



TREASURE HUNT - RF EDITION

PROJECT FOR ADVANCED TOPICS IN COMPUTER NETWORKS

TEAM B

DALLAS DIMITRIS 2412

MAROULIS MANOS 2465

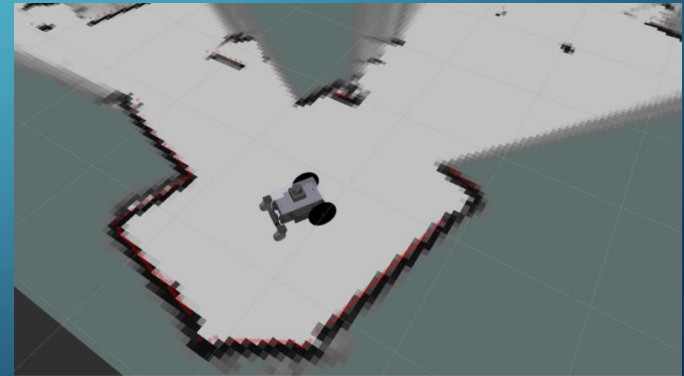
INTRODUCTION

- Find the Transmitter in the room based on RSSI
- Present a spectrum heatmap based on the recorded data.
- Equipment
 - 2x Adalm-Pluto SDR
 - 2x Raspberry Pi
 - Unmanned ground Rover
 - RP-LiDAR A1-M8
 - Handmade directional antenna

TOOLS

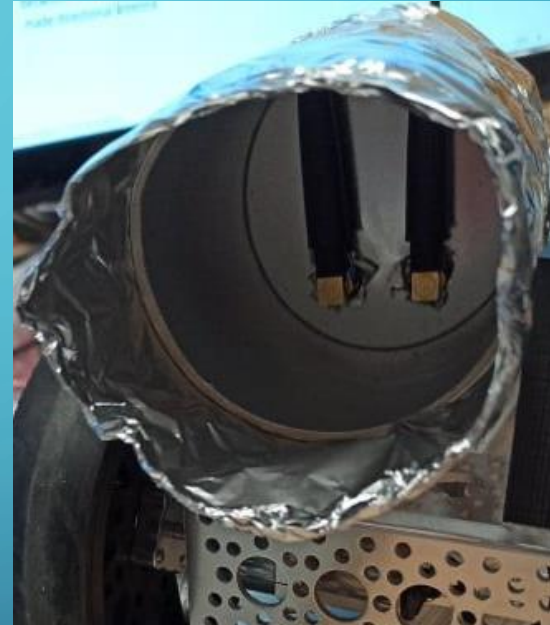
- What is ROS
- Mapping procedure
 - RP-LiDAR A1-M8, range finder sensor
 - SLAM algorithm
- Coordinates and goal
- Recovery behavior
- What is SDR and RSSI
 - AD9364 RF chip, 70MHz -6GHz
- Python APIs for libiio

ROS



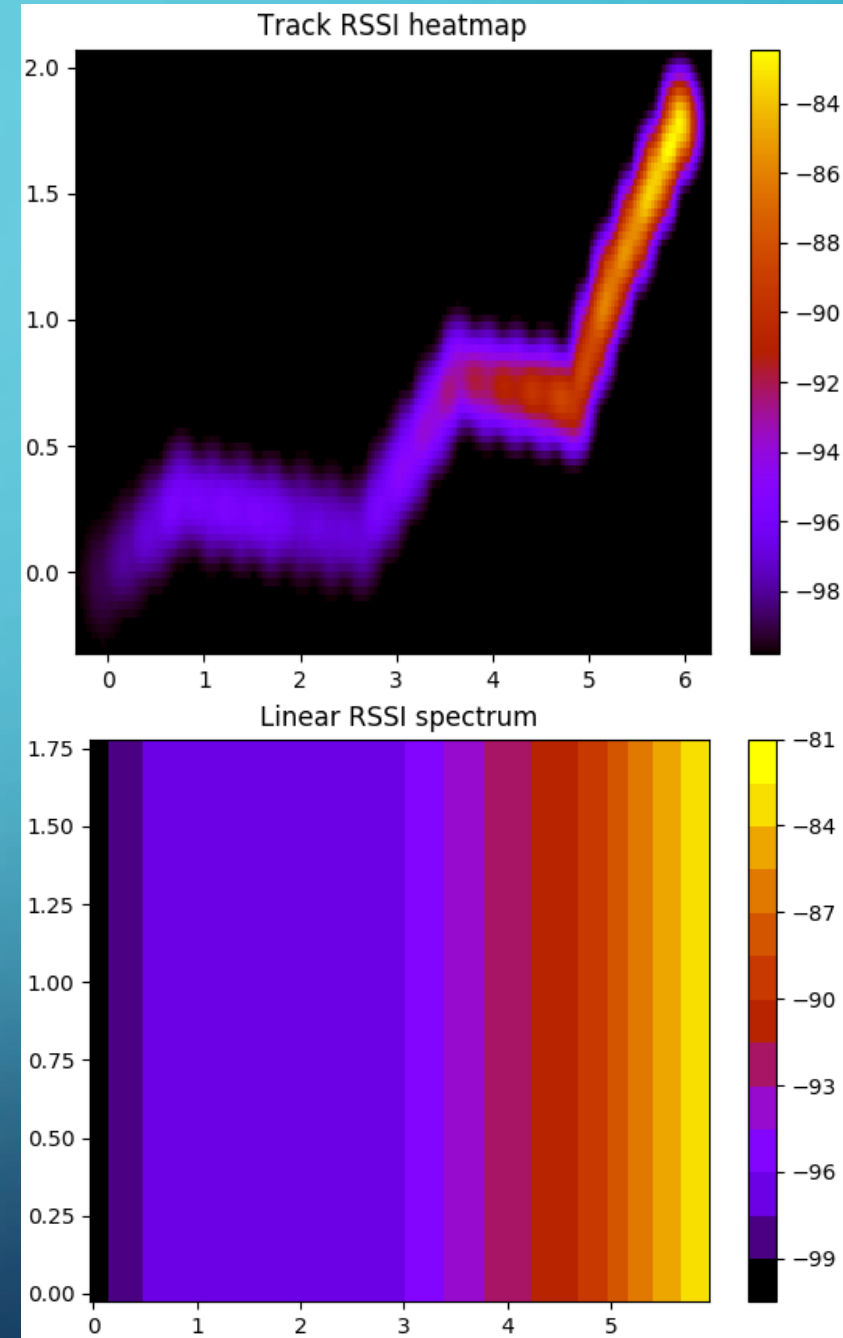
IMPLEMENTATION

- TX-RX properties
 - Transmitting IQ with TX buffer
 - No self-reception
- Stabilizing Measurements
 - Clearing bias
- Directional Antenna
- Robot Algorithm walkthrough
- Custom recovery



IMPLEMENTATION

- Dataset
 - "Virtual" scatter data points
 - Fill in the gaps
- Vehicle Route Heatmap
 - Kernel Density Estimation
- Linear Spectrum



A decorative graphic on the left side of the slide, consisting of a network of white lines and small circles on a blue gradient background, resembling a circuit board or a stylized tree structure.

THANK YOU FOR YOUR TIME