# The Attention Mechanism – Review

D. Gueorguiev 1/7/2023

## Introductory Notes

In many problems that involve the processing of natural language, the elements composing the source text are characterized by having each a different relevance to the task at hand. For instance, in aspect-based sentiment analysis, cue words, such as “good” or “bad”, could be relevant to some aspects under consideration but not to others. In machine translation, some words in the source text could be irrelevant in the translation of the next word. In a visual question-answering task, background pixels could be irrelevant in answering a question regarding an object in the foreground but relevant to questions regarding the scenery.

The effective solutions to such problems should factor in a notion of relevance, so as to focus the computational resources on a restricted set of important elements. One possible approach would be to tailor solutions to the specific genre at hand, on order to better exploit known regularities of the input, by feature engineering.

For example, in the argumentative analysis of persuasive essays, one could decide to give special emphasis to the final sentence. However, such an approach is not always viable, especially if the input is long or very information-rich, such as in text summarization, where the output is the condensed version of a possibly lengthy text sentence.

Another approach of increasing popularity amounts to machine learning the relevance of input elements. In that way, neural architectures could automatically weigh the relevance of any region of the input and take such a weight into account while performing the main task. The most common solution to this problem is a mechanism known as attention.

Attention was first introduced in NLP for machine translation tasks in [[4]](https://github.com/dimitarpg13/transformers_intro/blob/main/articles_and_books/NeuralMachineTranslationByJointlyLearningToAlignAndTranslateBahdanau2015.pdf). However, the idea of glimpses had already been proposed in Computer Vision by Larochelle and Hinton in [[19]](https://github.com/dimitarpg13/transformers_intro/blob/main/articles_and_books/NIPS-2010-learning-to-combine-foveal-glimpses-with-a-third-order-boltzmann-machine-Paper.pdf), following the observation that biological retinas fixate on relevant parts of the optic array, while resolution falls off rapidly with eccentricity. The term visual attention became especially popular after Mnih et al [20] significantly outperformed the state of the art in several image classification tasks as well as in dynamic visual control problems such as object tracking due to an architecture that could adaptively select and then process a sequence of regions or locations at high resolution and use a progressively lower resolution for further pixels.

The attention mechanism is a part of a neural architecture that enables dynamically to select relevant features in the input data which in NLP is typically a sequence of textual elements. The idea behind attention is to compute a weight distribution on the input sequence, assigning higher values to more relevant elements.

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## Appendix

### Probability Density Estimation

We consider the problem of modelling a probability density function , given a finite number of data points drawn from that density function. The methods for probability density estimation are used to build classifier systems by considering each of the classes in turn and estimating the corresponding class-conditional densities by making use of the fact that each data point is labelled according to its class. These densities can then be used with Bayes theorem to find the posterior probabilities corresponding to a new measurement of , which can in turn be used to make a classification of **.**

We consider three alternative approaches to density estimation. The first of these involves *parametric* methods in which a specific functional form for the density model is assumed. This contains a number of parameters which are then optimized by fitting the model to the data set.

#### Parametric Methods

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### Bi-directional Neural Networks

*Problem Statement*

Consider a (time) sequence of input data vectors

and a sequence of corresponding output data vectors

with neighboring data-pairs in time being statistically independent. Given time sequences and as training data, the aim is to learn the rules to predict output data given the input data. Inputs and outputs, can, in general, be continuous and/or categorical variables. When the outputs are continuous, we have *regression problem* at hand and when they are categorical (class labels), the problem is known as a *classification problem*. In general we talk about *prediction problem* which includes regression and classification.

1. *Unimodal Regression*

With unimodal regression or function approximation, the components of the output vectors are continuous variables. The network parameters are estimated to maximize some predefined objective criterion e.g. maximize the likelihood of the output data. When the distribution of the errors between the desired and the estimated output vectors is assumed to be Gaussian with zero mean and a fixed global data-dependent variance, the likelihood criterion reduces to the Euclidean distance measure between the desired and the estimated output vectors or the *mean-squared-error criterion*, which has to be minimized during training.

//TODO: finish this paragraph and the corresponding Appendix section which corresponds to Section B of [2]

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