view_frames Result Recorded at time: 18.709 odom Broadcaster: /gazebo Average rate: 10.204 Hz Most recent transform: 18.701 (0.008 sec old) Buffer length: 4.900 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (18.709 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (18.709 sec old) Most recent transform: 0.000 (18.709 sec old) Most recent transform: 18.701 (0.008 sec old) Most recent transform: 0.000 (18.709 sec old) Most recent transform: 0.000 (18.709 sec old) Most recent transform: 18.701 (0.008 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec camera_optical_link hokuyo left_wheel right_wheel camera_depth_frame caster