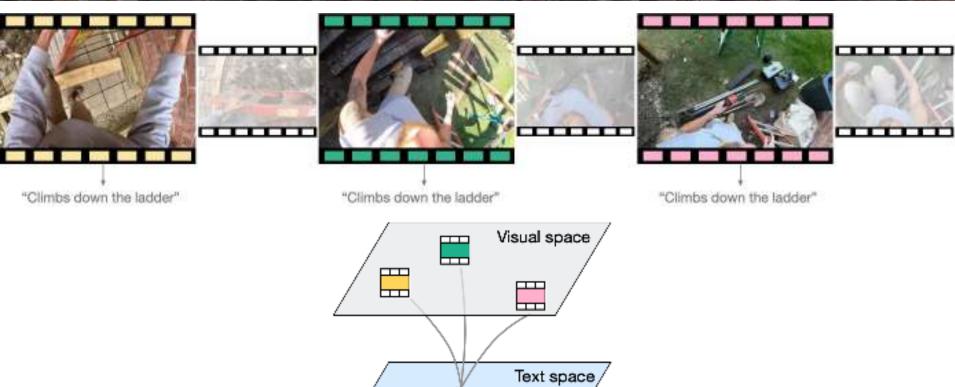
- Current methods caption clips independently
- They generate the same caption for similar clips

#### Goal:

Generate a unique caption for every clip in a set



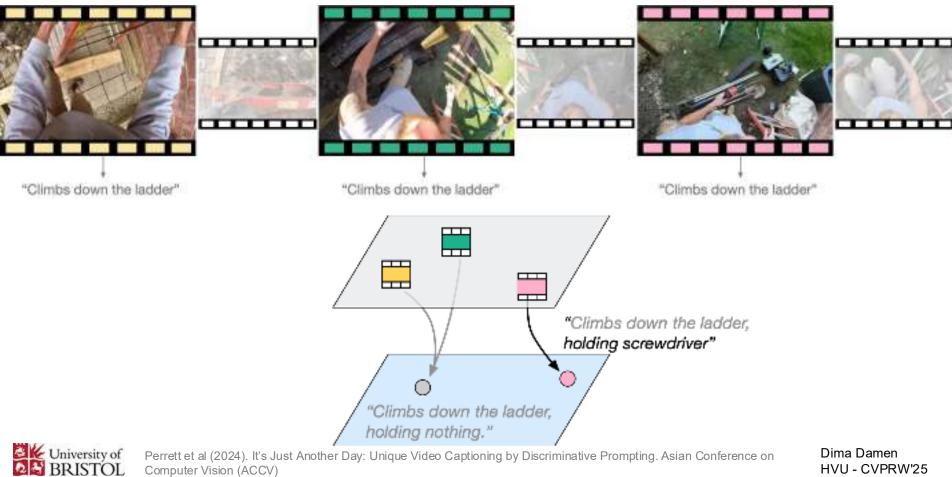
# Unique Video Captioning





Perrett et al (2024). It's Just Another Day: Unique Video Captioning by Discriminative Prompting. Asian Conference on Computer Vision (ACCV)

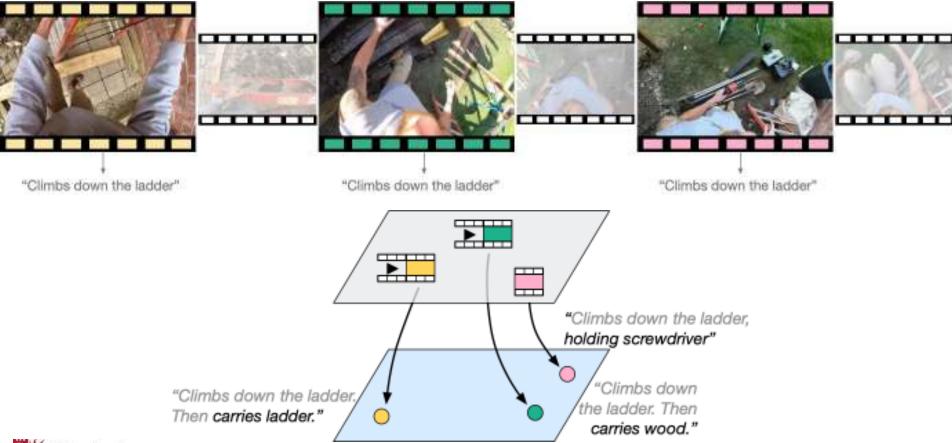
"Climbs down the ladder"



Perrett et al (2024). It's Just Another Day: Unique Video Captioning by Discriminative Prompting. Asian Conference on Computer Vision (ACCV)

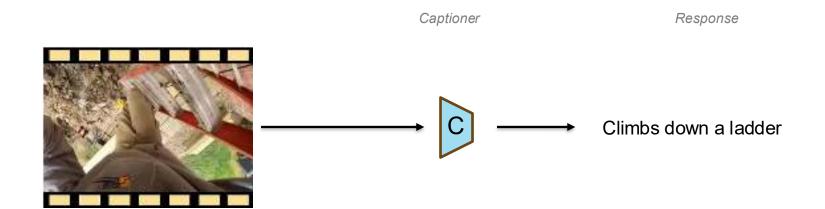
# Unique Video Captioning





University of BRISTOL

Perrett et al (2024). It's Just Another Day: Unique Video Captioning by Discriminative Prompting. Asian Conference on Computer Vision (ACCV)





Discriminative prompt

Captioner

Response

#### The person walks around





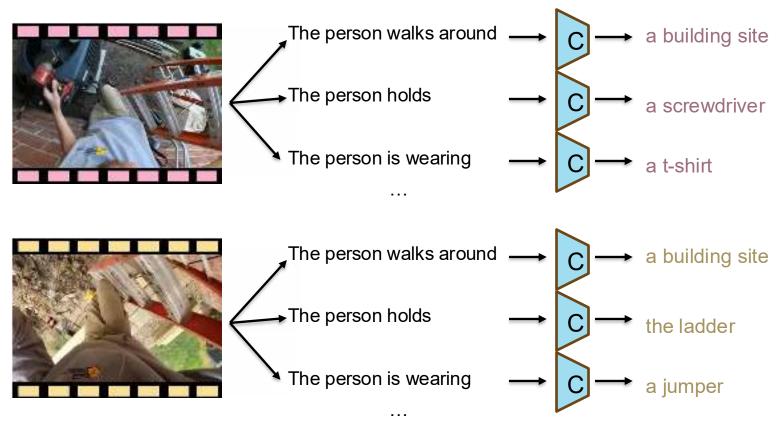
Climbs down a ladder and walks around

a building site.

# Captioning by Discriminative Prompting

Discriminative prompts

Responses

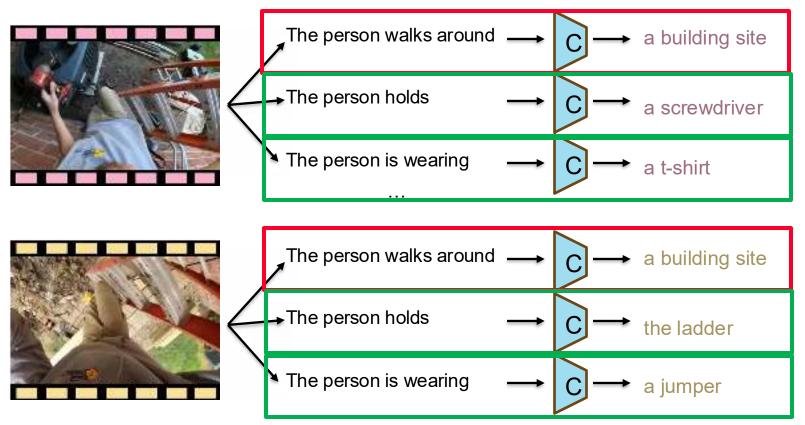




# Captioning by Discriminative Prompting

Discriminative prompts

Responses





Dima Damen

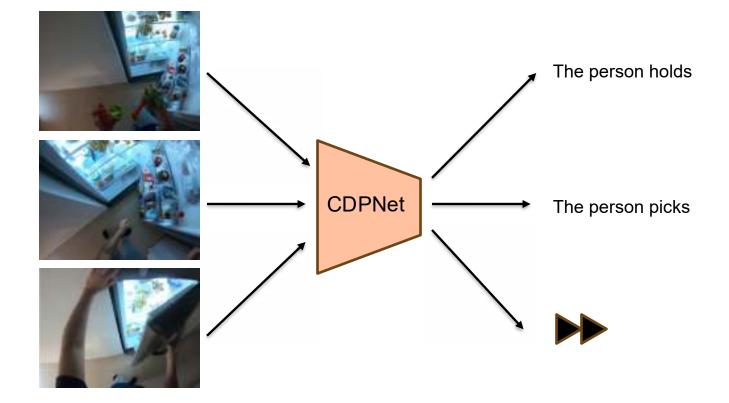
HVU - CVPRW'25

We propose to...
consider clips jointly
use a bank of discriminative prompts

But...
Expensive £££
What if there isn't a suitable prompt?



# Captioning by Discriminative Prompting

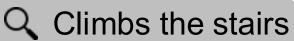




#### Average recall @ 1

Egocentric	+0s
LaViLa	37
LaViLa + CDP	45







#### Q Climbs the stairs







Climbs the stairs and

holds the phone

Climbs the stairs and

picks up the drill

Climbs the stairs and

holds a tape measure



Looks around the shelves



Dima Damen

HVU - CVPRW'25

#### Q Looks around the shelves





Looks around the shelves and



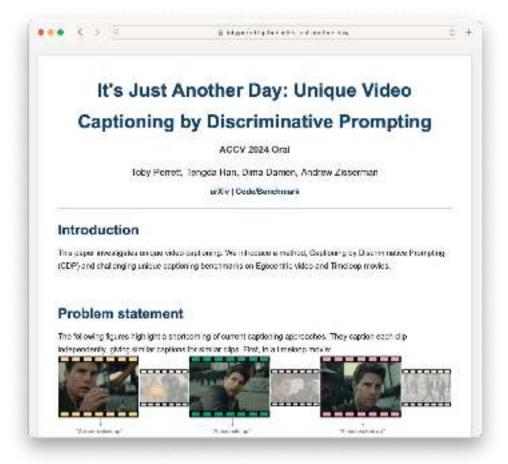
Looks around the shelves and the other man picks up a packet of biscuits from the shelf with his left hand

looks at the list

then picks up a packet of cough rubs

Looks around the shelves and

# Unique Video Captioning





#### In this talk...



**Unique Captioning** 



**Visual Instructions** 



Learning from Continuous Streams



Out of Sight, Not Out of Mind



HD-EPIC: A Highly-Detailed Egocentric Video Dataset



# Learning from a continuous video stream

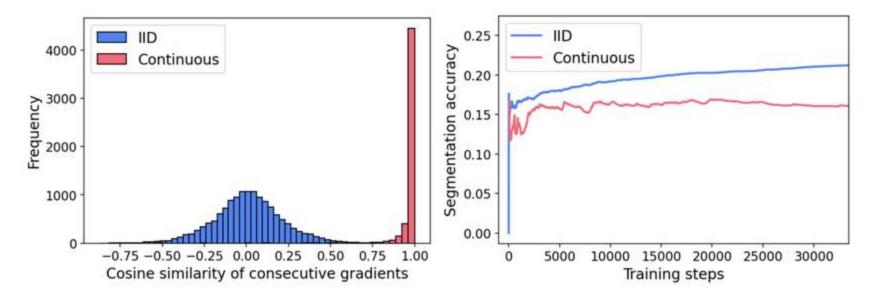


#### Current learning paradigms...





#### Current learning paradigms...





#### This year...

#### **Learning from Streaming Video with Orthogonal Gradients**

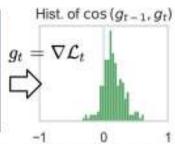
Tengda Han°, Dilara Gokay°, Joseph Heyward°, Chuhan Zhang° Daniel Zoran°, Viorica Pătrăucean°, João Carreira°, Dima Damen°<sup>†</sup>, Andrew Zisserman°<sup>‡</sup> °Google DeepMind, <sup>†</sup>University of Bristol, <sup>‡</sup>University of Oxford







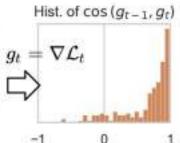




gradients are almost not correlated over training steps



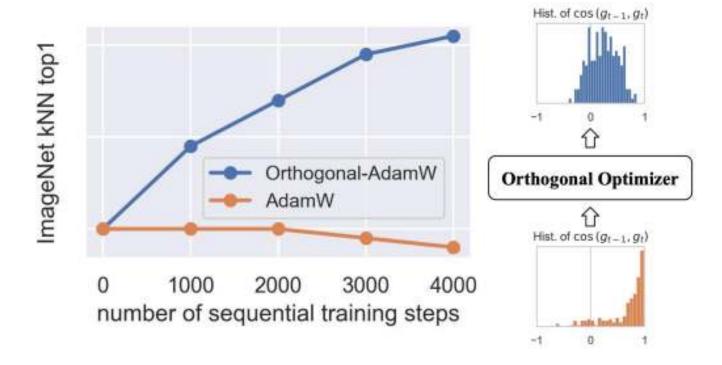




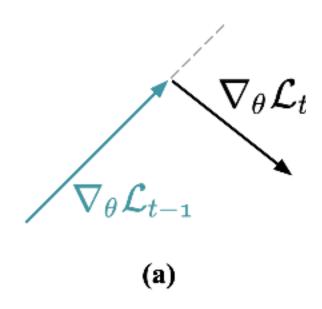
gradients are highly correlated over training steps



Han et al (2025). Learning from Streaming Video with Orthogonal Gradients. IEEE/CVF Computer Vision and Pattern Recognition (CVPR)









Algorithm 2	AdamW	
Require: Learn	ning rate $\eta > 0$ , weight decay coeffici	ieni
$\lambda > 0$ , deca	ay rates $\beta_1, \beta_2 \in [0, 1)$ , small const	tant
$\epsilon > 0$ , initial	d parameters $ heta_0$ , number of iterations $T$	
	st moment vector $m_0 = 0$ , nent vector $v_0 = 0$	and
2: <b>for</b> $t = 1$ to	T do	
<ol> <li>Sample a</li> </ol>	a mini-batch of data $\mathcal{B}_t$ from the training	sci
4: Compute	e the gradient: $q_t =  abla_{\theta} \mathcal{L}(\theta_{t-1}; \mathcal{B}_t)$	
8: Update $\beta_1 m_{t-1} + ($	biased first moment estimate: $m_1 = (1 - \beta_1)q_2$	=
	biased second moment estimate: $v_{\rm F}$	
		=
		=
$\beta_2 v_{t-1} + (1$	$(1-\beta_2)g_1^2$	
$eta_2v_{t-1}+ig(1 \  ext{Compute}$		
$eta_2v_{t-1}+ig(1 \  ext{Compute}$	$(1-\beta_2)g_1^2$ is bias-corrected first moment: $\hat{m}_t = rac{m}{1-\beta}$	
$\beta_2 v_{1-1} + (1$ 10: Compute $\frac{n_1}{1-\beta_2^2}$	$(1 - \beta_2)g_1^2$ is bias-corrected first moment: $\hat{m}_{t_0} = \frac{m}{1-\epsilon}$ bias-corrected second moment: $\hat{v}_t$	
$\beta_2 v_{1-1} + (1) = 0$ 10: Compute $\frac{v_1}{1-\beta_2^2}$ 12: Apply w	$(1-\beta_2)g_1^2$ is bias-corrected first moment: $\hat{m}_t = rac{m}{1-\beta}$	

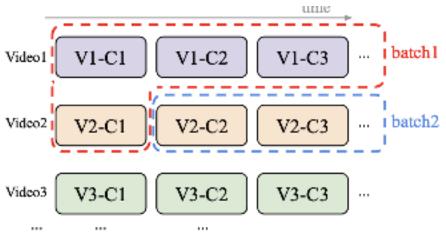


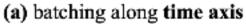
initialization	pretraining dataset: WT <sub>venice</sub>		downstream ImageNet	
	pretraining method	optimizer	linear probe top1	kNN top1
DINO <sub>ImageNet</sub>	S	(A)	-	74.4
DINO <sub>ImageNet</sub>	DoRA sequential (batch-along-time)	AdamW	6.1	1.8
DINO <sub>ImageNet</sub>	DoRA sequential (batch-along-time)	Orthogonal-AdamW	64.5	51.8

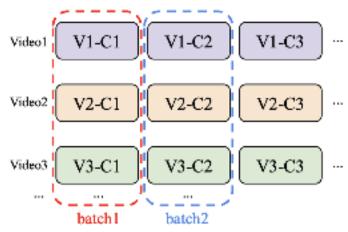
Venkataramanan et al (2024). Is ImageNet worth 1 video? learning strong image encoders from 1 long unlabelled video. ICLR



### Learning from Streaming Videos with Orthogonal Gradients



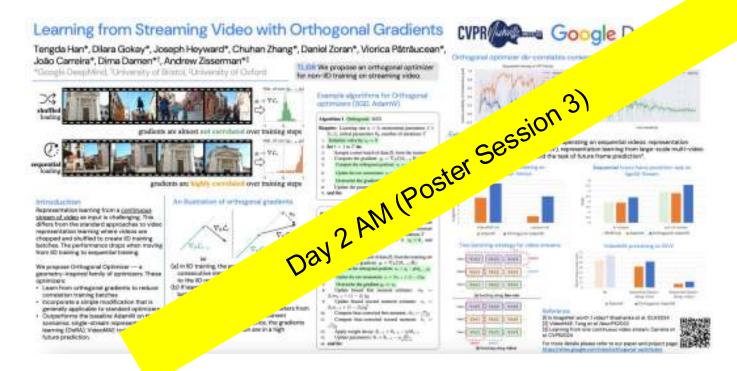




(b) batching along videos



## Learning from Streaming Videos with Orthogonal Gradients





Han et al (2025). Learning from Streaming Video with Orthogonal Gradients. IEEE/CVF Computer Vision and Pattern Recognition (CVPR)

# In this talk...



**Unique Captioning** 



Visual Instructions



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Out of Sight, Not Out of Mind



HD-EPIC: A Highly-Detailed Egocentric Video Dataset



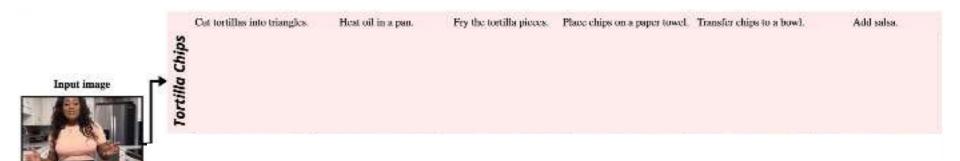


# ShowHowTo: Generating Scene-Conditioned Step-by-Step Visual Instructions

Tomáš Souček<sup>1</sup> Prajwal Gatti<sup>2</sup> Michael Wray<sup>2</sup> Ivan Laptev<sup>3</sup> Dima Damen<sup>2</sup> Josef Sivic<sup>1</sup>

<sup>1</sup>CIIRC CTU <sup>2</sup>University of Bristol <sup>3</sup>MBZUAI

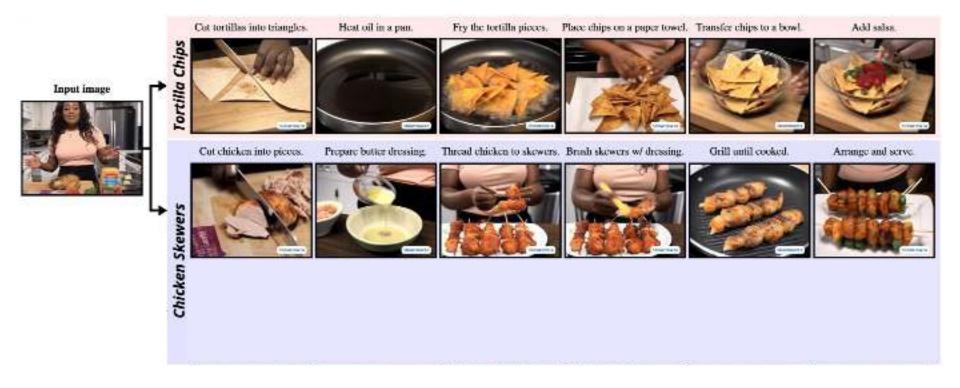














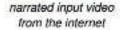






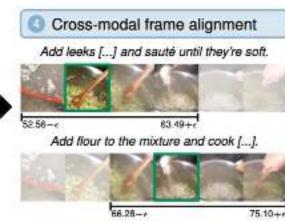












Processing 1M instructional videos in HowTo100M leads to...

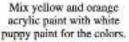
- ➤ A large-scale dataset (578K sequences, 4.5M steps)
- Task diversity (25K+ HowTo tasks)
- Ability to scale further (no manual annotation required)



Cut a piece of foam into a triangle shape to resemble a candy corn.

 Round off the rough edges of the foam triangle.

Paint the whole sponge with white puppy paint.



Paint the colors onto the sponge in the order of white, orange, and yellow.

Optional: Paint a cute face onto the squishy for extra kawaii-ness.









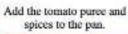




Heat olive oil in a pan and add coarsely pounded ginger and garlic.



Saute the onions until





Add the cashew paste and salt to the pan.



Add the boiled eggs and adjust the consistency of the curry.



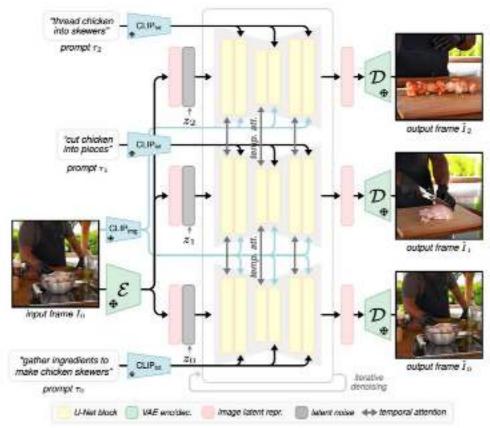
Simmer the curry for 5-10 minutes until all the flavors get into the eggs.

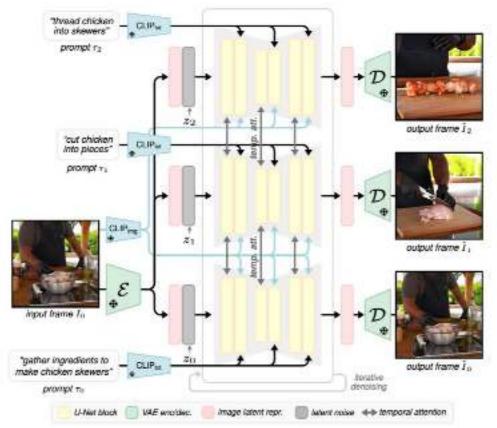


Garnish the curry with fresh coriander leaves.

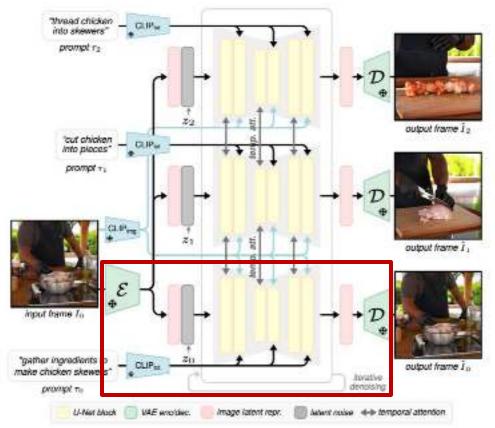




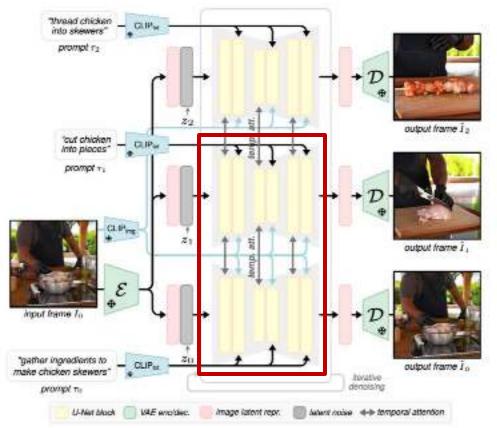




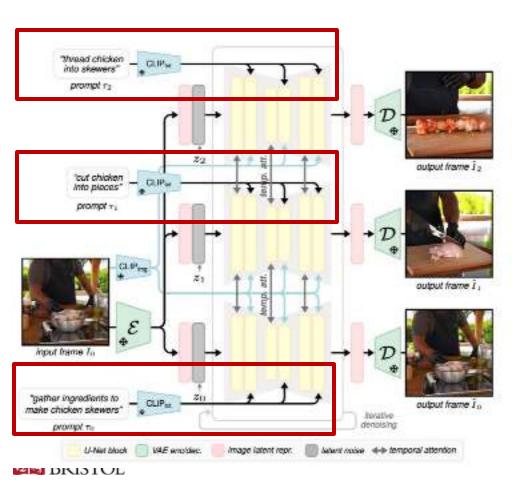
Benefits from a pretrained video generation model (DynamiCrafter)



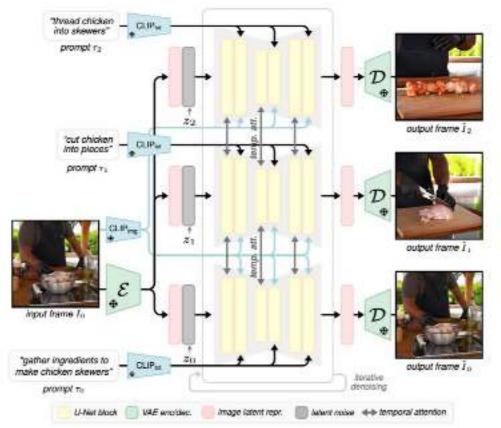
Benefits from a pretrained video generation model (DynamiCrafter)



Benefits from a pretrained video generation model (DynamiCrafter)



- Benefits from a pretrained video generation model (DynamiCrafter)
- Per-frame text conditioning



- Benefits from a pretrained video generation model (DynamiCrafter)
- Per-frame text conditioning
- Handles variable sequence-length generations

	Method	Step Faithf.	Scene Consist.	Task Faithf.	Overal
(a)	InstructPix2Pix [12]	0.25	0.17	0.25	0.22
(b)	AURORA [35]	0.25	0.33	0.24	0.27
(c)	GenHowTo [53]	0.49	0.13	0.27	0.29
(d)	Phung et al. [45]	0.36	0.03	0.38	0.26
	StackedDiffusion [41]	0.43	0.02	0.42	0.29
(f)	ShowHowTo	0.52	0.34	0.42	0.43
(g)	Random	0.19	0.00	0.01	0.07
(h)	Stable Diffusion [48]	0.70	0.03	0.44	0.39
	Copy of the input image	0.19	0.62	0.39	0.40
(i)	Source sequences	0.50	1.00	0.56	0.69

	Step w	vin rate	Scene	win rate	Task w	in rate	
	97%	3%	82%	18%	90%	10%	InstructPix2Pix
lowTo	92%	8%	68%	32%	96%	4%	AURORA
	86%	14%	77%	23%	85%	15%	GenHowTo
N/	84%	16%	91%	9%	78%	22%	Phung et al.
Shov	63%	37%	84%	16%	65%	35%	StackedDiffusion
	42%	58%	42%	58%	33%	67%	Source Sequences







Plant the cuttings in the

Input image



Wipe the humper clean, taking off the dead bugs and other debris.

Choose the size of the



Do not buff or sarub hard, as the product is designed to make chaning easy.

Hung the jersey in the

shadow box using straight



Input image

Apply a few drops of vagatable oil to the pen-



Wipe out the inside of the pun with the vegetable oil until it's shiny.

Prepare a pot of compost



Dry the pan over a moderate flame.



Input image your fireplace [...]



Light the kindling and let the fire grow.



Input image



Take the medium-sized

Leave a gap at the case of the paper, about a fourth of an inch.



Fold the paper over to create a butterfly shape:











Soucek et al (2025). ShowHowTo: Generating Scene-Conditioned Step-by-Step Visual Instructions. IEEE/CVF Computer Vision and Pattern Recognition (CVPR)

Input image



Gradually add flour until Add salt and mix well. a soft dough forms.



Knead the dough for 5 minutes.



Let the dough rise for 30 minutes.



Roll out the dough to 15 inches long and half an inch thick.



Cut off a slice of dough and roll it out to 15 in long and 0.5 in thick.



Make a pretzel shape by folding the dough and pinching the ends.



Dip the pretzel in a solution and then place it on a greased baking sheet.



Repeat the process until all dough is used up.



Bake the pretzels for 7-8 minutes or until soft and not hard on the bottom.



Serve the pretzels warm or at room temperature.



continuation of the top row

University of BRISTOL

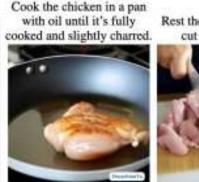




Scrape excess material off the cylinder head using a razor blade and scraper.



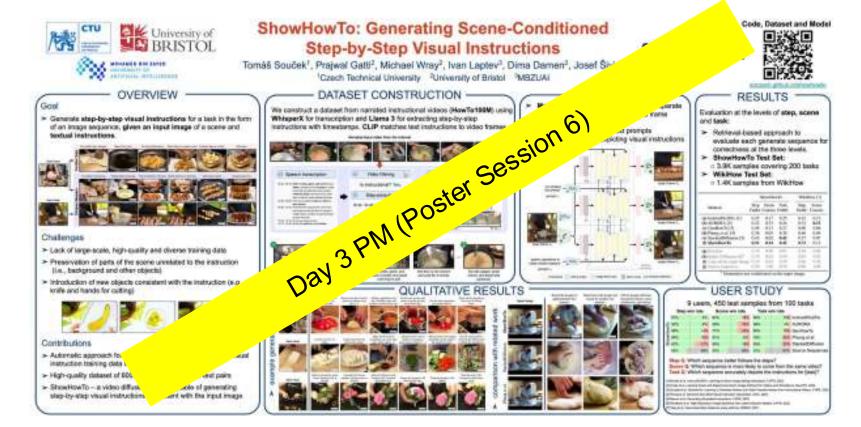






Can struggle with rare objects or tools

Can fail to update object states E.g., Raw → Cooked → Raw





# In this talk...



**Unique Captioning** 



**Visual Instructions** 



Learning from Continuous Streams



Out of Sight, Not Out of Mind



HD-EPIC: A Highly-Detailed Egocentric Video Dataset





## Spatial Cognition from Egocentric Video:

# Out of Sight, Not Out of Mind

Chiara Plizzari S

Shubham Goel

Toby Perrett

Jacob Chalk

Angjoo Kanazawa

Dima Damen

http://dimadamen.github.io/OSNOM











All active/moved objects in this video are represented by neon balls. Their initial positions are shown at the start of the video



All active/moved objects in this video are represented by neon balls. Their initial positions are shown at the start of the video

Lift

Match

Keep







0.0 ... 1.0

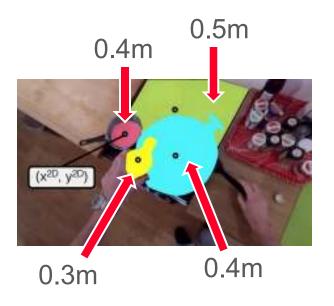
0.3m ... 1.8m





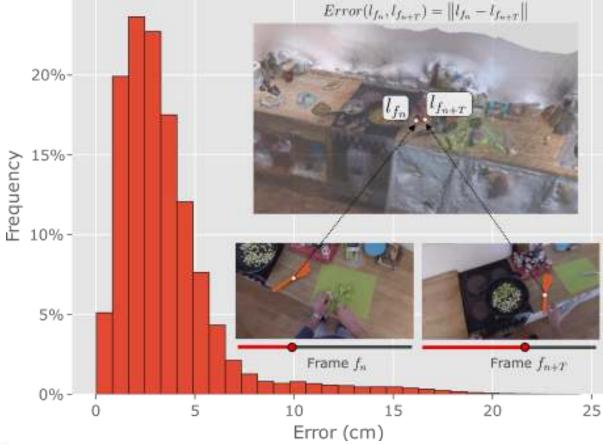
# Match

# Keep













Instead of tracking in 2D, we track in 3D, using combination of appearance and location distances



# Out of Sight, not Out of Mind

After we Lift, Match and Keep (LMK), we can reason about an object's visibility and position

- In-View vs Out-of-View
- In-Sight vs Out-of-Sight (Occluded)
- Within-Reach vs Out-of-Reach (defining the camera wearer's near space)





# Out of Sight, not Out of Mind

After we Lift, Match and Keep (LMK), we can reason about an object's visibility and position

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- Within-Reach vs Out-of-Reach (defining the camera wearer's near space)



with: Chiara Plizzari

**Toby Perrett** 



## Spatial Cognition from Egocentric Video:

# Out of Sight, Not Out

Chiara Plizzari

Shubham d-Truth?? oby Perrett

Jacob Chalk

Angi

Dima Damen

nttp://dimadamen.github.io/OSNOM









### In this talk...



**Unique Captioning** 



Visual Instructions



Learning from Continuous Streams



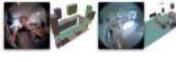
Out of Sight, Not Out of Mind



HD-EPIC: A Highly-Detailed Egocentric Video Dataset











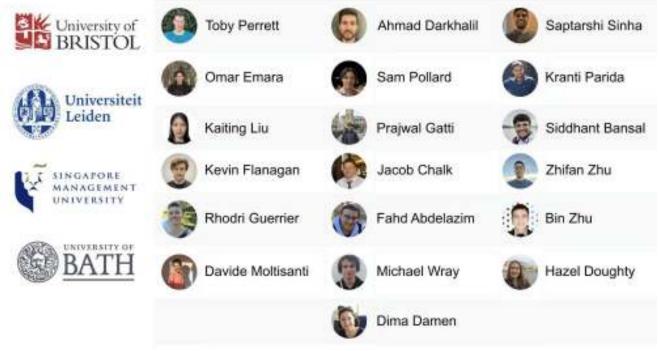








### HD-EPIC: A Highly-Detailed Egocentric Video Dataset



















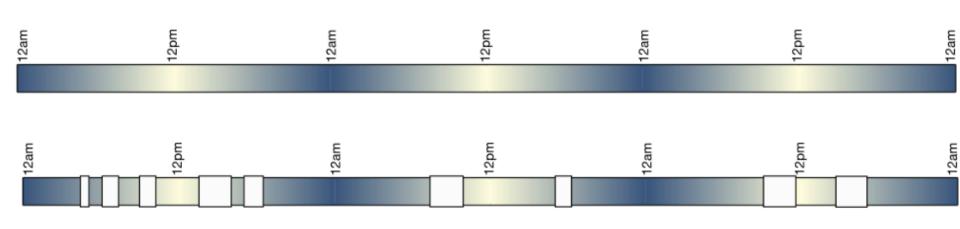


























# 























# 









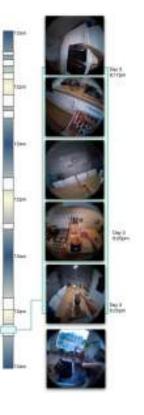
















2y 3 517pm















### Recipe: Southwestern Salad

1: Preheat the over to 400F

2: Wash and peel the sweet potatoes and chopinto bite-sized pieces. Put the sweet potatoes in a bowl and add the clive oil, curnin, and chili powder. Pour onto tray and roast for 10 mins.

3: Pulse all the dressing ingredients in a food processor. until mostly smooth.

Recipe and nutrition





















### Cacio e Pepe (modified)

### Ingredients:

2009 perme

400g of pasta of your choice (we recommend bucatini)

2 tablespoon of black peppercorn

309

200g of freshly grated pecorino cheese

+25g of slightly salted butter



### Steps:



1. Toast the peppercorns until fragrant in a dry frying pan over medium heat, about 2 minutes. Keep them moving to prevent them from burning.

Once teasted, roughly grush



Cook your choice of pasta in a large pot of generously salted boiling water for around 1.6 minutes, or until all dente.

3. While the pasta cooks, add freshly grated cheese and crushed black



on very low heat

peppercorns to a large serving bowl. Gradually add a cup of the boiling cooking water constantly mixing to obtain a silky, smooth sauce that's able to completely coat the pasta.

















- The **prep** of a corresponding **step** is defined as all essential actions the participant takes to get ready to execute a given step.
- For example, the **step** 'chop tomato':
  - **Prep:** retrieve tomato from storage, wash tomato, retrieve a knife and chopping board.
- the **step** 'add chopped onions and stir':
  - **Prep:** retrieve tomato from storage, wash tomato, retrieve a knife and chopping board, and chop the onions.













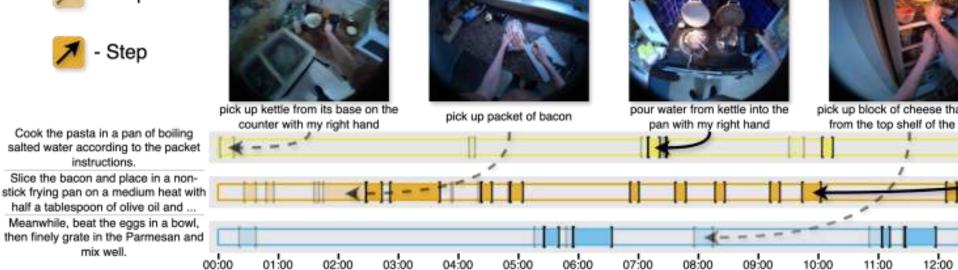






















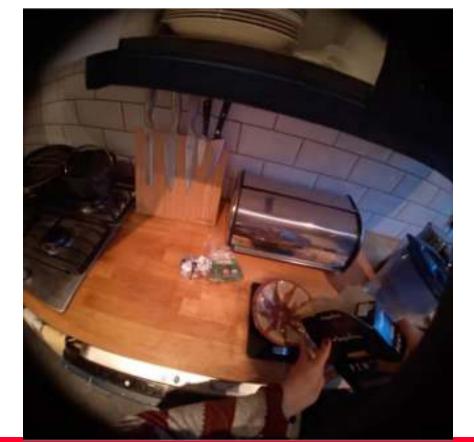








"P01\_R03\_I01": { "name": "penne pasta", "amount": 125, "amount unit": "g", "calories": 445, "fat": 1.9, "carbs": 90, "protein": 15,













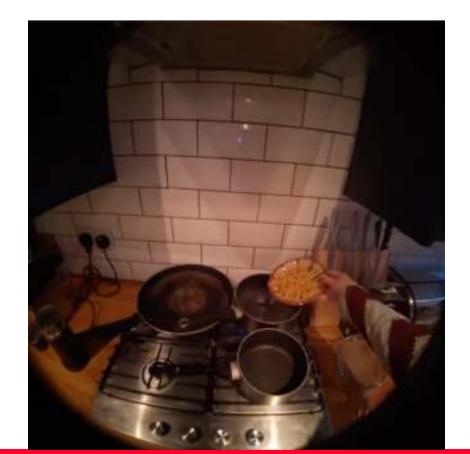








```
"P01 R03 I01": {
   "name": "penne pasta",
   "amount": 125,
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   "calories": 445,
   "fat": 1.9,
   "carbs": 90,
   "protein": 15,
```













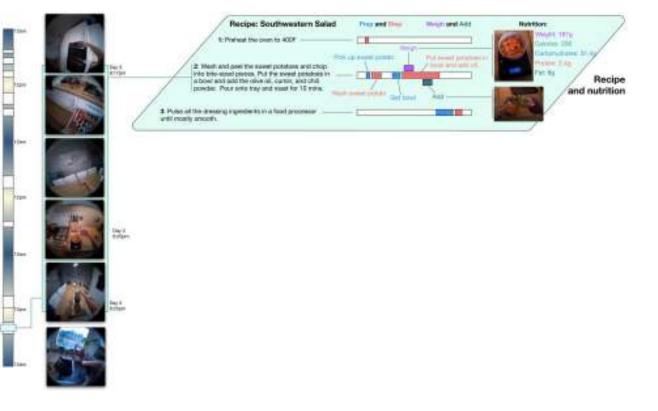














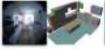






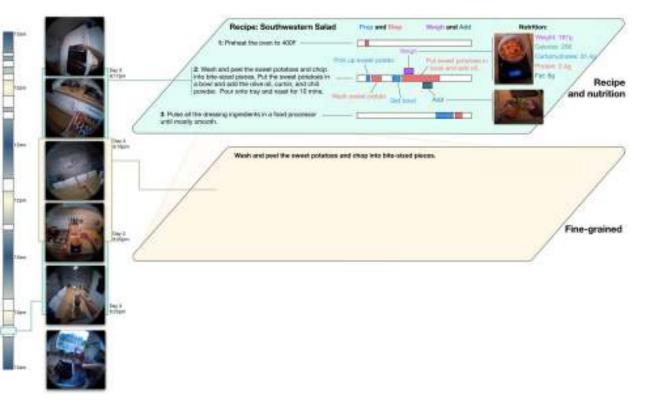






















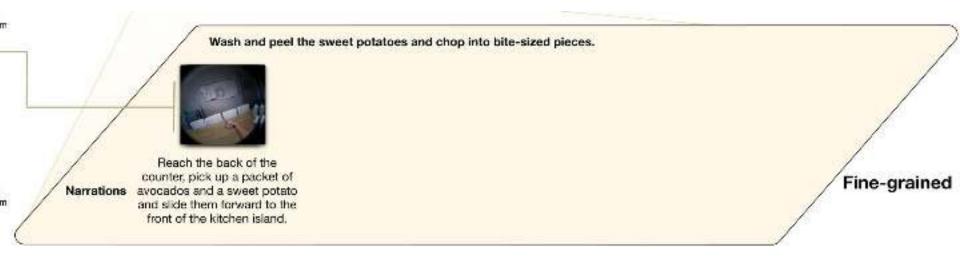










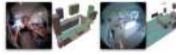






**Highly-Detailed Narrations** 

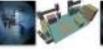






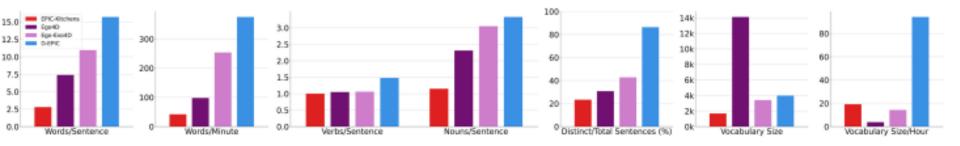






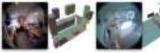


• 59,454 fine-grained actions, with a mean duration of 2.0s (±3.4s).











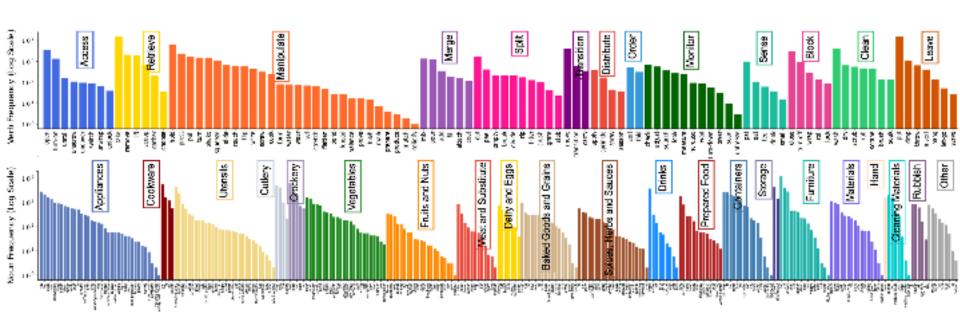








• 59,454 fine-grained actions, with a mean duration of 2.0s (±3.4s).













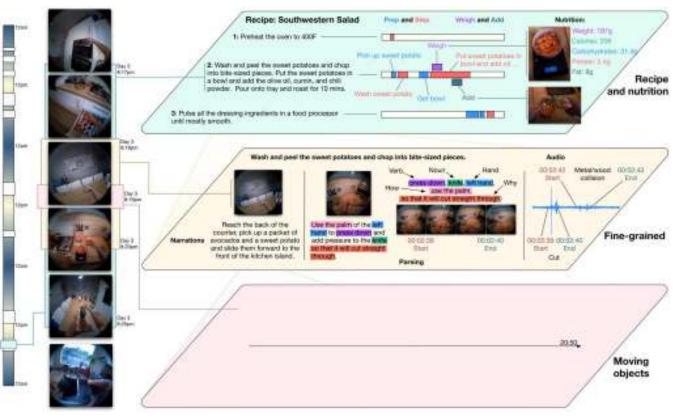






















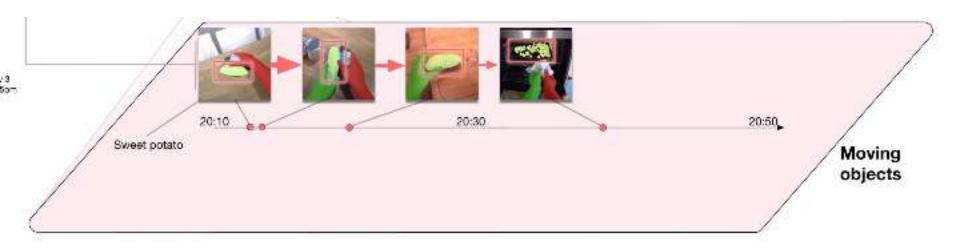






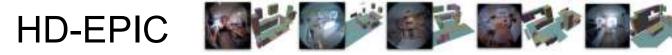














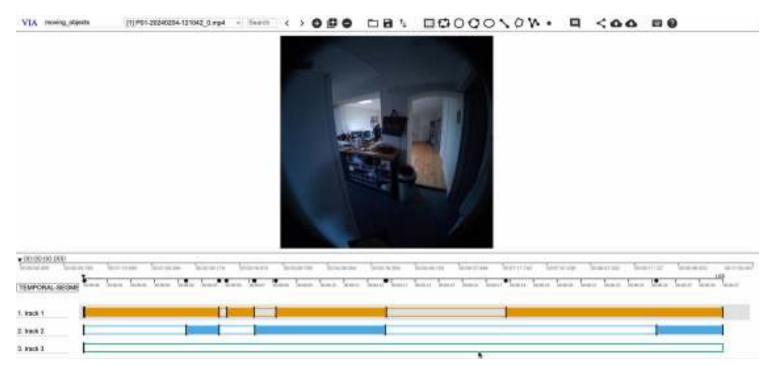








How to minimize the annotations for tracking objects...











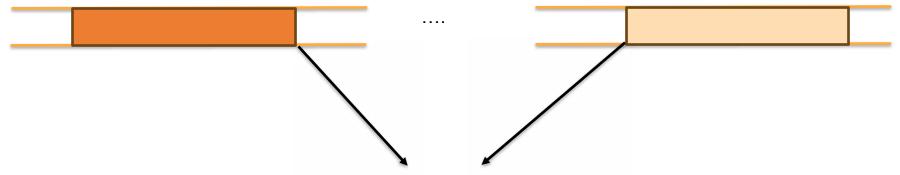








How to minimize the annotations for tracking objects...



Using appearance & 3D location information to match Manual confirmation in cases of confusion...



Static in 3D









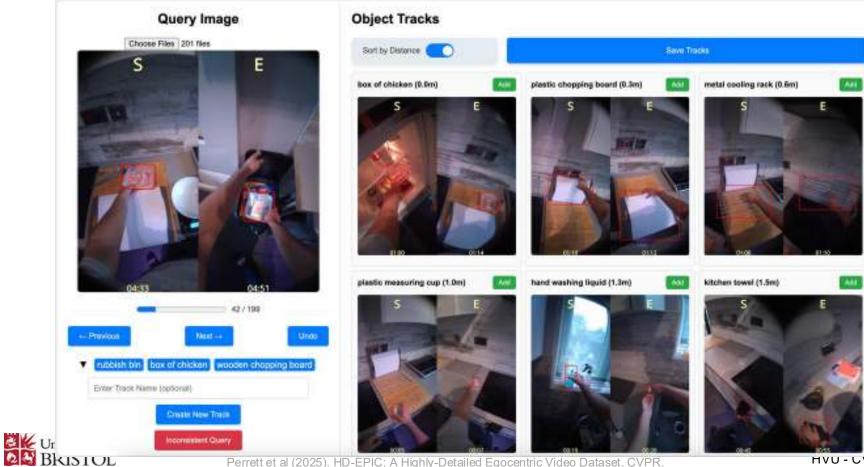




















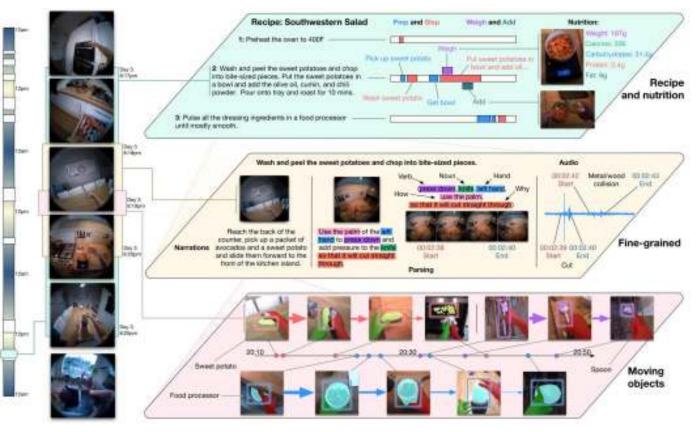






















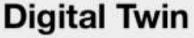


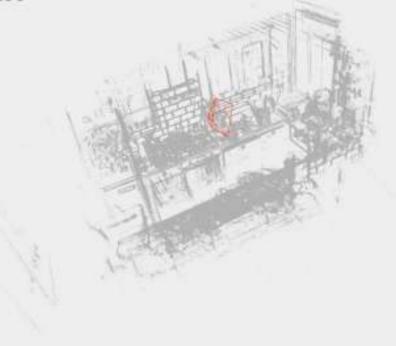






















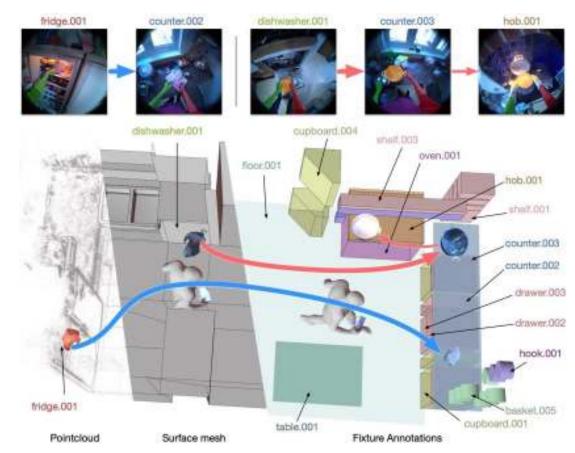


















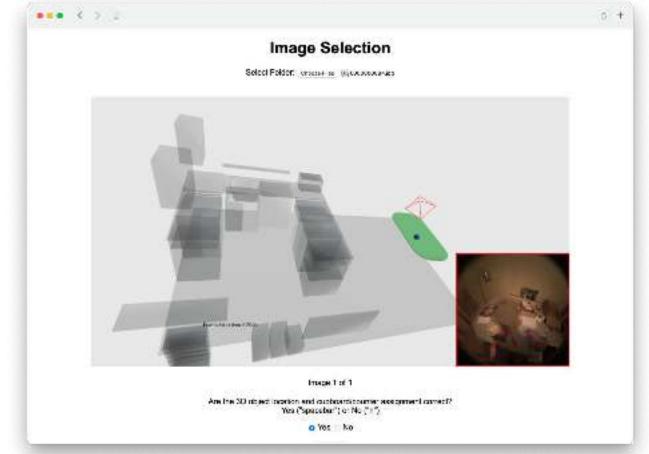








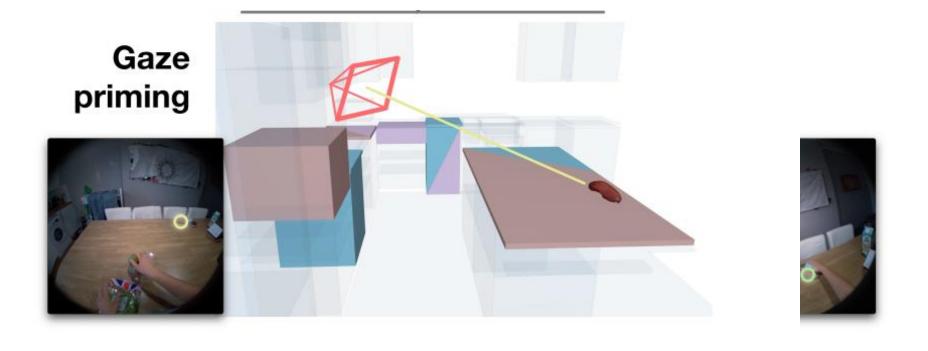






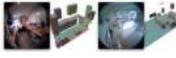












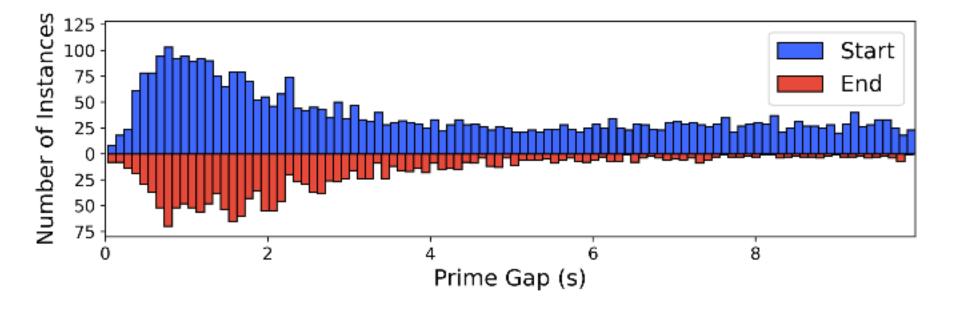










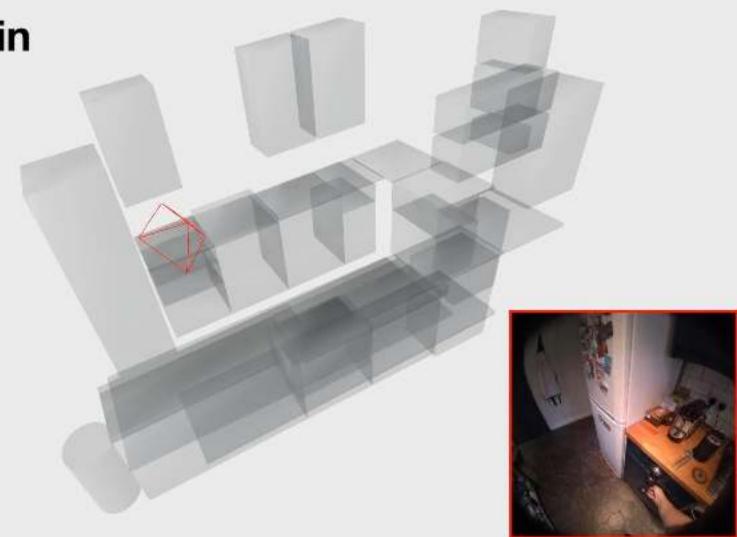




**Digital Twin** 

**Fixtures** 

Open drawer









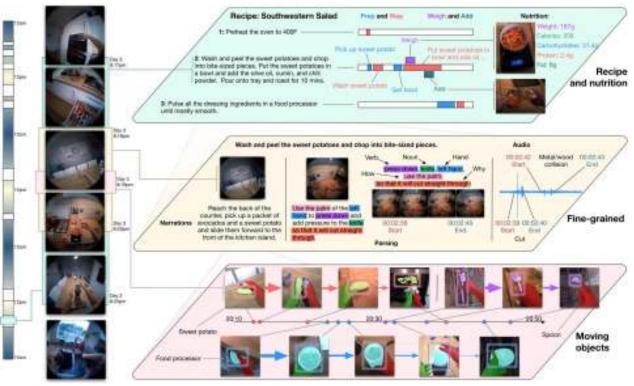


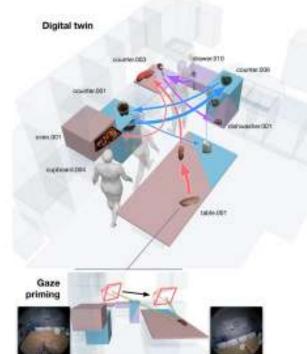














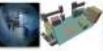














Annotation Type	Total annotations	Annotations/min	
Narrations	59,454	24.0	
Parsing (Verbs + Nouns + Hands + How + Why)	303,968	122.7	
Recipes (Preps + Steps)	4,052	1.6	
Sound	50,968	20.6	
Action boundaries	59,454	24.0	
Object Motion (Pick up + Put down + Fixtures + Bboxes + Masks)	153,480	62.0	
Object Itinerary	4,881	2.0	
Object Priming (Starts + Ends)	18,264	7.4	
Total		263.2	

Table A3. HD-EPIC annotations per minute









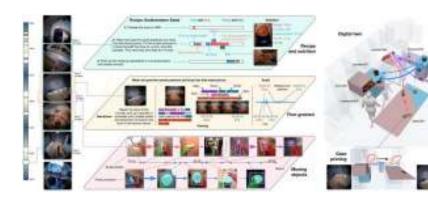














Sec 1: Highly-Detailed Dataset

Sec 2: HD-EPIC VQA Benchmark









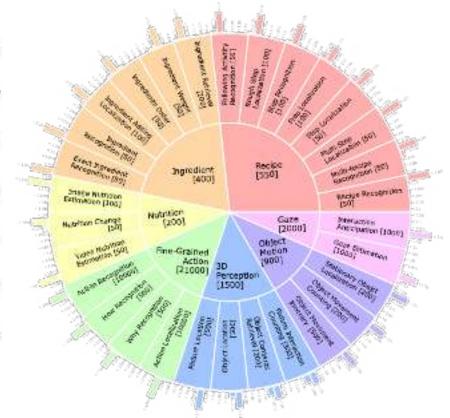








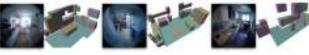
- Recipe. Questions on temporally localising, retrieving, or recognising recipes and their steps.
- 2. Ingredient. Questions on the ingredients used, their weight, their adding time and order.
- Nutrition . Questions on nutrition of ingredients and nutritional changes as ingredients are added to recipes.
- 4. Fine-grained action. What, how, and why of actions and their temporal localisation.
- 5. 3D perception. Questions that require the understanding of relative positions of objects in the 3D scene.
- 6. Object motion. Questions on where, when and how many times objects are moved across long videos.
- 7. Gaze. Questions on estimating the fixation on large landmarks and anticipating future object interactions.











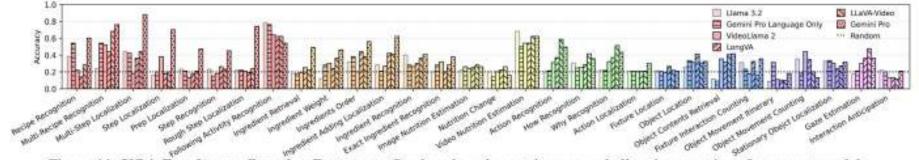


Figure 11. VQA Results per Question Prototype. Our benchmark contains many challenging questions for current models.

Model	Recipe	Ingredient	Nutrition	Action	3D	Motion	Gaze	Avg.
Blind - Language Only								
Llama 3.2	33.5	25.0	36.7	23.3	22.3	25.5	19.5	26.5
Gemini Pro	38.0	26.8	30.0	22.1	21.5	27.7	20.5	26.7
Video-Language								
VideoLlama 2	30.8	25.7	32.7	27.2	25.7	28.5	21.2	27.4
LongVA	29.6	30.8	33.7	30.7	32.9	22.7	24.5	29.3
LLaVA-Video	36.3	33.5	38.7	43.0	27.3	18.9	29.3	32.4
Gemini Pro	64.3	48.6	34.7	39.6	32.5	20.8	28.7	38.5
Sample Human Baseline	96.7	96.7	85.0	92.5	93.8	92.7	75.0	90.3





















### Which of these sentences best describe the action(s) in the video? [00:03:56 - 00:04:03]

- A. Wash the cutting board using the sponge in right hand, then, rotate the cutting board so that the back side can be washed
- B. With sponge in right hand, clean cutting board while holding board steady with left hand, then with left hand put cutting board under water to clean from soap
  - C. With left hand, grab cutting board from dish rack, then, with both hands put cutting board down on kitchen counter
  - D. With my left hand, pick up cutting board, then, with both hands, run the cutting board under water to clean
  - E. Pick up cutting board from drying rack using right hand, then, dry the cutting board using tea towel in left hand whilst flipping and rotating the cutting board with right hand





















What is the best description for how the person carried out the action pick up bowl of coconut milk in this video segment? [00:18:44 - 00:18:46]

- A. Using both hands holding the bowl from bowl rim.
  - B. By holding both sides using the oven gloves.
- C. using the right hand and lift the large white bowl up.
  - D. using left hand and removing the fork used to stir it using right hand.
  - E. using both hands from the kitchen top above the dishwasher.





























How many times did I open the item at bounding box (165, 452, 1408, 1408) in 00:00:57?

A. 3



C. 4

D. 5

E. 2















- May 2025: Eye-Gaze Priming data has now been released! Annotations link
- April 2025; VQA Challenge Benchmark is online now! Challenge link !!.
- April 2025: Masks and object association annotations have now been released.
- Feb 2025: HD-EPIC = accepted at CVPR 2025!



Dima Damen HVU - CVPRW'25

## An Outlook into the Future of Egocentric Vision

Chiara Plizzari\*, Gabriele Goletto\*, Antonino Furnari\*, Siddhant Bansal\*, Francesco Ragusa\*, Giovanni Maria Farinella†, Dima Damen†, Tatiana Tommasi†









# **Envisioning** an Ambitious Future and **Analysing** the Current Status of Egocentric Vision

How did we do this?

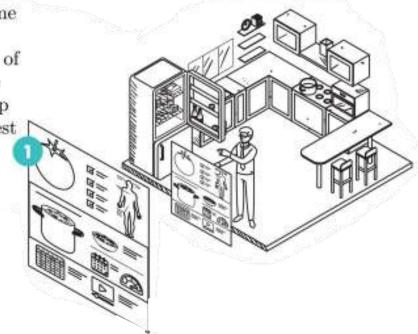


## We imagined a device – *EgoAl* and envisioned its utility in multiple scenarios

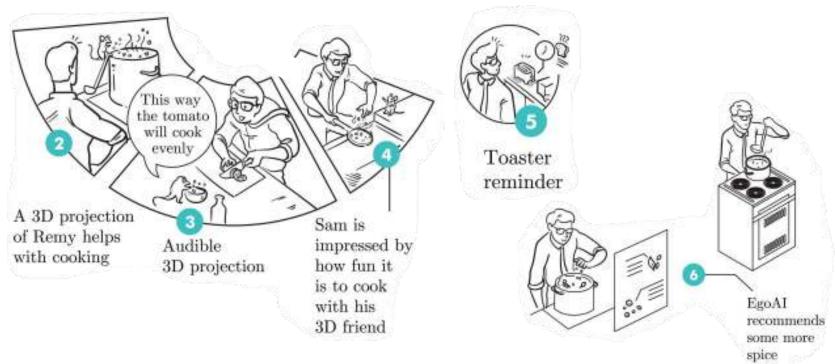




Sam is finally home after a long day.
EgoAl kept track of Sam's food intake and a tomato soup sounds like the best complementary nutrition



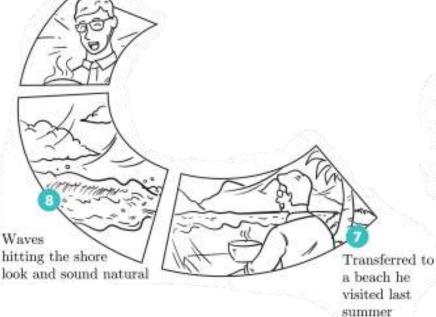






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### EGO-Home

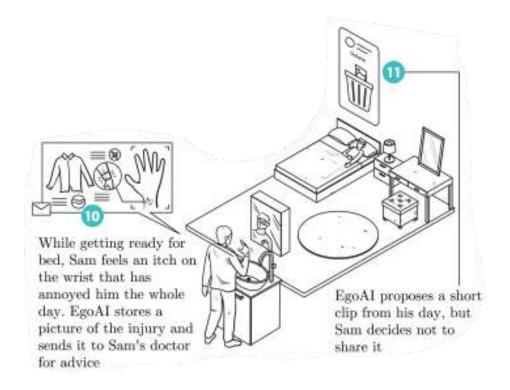


After dinner, Sam enjoys a group card game with his friends, who are connected through their own EgoAI





### EGO-Home

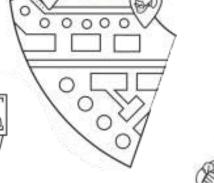




### From Stories to Tasks

with: Chiara Plizzari, Gabriele Goletto, Antonio Furnari, Siddhant Bansal, Francesco Ragusa, Giovanni Maria Farinella, Tatiana Tommasi

EgoAI helps Judy navigate through the shortest safe path to target places



EgoAI detected and re-identified the man before he passed Judy



**EGO-Police** 

Localisation and Navigation	00
Messaging	90
Action Recognition	<b>2</b> B
Person Re-ID	24
Object Detection and Retriev	al 🕖
Measuring System	89
Decision Making	9
3D Scene Understanding	10
Hand-Object Interaction	T2
Summarisation	13
Privacy	14

### In this talk...



**Unique Captioning** 



**Visual Instructions** 



Learning from Continuous Streams



Out of Sight, Not Out of Mind



HD-EPIC: A Highly-Detailed Egocentric Video Dataset



## The Team





Dima Damen HVU - CVPRW'25

## Thank you

For further info, datasets, code, publications...

http://dimadamen.github.io



@dimadamen



@dimadamen.bsky.social



http://www.linkedin.com/in/dimadamen



