

1. (2 points) Suppose the matrix A satisfies

$$A = ST$$

where

$$S = \begin{bmatrix} 1/\sqrt{3} & 1/\sqrt{2} & 1/\sqrt{6} \\ 1/\sqrt{3} & 0 & -2/\sqrt{6} \\ 1/\sqrt{3} & -1/\sqrt{2} & 1/\sqrt{6} \end{bmatrix}, \quad T = \begin{bmatrix} 0 & 3 & 2 \\ 0 & 3 & 2 \\ 0 & 0 & 5 \end{bmatrix}$$

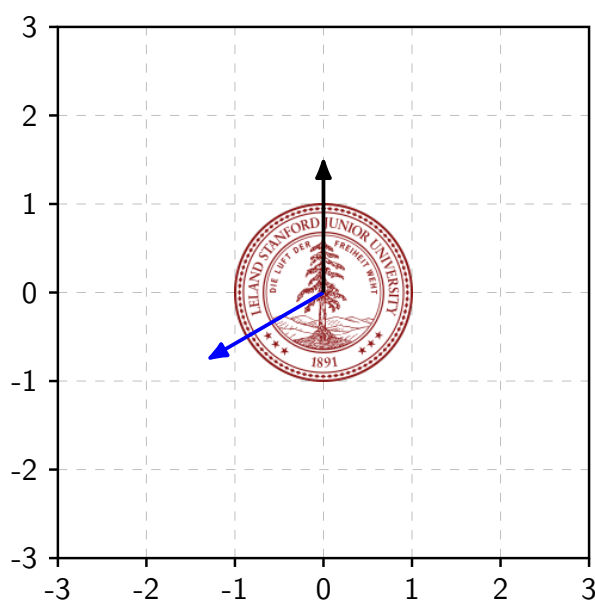
Observe that the columns of S are orthonormal.

What are the dimensions of $N(A)$ and $C(A)$ (i.e., the null space and column space of A , respectively)?

- (i) 0 (ii) 1 (iii) 2 (iv) 3

2. (4 points) Suppose A is a 2×2 matrix with eigenvalues μ_1, μ_2 ; and that B is a *symmetric* 2×2 matrix with eigenvalues λ_1, λ_2 .

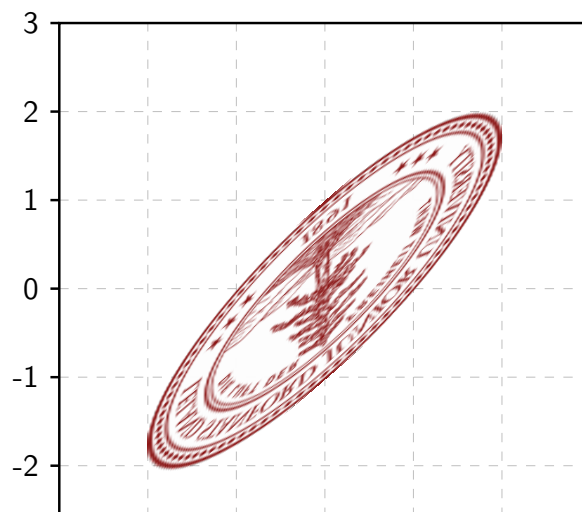
Consider also the following picture of the Stanford seal with two vectors (one black/vertical; one blue/non-vertical) superimposed, and suppose the additional three statements about these vectors, written alongside the figure:



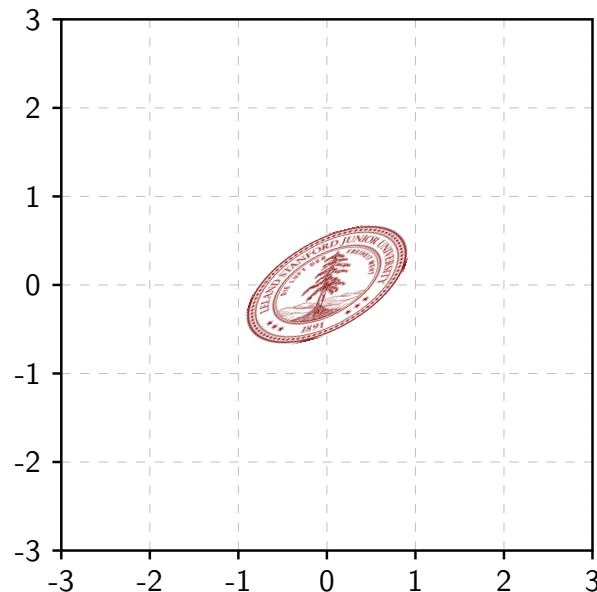
- The blue (non-vertical) vector shown above is an eigenvector of A with eigenvalue μ_1 .
- The black (vertical) vector shown above is an eigenvector of A with eigenvalue μ_2 .
- The blue (non-vertical) vector shown above is an eigenvector of B with eigenvalue λ_1 .

Finally, shown below are the outputs when these matrices are applied to the original picture of the Stanford seal:

Effect of applying the 2×2 matrix A :



Effect of applying the *symmetric* 2×2 matrix B :



Given all of this information, estimate: the eigenvalues μ_1, μ_2 , of A , and the eigenvalues λ_1, λ_2 of B .

- (i) -2 (ii) -1 (iii) -0.5 (iv) 0 (v) 0.5 (vi) 1 (vii) 2

3. (3 points) Suppose M is a symmetric 3×3 matrix with eigenvalues -2 and 1 , and suppose additionally that:

- vectors \mathbf{a} and \mathbf{b} are linearly independent, unit-length eigenvectors for M with eigenvalue -2 ; and
- vector \mathbf{c} is a unit-length eigenvector for M with eigenvalue 1 .

If we define the vector \mathbf{x} by

$$\mathbf{x} = M^{2021}(\mathbf{a} - \mathbf{c}),$$

then suppose

- the angle between \mathbf{x} and \mathbf{a} is A degrees; and
- the angle between \mathbf{x} and \mathbf{b} is B degrees; and
- the angle between \mathbf{x} and \mathbf{c} is C degrees.

What are the approximate values of A, B, C ?

- (i) 0 (ii) 45 (iii) 90 (iv) 135
 (v) 180 (vi) not enough information to determine

4. (2 points) Suppose A and B are 2×2 symmetric matrices. In which of the following situations can we conclude that the collection of A 's eigenvalues must be the same as the collection of B 's eigenvalues? Select all that apply. (Note that each situation is to be considered separately.)

- (i) A and B have the same determinant, and each has 5 as an eigenvalue.
 (ii) A and B have the same trace, and each has $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ as an eigenvector.
 (iii) A and B have the same trace and determinant.

5. (3 points) Let A be a 3×3 matrix and let λ be an eigenvalue of A . Which of the following are possible dimensions of $C(A - \lambda I_3)$?
Select all that apply.

(a) 0 (b) 1 (c) 2 (d) 3

6. (2 points) Recall from Exam 4 the Markov matrix

$$M = \begin{bmatrix} 3/4 & 1/6 & 0 \\ 1/4 & 2/3 & 1/2 \\ 0 & 1/6 & 1/2 \end{bmatrix}$$

describing the weekly dynamics of universities' opening and closing. M has eigenvectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ with corresponding eigenvalues $1, 2/3, 1/4$.

$M^{2021}(\mathbf{v}_1 + 2\mathbf{v}_2 + 3\mathbf{v}_3)$ is approximately

(a) \mathbf{v}_1 (b) $2\mathbf{v}_2$ (c) $3\mathbf{v}_3$ (d) $\mathbf{0}$

7. (2 points) Let L be a lower triangular matrix, and $A = LL^\top$. Which of the following statements are always true? Select all that apply.

- (a) LL^\top is an LU -decomposition of A .
 (b) $L^\top L$ is an LU -decomposition of A .
 (c) Solutions to $A\mathbf{x} = \mathbf{b}$ are the same as solutions to $L\mathbf{x} = \mathbf{b}$.
 (d) Solutions to $A\mathbf{x} = \mathbf{b}$ are the same as solutions to $L^\top \mathbf{x} = \mathbf{b}$.
 (e) If L is invertible, then solutions to $A\mathbf{x} = \mathbf{b}$ are the same as solutions to $L^\top \mathbf{x} = L^{-1}\mathbf{b}$.
 (f) Solutions to $A\mathbf{x} = \mathbf{b}$ are the same as solutions to $L\mathbf{x} = L^\top \mathbf{b}$.
 (g) Solutions to $A\mathbf{x} = \mathbf{b}$ are the same as solutions to $L^\top \mathbf{x} = L\mathbf{b}$.

8. (3 points) The symmetric matrix A has the property that

$$A \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ 1 \\ 2 \end{bmatrix} \quad \text{and} \quad A \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -14 \\ -7 \\ 7 \end{bmatrix}.$$

Which of the following vectors \mathbf{v} satisfies $q_A(\mathbf{v}) = \mathbf{v}^\top A \mathbf{v} = 0$?

- (a) $\begin{bmatrix} 0 \\ 3 \\ 9 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} - \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$
 (b) $\begin{bmatrix} -27 \\ -12 \\ 18 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} - 14 \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$
 (c) $\begin{bmatrix} 12 \\ 27 \\ 57 \end{bmatrix} = 14 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} - \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$
 (d) $\begin{bmatrix} -36 \\ -9 \\ 45 \end{bmatrix} = 6 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} - 21 \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$

9. (2 points) Suppose a 3×3 invertible matrix A has QR-decomposition given by $A = QR$. Suppose A_1 is obtained from A by scaling its second column by a factor of c , while the other two columns are the same as the corresponding columns of A . What can you say about the QR decomposition of A_1 ?
- $A_1 = Q_1 R_1$ where $Q_1 = Q$ and R_1 is obtained from R by scaling its second column by a factor of c , while the other two columns of R_1 are the same as the corresponding columns of R .
 - $A_1 = Q_1 R_1$ where $Q_1 = Q$ and R_1 is obtained from R by scaling its second row by a factor of c , while the other two rows of R_1 are the same as the corresponding rows of R .
 - $A_1 = Q_1 R_1$ where $R_1 = R$ and Q_1 is obtained from Q by scaling its second column by a factor of c , while the other two columns of Q_1 are the same as the corresponding columns of Q .
 - $A_1 = Q_1 R_1$ where $R_1 = R$ and Q_1 is obtained from Q by scaling its second row by a factor of c , while the other two rows of Q_1 are the same as the corresponding rows of Q .

10. (3 points) Suppose A is a 2×2 matrix with eigenvalues 2 and 3. Let

$$B = A^2 - 5A + 6I_2.$$

Which of the following statements are correct? Select all that apply.

- \mathbf{R}^2 has a basis consisting of eigenvectors of A .
 - If \mathbf{v} is an eigenvector for A , then \mathbf{v} is also an eigenvector for B .
 - If \mathbf{v} is an eigenvector for B , then \mathbf{v} is also an eigenvector for A .
 - $B = 0$, i.e. B is a 2×2 matrix all of whose entries are 0.
 - $B \neq 0$, i.e. B is not a 2×2 matrix all of whose entries are 0.
11. (3 points) A population of 60 goats moves between three meadows, labeled A , B , and C . Their daily movement is modeled by a symmetric Markov matrix M (whose rows and columns correspond to meadows A , B , and C , in that order).

Let

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}.$$

Assume that \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 are eigenvectors of M with eigenvalues $\lambda_1 = 1$, $\lambda_2 = \frac{5}{9}$, and $\lambda_3 = \frac{1}{3}$, respectively.

If k is large enough that $\left(\frac{5}{9}\right)^k \approx 0$ and $\left(\frac{1}{3}\right)^k \approx 0$, how many goats are there in meadow B after k days? (Your answer should be an integer.)

12. (4 points) Suppose A is a symmetric matrix with eigenvectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ and corresponding eigenvalues 1, 2, 3. Match each of the following inputs, (a)–(d), to its output (among (1)–(6); some inputs may match to the same output).

(a) $(\mathbf{v}_2 \cdot \mathbf{v}_3)\mathbf{v}_1$

(b) $(A\mathbf{v}_2 \cdot A\mathbf{v}_3)\mathbf{v}_1$

(c) $\mathbf{Proj}_{\mathbf{v}_2} A(\mathbf{v}_2 + \mathbf{v}_3)$

(d) $A(\mathbf{v}_1 + \mathbf{v}_2 + \mathbf{Proj}_{\mathbf{v}_2}(\mathbf{v}_3))$

(1) $\mathbf{0}$

(2) $6\mathbf{v}_1$

(3) $2\mathbf{v}_2$

(4) $2\mathbf{v}_1$

(5) $\mathbf{v}_1 + 2\mathbf{v}_2$

(6) $\mathbf{v}_1 + 2\mathbf{v}_2 + 3\mathbf{v}_3$