

# Machine Learning saves Computer Vision

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Origins of Computer Science

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University of  
**BRISTOL**

# Overview

- What is computer vision?
- Early attempts
- The need for machine learning
- Success Stories
  - Viola&Jones Face Detector
  - Pictorial Structures
  - Background Subtraction
- Have we been saved??

# What is computer vision?

- A digital image is just a bunch of samples (pixels) and quantised values (colour)

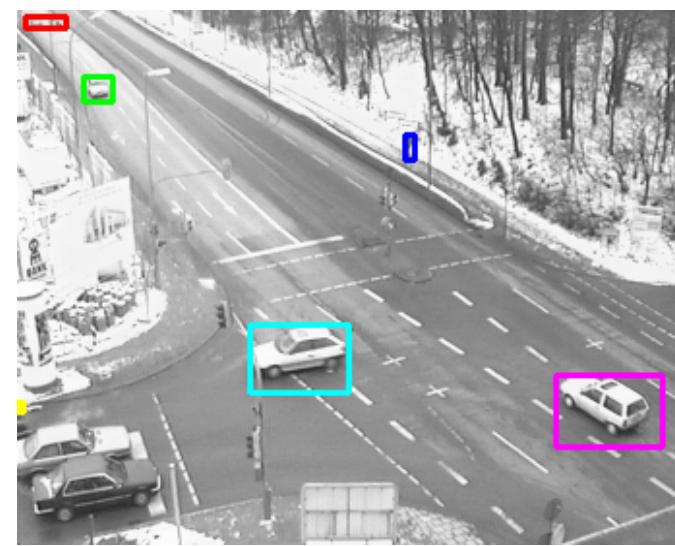
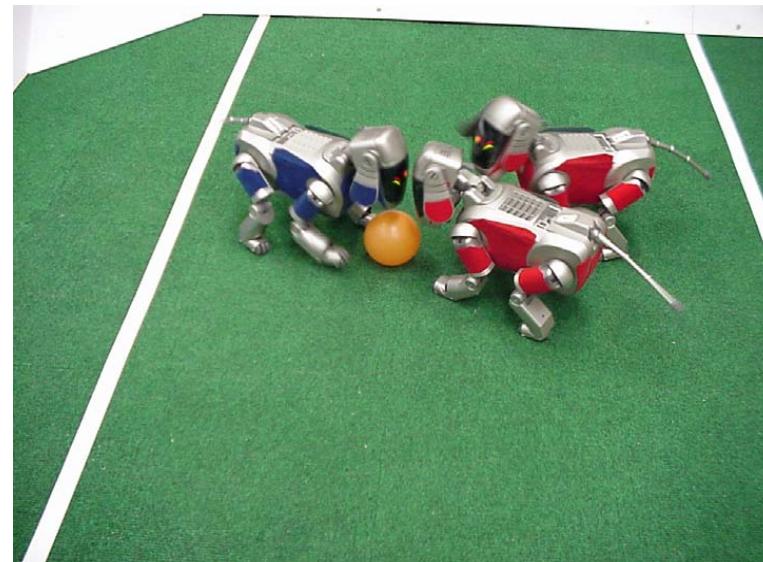
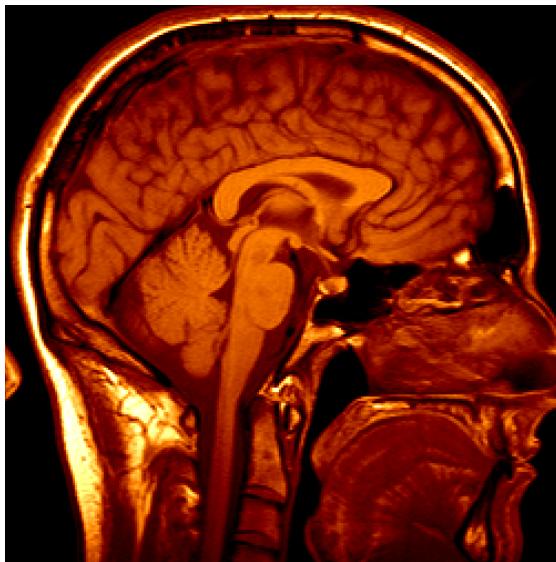


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66	68	71	73	75	79	81	85	87	92	96	100	104	109	116	73	37	57	73	89	107	125	137
69	71	74	76	78	82	85	89	93	96	101	106	110	116	113	29	1	6	6	8	13	19	27
71	74	77	78	82	87	90	93	96	101	105	110	115	125	81	18	8	6	7	7	10	10	13
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77	81	85	88	91	96	100	104	110	115	121	126	132	108	55	10	7	26	16	12	9	14	17
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83	85	90	94	98	103	108	114	119	126	130	136	142	147	142	37	17	31	33	37	17	15	28
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87	90	95	100	105	111	116	112	122	134	144	154	163	178	144	33	33	22	8	9	10	23	14
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111	116	121	128	132	140	101	16	29	37	31	10	14	17	21	21	9	32	21	12	13	38	41

# What is computer vision?

- Can we make computer understand
  - images? [photos, medical, ...]
  - videos? [tv broadcast, youtube, ...]
- Looks easy... but... !

# What is computer vision?

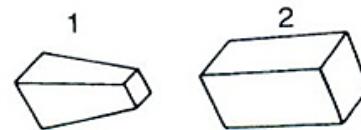


# Computer Vision

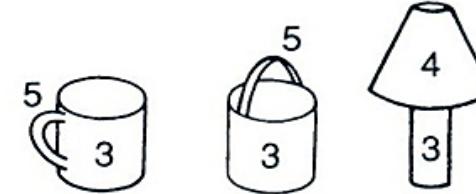
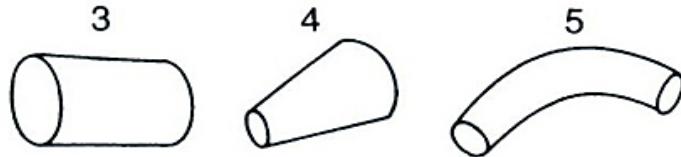
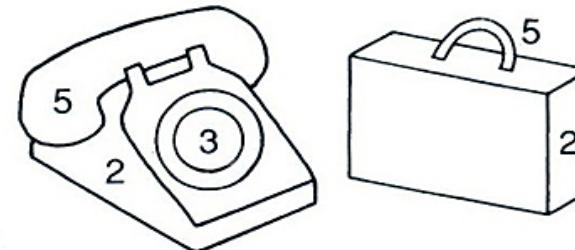
- Early computer vision methods tried to model the world, without using training data

(RBC – Recognition by Components)

**(a) Geones**



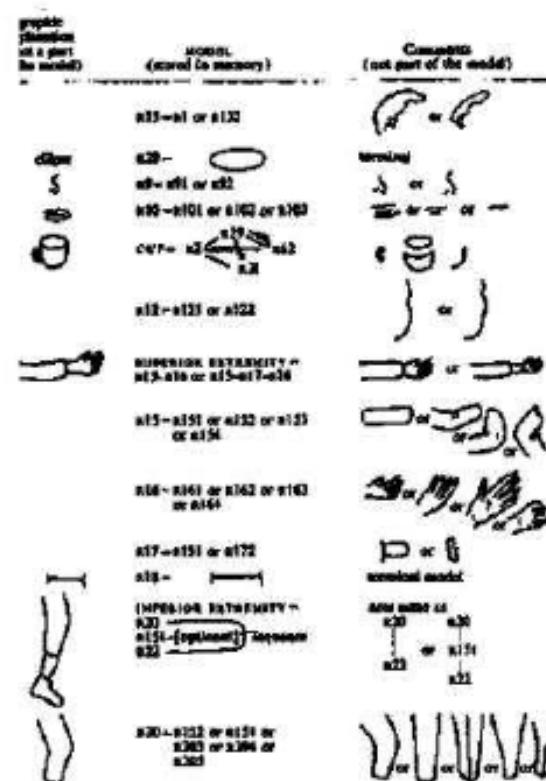
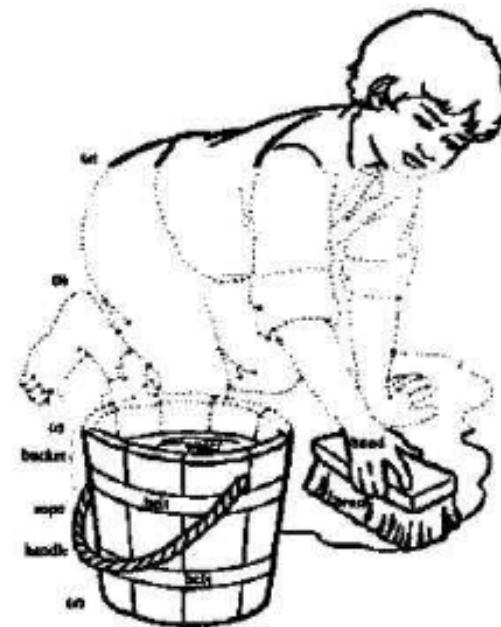
**(b) Objetos**



Biederman, I. (1987) Recognition-by-components: a theory of human image understanding. Psychol Rev. 1987;94(2):115-47.

# Computer Vision

- Early computer vision methods tried to model the world, without using training data  
(curves)



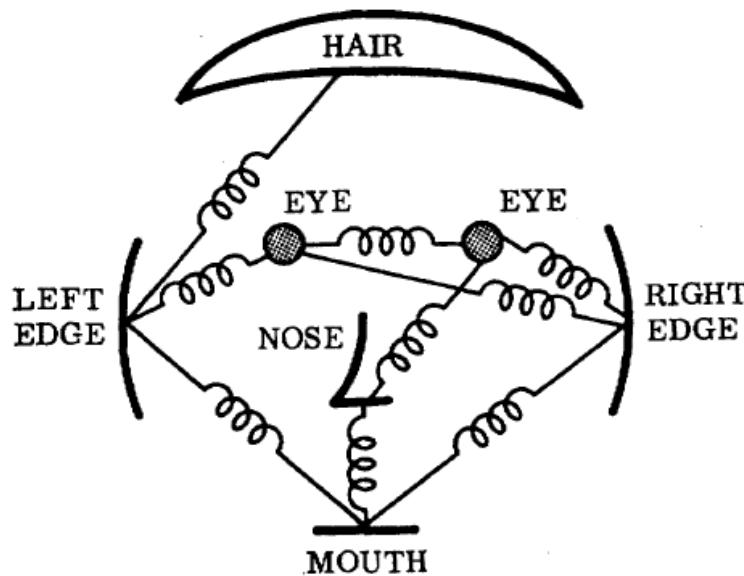
c)

A. Guzman (1971). Analysis of curved line drawings using context and global information.  
Machine Intelligence 6

# Computer Vision

- Early computer vision methods tried to model the world, without using training data

(Part-Based Models)



```

1 111Z112112Z11ZZZ1ZZZZZZZZZZZ
2 ZZZZZZZZZZZZZZZZZAAZZZZZZZZZZZZ
3 ZZZZZZZZZZZZZZZA9999MXZZXZZZXXXX
4 ZZZZZZZZZZZZZMX9999999999AXZXXXZXXXX
5 ZZZZZZZZZZZZM9999999999999999XZZZZZZZZ
6 111ZZZ11111A9999999999999999ZZZZZZZZ
7 111ZZ1111199999999999999999MZZZZZZZ
8 ZZZZZZZZZZ999999999999999999999999XZZZZZZZ
9 11111111111111111111111111MAXA999A
  99999999999999999999999999MAXAZ999A
10. 99999999999999999999999999MAXAZZ999+
11. +1A99999999999999999999999999MAXZZ999M
12. -11999XXXXXX99999999999999999999999999
13. (99AXAAAAXXXAAAAAZX9991
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17. +MM11Z1111ZXZ211Z9MZ
18. -A9Z111Z)11XZ21ZX9A+
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  9999999999999999999999999999999999999999999
21. 9999999999999999999999999999999999999999999
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23. -9999999999999999999999999999999999999999999
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27. M9999999999999999999999999999999999999999999
28. +X999999999999999999999999999999999999999999
29. A9999999999999999999999999999999999999999999
30. )9999999999999999999999999999999999999999999
31. -X999999999999999999999999999999999999999999
32. )9999999999999999999999999999999999999999999
33. I9999999999999999999999999999999999999999999
34. =Z9999999999999999999999999999999999999999999

```

123456789012345678901234567890123456

Original picture.

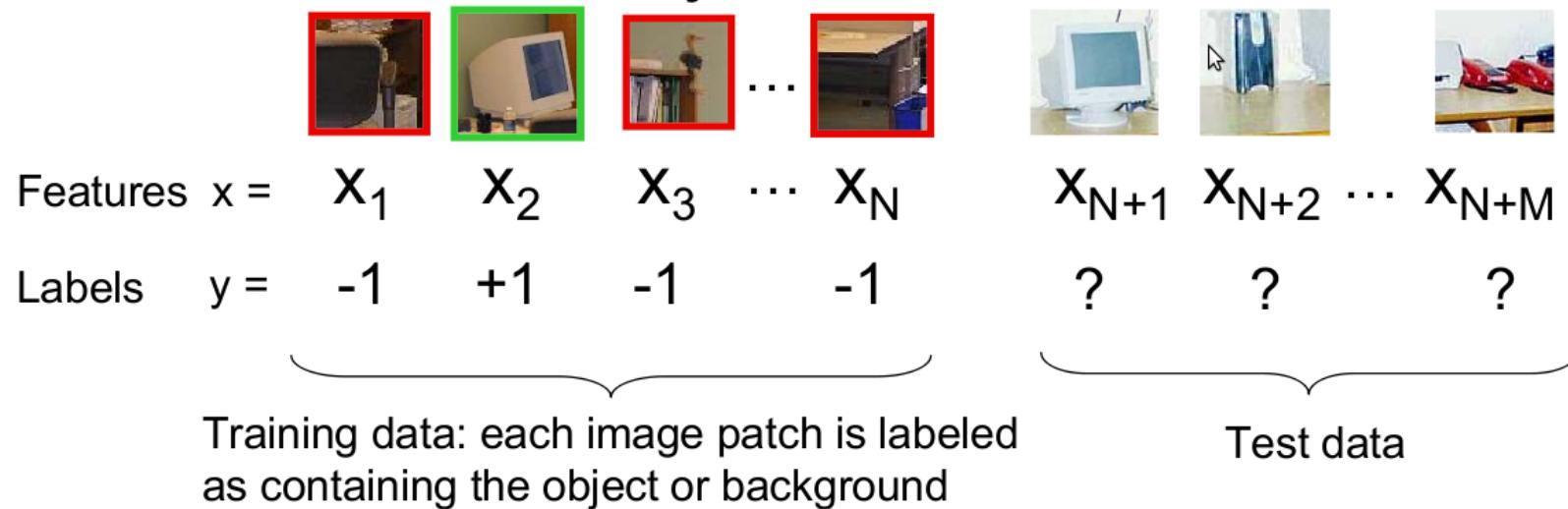
HAIR WAS LOCATED AT (7, 23)  
L/EDGE WAS LOCATED AT (17, 13)  
R/EDGE WAS LOCATED AT (17, 26)  
L/EYE WAS LOCATED AT (14, 17)  
R/EYE WAS LOCATED AT (14, 23)  
NOSE WAS LOCATED AT (20, 20)  
MOUTH WAS LOCATED AT (22, 20)

# What is Machine Learning?

- Algorithms for learning from data
- In 1959, Arthur Samuel defined machine learning as a "Field of study that gives computers the ability to learn without being explicitly programmed" [Wiki]

# The need for machine learning

- Vision can be formulated as a learning problem
- Formulation: binary classification



- Classification function

$$\hat{y} = F(x) \quad \text{Where } F(x) \text{ belongs to some family of functions}$$

- Minimize misclassification error

(Not that simple: we need some guarantees that there will be generalization)

# The need for machine learning

- Methods that use training data quickly outperformed modelling approaches (1990+).
- Machine learning is now a core part of computer vision.
- Nearly every machine learning algorithm has been used in one way or another in computer vision.
- Visual data (images and videos) is a new source for machine learning scientists.

# Success Stories

Several success stories have paved the way:

1. Viola & Jones Face Detector (2001)
2. Pictorial Structures (2001)

# Success Stories

- Face Detection – the Viola & Jones Face Detector

**BBC NEWS**      **LIVE**      **BBC NEWS CHANNEL**

Last Updated: Monday, 6 February 2006, 14:29 GMT

[E-mail this to a friend](#)      [Printable version](#)

## Face-hunting cameras boost Nikon

**Japanese camera maker Nikon has tripled its profits on the back of strong sales of digital cameras that automatically focus on human faces.**

Operating profit for the three months to 31 December was 19.8bn yen (\$167m; £95m), up from 5.9bn yen in 2004.

Nikon said that sales of compact digital cameras had been boosted by the success of new face recognition models.

It had also seen strong sales of its digital "SLR" cameras with interchangeable lenses and bodies



Face recognition cameras like the Coolpix L1 are popular

**SEE ALSO:**

- Nikon to focus on digital cameras 12 Jan 06 | Business
- Digital trouble hits Nikon shares 10 Feb 04 | Business
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- R.I.P. 35mm Camera 15 Jan 04 | Magazine

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- [Nikon](#)

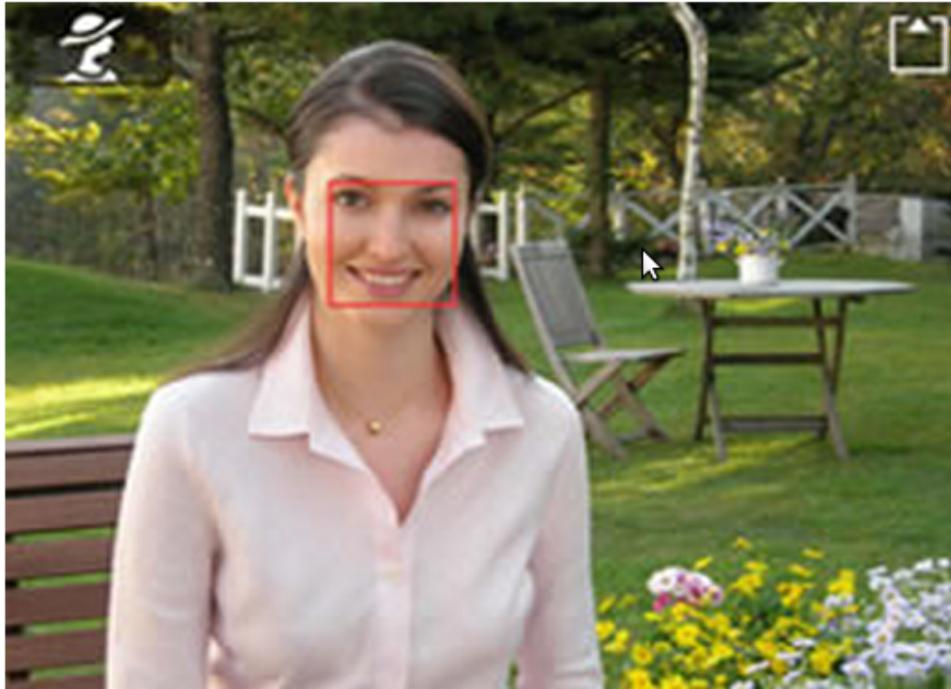
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**TOP BUSINESS STORIES**

- [Unemployment dips to 2.47](#)

# Success Stories

- Face Detection – the Viola & Jones Face Detector



**Sample image:** Subject as seen on the COOLPIX 5900 camera's color LCD and when using Nikon's Face-priority AF function

# Success Stories



# Case I: Viola & Jones Face Detector



**Paul Viola**  
MIT (1996-2000)  
MERL (2001-2002)  
Microsoft (2002 - now)



**Michael Jones**  
Compaq (-2000)  
MERL (2001-now)

# Case I: Viola & Jones Face Detector

## Robust Real-time Object Detection



Paul Viola

viola@merl.com

Mitsubishi Electric Research Labs  
201 Broadway, 8th FL  
Cambridge, MA 02139

Michael Jones

mjones@crl.dec.com

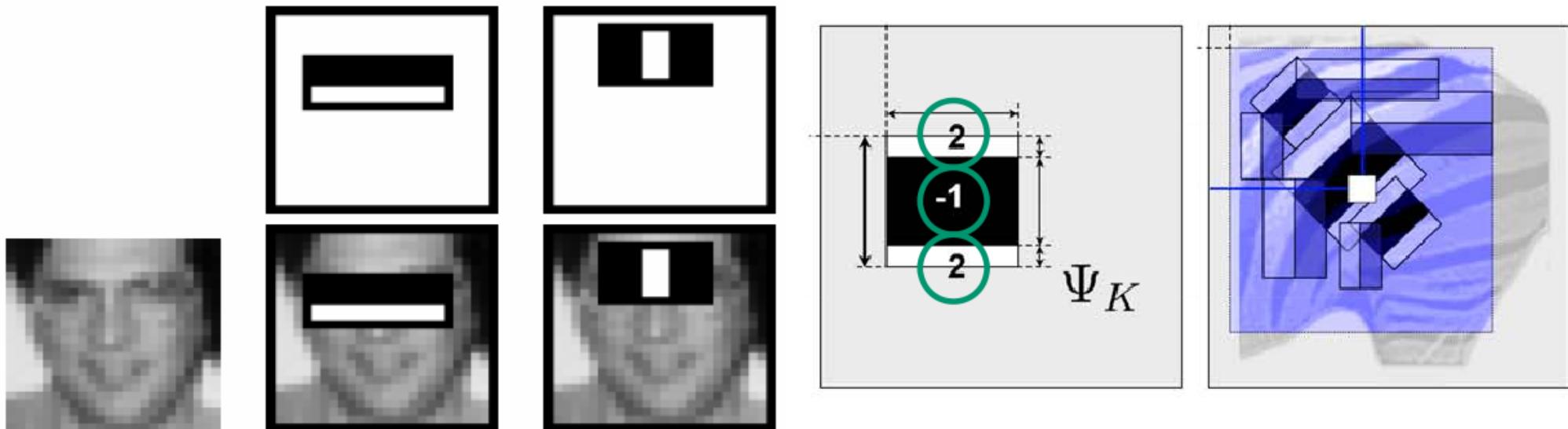
Compaq CRL  
One Cambridge Center  
Cambridge, MA 02142

### Abstract

*This paper describes a visual object detection framework that is capable of processing images extremely rapidly while achieving high detection rates. There are three key contributions. The first is the introduction of a new image representation called the “Integral Image” which allows the features used by our detector to be computed very quickly. The second is a learning algorithm, based on AdaBoost, which selects a small number of critical visual features and yields extremely efficient classifiers [6]. The third contribution is a method for combining classifiers in a “cascade” which allows background regions of the image to be quickly discarded while spending more computation on promising object-like regions. A set of experiments in the domain of face detection are presented. The system yields face detection performance comparable to the best previous systems [18, 13, 16, 12, 1]. Implemented on a conventional desktop, face detection proceeds at 15 frames per second.*

# Case I: Viola & Jones Face Detector

Haar wavelets and Integral Images

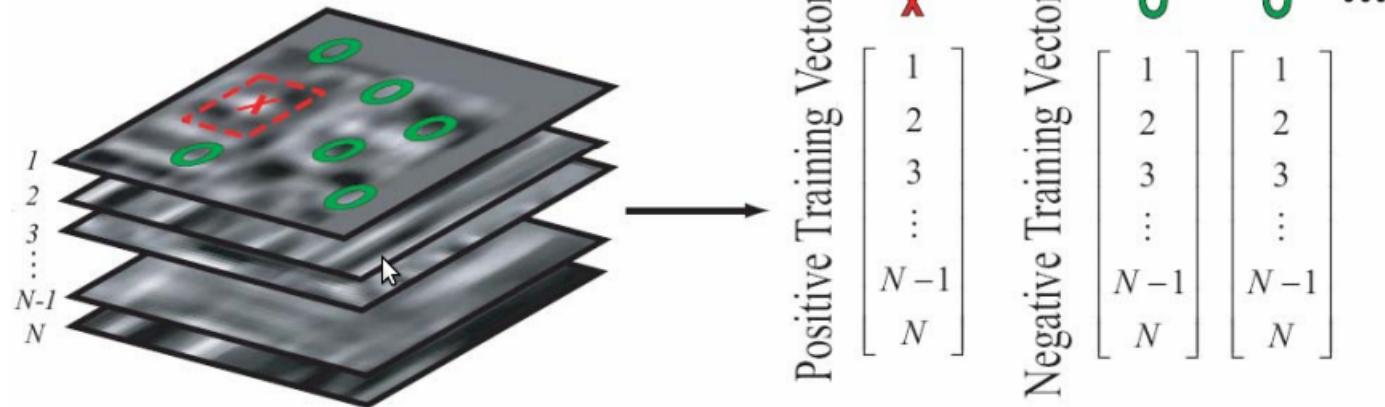


# Case I: Viola & Jones Face Detector

First we evaluate all the N features on all the training images.

$$\begin{aligned}
 \text{Feature 1} \quad & [ ( \text{Image} * \text{Feature Mask} ) \otimes \text{Weight} ] * \text{Bias} = \text{Output Image} \\
 \vdots \\
 \text{Feature N} \quad & [ ( \text{Image} * \text{Feature Mask} ) \otimes \text{Weight} ] * \text{Bias} = \text{Output Image}
 \end{aligned}$$

Then, we sample the feature outputs on the object center and at random locations in the background:



# Case I: Viola & Jones Face Detector

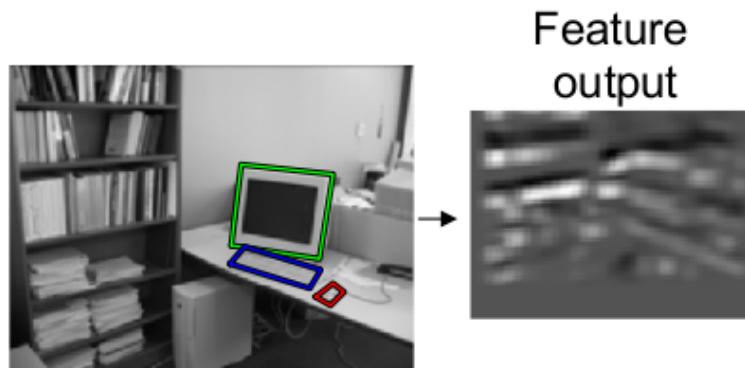
Training Data + 10,000 negative examples were selected by randomly picking sub-windows from 9500 images which did not contain faces



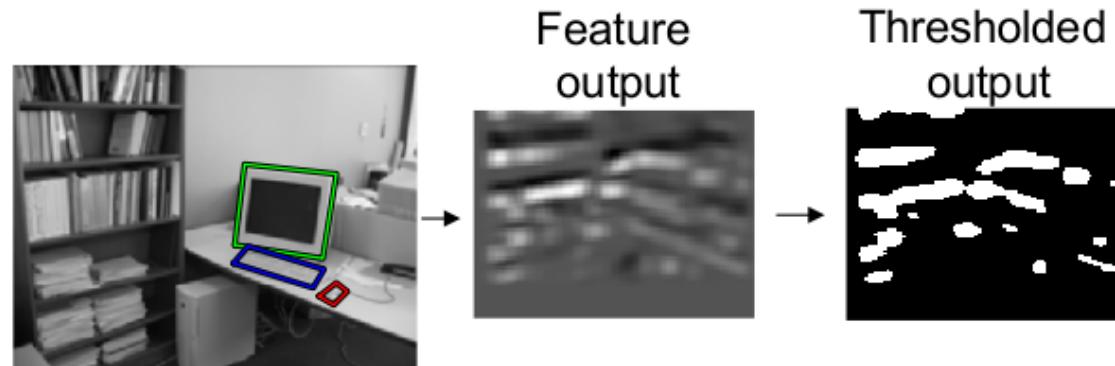
# Case I: Viola & Jones Face Detector

- AdaBoost Classification – a method for supervised learning
- Weak classifiers: classifiers that perform slightly better than chance. ( $\text{error} < 0.5$ )
- Boosting is an iterative algorithm that repeatedly constructs a hypothesis aimed at correcting mistakes of the previous hypothesis
- Strong classifier: has an error rate  $\epsilon$
- Introduced by Freund & Shapire (1995)

# Case I: Viola & Jones Face Detector



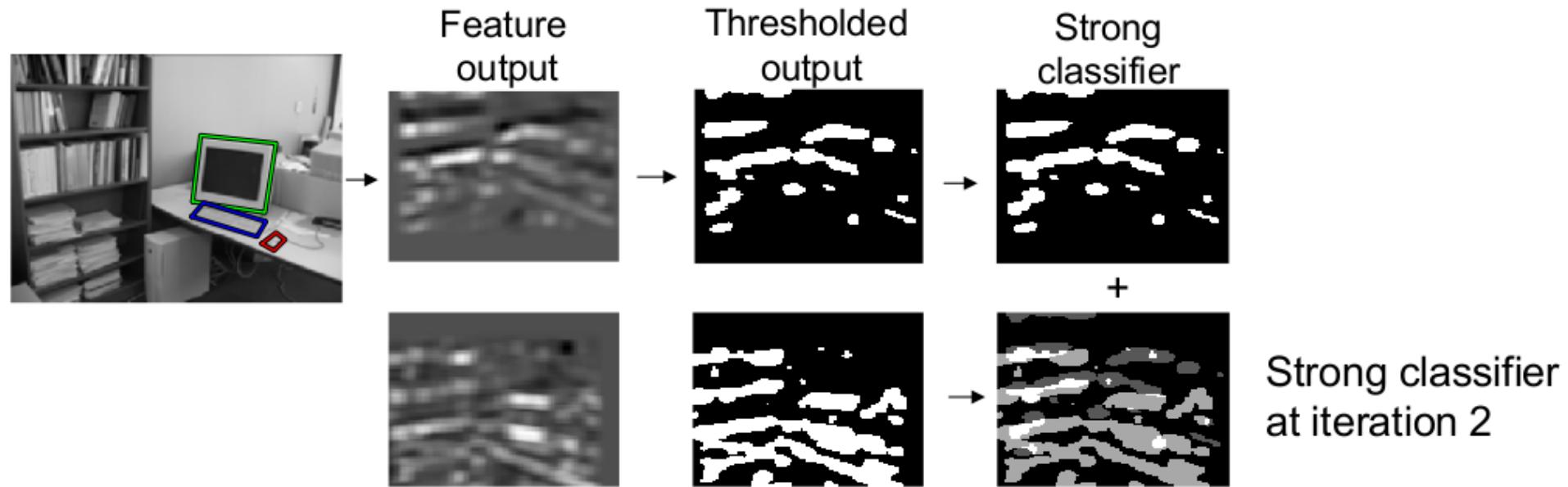
# Case I: Viola & Jones Face Detector



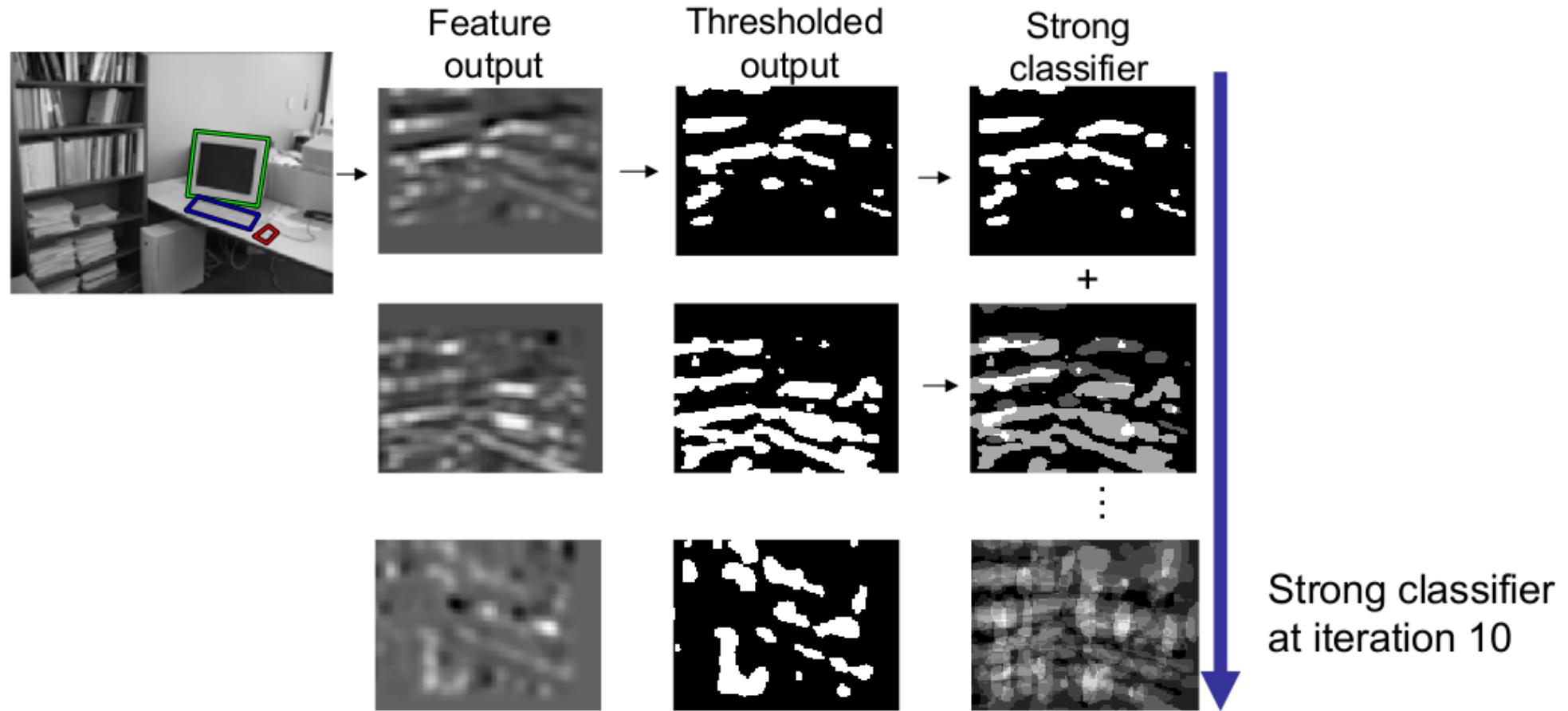
Weak 'detector'  
Produces many false alarms.



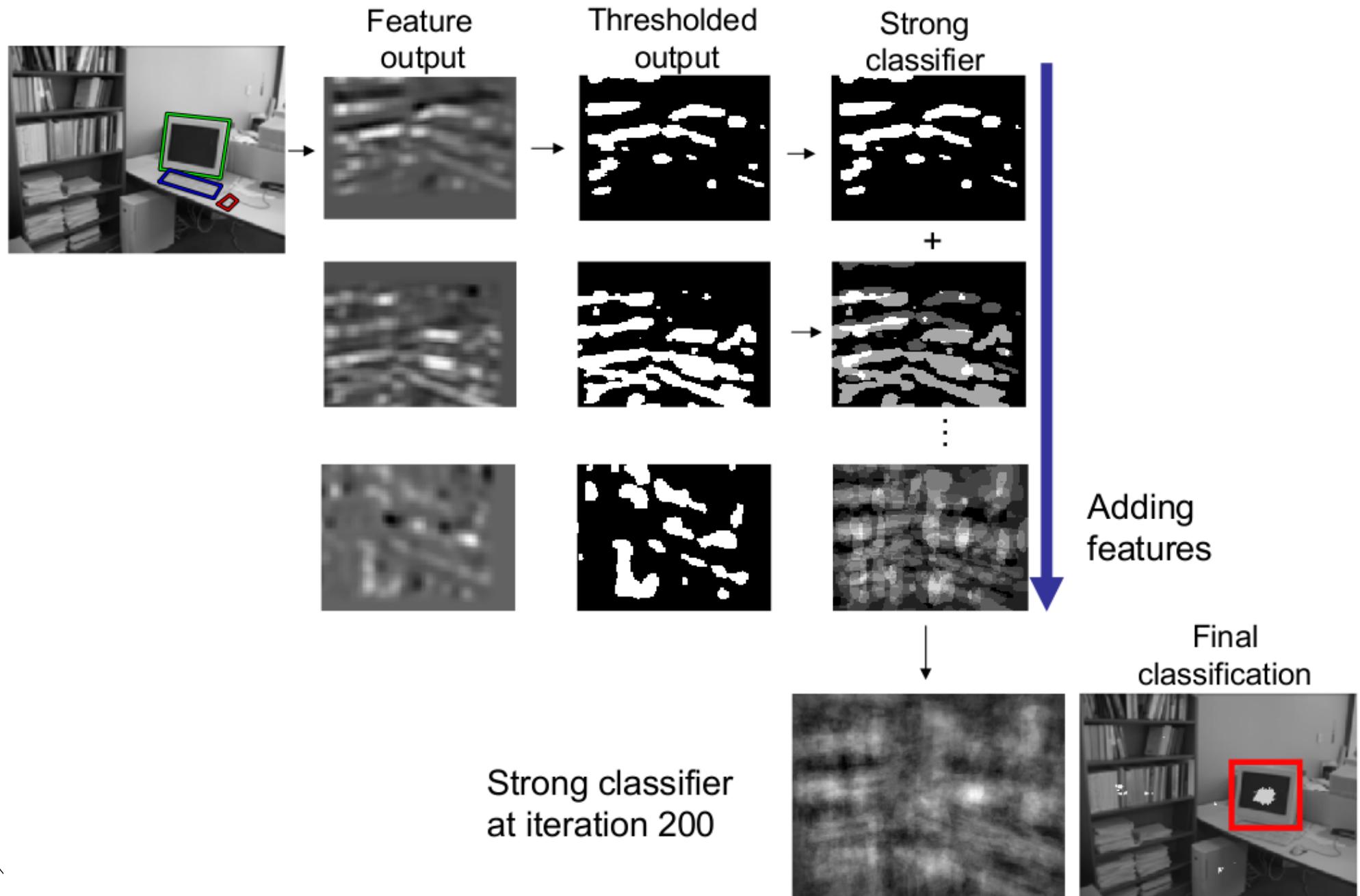
# Case I: Viola & Jones Face Detector



# Case I: Viola & Jones Face Detector

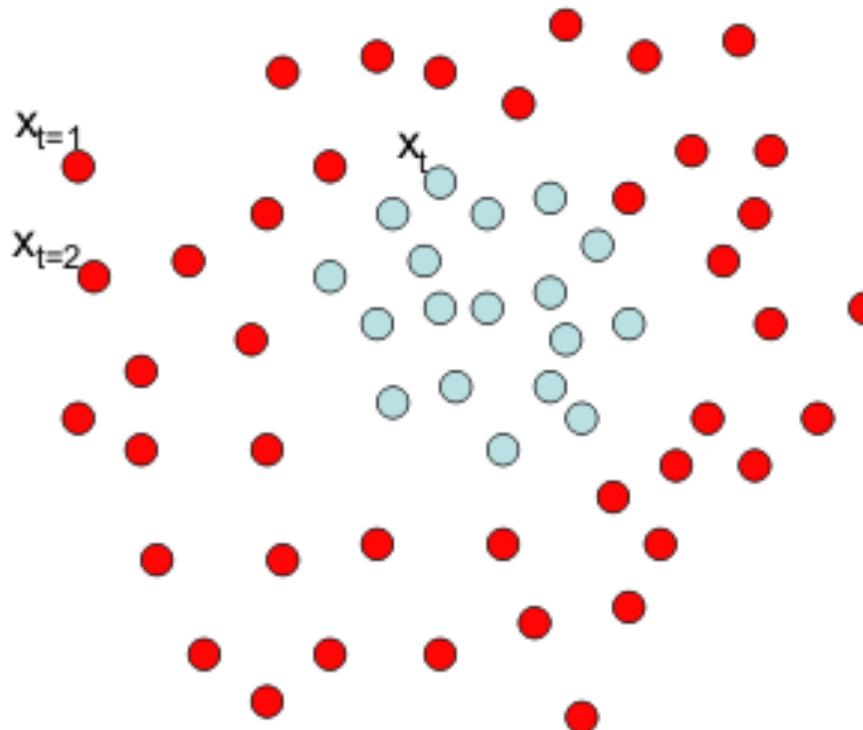


# Case I: Viola & Jones Face Detector



# Case I: Viola & Jones Face Detector

## Boost Classification



Each data point has  
a class label:

$$y_t = \begin{cases} +1 (\text{red}) \\ -1 (\text{light blue}) \end{cases}$$

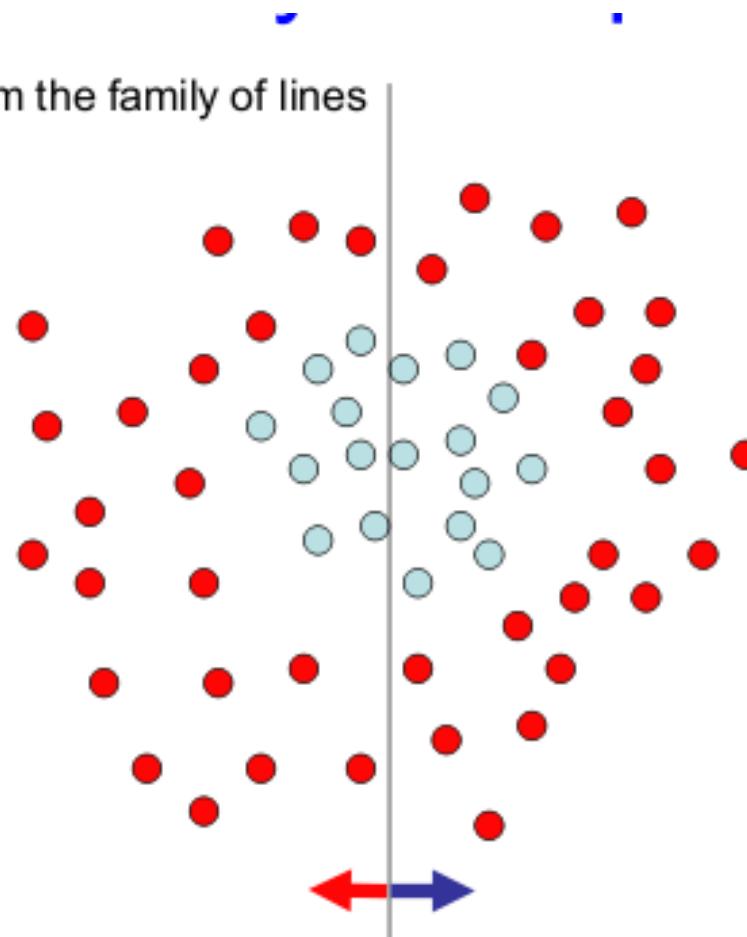
and a weight:

$$w_t = 1$$

# Case I: Viola & Jones Face Detector

## Boost Classification

Weak learners from the family of lines



Each data point has  
a class label:

$$y_t = \begin{cases} +1 (\text{red dot}) \\ -1 (\text{light blue circle}) \end{cases}$$

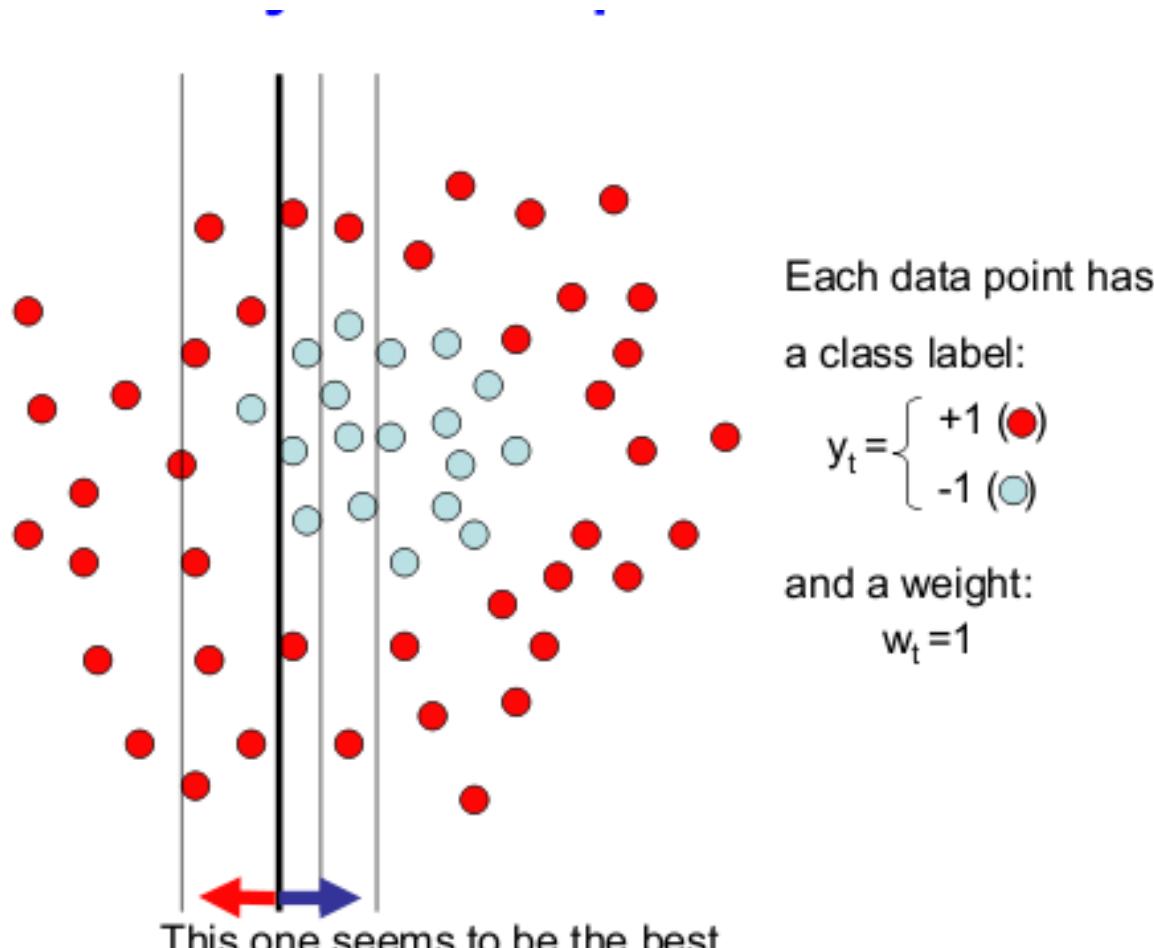
and a weight:

$$w_t = 1$$

$h \Rightarrow p(\text{error}) = 0.5$  it is at chance

# Case I: Viola & Jones Face Detector

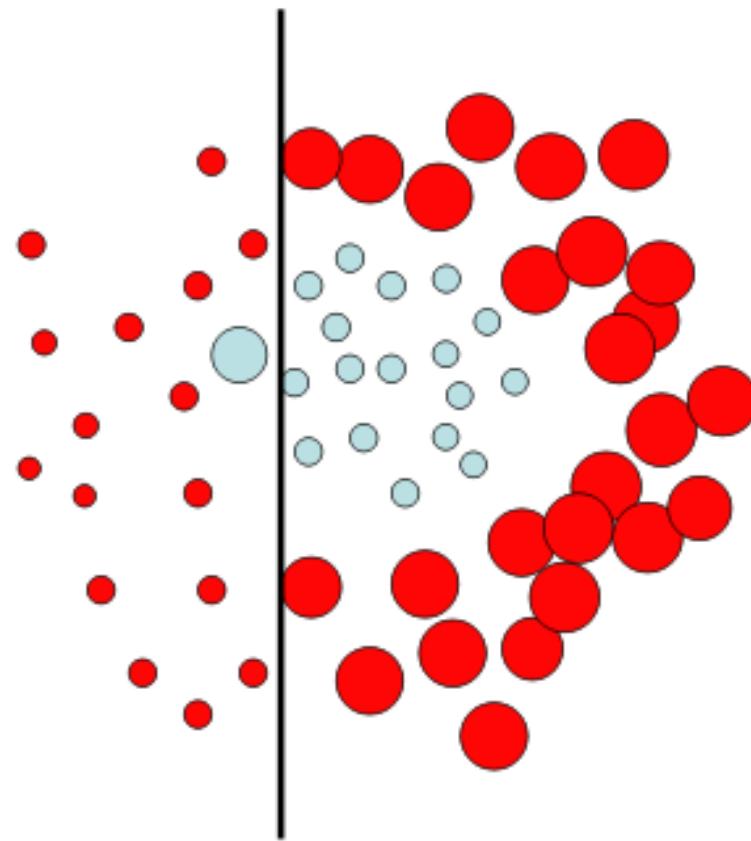
## Boost Classification



This is a '**weak classifier**': It performs slightly better than chance.

# Case I: Viola & Jones Face Detector

## AdaBoost Classification



Each data point has

a class label:

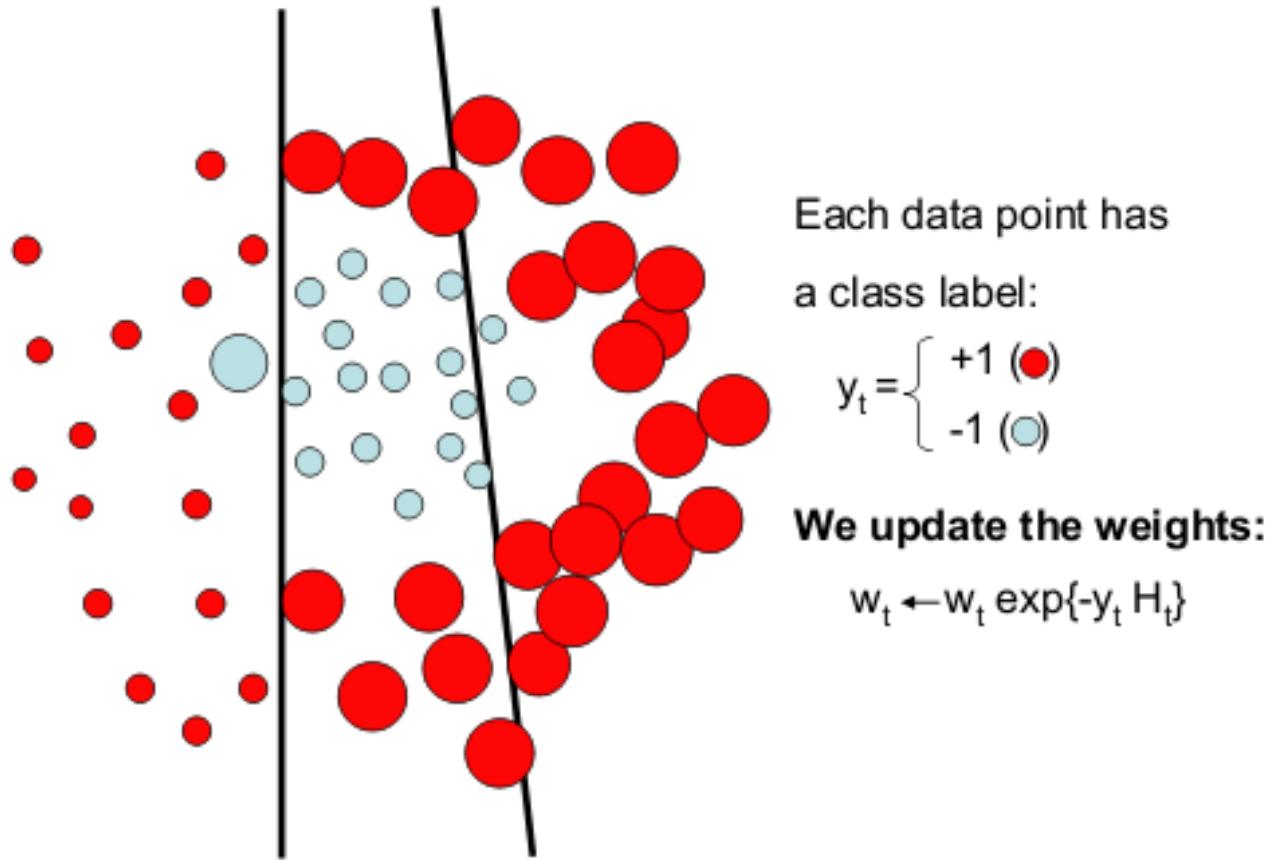
$$y_t = \begin{cases} +1 (\text{red circle}) \\ -1 (\text{blue circle}) \end{cases}$$

We update the weights:

$$w_t \leftarrow w_t \exp\{-y_t H_t\}$$

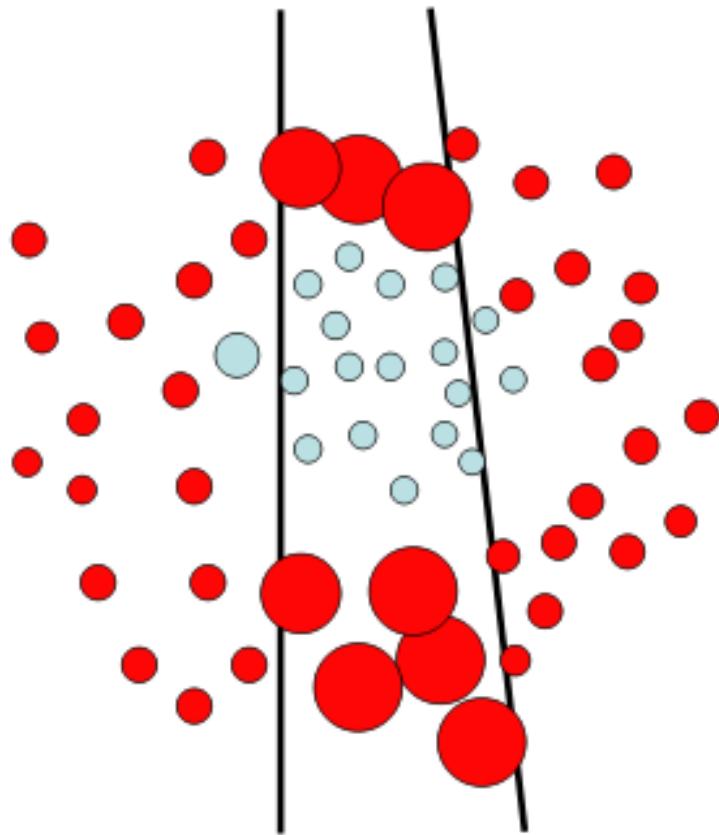
# Case I: Viola & Jones Face Detector

## Boost Classification



# Case I: Viola & Jones Face Detector

## Boost Classification



Each data point has  
a class label:

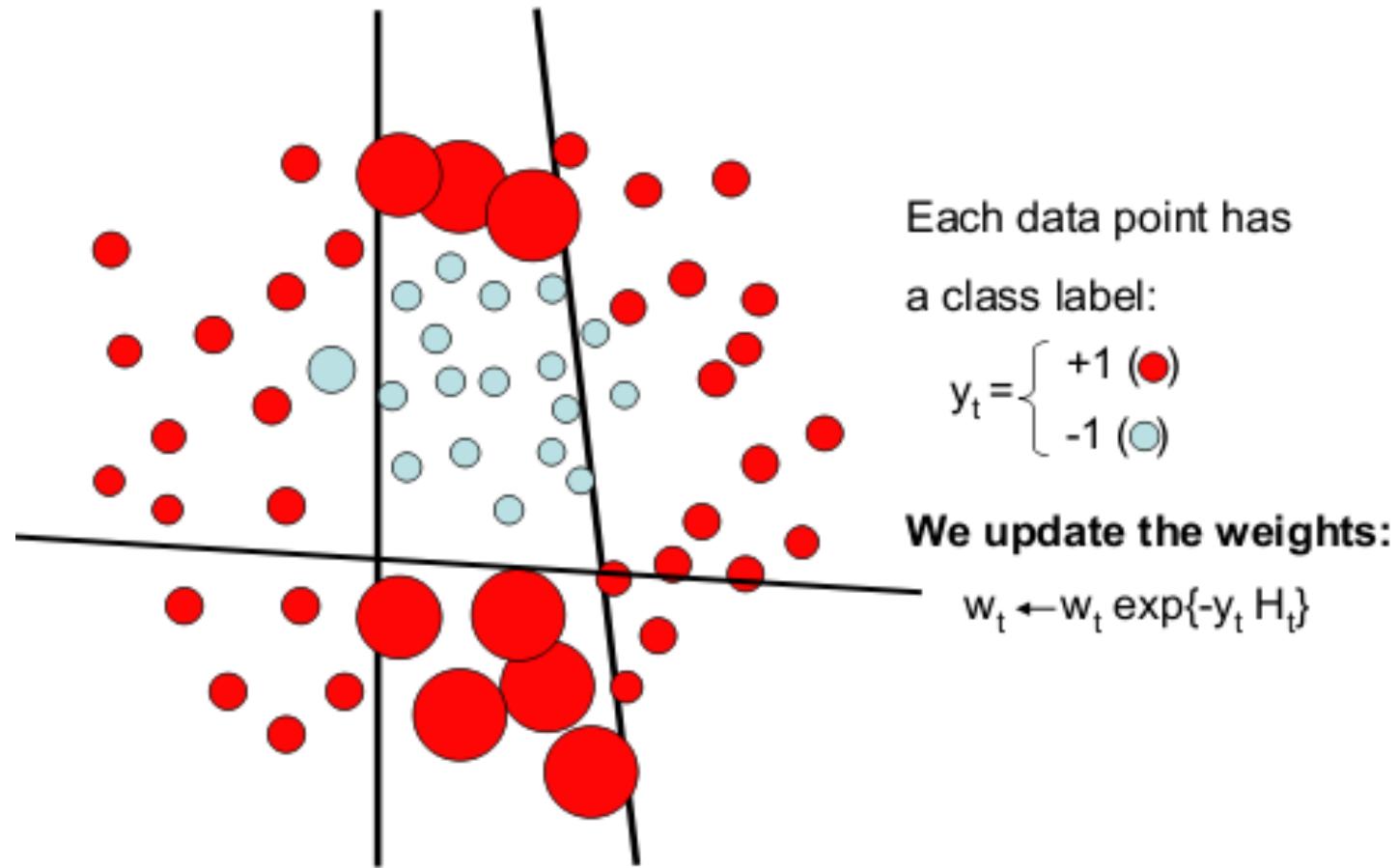
$$y_t = \begin{cases} +1 (\text{red}) \\ -1 (\text{light blue}) \end{cases}$$

We update the weights:

$$w_t \leftarrow w_t \exp\{-y_t H_t\}$$

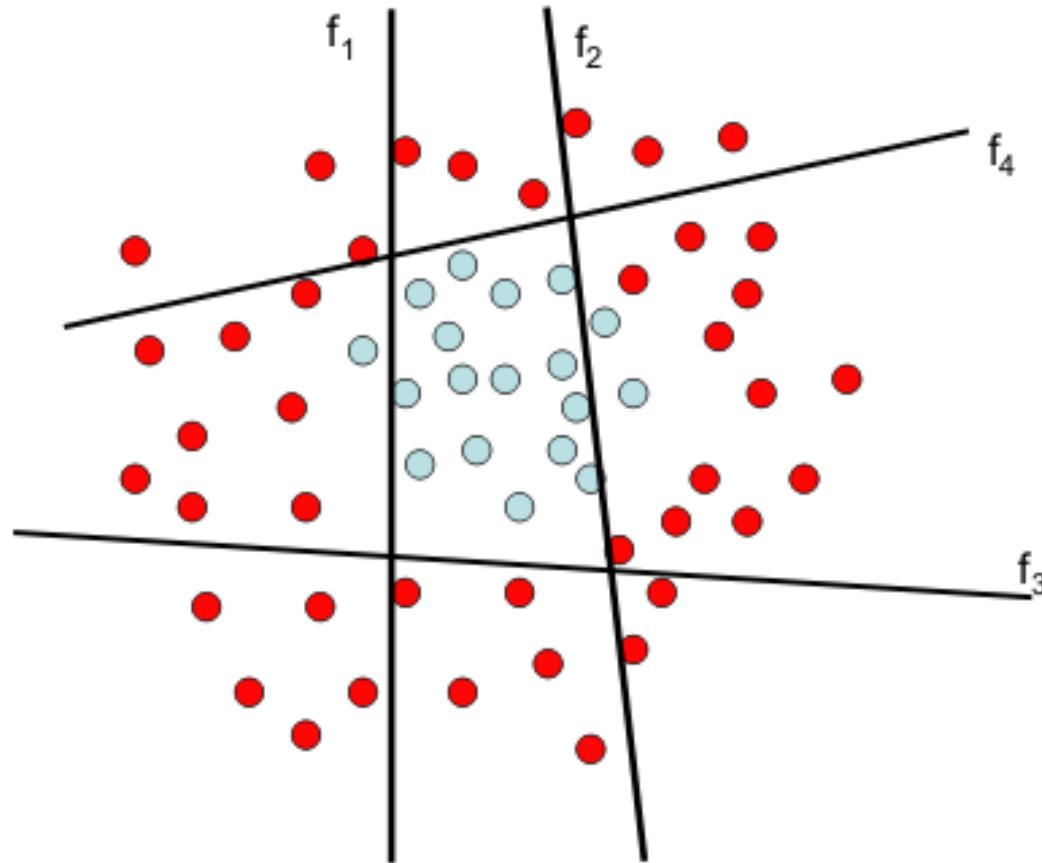
# Case I: Viola & Jones Face Detector

## Boost Classification



# Case I: Viola & Jones Face Detector

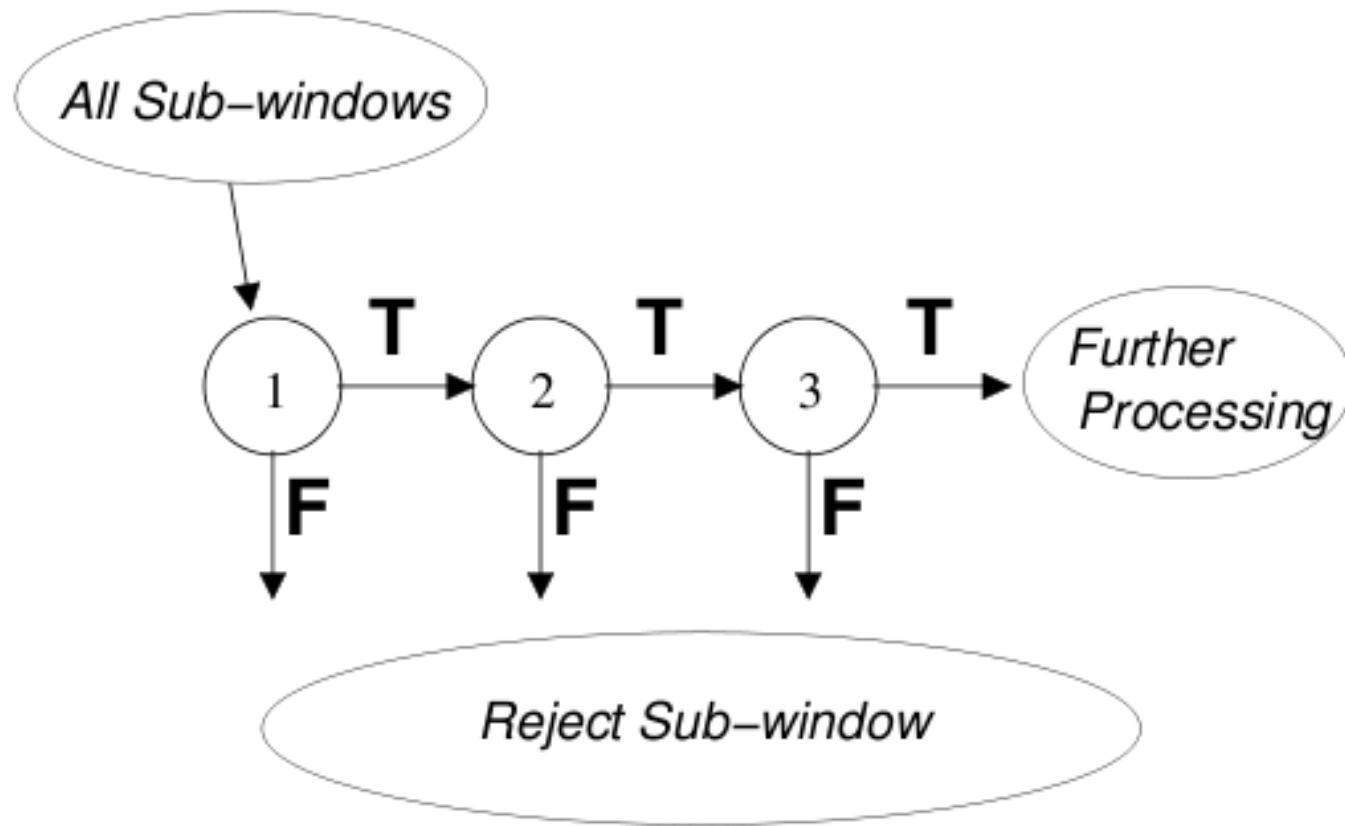
## Boost Classification



The strong (non- linear) classifier is built as the combination of all the weak (linear) classifiers.

# Case I: Viola & Jones Face Detector

Cascade of classifiers



# Case I: Viola & Jones Face Detector

Cascade of classifiers



# Case I: Viola & Jones Face Detector

Cascade of classifiers



# Case I: Viola & Jones Face Detector

Cascade of classifiers



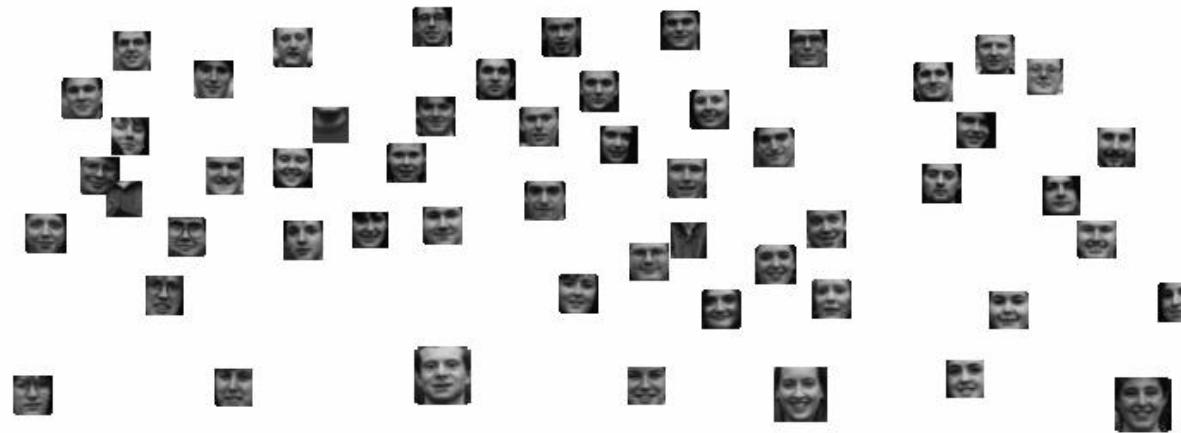
# Case I: Viola & Jones Face Detector

Cascade of classifiers



# Case I: Viola & Jones Face Detector

Cascade of classifiers

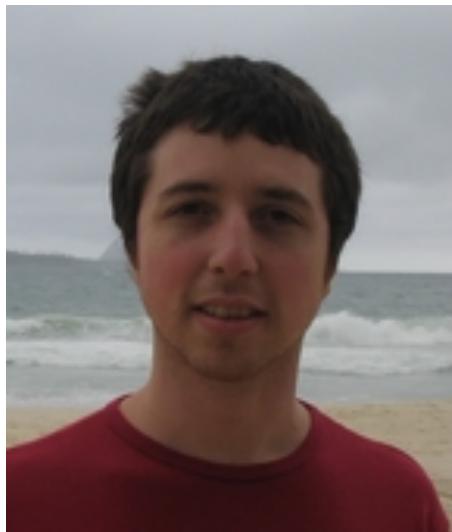


# Case I: Viola Jones Face Detector

- The processing time of a 384 by 288 pixel image on a conventional personal computer (back in 2001) about 0.067 seconds.
- Free implementation of it available as part of OpenCV

# Success Stories

Pictorial Structures...



Pedro Felzenszwalb  
MIT (1999-2003)  
Cornell University  
Chicago University  
Brown University (2011-now)



Daniel Huttenlocher  
Cornell University

# Case II: Pictorial Structures

## Efficient Matching of Pictorial Structures \*

Pedro F. Felzenszwalb  
 Artificial Intelligence Laboratory  
 MIT  
 Cambridge, MA 02139  
 pff@ai.mit.edu

Daniel P. Huttenlocher  
 Computer Science Department  
 Cornell University  
 Ithaca, NY 14853  
 dph@cs.cornell.edu

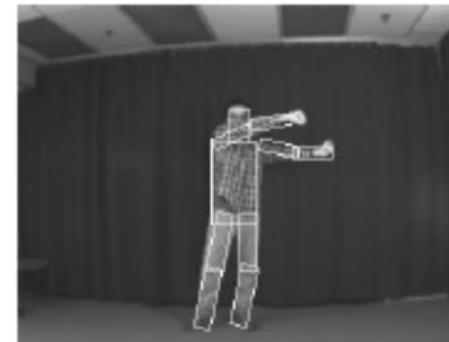
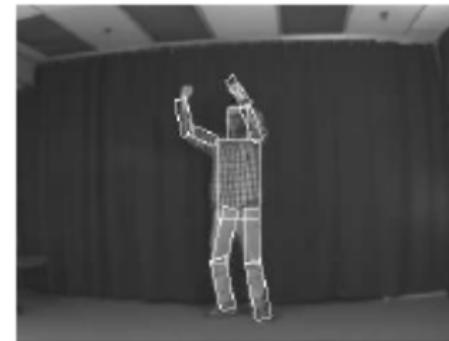
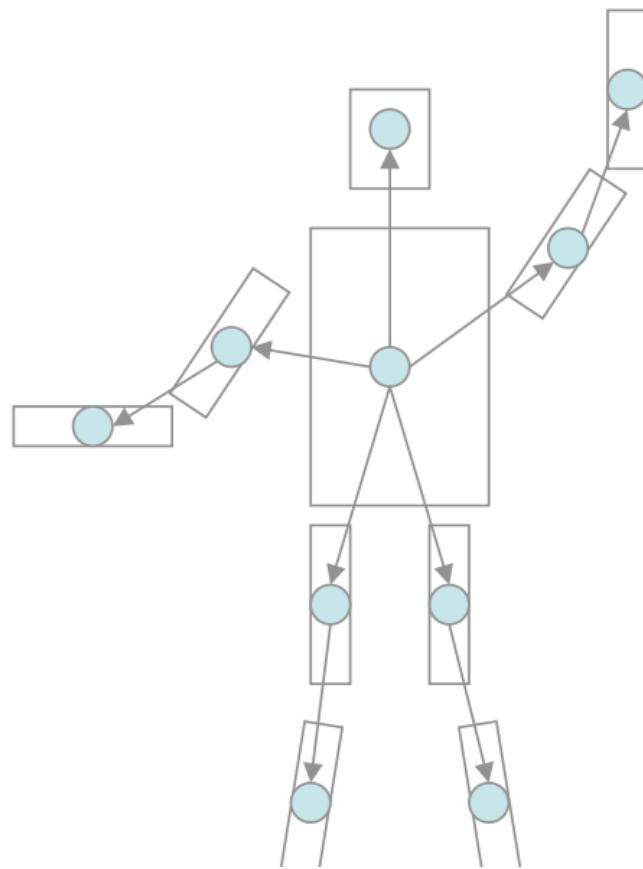
### Abstract

*A pictorial structure is a collection of parts arranged in a deformable configuration. Each part is represented using a simple appearance model and the deformable configuration is represented by spring-like connections between pairs of parts. While pictorial structures were introduced a number of years ago, they have not been broadly applied to matching and recognition problems. This has been due in part to the computational difficulty of matching pictorial structures to images. In this paper we present an efficient algorithm for finding the best global match of a pictorial structure to an image. The running time of the algorithm is optimal and it takes only a few seconds to match a model with five to ten parts. With this improved algorithm, pictorial structures provide a practical and powerful framework for qualitative descriptions of objects and scenes, and are suitable for many generic image recognition problems. We illustrate the approach using simple models of a person and a car.*

is providing a Bayesian interpretation of the problem, in terms of MAP estimation. The running time of our algorithm is optimal, in the sense that it runs as quickly as simply matching each part separately, without accounting for the relationships between parts. In practice the algorithm is also fast, finding the globally best match of a pictorial structure to an image in just a few seconds.

Pictorial structures provide a powerful framework for qualitative descriptions of objects and scenes, making them suitable for many generic image recognition problems. In [8] and in [7], pictorial structures were used to form generic models of a human face. Simple generic appearance models were used for parts such as the eyes, mouth, etc., and the connections between parts ensured that the geometric arrangement of the parts was face-like. In [16], pictorial structures were used to model generic scene concepts such as a waterfall, a snowy mountain, or a sunset. For example, a waterfall was modeled as a bright white region (water) in the middle of darker regions (rocks). The method

# Case II: Pictorial Structures



# Case II: Pictorial Structures

- Model is represented by a graph  $G = (V, E)$ .
  - $V = \{v_1, \dots, v_n\}$  are the parts.
  - $(v_i, v_j) \in E$  indicates a connection between parts.
- $m_i(l_i)$  is the cost of placing part  $i$  at location  $l_i$ .
- $d_{ij}(l_i, l_j)$  is a deformation cost.
- Optimal location for object is given by  $L^* = (l_1^*, \dots, l_n^*)$ ,

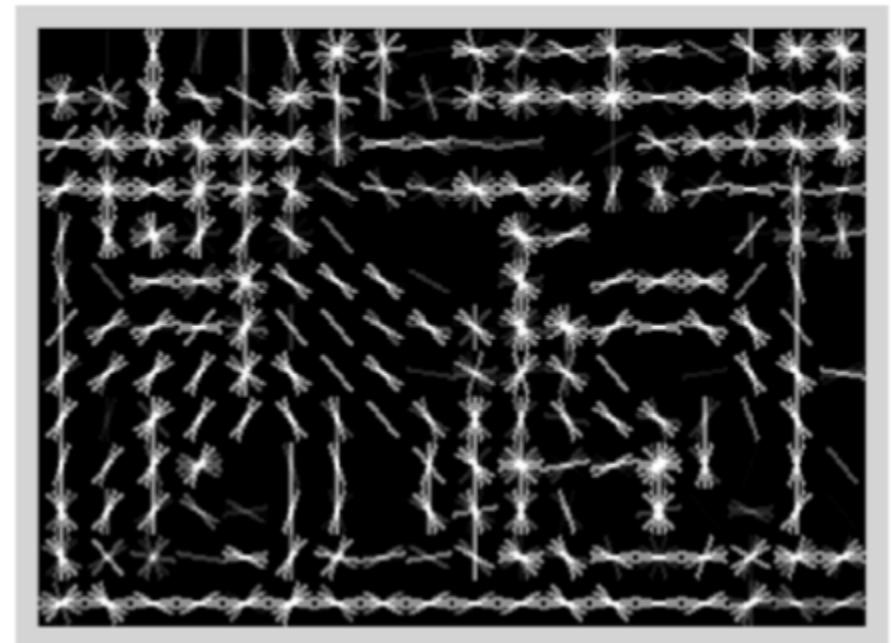
$$L^* = \operatorname{argmin}_L \left( \sum_{i=1}^n m_i(l_i) + \sum_{(v_i, v_j) \in E} d_{ij}(l_i, l_j) \right)$$

- $n$  parts and  $h$  locations gives  $h^n$  configurations.
- If graph is a tree we can use dynamic programming.

# Case II: Pictorial Structures

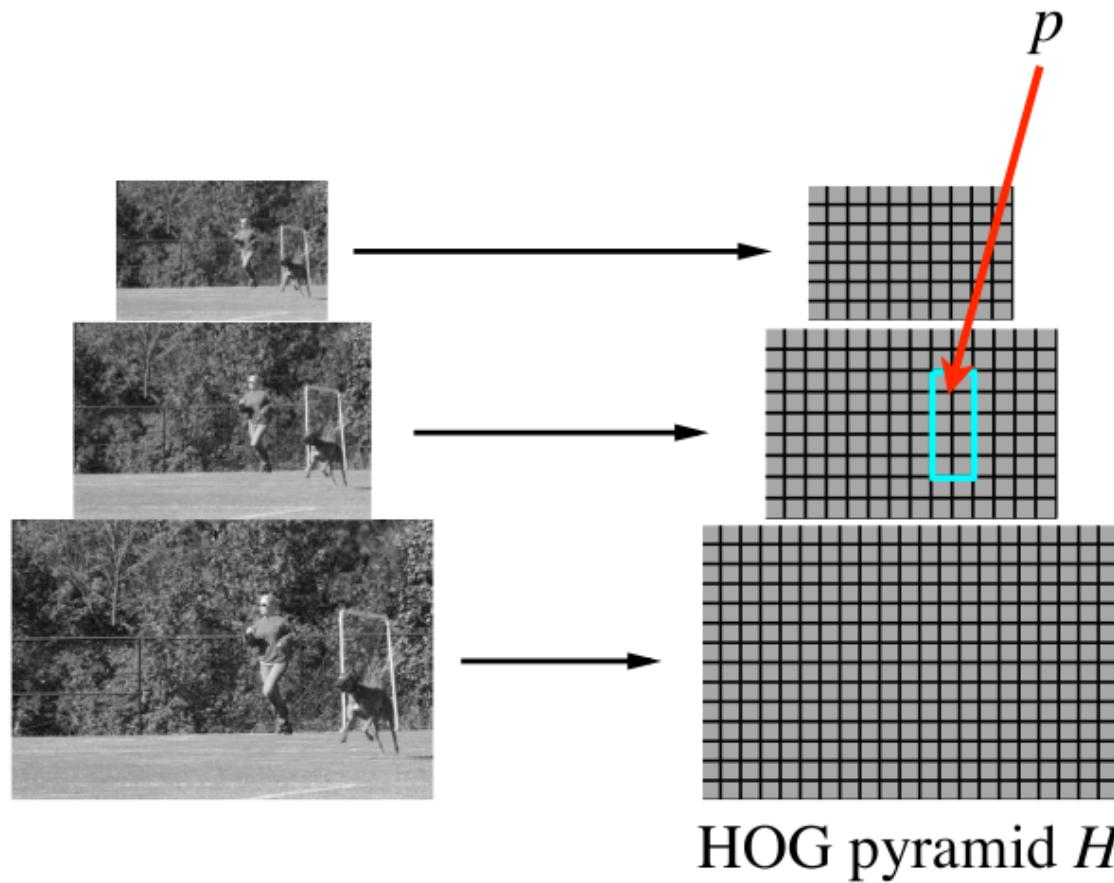
Parts can also be learnt from training data!

A complete framework for learning and detection of discriminative part-based models was proposed...

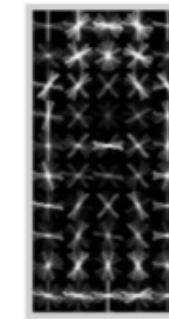


Histogram of Gradients (HoG) features

# Case II: Pictorial Structures



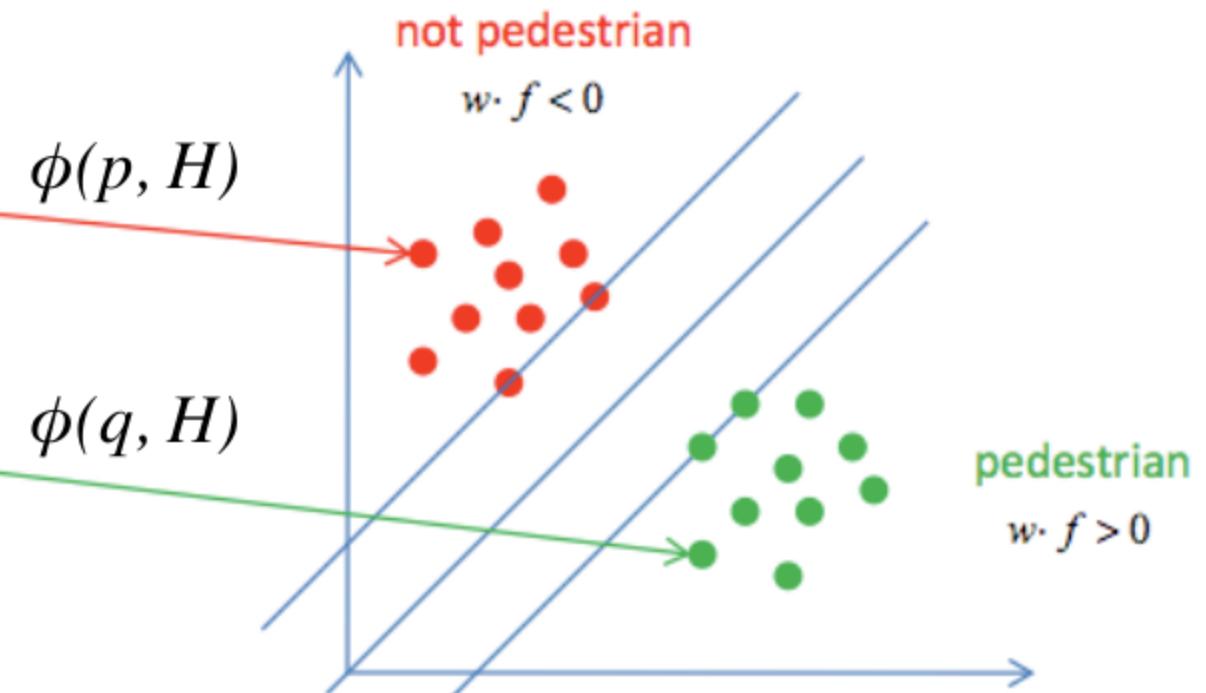
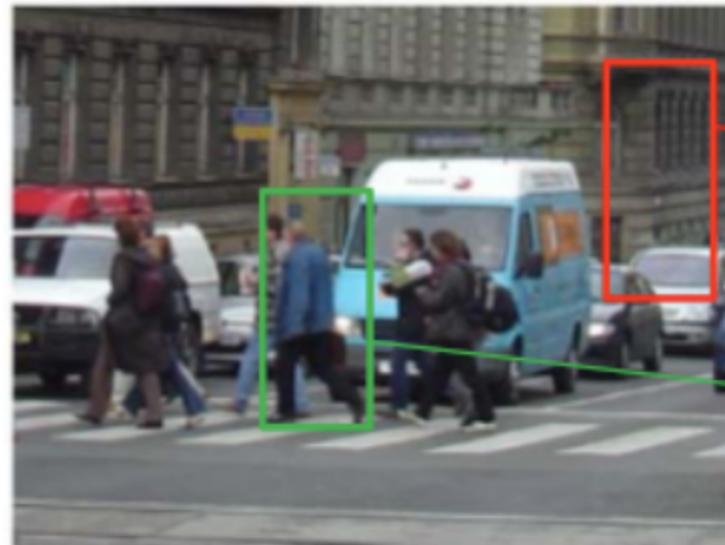
Filter  $F$



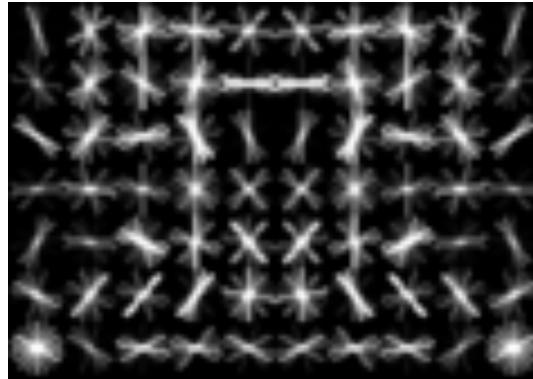
Score of  $F$  at position  $p$  is  
$$F \cdot \phi(p, H)$$

$\phi(p, H) =$  concatenation of  
HOG features from  
subwindow specified by  $p$

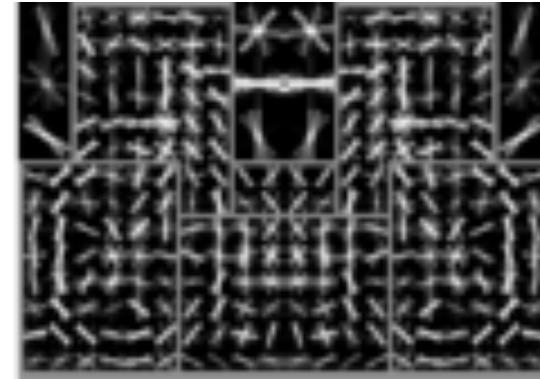
# Case II: Pictorial Structures



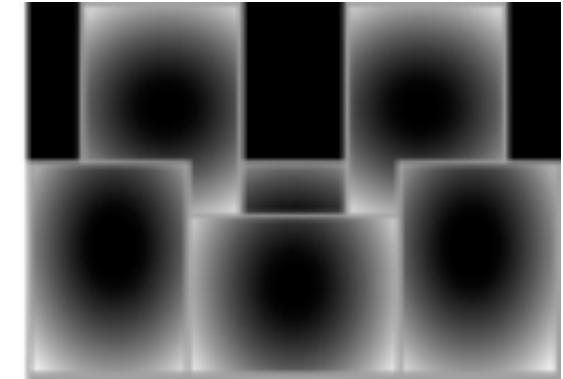
# Case II: Pictorial Structures



root filter



part-based filters



deformable model

$$\text{score}(p_0, \dots, p_n) = \sum_{i=0}^n F_i \cdot \phi(H, p_i) - \sum_{i=1}^n d_i \cdot (dx_i^2, dy_i^2)$$

“data term”

 $\sum_{i=0}^n F_i \cdot \phi(H, p_i)$ 

**filters**

“spatial prior”

 $\sum_{i=1}^n d_i \cdot (dx_i^2, dy_i^2)$ 

**displacements**

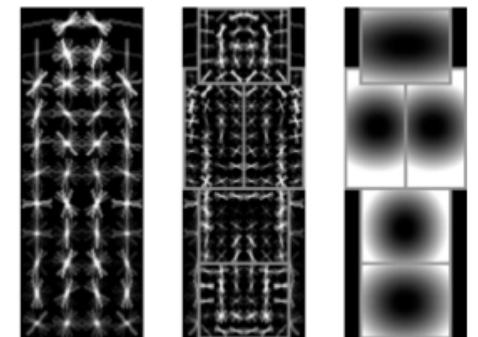
**deformation parameters**

# Case II: Pictorial Structures

Machine learning methods are needed for training



Training →



# The need for machine learning

- The PASCAL challenge



**PASCAL (2006)**  
- 5,304 images  
- 9,507 objects

# The need for machine learning

Pascal 2006 – Car category

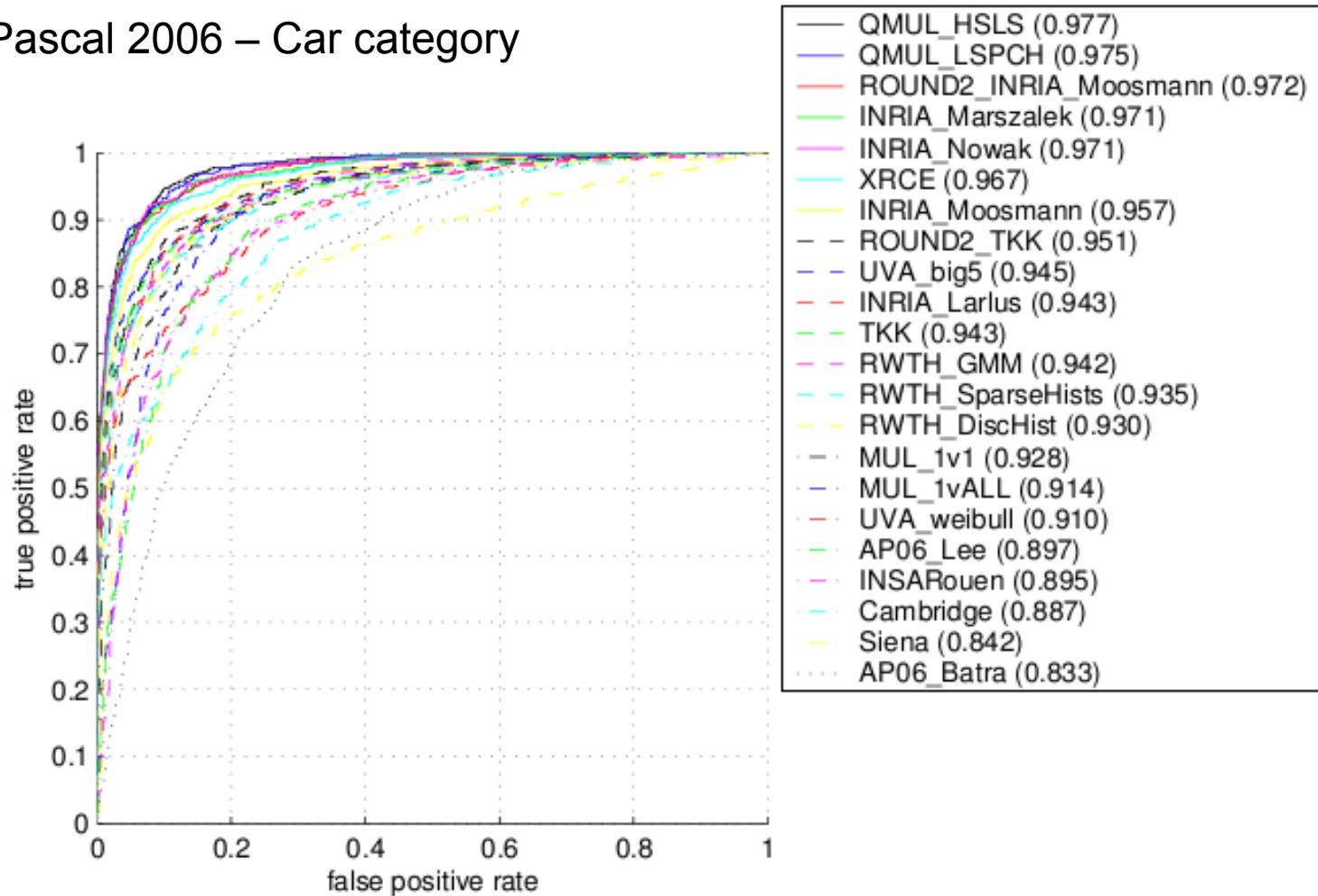


Figure 5: Competition 1.3: car (all entries)

# The need for machine learning



- 10,000,000 labeled images depicting 10,000+ object categories

# The need for machine learning



## Validation classification

<b>lens cap</b>	<b>abacus</b>	<b>slug</b>	<b>hen</b>
reflex camera Polaroid camera pencil sharpener switch combination lock	abacus typewriter keyboard space bar computer keyboard accordion	slug zucchini ground beetle common newt water snake	hen cock cocker spaniel partridge English setter
<b>tiger</b>	<b>chambered nautilus</b>	<b>tape player</b>	<b>planetarium</b>
tiger tiger cat tabby boxer Saint Bernard	lampshade throne goblet table lamp hamper	cellular telephone slot reflex camera dial telephone iPod	planetarium dome mosque radio telescope steel arch bridge

# Have we been saved?



Image size:  
800 × 600

No other sizes of this image found.

Best guess for this image: [\*\*golden gate bridge\*\*](#)

[\*\*Golden Gate Bridge\*\*](#)

[www.goldengatebridge.org/](http://www.goldengatebridge.org/)

**Golden Gate Bridge** Highway and Transportation District.

[\*\*Golden Gate Bridge - Wikipedia, the free encyclopedia\*\*](#)

[en.wikipedia.org/wiki/Golden\\_Gate\\_Bridge](http://en.wikipedia.org/wiki/Golden_Gate_Bridge)

The **Golden Gate Bridge** is a suspension bridge spanning the Golden Gate, the opening of the San Francisco Bay into the Pacific Ocean. As part of both U.S.  
... 14 images

[\*\*Visually similar images - Report images\*\*](#)



# But...

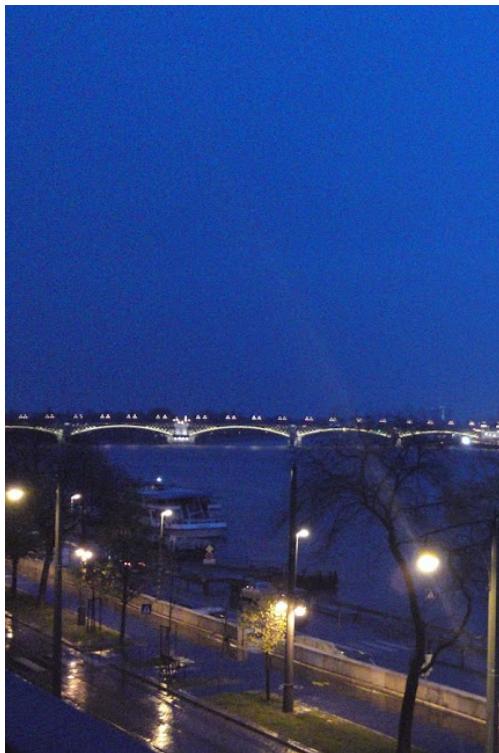


Image size:  
1152 × 648

No other sizes of this image found.

[Visually similar images](#) - Report images



# Conclusion

Vision problems have been increasingly solved using statistical inference

Training data and standardised datasets are a common practice in computer vision

But... might not work in unforeseen situations

... Different results for different datasets

... Computational complexity is still a bottleneck for real-time performance

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