## On the signature matrix of semantic property

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## Notation

L: the number of semantic dimensions

K: the number of semantic dimensions in a property represented as K-polytope

N: number of semantic aspects in a property

 $\mathcal{P}$ : set of points forming the K-polytope of a semantic property

 $A_i$ : denotes the *i*-th semantic aspect of a semantic property

 $P_i$ : denotes semantic property

 $V_i$ : denotes primitive semantic particle

 $\vec{p}_c$ : in the context of a property: the center of mass of the property
In the context of an ensemble of properties: the center of mass of the ensemble

 $\vec{p}_i$ : In the context of a property: semantic position of the aspect  $A_i$ In the context of an ensemble of properties: the center of mass of the property

 $l_i$ : the type of the aspect  $A_i$ 

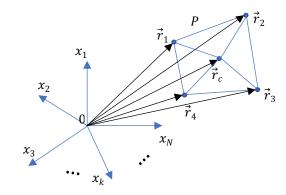
 $\theta_i$ : angle between the current aspect and semantic axis  $x_i$ 

 $oldsymbol{ heta}$  : a vector with all angular coordinates of the current aspect to the semantic axes

$$\vec{r}_{c} = \frac{\sum_{i=1}^{|\mathcal{P}|} m_{i} \vec{r}_{i}}{\sum_{l=1}^{|\mathcal{P}|} m_{l}}$$
 (1)

$$\mathsf{If}\, \mathsf{m}_l = \mathsf{m} = const$$

$$\vec{r}_c = \frac{\sum_{i=1}^{|\mathcal{P}|} \vec{r}_i}{|\mathcal{P}|}$$
 (2)



$$\vec{p}_i = \vec{r}_i - \vec{r}_c \tag{3}$$

$$\vec{p}_i = \left(1 - \frac{m_i}{\sum_{l=1}^{|\mathcal{P}|} m_l}\right) \vec{r}_i - \sum_{j=1, j \neq i}^{|\mathcal{P}|} \frac{m_j}{\sum_{l=1}^{|\mathcal{P}|} m_l} \vec{r}_j$$
 (4)

With 
$$\widehat{\mathfrak{m}}_i = \frac{\mathfrak{m}_i}{\sum_{l=1}^{|\mathcal{P}|} \mathfrak{m}_l}$$
 we write:

$$\vec{p}_i = (1 - \widehat{\mathbf{m}}_i)\vec{r}_i - \sum_{j=1, j \neq i}^{|\mathcal{P}|} \widehat{\mathbf{m}}_j \vec{r}_j$$
 (5)

In a matrix form:

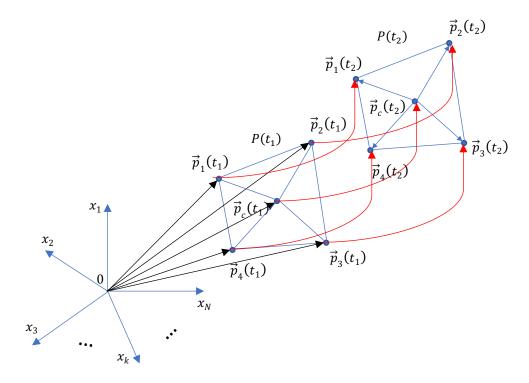
$$P = \begin{bmatrix} 1 - \widehat{\mathfrak{m}}_1 & -\widehat{\mathfrak{m}}_2 & \cdots & -\widehat{\mathfrak{m}}_N \\ -\widehat{\mathfrak{m}}_1 & 1 - \widehat{\mathfrak{m}}_2 & \cdots & -\widehat{\mathfrak{m}}_N \\ \vdots & \vdots & \vdots & \vdots \\ -\widehat{\mathfrak{m}}_1 & -\widehat{\mathfrak{m}}_2 & \cdots & 1 - \widehat{\mathfrak{m}}_N \end{bmatrix} \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_N \end{pmatrix}$$
(6)

or succinctly

$$P = MX$$
 (7)

where 
$$M = \begin{bmatrix} 1 - \widehat{\mathfrak{m}}_1 & -\widehat{\mathfrak{m}}_2 & \cdots & -\widehat{\mathfrak{m}}_N \\ -\widehat{\mathfrak{m}}_1 & 1 - \widehat{\mathfrak{m}}_2 & \cdots & -\widehat{\mathfrak{m}}_N \\ \vdots & \vdots & \vdots & \vdots \\ -\widehat{\mathfrak{m}}_1 & -\widehat{\mathfrak{m}}_2 & \cdots & 1 - \widehat{\mathfrak{m}}_N \end{bmatrix} X = \begin{bmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,L} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,L} \\ \vdots & \vdots & \vdots & \vdots \\ x_{N,1} & x_{N,2} & \cdots & x_{N,L} \end{bmatrix}$$
 (8)

While P is traversing the semantic space each aspect  $A_i$  retains its properties – this means that each  $\vec{p}_i$  is invariant when P traverses semantic space. That is -  $l_i$  and  $\theta_i$  remain constant.



The last statement, obviously, implies that there does not exist inverse matrix  $M^{-1}$  as the set of  $N \times N$  matrices X which map to a given matrix P is a continuum.