Problem 1: Large powers of symmetric matrices (a 3×3 example)

Consider the matrix

$$M = \begin{bmatrix} 3/5 & 1/5 & 1/5 \\ 1/5 & 3/5 & 1/5 \\ 1/5 & 1/5 & 3/5 \end{bmatrix}$$

Since M is symmetric, the Spectral Theorem implies that there is an orthogonal basis for \mathbf{R}^3 consisting of eigenvectors for M. For this problem, assume that we are also given that the eigenvalues of M are $\lambda_1=1$ and $\lambda_2=\frac{2}{5}$.

- (a) Let V_1 be the λ_1 -eigenspace. Verify that $\mathbf{w}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ lies in V_1 , and explain why it spans that space.
- (b) Find the λ_2 -eigenspace V_2 , and write it as the span of two orthogonal vectors \mathbf{w}_2 , \mathbf{w}_3 .
- (c) Let $\mathbf{w}_1', \mathbf{w}_2', \mathbf{w}_3'$ be unit vectors obtained from $\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3$. Let W be the matrix whose columns are $\mathbf{w}_1', \mathbf{w}_2', \mathbf{w}_3'$. Find the diagonal matrix D where $M = WDW^{\top}$.
- (d) Using the fact that $(2/5)^{100} \approx 0$ to over thirty-five decimal places, calculate M^{100} explicitly.

Problem 2: Large powers of symmetric matrices (a 2×2 example)

Let $A = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$, a symmetric matrix.

- (a) Compute the eigenvalues $\lambda_1 > \lambda_2$ of A and find eigenvectors $\mathbf{v}_1, \mathbf{v}_2$ for λ_1, λ_2 , respectively. Check that $\mathbf{v}_1, \mathbf{v}_2$ are orthogonal.
- (b) Write $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ as linear combinations of the orthogonal basis $\{\mathbf{v}_1, \mathbf{v}_2\}$.
- (c) Use your expressions from part (b) to give an exact expression for A^{100} . (Hint: note that the first column of A^{100} is equal to $A^{100}\mathbf{e}_1$, and similarly for the second column. Use (b) to compute $A^{100}\mathbf{e}_i$.)
- (d) Using the (very accurate!) approximation $(\lambda_2/\lambda_1)^{100} \approx 0$, give a much simpler approximate expression for A^{100} .

Problem 3: Calculating multiple derivatives

Consider the function

$$f(x,y) = e^{x\sin y}.$$

- (a) Find all first and second partial derivatives of f.
- (b) Find the gradient vector and Hessian matrix of f at (1,0).
- (c) Find the quadratic approximation to f(1+h,k) for h and k near 0.

Problem 4: Level sets of quadratic forms

Consider the quadratic form $Q(x, y) = x^2 + 6xy + y^2$.

- (a) Find the symmetric 2×2 matrix A for which $\begin{bmatrix} x & y \end{bmatrix} A \begin{bmatrix} x \\ y \end{bmatrix} = Q(x, y)$.
- (b) Find the eigenvalues λ_1 and λ_2 of A, and find unit eigenvectors \mathbf{v}_1 and \mathbf{v}_2 for these respective eigenvalues.
- (c) We can use the eigenvalues to express Q when its input is written in a basis of *unit* eigenvectors of A:

$$Q(x'\mathbf{v}_1 + y'\mathbf{v}_2) = \lambda_1 x'^2 + \lambda_2 y'^2.$$

Use this to sketch the level curves $Q(x'\mathbf{v}_1 + y'\mathbf{v}_2) = \pm 8$ as well as $Q(x'\mathbf{v}_1 + y'\mathbf{v}_2) = 0$ in an x'y'-coordinate plane, indicating where each crosses a coordinate axis.

(d) Explain why rotating the "standard basis" onto the orthonormal basis $\{\mathbf{v}_1, \mathbf{v}_2\}$ carries $x'\mathbf{e}_1 + y'\mathbf{e}_2$ onto $x'\mathbf{v}_1 + y'\mathbf{v}_2$, and carries the x', y' coordinate axes onto the "eigenlines" of A. Sketch the resulting rotation of the picture in (c); why is it the level sets Q(x,y) = -8,0,8? (This gives a *general technique* to draw level sets of any $Ax^2 + Bxy + Cy^2$.)

