# Inference and Execution of Semantic Structures

## Note on Semantic Signature of a particle

Recall, the semantic signature of compound particle is defined as shown below:

Signature of a thought particle is a matrix where .

For each particle property the property type, property name and property value of each property are stored in encoded binary format inside the binary signature matrix .

Rule for calculation of the semantic signature of a compound thought particle

which is also matrix

The last line can be written with the following syntax using radicals:

Obviously, the signature of every compound thought particle is matrix.

Every connecting particle signature encodes the operation which will be applied to the object particle on the left and the operation which will be applied to the object article on the right. Those operations and will preserve the original information contained in the signature of object particle which is being operated on with an additional information pertaining to the link particle.

### An alternative formulation of the semantic signature of

The semantic tree of the compound particle is traversed pre-order. Each particle which is a constituent of is traversed pre-order and its relevant set of properties are added to the signature sorted by type and name. Each particle property occupies a column in the signature matrix. The first particle property serves as a separator from the set of properties corresponding to the previous particle in the pre-order traversal. Recall that the property type, name and value are encoded as binary blobs and are stored as binary arrays within the corresponding signature matrix column.

Let us have the compound particle represented by its elementary particle sequence and semantic tree :

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The property sets for each V-particle are given with

and obviously the signature matrix which will be a bitmap will be composed as:

Here , , and are column bit vectors containing the binary codes which correspond to the property type, name and value of the -th property of the -th particle in the pre-order traversal of the semantic tree . Notice that the indices and in the signature matrix denote *bitwise access* – i.e. the bit which is on the -th row and the -th column in . The zones

Later we will show that the introduction of *dependent property values* will be desired ~~for paradox detection in thought sequence~~ in certain scenarios. A child particle may have properties with the same type and name as a property in the parent particle in the semantic tree of the compound particle .

Portion of the semantic tree of :

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Let us denote with one such property in the parent particle by the triplet . Then the child particle may have a property with the same type and name as the parent property and a value which is dependent of the parent property value . Let us denote by this functional dependence of the child property value. Then the child property can be written as or in short-hand notation: . For instance, definite terms and indefinite articles can use dependent property values on the parent noun.

Also in general there can be *additive overlap* between the zones corresponding to neighbor particles in the signature matrix. For instance, for and the corresponding sector of the signature matrix for the compound particle may look as:

Here denotes the binary blob which results from summation of the values and . Here the index is on the set of all overlapping columns; in this example .

## Note on vectorization of Semantic Signature

Let us have two elementary particles and represented by their corresponding sets of properties:

The property weight of a property models the semantic significance of this property and varies

The property weights for each of the two particles are denoted with:

The property weights are stored in the consumed by -particle which is a carrier of the corresponding property triplet:

such that

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The pairs form a basis in property space.

Then it becomes obvious how to vectorize a particle signature: it is

where the basis vectors are represented by the tuples . The basis vectors will define dimensional vector space also known as the *property dimension* of. Obviously for composite particles the property dimension will be higher or equal to the property dimension of the elementary particles which compose it: .

Two particles and have the same semantic meaning if their vectorized semantic signatures are close enough in every property dimension. This is expressed as:

such that where is some chosen small constant which is orders of magnitude smaller than the smallest factor and the smallest -factor of the -quantum : . Since the difference between any two property values is guaranteed to be larger than the -quantum the condition which remains is as it implies the other.

If has a property with type and name not available among property set then and do not have the same semantic meaning ( abbreviated with ). Otherwise, we write stating that and are equivalent semantically.

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## Note on Semantic distance between thoughts

Let us have the thoughts and represented by their particle sequence and their semantic trees:

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Let us denote by the tree sequence where each tree in the sequence is built only from the first levels of the original tree . Here contains only the particle at the root (usually verb) while consists of the entire tree .

Two semantic trees T1 and T2 are topologically equivalent if

1. root(T1) = root(T2)
2. for there exist an ordering such that where 0 < i < |childlist(root(T1))| = ||
3. repeat 1) and 2) with and being the roots of the new pair of trees to compare.

We say that T1 and T2 are - equivalent if and only if all of the following is true:

1. is small enough and is close enough to 1.0

## Comparing thought sequences and paradox analysis

Let us denote by a sequence composed of thoughts from a set of contexts on the same context path. Let us denote with the thoughts in , .

Let us denote by another sequence composed of thoughts from a set of contexts on the same context path. Let us denote with the thoughts in .

Let us assume that there are two thoughts and for which the semantic distance is negative.

## General Form for the Rules of inference for a sequence of thoughts

Let us denote by a thought sequence composed of thoughts from a set of contexts on the same context path. Let us denote with the thoughts in . Let us denote by a set of -particles which are entirely contained in the thought sequence such that each of the thoughts in contains at least one -particle from . The set will be the *inference trigger* which if present will kick start the synthesis of a new sequence of thoughts which will be the result of the inference. The new ordered sequence of thoughts will be denoted with . The mapping from to will represent inference operation which will be triggered by the presence of .

Let us consider the following set of examples:

*Example 1a (Simple Inference): I do not know John.*

*Inference a: I do not know John*

*I do know John*

*Example 1b (Simple Inference): I probably do not know John. “Probably” means I am not certain.*

*Inference a: I am not certain that I do know John. -or-*

*b: I am not certain that I do not know John.*

*Example 1c (Simple Inference): He probably does not know John. “Probably” means I am not certain.*

*Inference: a: He is not certain that he knows John. -or-*

*b: He is not certain that he does not know John*

*Example 2 (Complex Inference): Dimitar thought John was Peter’s son. Peter was scientist and excellent mathematician. Peter’s family name was Henderson. John Henderson is from the same city as Dimitar is and apparently has filed a US patent a.b.c.d. I checked and found that US patent a.b.c.d is about a chatbot created and trained from individual personal data scraped from Internet logs. Such chatbot is a spoofing device for somebody’s internet persona.*

*Inference:*

*Peter’s son is the inventor of a device spoofing people’s internet persona based on collected from internet personal data.*

*Example 3 (Inference): Human can breathe using their lungs.*

*Fish don’t have lungs.*

*Inference: a: Therefore, fish don’t breathe! -or-*

*b: Despite that, fish can breathe!*

*Example 4* (*Generalization*): *Human can breathe using their lungs.*

*Fish don’t have lungs.*

*Generalization*: *A can do B using their C. D do not have C. Therefor D cannot do B.*

## Learning to Infer

Algorithm for learning to infer can be something like

Learning data:

*Humans can breathe using their lungs.*

*Fish don’t have lungs. Therefore, fish don’t breathe.*

*Cars can move using their engines.*

*Bicycles do not have engines. Therefore bicycles do not move.*

*People can walk using their legs. Snakes do not have legs.*

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text() = “Humans” text() = “Fish” text() = “Therefore”

text() = “can” text() = “don’t” text() = “fish”

text() = “breathe” text() = “have” text() = “don’t”

text() = “using” text() = “lungs” text() = “breathe”

text() = “lungs”

text() = “their”

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text() = “Cars” text() = “Bicycles” text() = “Therefore”

text() = “can” text() = “don’t” text() = “bicycles”

text() = “move” text() = “have” text() = “don’t”

text() = “using” text() = “engines” text() = “move”

text() = “engines”

text() = “their”

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text() = “People” text() = “Snakes”

text() = “can” text() = “don’t”

text() = “walk” text() = “have”

text() = “using” text() = “legs”

text() = “legs”

text() = “their”

Training set: , ; ,

Test set: ,

How could the inference work? Generally, by setting up a predictor (regressor, neural net, etc) and train it.

Simple way to perform the learning step: *semantic structure property swarm with adaptive plasticity*. The properties which are “seen” more than once in the training examples on similar relative locations are strengthened. Tuning the strengthening algorithm with a meta-algorithm is desirable. How does the meta algorithm do the tuning? One output of the tuning algorithm would be the strengthening or weakening of the retainability rank of each property. Second optimization cohort in the algorithm would be to maintain alternative property representation for each semantic particle and to rank each alternative representation. Each V-particle will be semantically identified by DAG of properties as shown below:

Properties and Dependent Properties:

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The set of properties associated with each naked V-particle will be inferred during the continuous semantic parsing which has been discussed in other documents in this collection. Properties are created following the rules for creating properties:

Rules for creating properties:

By splitting existing particles:

Weight, rotation speed, acceleration

New particles:

Semantic inference: Weight comparisons with existing thoughts

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We need only one inference algorithm – both for generating new thoughts and for thoughts entering the system.

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## Types of Inference Processes

We recognize three types of inference processes – Inductive, Deductive and Abductive inference (Peirce, 1878).

### Inductive Inference

It is kind of specialization. Replaces entities which are in context with entities which are out of context ([Supplement\_8-12-20\_page4.jpg](https://github.com/dimitarpg13/aiconcepts/blob/master/Supplement_8-12-20_page4.jpg)).

### Deductive Inference

It is a kind of generalization. Replaces entities which are out of context with entities in context ([Supplement\_8-12-20\_page4.jpg](https://github.com/dimitarpg13/aiconcepts/blob/master/Supplement_8-12-20_page4.jpg)).

### Abductive Inference

Multi-step process for building and refining a hypothesis

Inference can be posed as a discrete optimization problem solved by a reinforcement learning algorithm.

Hypothesis is synthesized and refined in a set of iterations. After it matches the input and output the hypothesis will be used for making an inference, ranked and stored for a future use.

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## Learning Model for Inference Processes

Hypothesis Synthesis of new thoughts Hypothesis

## Execution of thoughts

Continuous adaptive learning process for thoughts which are to be executed

Let the graph represents a thought which is marked for execution. The set represents its -particles and is the set of its -particles. Portions of this thought are mapped to various executable structures. Executable structures are constructed of -particles and various -particles. -particles are directors – they redirect the execution path to appropriate subgraphs of -particles. Therefore the -particles implement conditional processing of the newly synthesized thought composed originally from naked particles. redirecting execution to a subgraph of -particles which

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## Execution Structures and Learning

An *execution structure* is a weighted directed graph composed of the node set consisting of -particles and the set of arcs with weights . The arc set gives directionality of the execution flow while the weights determine the stopping condition for loops. The -particles are composite in nature – new -particle can be obtained from merging -particles which are connected in a path . The rules for merging execution structures determine how new structures relevant for execution will be reconciled with the already existing ones.

An execution structure, as any other structure, is assigned a rank through attachment of ranking particles (-particle).

An execution structure can operate on a semantic structure (graph) or on another execution structure. In the latter case we are talking about *execution-modifying execution structure*.

Execution particles can be created by executing new or inferred thoughts. New execution structures can be assembled by executing new or inferred thoughts.

Each execution structure has at least one target on which it will operate. The execution structure provides a plan what to do with that target. The target can be another execution structure or a regular semantic structure. Each execution structure can be reduced / merged to simpler execution structure which has the following form:

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The root of the reduced execution tree is a D-particle. The reduced E-particles can contain loops.

## Discussion on Execution Particles

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