Notes on Least Squares and Nearest Neighbors

compiled from Elements of Statistical Learning by D. Gueorguiev, Oct 25, 2024

# Linear Models and Least Squares

The linear model is defined as:

Given a vector of inputs the output is predicted as:

(1)

where is the *intercept* or *bias*. Often, we include a unit constant ‘variable’ additionally in X and include the bias in the vector of the coefficients . Then we can rewrite (1) as :

(2)

where denotes a row vector or matrix transpose ( is a column vector).

Here we are modeling a single output so is a scalar; in general can be a -vector, in which case would be a matrix of coefficients. In the – dimensional input-output space, represents a hyperplane. If the constant is included in , then the hyperplane includes the origin and is a subspace; If not, it is an affine set cutting the -axis at the point . From now we assume that the intercept is included in .

# References

[1] [The Elements of Statistical Learning; Data Mining, Inference, Prediction, Trevor Hastie, Robert Tibshirani, Jerome Friedman, Second Edition, 2017](https://github.com/dimitarpg13/statistical_learning_and_kernel_methods/blob/main/literature/books/EelementsOfStatisticalLearning_print12.pdf)

# Appendix

## Affine Space

### Informal discussion

Affine space is what is left from vector space after one has forgotten which point is the origin.

Imagine that there are two observers – observer *A* and observer *B*. Observer *A* knows the real origin, but Observer *B* believes that another point is the origin. Two vectors , and , are to be added. Observer *B* believes he has computed the distance but observer A knows better – B has actually computed .

Similarly, observers *A* and *B* may evaluate any linear combination of and or of any finite set of vectors and will generally get different answers. However, if the sum of the coefficients is unit then the observers will arrive at the same answer. Moreover, for any finite number of observers if the sum of the coefficients is unity each of them will come to the same answer.

Origin according to observer B

Origin according to observer A

*according to origin A*

*according to origin B*

according to origin A

*according to origin A*

Figure A.1: origins and vector computations from the perspectives of observer A (red) and observer B (blue)

In the example on Figure A.1 if observer *A* travels to and observer *B* travels using the same route then observer *A* will observe from his frame of reference the following path of observer *B* :

So under the condition all observers who have different frames of reference will describe the same point with the same linear combination despite the different origins. While only observer *A* on the earlier example knows the *linear structure* both observers *A* and *B* know the *affine structure* that is, the values of affine combinations defined as linear combinations in which the sum of the coefficients is unity.

**Definition** *Affine Space*

A set together with a vector space , and a transitive and free action of the additive group of on the set . The elements of the affine space are called points. The vector space is said to be associated with the affine space and its elements are called *translations,* or *free vectors*.

The action in affine space will be denoted as addition and it is a mapping having the following properties:

1) *Right identity*:

, where is the zero vector in

2) *Associativity*:

, (here the last is the addition in )

3) *Free and transitive action*:

, is a bijection

The first two properties are simply defining properties of a (right) group action. The third property characterizes free and transitive actions, and onto character coming from transitivity, and then the injective character follows from the action being free. Forth property follows from 1) and 2)

4) *Existence of one-to-one translations*

the mapping is a bijection

3) is often used in the following equivalent form :

5) *Subtraction*

denoted with such that