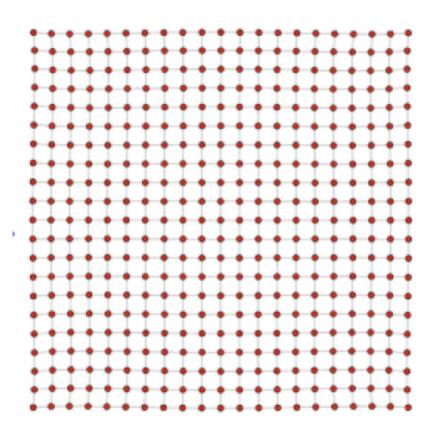
UNDIRECTED MODELS

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Reading: Murphy, §19.1-19.5.1

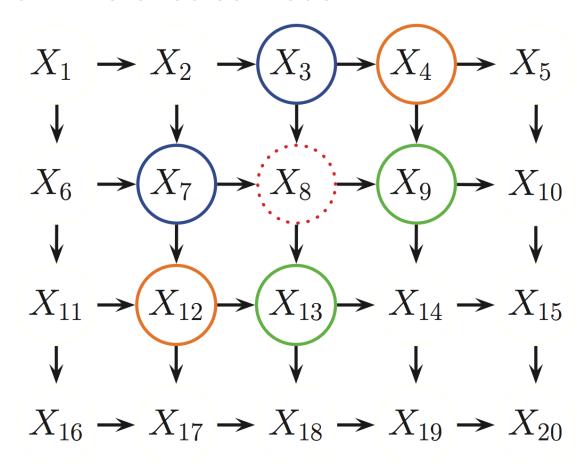
How to model an image?

Or crop yields, or the height of the earth, or...



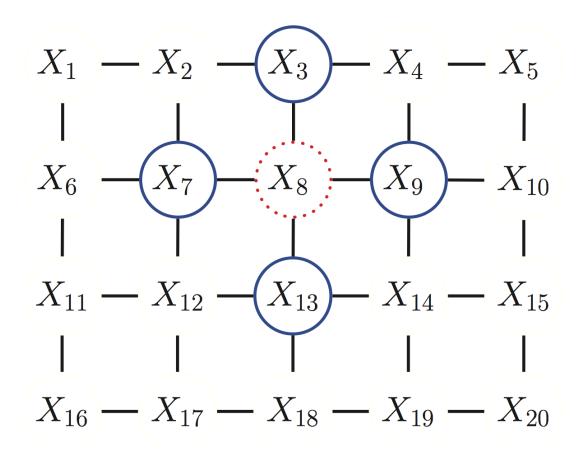
How to model an image?

Awkward with a directed model



How to model an image?

Sometimes, prefer the Markov blanket is all <u>neighbors</u>.



Definition

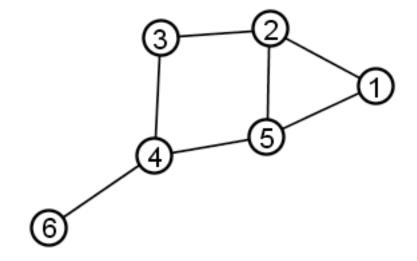
• A probability distribution over x is a Markov random field (or undirected model) with respect to a graph G if

 $x_A \perp x_B | x_C$ if and only if C separates A from B in G.

for all A, B, C.

Which is true?

- $A) x_1 \perp x_3 | x_2 |$
- B) $x_1 \perp x_3 | x_{2,4}$
 - $(C) x_1 \perp x_3 | x_{2,5}$
 - $D) x_6 \perp x_1 | x_{2,3,4,5}$
 - $(E) x_6 \perp x_1 | x_{2,4}$
 - $F) x_6 \perp x_1 | x_4 |$
 - $G) x_6 \perp x_1 | x_2$
 - $H) x_{6,1} \perp x_{3,5} | x_{2,4}$
 - I) $x_{6,1} \perp x_{3,5} | x_4$



Which is true?

true
$$A$$
) $x_1 \perp x_3 | x_2$

true B) $x_1 \perp x_3 | x_{2,4}$

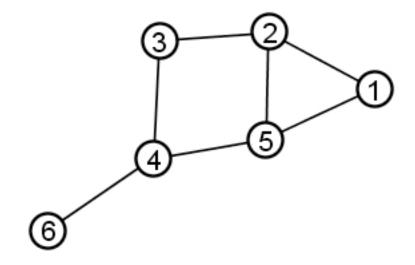
true C) $x_1 \perp x_3 | x_{2,5}$

true D) $x_6 \perp x_1 | x_{2,3,4,5}$

true E) $x_6 \perp x_1 | x_{2,4}$
 F) $x_6 \perp x_1 | x_4$

true G) $x_6 \perp x_1 | x_2$

true H) $x_{6,1} \perp x_{3,5} | x_{2,4}$
 I) $x_{6,1} \perp x_{3,5} | x_4$



Definition

• A probability distribution over x is a Markov random field (or undirected model) with respect to a graph G if

 $x_A \perp x_B | x_C$ if and only if C separates A from B in G.

for all A, B, C.

... But how to we actually write down such a p(x)?

How do we write down all such p(x)??

Hammersley-Clifford Theorem

- Varying esteem for this theorem among your lecturers.

- History:

- Proved by Hammersley and Clifford in 1971 using a "blackening algebra"
- H&C didn't like the positivity condition. Delayed publishing in the hopes of getting rid of it.
- Besag proved/published theorem in 1974. (5073 citations to date!)
 - Also, Grimmett, Preston and Sherman, same year.
- Moussouris in 1974 gave an example with 4 nodes that needs positivity.

Hammersley-Clifford Theorem

• A positive distribution p(x) > 0 is an MRF with respect to a graph G if and only if p(x) can be represented as

$$p(x|\theta) = \frac{1}{Z(\theta)} \prod_{c \in \mathcal{C}} \psi_c(x_c|\theta_c)$$

where C is the set of all cliques, and

$$Z(\theta) = \sum_{x} \prod_{c \in \mathcal{C}} \psi_c(x_c | \theta_c)$$

is the partition function.

Notes:

- This isn't obvious!
- No direct probabilistic interpretation for ψ .

Hammersley-Clifford Theorem

Proof sketch:

- Assumes $x_i \in 0, 1, 2, ..., K_i$.
- It's easy to show that $p(x|\theta) = \frac{1}{Z(\theta)} \prod_{c \in \mathcal{C}} \psi_c(x_c|\theta_c)$ obeys this conditional independence assumptions of a graph.
- Instead, we start with a arbitrary distribution that obeys the conditional independence assumptions, and show that it can indeed be written like this.

Define $x^* = (0, 0, ..., 0)$ and $Q(x) := \ln(p(x)/p(x^*))$.

Step 1: Can write Q uniquely as:

$$Q(x) = \sum_{i} x_{i}G_{i}(x_{i}) + \sum_{i < j} x_{i}x_{j}G_{ij}(x_{i}, x_{j}) + \sum_{i < j < k} x_{i}x_{j}x_{k}G_{ijk}(x_{i}, x_{j}, x_{k}) + \dots + x_{1}x_{2}\dots x_{n}G_{12\dots n}(x_{1}, x_{2}, \dots, x_{n})$$

Step 2: Define $x^i=(x_1,...,x_{i-1},0,x_{i+1},...,x_n)$. Then, $\exp(Q(x)-Q(x^i))=\frac{p(x)}{p(x^i)}=\frac{p(x_i|x_{-i})}{p(0|x_{-i})}$

Step 3: Pick node 1 w.o.l.o.g. Then, write

$$Q(x) - Q(x^{1}) = x_{1}(G_{1}(x_{1}) + \sum_{1 < j} x_{j}G_{1j}(x_{1}, x_{j}) + \sum_{1 < j < k} x_{j}x_{k}G_{1jk}(x_{i}, x_{j}, x_{k}) + \dots + x_{2}\dots x_{n}G_{12\dots n}(x_{1}, x_{2}, \dots, x_{n}))$$

Step 4: Suppose t is not a neighbor of 1. All terms involving x_t must be zero.

Why? A) $Q(x)-Q(x^1)$ is independent of x_t since $p(x_i|x_{-i})$ is. B) If we set $x_i=0, i\not\in\{1,t\}$ then G_{1t} must be zero.

C) Similarly for third/fourth/n-th order terms

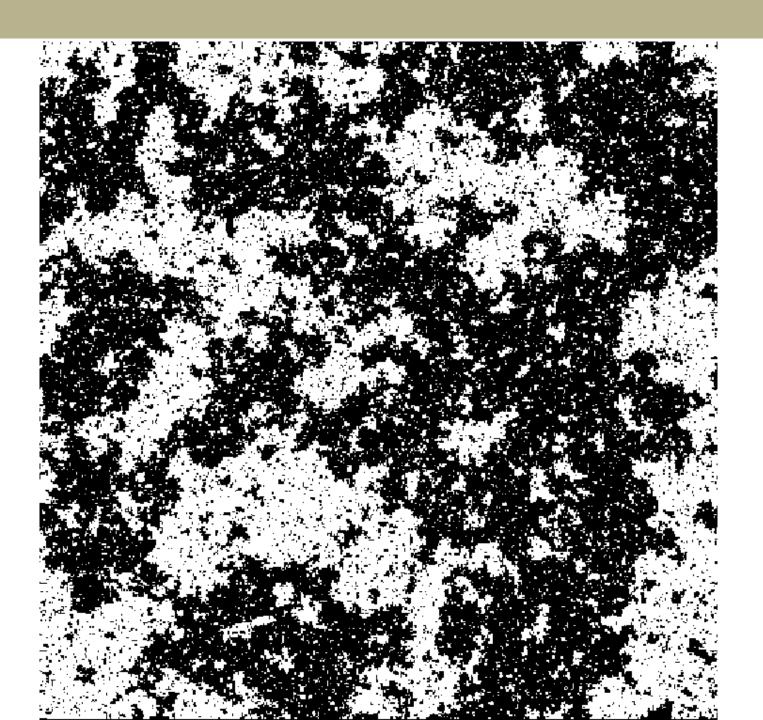
Example: Ising Model

- Invented by Lenz in 1920, given to Ising.
 - Used by physicists to understand phase transitions and magnetism.
- Assume Binary States

$$x_i \in \{-1, +1\}$$

Univariate ("field") and pairwise terms

$$p(x) = \frac{1}{Z} \prod_{s} \exp(b_s x_s) \prod_{(s,t)} \exp(w_{st} x_s x_t)$$



Learning Markov Random Fields

- For now, we are interested in parameter learning.
- Maximum-Likelihood Learning. Given $x^1, x^2, ..., x^D$, we want to pick θ to maximize

$$\prod_{d=1}^{D} p(x^d | \theta)$$

Convenient to re-formulate this as

$$\arg \max_{\theta} \frac{1}{D} \sum_{d=1}^{D} \log p(x^d | \theta)$$

• First problem: Given θ , how high does it score?

Learning Markov Random Fields

$$\arg\max_{\theta} \frac{1}{D} \sum_{d=1}^{D} \log p(x^d | \theta)$$

$$= \arg \max_{\theta} \frac{1}{D} \sum_{d=1}^{D} \log \left(\frac{1}{Z(\theta)} \prod_{c \in \mathcal{C}} \psi_c(x_c^d | \theta_c) \right)$$

$$= \arg \max_{\theta} \frac{1}{D} \sum_{d=1}^{D} \sum_{c \in \mathcal{C}} \log \psi_c(x_c^d | \theta_c) - \log(Z(\theta))$$

This is easy to compute.

This is hard, since

$$Z(\theta) = \sum_{x} \prod_{c \in \mathcal{C}} \psi_c(x_c | \theta_c)$$

Computing Z

Does this remind you of belief propagation?

Suppose we have a simple chain:

$$p(x) = \frac{1}{Z}\psi(x_{1,2})\psi(x_{2,3})\psi(x_{3,4})...\psi(x_{n-1,n})$$

$$Z = \sum_{x} \psi(x_{1,2}) \psi(x_{2,3}) \psi(x_{3,4}) ... \psi(x_{n-1,n})$$

How to compute Z? Well, we could define

$$T_i(x_i) = \sum_{x_1,...x_{i-1}} \psi(x_{1,2})...\psi(x_{i-1},x_i)$$

Then we have the simple recurrence that

$$T_1(x_1) = 1$$
 $T_{i+1}(x_{i+1}) = \sum_{x_1, \dots x_i} T_i(x_i) \psi(x_i, x_{i+1})$

And, finally,

$$Z = \sum_{x_n} T_n(x_n)$$

What to take home

- Definition of MRFs in terms of conditional independence and separation.
- The Hammersley-Clifford theorem, why it is very surprising and wondeful, and how to prove it.
- How learning an MRF requires computing the (log)
 partition function, and how the difficulty of computing the
 log-partition function is connected to the difficulty of
 computing marginals.