Notes on Gaussian Processes

Compiled by D.Gueorguiev, 12/7/2024

# Introductory Notes

## Gaussian Models

The PDF of an MVN in dimensions is defined by the following:

(1)

where is the mean vector , and is the covariance matrix.

is known as the *precision matrix* or *concentration matrix*. The normalization constant ensures that the pdf integrates to 1.

A full covariance

The expression inside the exponent is the Mahalanobis distance between a data vector and the mean vector .

## Gaussian Processes (GP)

A Gaussian Process is a Gaussian distribution over functions:

## Noiseless Gaussian Process Regression

We observe a training set where

Given the test set of size , we want to predict the function outputs .

where is matrix, is matrix, and is

Here

Computing predictions is just a question of deriving the conditional distribution from the joint distribution.

# Appendix

## Covariance and Correlation

Covariance between two r.v.’s and measures the degree to which X and Y are related linearly. Covariance is defined as:

A group of symbols with numbers

Description automatically generated with medium confidence

Figure: several sets of points, with the correlation coefficient of and for each set. Note that the correlation reflects the noisiness and the direction of a linear relationship (top row) but not the slope of the relationship (middle), nor the shape indicating non-linear relationship (bottom). Source: <http://en.wikipedia.org/wiki/File:Correlation_examples.png>

If x is a d-dimensional vector, its covariance matrix is defined as the following symmetric positive definite matrix

The Pearson correlation coefficient between and is defined as:

The correlation matrix has the form

**Statement**:

Proof: We have to prove that (A.1)

Cauchy-Schwarz in : (A.2)

Clearly for discrete r.v.’s and (A.1) follows from (A.2).

For continuous r.v.’s and we use the Cauchy-Schwarz in

(A.3) where the integration is performed over some domain of .

A substitution of the distribution function of with and the distribution function of with in (A.3) yields (A1) for the case of continuous r.v.’s.

# References

[1] [Gaussian Processes, Lecture by Nando Freitas, Feb 5th, 2013, UBC course CPSC 540-2013](https://youtu.be/MfHKW5z-OOA?si=QgoG1JPk40GsiXEI)

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[3] [Introduction to Gaussian Processes part 1: Bayesian Linear Regression, Lecture by Stefan Harmeling, TU Dortmund, Jan 9th, 2023](https://youtu.be/148EUutsU8Q?si=Quh1V_pPAAJzvfMw)

[4] [Introduction to Gaussian Processes part 2: Implementation, Lecture by Stefan Harmeling, TU Dortmund, Jan 11th, 2023](https://youtu.be/wyCj9y1dFFY?si=j1q_oz13OlctTX4K)

[5] [Introduction to Gaussian Processes part 3: Kernel Design, Model Selection, GP Classification, Laplace Approximation, Lecture by Stefan Harmeling, TU Dortmund, Jan 16th, 2023](https://youtu.be/LFu7DAJcGKI?si=1hxx01IlX4ssJNBg)

[6] [Machine Learning Tutorial at Imperial College London: Gaussian Processes, Richard Turner, U of Cambridge, Nov 23th, 2016](https://youtu.be/92-98SYOdlY?si=K6cMS8998JFbpMi9)

[7] [Machine Learning: Probabilistic Perspective, Kevin P. Murphy, 2012](https://github.com/dimitarpg13/probabilistic_machine_learning/blob/main/books/MachineLearningProbabilisticPerspective.pdf)