## Practical Examples Using Semantic Simulation With Reinforcement Learning D. Gueorguiev 12/4/2022

## The Game Addition

Let us consider the game *Addition* described in *Blackwell's Theory of Games and Statistical Decisions* (Blackwell & Girshik, 1978, p. 14):

I and II alternatively choose integers, each choice being one of the integers 1, ..., k and each choice made with the knowledge of all preceding choices. As soon as the sum of the chosen integers exceeds N, the last player to choose pays his opponent one unit.

The situation at which player I finds himself at his rth move is described by a sequence  $s_r = (i_1, i_2, ..., i_{2r-2})$  with each  $i_i$  being one of the integers 1, ..., k and

$$\sum_{j=1}^{2r-2} i_j \le N$$

Denote by  $S_r$  the set of possible sequences  $s_r$  where  $r=2,...,\left[\frac{N}{2}\right]+1$  and [z] denotes the closest integer which does not exceed z. A strategy x for I consists of a set of  $\left[\frac{N}{2}\right]+1$  functions  $f_1,...,f_{\left[\frac{N}{2}\right]+1}$ , where  $f_r$  is a function defined on  $S_r$  assuming only values 1,2,...,k:  $f_r$  specifies I's rth move when the previous history of the play is  $s_r$ . Similarly, a strategy p for p is a set of p functions p functions

$$\sum_{j=1}^{2r-1} i_j \le N$$

Define 
$$i_1(x, y) = f_1$$
 and inductively for  $j > 0$ ,  $i_{2j}(x, y) = g_j \left( i_1(x, y), ..., i_{2j-1}(x, y) \right)$   $i_{2j+1}(x, y) = f_{j+1} \left( i_1(x, y), ..., i_{2j}(x, y) \right)$ 

(this induction describes the manner in which a referee would carry out the instructions of the players) and let  $j^*(x, y)$  be the largest j for which  $i_j(x, y)$  is defined. Then

$$M(x,y) = \begin{cases} 1 \text{ if } j^*(x,y) \text{ is even} \\ -1 \text{ if } j^*(x,y) \text{ is odd} \end{cases}$$

## Constructing semantic universe for the game Addition

Let us consider the following thought experiment – we have two players playing the *Addition* game described earlier. Each player is represented by semantic simulation which has its own set of semantic structures and semantic template which recognizes the rules of the game. Let us start our experiment by looking in the semantic template which recognizes the rules of the game which we will name *semantic* 

*recognizer*. That is - we are interested in what the semantic recognizer might be taking as an input and producing as an output and how the semantic recognizer template would be interacting with the rest of the semantic structures running in the simulation.

Let us assume that the semantic simulation corresponding to each of the two players I and II is limited to the simply connected regions  $R_1$  and  $R_2$  in semantic space. Additionally, we introduce an Arbiter which will be assigned its own simply connected region  $R_3$  in semantic space. Let  $\dim(R_1) = \dim(R_2) = \dim(R_3) = L$ . Let us assume that  $R_1 \cap R_2 \cap R_3 = C$  where C is finite, closed and simply connected region of semantic space with the same number of dimensions L. We will denote C as the common simulation region.

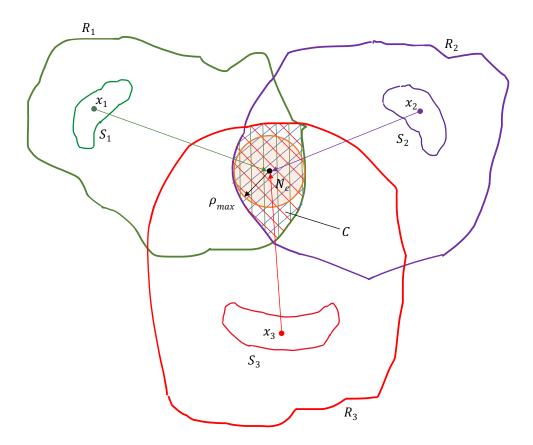


Figure 1: Layout of the simulation space in Blackwell's game Addition

Definition: neutral point of a simply connected region in metric space. Let  $\mathcal C$  is a simply connected region in some  $\mathcal L$  dimensional metric space. Then the point  $\mathcal N_c$  is a neutral point  $\mathit{iff}$  it is the center of the largest  $\mathcal L$  dimensional sphere which can fit entirely in the simply connected region  $\mathcal C$  without including any points outside of  $\mathcal C$ . Formally,

$$\exists \ N_c \in C \ \because \ \rho_{max} = \ \max_{\rho} \ |N_c - x| \le \rho \ \forall \ x \in C$$

With  $N_c$  we denote the neutral point of the common simulation region C. The neutral point will be the attraction center for all outputs from player I and II's as well as the arbiter simulations. Both players I and II as well as the Arbiter will produce an output which will be a semantic particle starting its existence at a point inside their respective regions  $S_1, S_2, S_3$  shown on Figure 1.

Here is how the game simulation will proceed:

For simplicity let us assume that the game parameter N defined earlier is given and it is known by the two players and the Arbiter. Also, we will assume that the Arbiter will make decision who will be the first of the two players to play where for simplicity the decision-making process of the Arbiter will be omitted from the discussion.

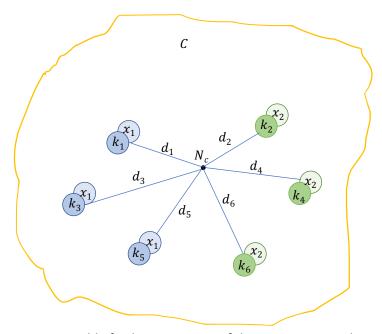


Figure 2: Possible final arrangement of the semantic particles produced by the two players at the end of a game of *Addition* 



Figure 3: Semantic structure formed by the final arrangement of the output of the two players

A semantic particle is produced at  $S_0$  in C by the arbiter announcing a proposed value of N.

## Bibliography

Bang-Jensen, J., & Gutin, G. (2007). *Diagraphs: Theory, Algorithms and Applications*. Odense, Denmark, London, UK: Springer-Verlag.

- Bellman, R. (1972). *Dynamic Programming*. Princeton, NJ: Princeton University Press, Sixth Printing. Blackwell, D. A., & Girshik, M. A. (1978). *Theory of Games and Statistical Decisions*. New York: Dover Publications; Illustrated edition.
- Denardo, E. V. (1982). *Dynamic Programming: Models and Applications*. Englewood Cliffs, NJ: Prentice-Hall.
- Francois-Lavet, V., Henderson, P., Islam, R., Bellemare, M. G., & Pineau, J. (2018). An Introduction To Deep Reinforcement Learning. *Foundations and Trends in Machine Learning: Vol. 11, No. 3-4.*
- Gosavi, A. (2022). Reinforcement Learning: Tutorial and Recent Advances. *INFORMS Journal on Computing*.
- Harmon, M. E., & Harmon, S. S. (Jan 1997). *Reinforcement Learning: A Tutorial.* Wright Patterson AFB OH 45433: Avionics Directorate, Wright Laboratory, Air Force Materiel Command.
- Levine, S., Kumar, A., Tucker, G., & Fu, J. (2020, Nov 1). *Offline Reinforcement Learning: Tutorial, Review, and Perespectives on Open Problems*. Retrieved from arxiv.org: https://arxiv.org/abs/2005.01643
- Neapolitan, R. E. (2019). Bayesian Networks. Upper Saddle River, NJ: Prentice-Hall.
- Sutton, R. S., & Barto, A. G. (2018). *Reinforcement Learning: Introduction, second edition*. Cambridge, Massachusetts: The MIT Press.