The Notion of Emotions

Emotions are a type of heuristic mechanism that plays important role in making future decisions within the Semantic State Machine. Emotions record negative or positive historical experiences and predetermine future decisions which are semantically related to past decisions and past experiences to which there have been attributed emotions of similar sign and order of magnitude. It is important to understand that in order to experience positive or negative emotion the current environment (or context) does not need to be identical or equivalent to a past context. Rather it needs to bear a sufficient degree of semantic similarity. To put this definition on more precise footing let us define the following objects:

 E_0 : original state of the environment

 C_0 : a historical context at moment t0

 CT_0 : a chain of thoughts $T_0 \to T_1 \to T_2 \to ... \to T_k$ in context C_0

 ${\it D}_0$: decision resulting from the context ${\it C}_0$ and the thought chain ${\it CT}_0$

 $E_{changed}$: state of environment modified after the execution of decision D_0

 $C_{changed}$: a changed context created after the execution of decision D_0

 CT^0 : a chain of thoughts $T^0(D_0) \to T^1(D_0) \to T^2(D_0) \to ... \to T^l(D_0)$ generated in the context $C_{changed}$. All the thoughts in the chain are conditionally dependent on the decision D_0 which is one of the reasons for the changed environment $E_{changed}$.

 SE_0 : a set of Sensibility structures affected by the changed environment $E_{changed}$.

 EM_0 : a set of emotions produced after the Sensibility structures SE_0 interact with the changed environment through a chain of thoughts CT^0 generated as a result of the changed environment $E_{changed}$.

The set of emotions EM_0 are associated with the semantic signature of the chain of thoughts CT_0 in the context C_0 . Let us assume that after some period of time a context C_1 is created and a chain of thoughts CT_1 is generated in it. Let us assume that there is a subset of semantic dimensions $\mathfrak D$ in which $sdist(sig(CT_0(C_0))[\mathfrak D], sig(CT_1(C_1))[\mathfrak D]) < \gamma$