

On the signature matrix of semantic property

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Notation

L : the number of semantic dimensions

K : the number of semantic dimensions in a property represented as K -polytope

N : number of semantic aspects in a property

\mathcal{P} : set of points forming the K -polytope of a semantic property

A_i : denotes the i -th semantic aspect of a semantic property

P_i : denotes semantic property

V_i : denotes primitive semantic particle

\vec{r}_c : in the context of a property: the center of mass of the property

In the context of an ensemble of properties: the center of mass of the ensemble

\vec{p}_i : In the context of a property: semantic position of the aspect A_i

In the context of an ensemble of properties: the center of mass of the property

l_i : the type of the aspect A_i

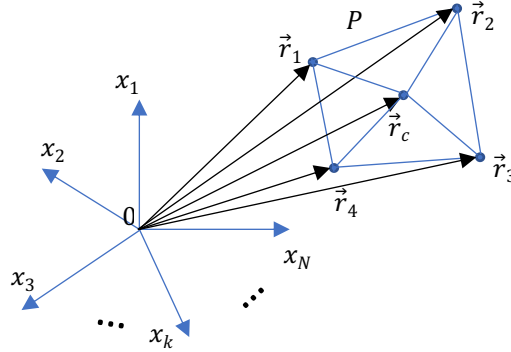
θ_j : angle between the current aspect and semantic axis x_j

Θ : a vector with all angular coordinates of the current aspect to the semantic axes

$$\vec{r}_c = \frac{\sum_{i=1}^{|\mathcal{P}|} m_i \vec{r}_i}{\sum_{i=1}^{|\mathcal{P}|} m_i} \quad (1)$$

If $m_l = m = \text{const}$

$$\vec{r}_c = \frac{\sum_{i=1}^{|\mathcal{P}|} \vec{r}_i}{|\mathcal{P}|} \quad (2)$$



$$\vec{p}_i = \vec{r}_i - \vec{r}_c \quad (3)$$

$$\vec{p}_i = \left(1 - \frac{m_i}{\sum_{l=1}^{|\mathcal{P}|} m_l}\right) \vec{r}_i - \sum_{j=1, j \neq i}^{|\mathcal{P}|} \frac{m_j}{\sum_{l=1}^{|\mathcal{P}|} m_l} \vec{r}_j \quad (4)$$

With $\hat{m}_i = \frac{m_i}{\sum_{l=1}^{|\mathcal{P}|} m_l}$ we write:

$$\vec{p}_i = (1 - \hat{m}_i) \vec{r}_i - \sum_{j=1, j \neq i}^{|\mathcal{P}|} \hat{m}_j \vec{r}_j \quad (5)$$

In a matrix form:

$$P = \begin{bmatrix} 1 - \hat{m}_1 & -\hat{m}_2 & \cdots & -\hat{m}_N \\ -\hat{m}_1 & 1 - \hat{m}_2 & \cdots & -\hat{m}_N \\ \vdots & \vdots & \ddots & \vdots \\ -\hat{m}_1 & -\hat{m}_2 & \cdots & 1 - \hat{m}_N \end{bmatrix} \begin{Bmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_N \end{Bmatrix} \quad (6)$$

or succinctly

$$P = MX \quad (7)$$

$$\text{where } M = \begin{bmatrix} 1 - \hat{m}_1 & -\hat{m}_2 & \cdots & -\hat{m}_N \\ -\hat{m}_1 & 1 - \hat{m}_2 & \cdots & -\hat{m}_N \\ \vdots & \vdots & \ddots & \vdots \\ -\hat{m}_1 & -\hat{m}_2 & \cdots & 1 - \hat{m}_N \end{bmatrix} \quad X = \begin{bmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,L} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,L} \\ \vdots & \vdots & \ddots & \vdots \\ x_{N,1} & x_{N,2} & \cdots & x_{N,L} \end{bmatrix} \quad (8)$$

Obviously, there does not exist inverse matrix M^{-1} as the set of matrices X which map to a given matrix P is a continuum.