#### CS 5/7320 Artificial Intelligence

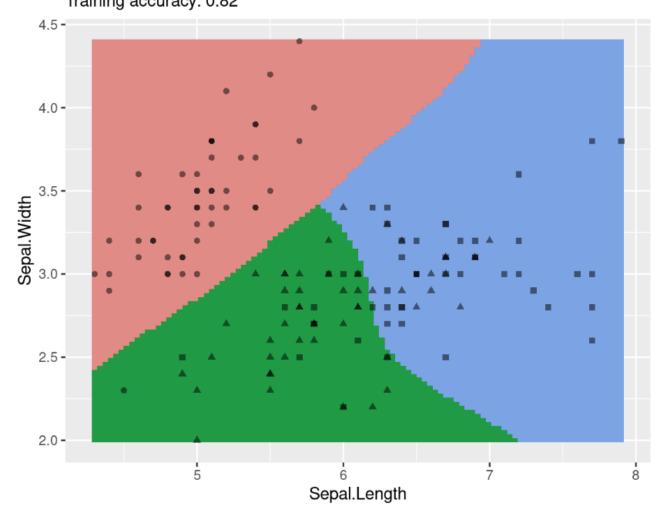
# **Learning from Examples**AIMA Chapter 19

Slides by Michael Hahsler Based on slides by Dan Klein, Pieter Abbeel, Sergey Levine and A. Farhadi (<a href="http://ai.berkeley.edu">http://ai.berkeley.edu</a>) with figures from the AIMA textbook.



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#### SVM (radial kernel) Training accuracy: 0.82



# Topics



# Learning from Examples: Machine Learning

#### Up until now in this course:

Hand-craft algorithms to make rational/optimal or at least good decisions.
 Examples: Search strategies, heuristics.

#### Issues

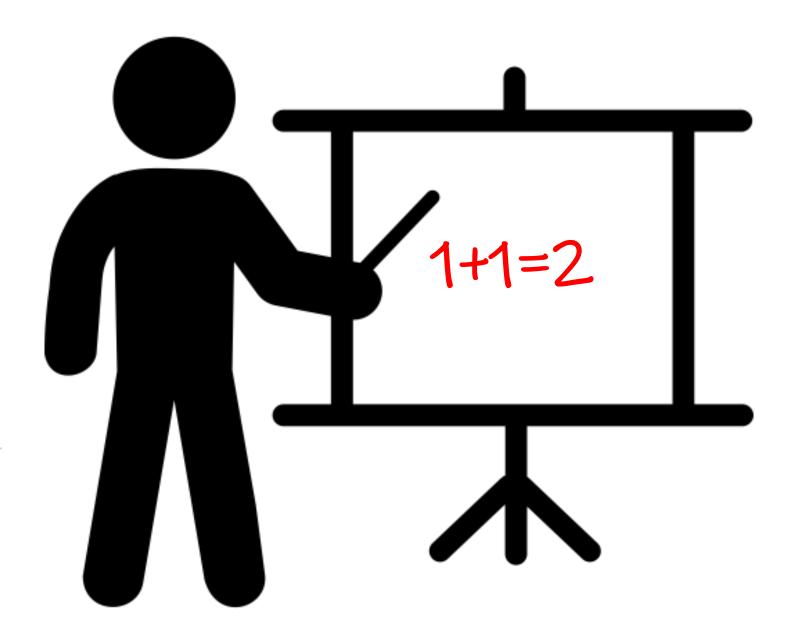
- Designer cannot anticipate all possible future situations.
- Designer may have examples but does not know how to program a solution.

#### **Machine Learning**

- **Learning**: Improve performance after making observations about the world. That is, learn what works and what doesn't to get closer to optimal decisions.
- How to learn a model to make better decisions from data/experience?
  - **Supervised Learning**: Learn a function (model) to map input to output from a training set. Examples:
    - Use a naïve Bayesian classifier to distinguish between spam/no spam
    - Learn a playout policy to simulate games (current board -> good move)
  - Unsupervised Learning: Organize data (e.g., clustering, embedding)
  - **Reinforcement Learning**: Learn from rewards/punishment (e.g., winning a game) obtained via interaction with the environment over time.

We focus on supervised learning

Supervised Learning



# Supervised Learning

#### • Examples

- We assume there exists a target function y = f(x) that produces iid (independent and identically distributed) examples possibly with noise and errors.
- Examples are observed input-output pairs  $E = (x_1, y_1), ..., (x_i, y_i), ..., (x_N, y_N),$  where x is a vectors called the feature vector.

#### Learning problem

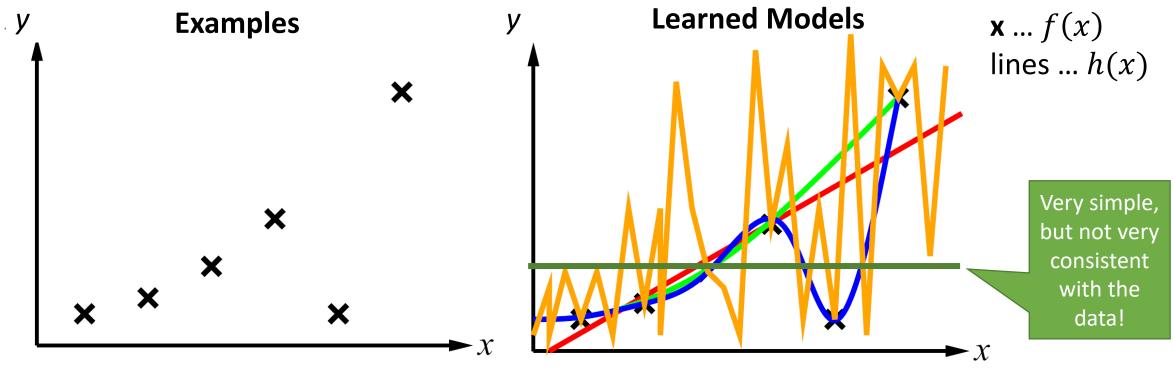
- Given a hypothesis space H of representable models.
- Find a hypothesis  $h \in H$  such that  $\hat{y}_i = h(x_i) \approx y_i \ \forall i$
- That is, we want to approximate f by h using E.

#### Supervised learning includes

- Classification (outputs = class labels). E.g., x is an email and f(x) is spam / ham.
- Regression (outputs = real numbers). E.g., x is a house and f(x) is its selling price.

# Consistency vs. Simplicity

Example: Univariate curve fitting (regression, function approximation)



- Consistency:  $h(x_i) \approx y_i$
- Simplicity: small number of model parameters

### Measuring Consistency using Loss

**Goal of learning**: Find a hypothesis that makes predictions that are consistent with the examples  $E = (x_1, y_1), ..., (x_i, y_i), ..., (x_N, y_N)$ .

 $\hat{y} = h(x) \approx y$ . That is,

- Measure mistakes: Loss function  $L(y, \hat{y})$

$$L_1(y,\hat{y}) = |y - \hat{y}|$$

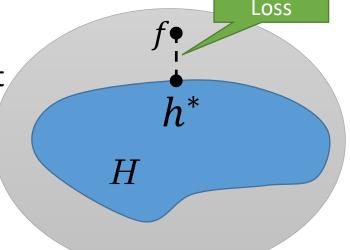
• Absolute-value loss 
$$L_1(y,\hat{y}) = |y - \hat{y}|$$
  
• Squared-error loss  $L_2(y,\hat{y}) = (y - \hat{y})^2$ 

• 0/1 loss

For Regression

- Log loss, cross-entropy loss and many others...
- Empirical loss: average loss over the N examples in the dataset.

$$EmpLoss_{L,E}(h) = \frac{1}{|E|} \sum_{(x,y) \in E} L(y,h(x))$$



# Learning Consistent h by Minimizing the Loss

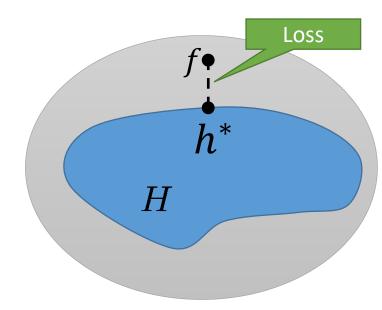
Empirical loss

$$EmpLoss_{L,E}(h) = \frac{1}{|E|} \sum_{(x,y) \in E} L(y,h(x))$$

• Find the best hypothesis that minimizes the loss

$$h^* = \underset{h \in H}{\operatorname{argmin}} EmpLoss_{L,E}(h)$$

- Reasons for  $h^* \neq f$ 
  - a) Realizability:  $f \notin H$
  - b) f is nondeterministic or examples are noisy.
  - c) It is computationally intractable to search all H, so we use a non-optimal heuristic.



# The Bayes Classifier

For 0/1 loss, the empirical loss is minimized by the model that predicts for each x the most likely class y using MAP (Maximum a posteriori) estimates. This is called the Bayes classifier.

$$h^*(x) = \underset{y}{\operatorname{argmax}} P(Y = y \mid X = x) = \underset{y}{\operatorname{argmax}} \frac{P(x \mid y) P(y)}{P(x)} = \underset{y}{\operatorname{argmax}} P(x \mid y) P(y)$$

**Optimality**: The **Bayes classifier is optimal for 0/1 loss.** It is the most consistent classifier possible with the lowest possible error called the **Bayes error rate**. No better classifier is possible!

**Issue**: The classifier requires to learn  $P(x \mid y) P(y) = P(x, y)$  from the examples.

- It needs the complete joint probability which requires in the general case a probability table with one entry for each possible value for the feature vector x.
- This is impractical (unless a simple Bayes network exists) and most classifiers try to approximate the Bayes classifier using a simpler model with fewer parameters.

# Simplicity

#### Ease of use

Simpler hypotheses have fewer model parameters to estimate and store.

#### **Generalization**: How well does the hypothesis perform on new data?

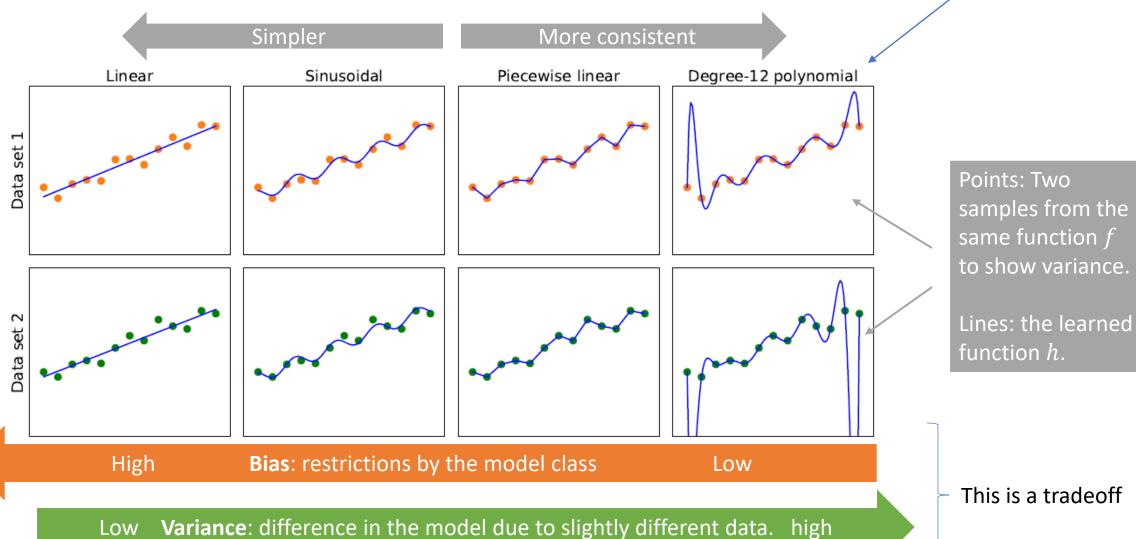
- We do not want the model to be too specific to the training examples (an issue called overfitting).
- Simpler models typically generalize better to new examples.

#### How to achieve simplicity?

- a) Model bias: Restrict H to simpler models (e.g., assumptions like independence, only consider linear models).
- b) Feature selection: use fewer variables from the feature vector x
- c) Regularization: penalize model for its complexity (e.g., number of parameters)

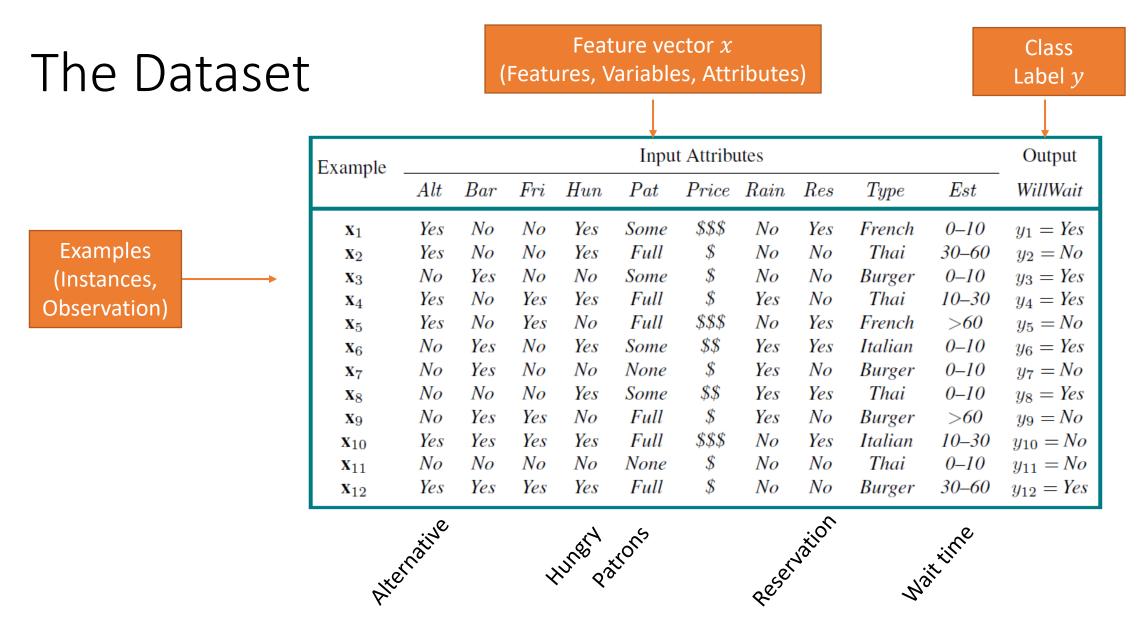
$$h^* = \underset{h \in H}{\operatorname{argmin}} \left[ EmpLoss_{L,E}(h) + \lambda \ Complexity(h) \right]$$
Penalty term

#### Model Selection: Bias vs. Variance



This is a tradeoff

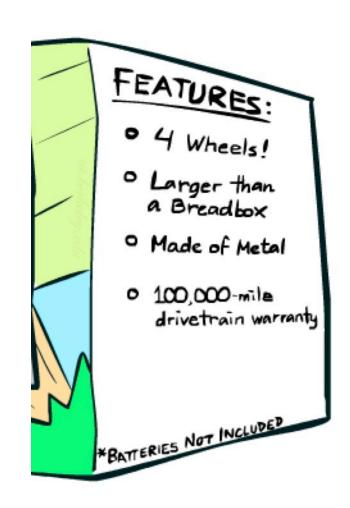
Data



Find a hypothesis (called "model") to predict the class given the features.

# Feature Engineering

- Add information sources as new variables to the model.
- Add derived features that help the classifier (e.g.,  $x_1x_2$ ,  $x_1^2$ )
- Embedding: E.g., convert words to vectors where vector similarity between vectors reflects semantic similarity.
- Example for Spam detection: In addition to words
  - Have you emailed the sender before?
  - Have 1000+ other people just gotten the same email?
  - Is the header information consistent?
  - Is the email in ALL CAPS?
  - Do inline URLs point where they say they point?
  - Does the email address you by (your) name?
- Feature Selection: Which features should be used in the model is a model selection problem (choose between models with different features).



Training and Testing



# Model Evaluation (Testing)

The model was trained on the training examples E. We want to test how well the model will perform on new examples T (i.e., how well it **generalizes to new data**).

• Testing loss: Calculate the empirical loss for predictions on a testing data set T that is different from the data used for training.

$$EmpLoss_{L,T}(h) = \frac{1}{|T|} \sum_{(x,y) \in T} L(y,h(x))$$

• For classification we often use the **accuracy** measure, the proportion of correctly classified test examples.

$$accuracy(h, T) = \frac{1}{|T|} \sum_{(x,y) \in T} [h(x) = y] = 1 - EmpLoss_{L_{0/1},T}(h)$$

# Training a Model

• Models are "trained" (learned) on the training data. This involved estimating:

- **1. Model parameters** (the model): E.g., probabilities, weights, factors.
- **2.** Hyperparameters: Many learning algorithms have choices for learning rate, regularization  $\lambda$ , maximal decision tree depth, selected features,... The algorithm tries to optimizes the model parameters given user-specified hyperparameters.

We need to tune the hyperparameters!

Training Data



# Hyperparameter Tuning/Model Selection

- 1. Hold a validation data set back from the training data.
- 2. Learn models using the training set with different hyperparameters. Often a grid of possible hyperparameter combinations or some greedy search is used.
- 3. Evaluate the models using the validation data and choose the model with the best accuracy. Selecting the right type of model, hyperparameters and features is called model selection.
- 4. Learn the final model with the chosen hyperparameters using all training (including validation data).
- Notes:
  - The validation set was not used for training, so we get generalization accuracy for the different hyperparameter settings.
  - If no model selection is necessary, then no validation set is used.





# Testing a Model

• After the model is selected, the final model is evaluated against the test set to **estimate the final model accuracy**.

• Very important: never "peek" at the test set during training!





### How to Split the Dataset

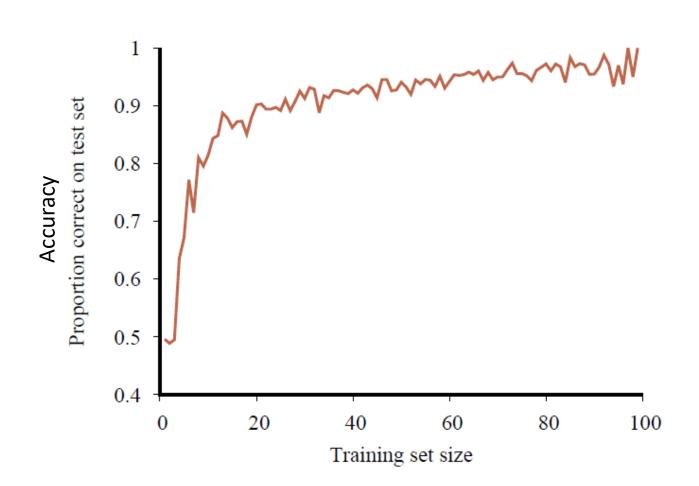
- Random splits: Split the data randomly in, e.g., 60% training, 20% validation, and 20% testing.
- **Stratified splits:** Like random splits, but balance classes and other properties of the examples.
- k-fold cross validation: Use training & validation data better
  - Split the training & validation data randomly into k folds.
  - $\bullet\,$  For k rounds hold one fold back for testing and use the remaining k-1 folds for training.
  - Use the average error/accuracy as a better estimate.
  - Some algorithms/tools do this internally.
- **LOOCV** (leave-one-out cross validation): k=n used if very little data is available.

Training Data

Validation Data

> Test Data

# Learning Curve: The Effect the Training Data Size



Accuracy of a classifier when the amount of available training data increases.

#### More data is better!

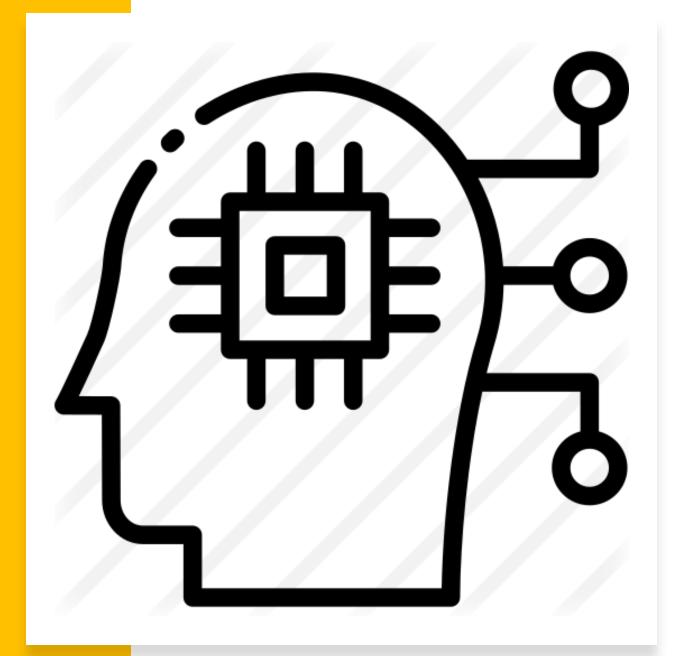
At some point the learning curve flattens out and more data does not contribute much!

#### Comparing to a Baselines

- First step: get a baseline
  - Baselines are very simple straw man model.
  - Helps to determine how hard the task is.
  - Helps to find out what a good accuracy is.



- Weak baseline: The most frequent label classifier
  - Gives all test instances whatever label was most common in the training set.
    - Example: For spam filtering, give every message the label "ham."
  - Accuracy might be very high if the problem is skewed (called class imbalance).
    - Example: If calling everything "ham" gets already 66% right, so a classifier that gets 70% isn't very good...
- Strong baseline: For research, we typically compare to previous published stateof-the-art as a baseline.



# Types of Models

Regression: Predict a number

Classification: Predict a label



### Regression: Linear Regression

Model: 
$$h_{\mathbf{w}}(\mathbf{x}_{j}) = w_{o} + w_{1}x_{j,1} + \dots + w_{n}x_{j,n} = \sum_{i} w_{i}x_{j,i} = \mathbf{w}^{T}\mathbf{x}_{j}$$

Empirical Loss:  $L(w) = ||Xw - y||^2$ 

Gradient:  $\nabla L(\mathbf{w}) = 2\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{y})$ 

Find:  $\nabla L(\mathbf{w}) = 0$ 

Gradient descend:

$$\mathbf{w} = \mathbf{w} - \alpha \nabla L(\mathbf{w})$$

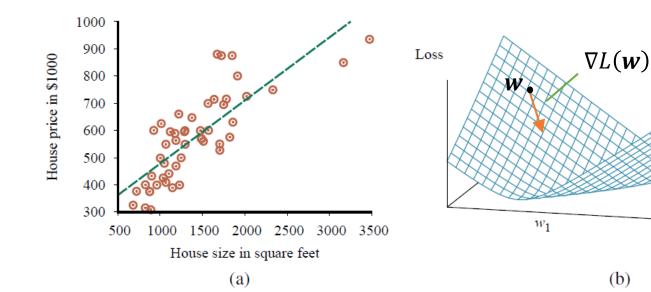
Analytical solution:

$$\boldsymbol{w}^* = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{y}$$
Pseudo inverse

Squared error loss over the whole data matrix X

The gradient is a vector of partial derivatives

$$\nabla L(\mathbf{w}) = \left[ \frac{\partial L}{\partial w_1}(\mathbf{w}), \frac{\partial L}{\partial w_2}(\mathbf{w}), \dots, \frac{\partial L}{\partial w_n}(\mathbf{w}) \right]^{\frac{1}{2}}$$



# Naïve Bayes Classifier

• Approximates a Bayes classifier with the **naïve independence assumption** that all n features are conditional independent given the class.

$$h(x) = \underset{y}{\operatorname{argmax}} P(y) \prod_{i=1}^{n} P(x_i \mid y)$$

The P(y)s and the  $P(x_i \mid y)$ s are estimated from the data by counting.

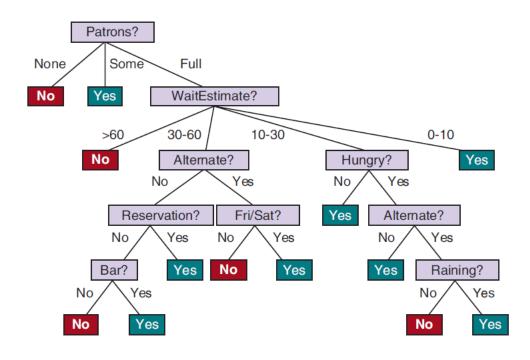
 Gaussian Naïve Bayes Classifiers extend the approach to continuous features by assuming:

$$P(x_i \mid y) \sim N(\mu_y, \sigma_y)$$

The parameters for the normal distribution  $N(\mu_y, \sigma_y)$  are estimated from data.

#### **Decision Trees**

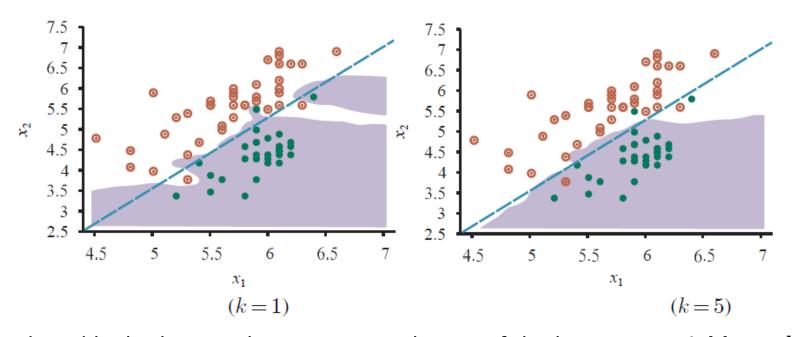
Example	Input Attributes										Output
	Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	WillWait
$\mathbf{x}_1$	Yes	No	No	Yes	Some	\$\$\$	No	Yes	French	0–10	$y_1 = Yes$
$\mathbf{x}_2$	Yes	No	No	Yes	Full	\$	No	No	Thai	<i>30–60</i>	$y_2 = No$
$\mathbf{x}_3$	No	Yes	No	No	Some	\$	No	No	Burger	0-10	$y_3 = Yes$
$\mathbf{x}_4$	Yes	No	Yes	Yes	Full	\$	Yes	No	Thai	10-30	$y_4 = Yes$
$\mathbf{x}_5$	Yes	No	Yes	No	Full	<b>\$\$\$</b>	No	Yes	French	>60	$y_5 = No$
$\mathbf{x}_6$	No	Yes	No	Yes	Some	\$\$	Yes	Yes	Italian	0-10	$y_6 = Yes$
$\mathbf{x}_7$	No	Yes	No	No	None	\$	Yes	No	Burger	0-10	$y_7 = No$
$\mathbf{x}_8$	No	No	No	Yes	Some	\$\$	Yes	Yes	Thai	0-10	$y_8 = Yes$
<b>X</b> 9	No	Yes	Yes	No	Full	\$	Yes	No	Burger	>60	$y_9 = No$
$\mathbf{x}_{10}$	Yes	Yes	Yes	Yes	Full	\$\$\$	No	Yes	Italian	10-30	$y_{10} = No$
$\mathbf{x}_{11}$	No	No	No	No	None	\$	No	No	Thai	0-10	$y_{11} = No$
$\mathbf{x}_{12}$	Yes	Yes	Yes	Yes	Full	\$	No	No	Burger	<i>30–60</i>	$y_{12} = Yes$



- A **sequence of decisions** represented as a tree.
- Many implementations that differ by
  - How to select features to split?
  - When to stop splitting?
  - Is the tree pruned?
- Approximates a Bayesian classifier by

$$h(x) = \underset{y}{\operatorname{argmax}} P(Y = y \mid \operatorname{leafNodeMatching}(x))$$

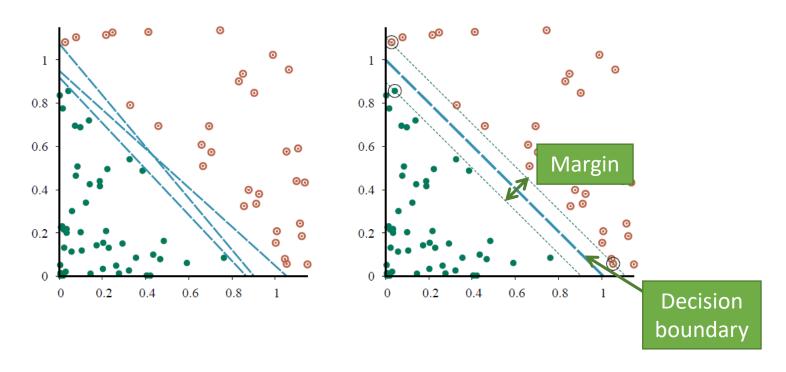
#### K-Nearest Neighbors Classifier



- Class is predicted by looking at the majority in the set of the k nearest **neighbors**. k is a hyperparameter. Larger k smooth the decision boundary.
- Neighbors are found using a distance measure (e.g., Euclidean distance between points).
- Approximates a Bayesian classifier by

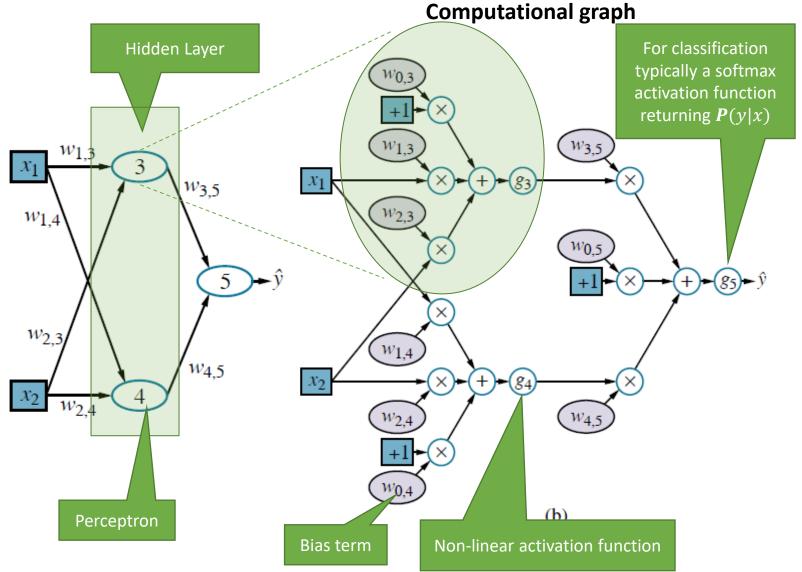
$$h(x) = \underset{v}{\operatorname{argmax}} P(Y = y \mid \operatorname{neighborhood}(x))$$

# Support Vector Machine (SVM)



- Linear classifier that finds the maximum margin separator using only the points that are "support vectors" and quadratic optimization.
- The kernel trick can be used to learn non-linear decision boundaries.

# Artificial Neural Networks/Deep Learning



- Represent  $\hat{y} = h(x)$  as a network of weighted sums with non-linear activation functions g (e.g., logistic, ReLU).
- Learn weights **w** from examples using **backpropagation** of prediction errors  $L(\hat{y}, y)$  (gradient descend).
- ANNs are universal approximators. Large networks can approximate any function (no bias). Regularization is typically used to avoid overfitting.
- Deep learning adds more hidden layers and layer types (e.g., convolution layers) for better learning.

# Other Popular Models and Methods

#### Many other models exist

• Generalized linear model (GLM): This important model family includes linear regression and the classification method logistic regression.

#### Often used methods

- **Regularization:** enforce simplicity by using a penalty for complexity.
- **Kernel trick:** Let a linear classifier learn non-linear decision boundaries ( = a linear boundary in a high dimensional space).
- Ensemble Learning: Use many models and combine the results (e.g., random forest, boosting).
- Embedding and Dimensionality Reduction: Learn how to represent data in a simpler way.

### Some Use Cases of ML for Intelligent Agents

#### **Learn Actions**

 Directly learn the best action from examples.

action = h(state)

 This model can also be used as a playout policy for Monte Carlo tree search with data from self-play.

#### **Learn Heuristics**

 Learn evaluation functions for states.

$$eval = h(state)$$

 Can learn a heuristic for minimax search from examples.

#### Perception

- Natural language processing: Use deep learning / word embeddings / language models to understand concepts, translate between languages, or generate text.
- Speech recognition: Identify the most likely sequence of words.
- Vision: Object recognition in images/videos.
   Generate images/video.

#### **Compressing Tables**

- Neural networks can be used as a compact representation of tables that do not fit in memory. E.g.,
  - Joint probability table
  - State utility table
- The tables can be learned form data.

**Bottom line**: Learning a function is often more effective than hard-coding it However, we do not always know how it performs in very rare cases!