Last time:

- · powers of symmetric matrices
- · Hessian matrix and quadratic approximation of functions
- · level sets of quadratic forms

Today:

- · using the Hessian to analyze critical points
- · critical points & contour plots 2.0

Problem 1: Unconstrained local extrema via Hessian

For each of the following functions $\mathbb{R}^2 \to \mathbb{R}$, use the gradient to find all critical points and characterize each critical point (i.e., local maximum, local minimum, saddle point, or otherwise) by computing the Hessian in general and analyzing it at each critical point.

(a)
$$x^4y^4 - 2x^2 - 2y^2$$

Recall: If à is a critical pt of f, then

if $(Hf)(\vec{a})$ is pos def \Rightarrow à is a local min

if $(Hf)(\vec{a})$ is neg. def \Rightarrow à is a local max

• if (Hf)(à) is indefinite ⇒ à is a sadde pt.

If (Hf)(a) pos.-semidef/neg-semidef (and not pos def./neg. def), need more info.

$$\begin{aligned}
& 7f = \begin{bmatrix} 4x^{3}y^{4} - 4x \\
4x^{4}y^{3} - 4y \end{bmatrix} = \begin{bmatrix} 0 \\
0 \\
0 \end{bmatrix} & 4x(x^{2}y^{4} - 1) = 0 \\
& x = 0 \text{ or } x^{2}y^{4} = 1 \\
& 4y(x^{4}y^{2} - 1) = 0 \\
& y = 0 \text{ or } x^{4}y^{2} = 1 \\
& x = ty = t \\
& (0,0), (1,1), (-1,-1), (1,-1), (-1,1)
\end{aligned}$$

$$(Hf)(x,y) = 12x^2y^4 - 4 + 16x^3y^3$$

$$16x^3y^3 + 12x^4y^2 - 4$$

$$(0,0):$$

$$(Hf)(0,0) = \begin{bmatrix} -4 & 0 \end{bmatrix} \text{ one elval: } -4$$

$$\Rightarrow \text{ neg. def}$$

$$\Rightarrow (0,0) \text{ local max}$$

$$\pm (1,1)$$
:

 $(Hf)(\pm (1,1)) = \begin{bmatrix} 8 & 16 \\ 16 & 8 \end{bmatrix}$
 $det = 8^2 - 16^2 < 0$
 \Rightarrow two evals have opposite signs

 \Rightarrow indefinite

 $\Rightarrow (1,1),(-1,-1)$ saddle pts

In general: $\lambda^2 - tr(Hf)\lambda + det(Hf) = (\lambda - \lambda_1)(\lambda - \lambda_2)$
 $det(Hf) = product of evals$
 $tr(Hf) = sum of evals$

$$\frac{(1,-1)}{(1,-1)} = \begin{bmatrix} 8 & -16 \end{bmatrix} \text{ det} = 8^2 - 16^2 < 0$$

$$\frac{(1,-1)}{(1,-1)} = \begin{bmatrix} 8 & -16 \end{bmatrix} \text{ indefinite}$$

$$\frac{(1,-1)}{(1,-1)} = \begin{bmatrix} 8 & -16 \end{bmatrix} \text{ saddle pts}$$

(b)
$$-3x^{2} + 2xy - (3/2)y^{2} + y^{3}$$

$$\nabla f = \begin{bmatrix} -6x + 2y \\ 2x - 3y + 3y^{2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad 5x = 2y \\ 3x = y$$

$$2x - 9x + 27x^{2} = 0$$

$$x(27x - 7) = 0$$

$$x = 0 \text{ or } x = \frac{7}{27}$$

$$(-it pts: (0,0), (7/27, 7/4)$$

$$Hf = \begin{bmatrix} -6 & 2 \\ 2 & -3 + 6y \end{bmatrix}$$

$$(Hf)(0,0) = \begin{bmatrix} -6 & 2 \\ 2 & -3 \end{bmatrix} \xrightarrow{\text{det}} = 18 - 4 > 0$$

$$\Rightarrow \text{ product of elabs}$$

$$\Rightarrow \text{ elvals have some}$$

$$= -6 - 3$$

$$tr = -9 < 0$$

=) Sum of e'vals is <0

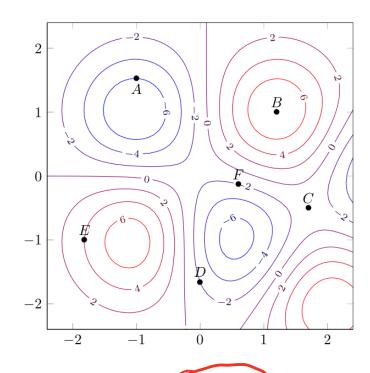
$$(4f)(7/27,7/9)=[-6 2 2 -3+14]$$
 $det=-6(-3+\frac{14}{3})-4$
 $=18-28-4<0$
 \Rightarrow evals have opposite signs

 \Rightarrow indefinite \Rightarrow $(7/27,7/9)$ saddle pt

Consider the given contour plot for a function $f: \mathbb{R}^2 \to \mathbb{R}$.

Problem 2: Visually interpreting critical points

- (a) Assuming B is a critical point, is the Hessian matrix of f at B: (i) positive-definite (ii) negative-definite, or (iii) indefinite? (Assume it is one of these.)
- (b) Assuming C is a critical point, is the Hessian matrix of f at C: (i) positive-definite, (ii) negative-definite, or (iii) indefinite? (Assume it is one of these.)



Recall: max or min looks like consider saddle pt looks like side

Problem 3: Using Hessian eigenvalues to characterize critical points

Consider a critical point **a** of $f: \mathbf{R}^n \to \mathbf{R}$ whose Hessian $(Hf)(\mathbf{a})$ has eigenvalues $\lambda_1, \ldots, \lambda_n$ for some orthogonal basis (as we are guaranteed always happens, by the Spectral Theorem). For each of the following possibilities for the list of eigenvalues, is the behavior of f at **a** a local maximum, local minimum, or saddle point? (It is one of these in each case below.)

(a) eigenvalues 43, 5, 1 all >0 => pos. def => local min

(b) eigenvalues 5, -3, -7 Some 20, some 20 = indéfinite = sadle pt

(c) eigenvalues 1, 0, -1 Some 20, some 20 =) indefinite =) saddle pt

(d) eigenvalues 1, 1, 1, 1 all >0 => pos. def => local min

(e) eigenvalues -1, -5 all 20 > neg. def => local max

(f) -1,-5,0 not enough info