Introduction to Transformers

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# Preliminaries

*Note 0*: Knowledge of feed-forward neural networks and the back-propagation algorithm is assumed.

## Language Modeling

Tools for Language Modeling:

* Sequential Models
* Probabilistic Models e.g. Latent Semantic Analysis (LSA)

## Sequential Modeling

In general, we build ML models where we have data points which are usually uncorrelated, and no order relation can be imposed on them.

*Sequential models*: In many cases such as language, voice, and time-series data a data point is dependent on a set of other data points which have already been processed. We call such stream of data points a stream of *sequential data*. Machine learning models which accept input or create an output sequence of data points are known as *sequential models*.

Previous tools for sequence modeling:

* Recurrent Neural Networks
* Long Short Term Memory
* Gated Recurrent Neural Nets

### Notes on RNN (Recurrent Neural Networks)

What is RNN?

RNN is a Neural network with at least one cycle. If the network contains cycle the computation is not uniquely defined by the interconnection pattern and the *temporal dimension* must be considered. When the output of one neural node is fed back to the same node we are dealing with recursive computation. We must define what we expect from the network – is the fixed point of the recursive evaluation the desired result or one of the intermediate computations? We can assume that every computation takes a fixed amount of time and can be expressed as a certain number of time units. If the inputs of a neural node have been sent at time , its output will be available at time . A recursive computation can be stopped after predetermined number of steps and the last output will be considered the result of the recursive computation.

Continuous vs Epochwise mode

Two approaches to operate and train an RNN:

* *Epochwise operation*

The network is run from a given start time until a given stopping time is reached. After reaching the stopping time the network is reset in its *initial state* for the next epoch. It is not essential that all of *the state* at the beginning of each epoch is the same. The important aspect of the *Epochwise operation* is the starting state of a new Epoch is not causally related to the ending state of the previous epoch.

Thus, every epoch serves as a boundary through which learning credit cannot pass. The purpose of the epoch boundaries is to make sure that activity from one epoch is causally related to activity in another later epoch. Note that the notion of epoch is defined in a loose sense indicating only that the boundaries are present between an interval(s) and an interval of past activity is separated by boundary from the activities after the boundary.

This allows us to introduce the notion of *batch training* distinguished from the notion of *incremental training*. The difference between the batch training vs incremental training is in when the network weights are updated. With the batch training approach weights are updated only after presenting a complete set of training examples. With the incremental approach the weights are updated after presenting each training example.

* *Continuous operation*

No manual state resets nor any barriers against the flow of training credit are imposed in the network.

Continuous operation makes sense when online learning is required.

Backpropagation through time (BPTT)

For simplicity, let us consider a finite number of iterations only. Assume that a network of computing nodes is fully connected and that

### Notes on LSTM (Long Short Term Memory)

### Notes on Gated Recurrent Neural Nets

## Latent Semantic Analysis (LSA)

LSA belongs to the family of *Probabilistic Methods* for analyzing and modeling the structure of the language.

# The Attention Mechanism