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AN EFFECTIVE NEW HEURISTIC ALGORITHM FOR SOLVING PERMUTATION FLOW SHOP SCHEDULING PROBLEM

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ABSTRACT. The deterministic permutation flow shop scheduling problem with makespan criterion is not solvable in polynomial time. Therefore, researchers have thought about heuristic algorithms. There are many heuristic algorithms for solving it that is a very important combinatorial optimization problem. In this paper, a new algorithm is proposed for solving the mentioned problem. The presented algorithm chooses the weighted path that starts from the up-left corner and reaches the down-right in the matrix of jobs processing times and calculates the biggest sum of the times in the footprints of this path. The row with the biggest sum permutes among all the rows of the matrix for locating the minimum of makespan. This method was run on Taillards standard benchmark and the solutions were compared with the optimum or the best ones as well as 14 famous heuristics. The validity and effectiveness of the algorithm are shown with tables and statistical evaluation.

1. Introduction

In recent years, the number of efficient and good heuristic algorithms for solving n jobs, m machines deterministic permutation flow shop scheduling problems (PFSP) with the makespan criterion has been reduced. About 70 years have passed from the beginning of studying PFSP. Unfortunately, it has not been solved exactly. In spite of all these issues, it was proved by Garey et al. that PFSP for m greater than three is NP-complete in the strong sense [11]. Therefore, that was motivated into solving the problem with heuristic methods.

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In 1954, an exact algorithm was presented by Johnson for solving PFSP with m = 2 [18]. However, sometimes problems with three or more machines have converted to some with two machines.

The most famous heuristic algorithms for solving PFSP have been proposed by Page [26], Palmer [27], Campbell et al. [5], Gupta [13], Bonney and Gundry [3], Dannenbring [6], King and Spachis [20], and Stinson and Smith [34].

In 1983, a heuristic algorithm was presented by Nawaz, Enscore, and Ham (NEH) for solving PFSP, which is the lord of heuristic algorithms [24]. In 2005, Kalszynski and Kamburowski as well as Ruiz and Maroto showed that the quality and running time of NEH were better than those of all the others [19, 30]. Afterward, there have been many works about solving PFSP for example, Hundal and Rajgopal [16], Ho and Chang [15], Sarin and Lefoka [31], Koulamas [21], and Suliman [35]. After these years, studying and researching about the heuristic algorithms for solving PFSP with makespan criterion have demonstrated that proposed algorithms are not better than NEH.

Also, the summary of all these subjects and papers for solving PFSP with heuristic algorithms can be found in Framinan et al. [10], Ruiz and Maroto [30], Hejazi and Saghafian [14], T'kindt and Billaut [38], and Pott and Strusevich [28].

Rad et al. [29] proposed five new algorithms. In 2012, Ancau proposed a constructive algorithm [1]. Singhal et al. [33] proposed a method that was obtained by modifying the NEH algorithm.

Malik and Dhingra [23] presented a comparative analysis of heuristics for minimizing C_{max} in PFSP. Xu et al. [40] improved an algorithm based on a dynamic neighborhood for the PFSP. Valada et al. [39] discovered a new benchmark for PFSP with minimizing makespan criterion. Liu et al. [22] proposed a new NEH based heuristic. Fernandez et al. [9] presented a new vision of approximate methods for the problem. Brum and Ritt [4] studied the application of automatic algorithm configuration. Nurdiansyah et al. [25] proposed an improved differential evaluation algorithm. Sauvey and Sauer [32] discovered two new heuristic improvements to the original NEH.

There are a large number of algorithms that were proposed for solving PSFP with makespan criterion, but the results of these algorithms are studied on problems with different measures and only on little amounts of m and n. For comparing the validity and effectiveness of this category of algorithms, it is convenient that the number of machines is equal and then the number of jobs is even in them as far as possible. Furthermore, the jobs processing times are alike for all algorithms and these specified uniformed of m and n. All the above algorithms were run on Taillard's benchmark. Collecting both traditional and contemporary conclusions of numerousness of other algorithms is impossible because they were not run on the same standard benchmark.

This paper includes five sections. In the remainder, four sections are presented. Section two provides assumptions that are in an arbitrary PFSP with minimizing makespan denoted by $C_{\rm max}$. In section three, we study the proposed algorithm step by step. Next, we explain the running of this algorithm on Taillard's benchmark. Finally, the results are given plus the comparison of 15 heuristics, including ours and 14 others.

2. Problem Description

A PFSP deals with finding the best queue of n jobs that are to be processed on m machines. Processing of jobs on machines has the same order. Let p_{ij} denotes the processing time of job j at machine i. We suppose that each p_{ij} is strictly positive and deterministic. After studying partial sequences of jobs, our objective is to determine a sequence that minimizes the maximum completion time. This objective is called makespan or C_{max} .

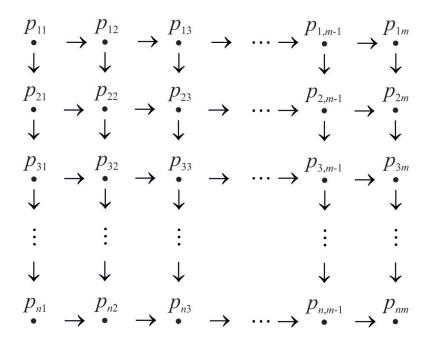
In PFSP, we suppose that:

- (1) All jobs and machines are ready for starting and continuing the process.
- (2) All jobs are separately processed.
- (3) There is a one to one corresponding between jobs processing and machines at any time.
- (4) Each job continuously is processed at a machine.
- (5) Processing times are included the set-up times.
- (6) In processing, between any two machines buffer storage is infinite.

In general, we have many possible job orders. Since every order can change from one machine to another, there are $(n!)^m$ schedules. As for all machines the order is the same and fixed, there are n! possible schedules. This problem is denoted as $Fm|Prmu|C_{\text{max}}$ by Graham et al. [12].

3. Heuristic Algorithm

Let $M = [p_{ij}], n \ge i \ge 1, m \ge j \ge 1$, be the matrix of jobs processing times in PFSP. From the scheduling literature, we have the following directed graph.



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As shown in Bellman et. al. [2], the PFSP from another perspective is a permutation of rows in M so that the length of the longest path is reduced. Additionally, in the base of problem conditions in a given solution one path that starts from p_{11} must end in p_{nm} only with passes to right and to below. This path crosses from m + n - 1 $p_{ij}s$ which are called footprints. The sum of all footprints in a path is called weight of this path.

Based on the above ideas, each row in M is chosen and the possible nodes at it are evaluated while we try to minimize C_{max} .

We present a new algorithm that is divided into six steps:

- (1) All the paths that start from the up-left corner and reach the down-right one are held.
- (2) The weighted path in step one is chosen.
- (3) In the previous step, the weighted path's footprints are followed in each row and sum all the times in these footprints is obtained in it. Then, the biggest one in these sums is determined.
- (4) The row to which the biggest sum in the previous step was related, is specified. This row is permuted among all the rows of M and, in each case, the minimum of makespans is calculated.
- (5) The row that is obtained in step 4 is determined and its place that causes the least of minimums is obtained. The row is stabilized in this place and then step 1 is repeated.
- (6) The above process is repeated and the obtained rows are stabilized. Finally, the minimum of makespans of the obtained matrix is determined.

This algorithm is denoted in abbreviation by FRS.

4. Computation Evaluation

The heuristic was implemented in Visual Basic and all the problems were carried on a Pentium IVPC/AT computer running at 3.2 GHz with 2 GB RAM memory.

The proposed algorithm was tested on the standard benchmark set by Taillard [36]. The results of these tests are shown in Table 1. The set of Taillard's problems includes 120 instances divided into 12 groups with 10 replicates each. The sizes range from 20 jobs and 5 machines to 500 jobs and 20 machines. This benchmark has been used extensively in these years. For each problem, a very tight lower bound and upper bound are known. All ten in 50×20 , nine in 100×20 , six in 200×20 , and three in 500×20 instances are still open. All other instances have optimum solutions.

In each case, the relative percentage deviation (RPD) was used:

$$RPD = \frac{Heu_{sol} - Best_{sol}}{Best_{sol}} \times 100.$$

In this formula, Heu_{sol} is the solution of the discussed heuristics for a given case and Best_{sol} is the optimum solution or the lowest known upper bound for Taillard problems.

 $\ensuremath{\mathsf{TABLE}}$ 1. Makespans and RPD's for Taillard's benchmark problems

Instance	ID	Heuristic Makespan	RPD	Instance	ID	$Heuristic\\ Makespan$	RPD
20×5				100×5			
	1	1324	0.03		1	5564	0.01
	2	1383	0.01		2	5385	0.02
	3	1246	0.15		3	5325	0.02
	4	1446	0.11		4	5058	000
	5	1355	0.09		5	5439	0.03
	6	1268	0.06		6	5235	0.01
	7	1296	0.05		7	5373	0.02
	8	1283	0.06		8	5270	0.03
	9	1313	0.06		9	5506	0.01
	10	1167	0.05		10	5386	0.01
20×10				100×10			
	1	1731	0.09		1	5975	0.03
	2	1821	0.09		2	5678	0.06
	3	1647	0.10		3	5875	0.03
	4	1505	0.09		4	6143	0.06
	5	1718	0.21		5	5774	0.05
	6	1501	0.07		6	5552	0.04
	7	1635	0.10		7	5924	0.05
	8	1689	0.09		8	5887	0.04
	9	1730	0.08		9	6198	0.05
	10	1831	0.15		10	6114	0.04
20×20				100×20			
	1	2451	0.06		1	6715	0.09
	2	2245	0.06		2	6768	0.09
	3	2492	0.07		3	6838	0.04
	4	2484	0.11		4	6679	0.06
	5	2435	0.06		5	6892	0.10

	6	2346	0.05		6	6930	0.09
	7	2410	0.06		7	6881	0.11
	8	2325	0.05		8	6923	0.09
	9	2381	0.06		9	6815	0.09
	10	2360	0.08		10	6885	0.07
50×5				20×10			
	1	2774	0.01		1	11281	0.03
	2	2934	0.03		2	10705	0.02
	3	2710	0.03		3	11159	0.02
	4	2973	0.08		4	11210	0.02
	5	2935	0.02		5	10897	0.03
	6	2881	0.01		6	10692	0.03
	7	2888	0.05		7	11165	0.02
	8	2808	0.04		8	10961	0.02
	9	2654	0.03		9	10736	0.02
	10	2850	0.02		10	10921	0.02
50×10				200×20			
	1	3288	0.09		1	11952	0.07
	2	3136	0.09		2	12025	0.06
	3	3154	0.11		3	12051	0.06
	4	3270	0.06		4	12034	0.06
	5	3262	0.09		5	11825	0.05
	6	3252	0.08		6	11925	0.06
	7	3462	0.11		7	12175	0.07
	8	3253	0.07		8	11978	0.05
	9	3261	0.12		9	11971	0.07
	10	3375	0.10		10	12081	0.07
50×20				500×20			
	1	4161	0.10		1	26957	0.03
	2	4117	0.12		2	27391	0.03
	3	4010	0.11		3	27337	0.03

4	4099	0.12	4	27390	0.03
5	4087	0.15	5	27227	0.03
6	4035	0.10	6	27541	0.04
7	4016	0.09	7	27051	0.02
8	3964	0.09	8	27446	0.03
9	4110	0.12	9	27101	0.04
10	4073	0.10	10	27336	0.03

In 20×5 , 20×10 , and 20×20 problems, the average RPD was obtained as 6.7%, 10.7%, and 6.6%, respectively. These were desired results for 20 job problems. In 50×5 , 50×10 , and 50×20 problems, the average RPD was obtained as 3.2%, 9.3%, and 11%, respectively. In 100×5 , 100×10 and 100×20 problems, average RPD is 1.6%, 4.5% and 8.4% respectively, that are favorable results.

For 200×10 , 200×20 , and 500×20 problems, the average RPD is 2.3%, 6.2%, and 3.1%, respectively, which are excellent. Thus, it seems that the proposed algorithm is suitable for large scale problems than others. It is also observed that, for a number of Taillard problems, the results of the proposed algorithm are close to the optimum. The average percentage increase over the best solution known for the proposed algorithm is shown in Table 2. It is worth mentioning that authors rarely have calculated

Table 2. Average percentage increase over the best solution known for the FRS

Problem	heuristic
20×5	6.6
20×10	10.7
20×2	6.8
50×5	3.4
50×10	9.2
50×20	11
100×5	1.6
100×10	4.5
100×20	8.3
200×10	2.3
200×20	6.2
500×20	3.1

the complexity of their algorithms for PFSP in previous decades. In Table 3, the complexity and acronyms of some algorithms are collected.

year Author Acronym Complexity 1954 Johnson Johns $O(n \log n)$ 1961 Page Page — 1965 Palmar Palme $O(mn + n \log n)$ 1970 Campbell CDS $O(m^2n + n \log n)$ 1972 Gupta — 1977 Dannenloring RA $O(mn + n \log n)$ RACS — RAES — 1983 Nawaz et al. NEH $O(n^2m)$ 1988 Hunda and Rajgopal HunRa $O(mn + n \log n)$ 1991 Ho and Chang Hocha — 1998 Koulamas Koula $O(m^2n^2)$ 2000 Suliman Sulim — 2001 Davoud Pour Pour — 2012 Ankau CG $O(n^3)$ SG $O(n^2)$				
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	year	Author	A cronym	Complexity
1965 $Palmar$ $Palme$ $O(mn + n \log n)$ 1970 $Campbell$ CDS $O(m^2n + n \log n)$ 1972 $Gupta$ $Gupta$ $-$ 1977 $Dannenloring$ RA $O(mn + n \log n)$ $RACS$ $ RAES$ $-$ 1983 $Nawaz$ et al. NEH $O(n^2m)$ 1988 $Hunda$ and $Rajgopal$ $HunRa$ $O(mn + n \log n)$ 1991 Ho and $Chang$ $Hocha$ $-$ 1998 $Koulamas$ $Koula$ $O(m^2n^2)$ 2000 $Suliman$ $Sulim$ $-$ 2001 $Davoud$ $Pour$ $Pour$ $-$ 2012 $Ankau$ CG $O(n^3)$	1954	Johnson	Johns	$O(n \log n)$
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	1961	Page	Page	_
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1965	Palmar	Palme	$O(mn + n\log n)$
1977 Dannenloring RA $O(mn + n \log n)$ RACS — RAES — 1983 Nawaz et al. NEH $O(n^2m)$ 1988 Hunda and Rajgopal HunRa $O(mn + n \log n)$ 1991 Ho and Chang Hocha — 1998 Koulamas Koula $O(m^2n^2)$ 2000 Suliman Sulim — 2001 Davoud Pour Pour — 2012 Ankau CG $O(n^3)$	1970	Campbell	CDS	$O(m^2n + n\log n)$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1972	Gupta	Gupta	_
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1977	Dannenloring	RA	$O(mn + n\log n)$
1983 Nawaz et al. NEH $O(n^2m)$ 1988 Hunda and Rajgopal HunRa $O(mn + n \log n)$ 1991 Ho and Chang Hocha — 1998 Koulamas Koula $O(m^2n^2)$ 2000 Suliman Sulim — 2001 Davoud Pour Pour — 2012 Ankau CG $O(n^3)$			RACS	_
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1991 Ho and Chang Hocha — 1998 Koulamas Koula $O(m^2n^2)$ 2000 Suliman Sulim — 2001 Davoud Pour Pour — 2012 Ankau CG $O(n^3)$	1983	Nawaz et al.	NEH	$O(n^2m)$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1988	Hunda and Rajgopal	HunRa	$O(mn + n\log n)$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1991	Ho and Chang	Hocha	_
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1998	Koulamas	Koula	$O(m^2n^2)$
2012 $Ankau$ CG $O(n^3)$	2000	Suliman	Sulim	_
	2001	Davoud Pour	Pour	_
SG $O(n^2)$	2012	Ankau	CG	$O(n^3)$
			SG	$O(n^2)$

Table 3. Complexity and Acronyms of Compared Algorithms

Our results were compared with the information about famous heuristics in the literature in Tables 1 and 3 of Ruiz and Maroto [30]. However, all the algorithms have not been executed in the same computer environment. We see that our heuristic is really better than the other 13 methods. Unfortunately, the results of SG and CG are not completely mentioned in Ankau's paper [1].

As it mentioned before in many last papers, NEH algorithm is the best one among heuristic algorithms for solving PFSP. We just compare the results of the above FRS with the other 14 ones in Table 4. For every problem size, the solutions have averaged the 10 corresponding instances.

As can be seen in Table 4, the RPD results of Gupta are usually larger than the others, so they are not suitable. However, in the comparison of algorithms, both complexity and running time shouldn't be ignored. The results of Table 4 also lead to the conclusion that FRS is much better than the 13 prior algorithms' to NEH. The presented algorithm i.e. FRS outperforms Johns, Page, CDS, Gupta, RA, Racs, RAES, HunRa, Hocha, kula, Sulim, and Pour. It has better solutions in 141 cases and gives worse in 15 instances than them. In the 13 algorithms prior to FRS, Sulim is better than the others. On the other hand, FRS is about 91% better than the 13 prior algorithms but in the instances group 20×5 , 20×10 , 20×20 , 50×5 , 50×10 , 50×20 and 100×5 is worse in 2, 4, 2, 3, 1, 2 and 1 cases respectively.

TABLE 4. Average percentage increase over the best solution known for the heuristic algorithms

J/M	Johns	Page	Palme	CDS	Gupta	RA	RACS	RAES	NEH	HunRa	Hocha	Koula	Sulim	Pour	FRS
20×5	12.78	15.15	10.58	9.54	12.45	8.86	7.71	4.95	3.35	9.35	6.94	7.68	4.46	12.05	6.60
20×10	19.97	20.43	15.28	12.13	24.48	15.40	10.66	8.62	5.02	13.34	10.51	11.82	7.84	12.34	10.70
20×20	16.47	16.18	16.34	9.64	22.53	16.35	8.16	6.41	3.73	13.47	8.30	11.89	6.69	10.71	6.80
50×5	10.43	10.14	5.34	6.10	6.30	6.30	5.40	3.28	0.84	4.21	3.33	4.03	2.20	6.58	3.40
50×10	21.90	20.47	14.01	12.98	22.05	15.05	12.19	10.41	5.12	13.35	11.29	12.13	8.46	14.44	9.20
50×20	22.81	23.12	15.99	13.85	23.66	18.88	12.86	10.00	6.20	14.99	12.40	14.93	9.62	14.87	11.00
100×5	6.84	7.98	2.38	5.01	6.02	3.54	4.58	3.25	0.46	1.99	2.70	3.12	1.28	4.06	1.60
100×10	15.1	15.79	9.20	9.15	15.12	10.48	8.72	7.31	2.13	8.12	7.96	7.50	5.75	7.82	4.50
100×20	21.15	21.68	14.41	13.12	22.68	16.96	12.48	10.56	5.11	13.65	11.10	14.04	9.28	13.18	8.30
200×10	11.47	12.74	5.13	7.38	11.80	6.17	7.11	6.16	1.43	4.50	5.11	5.09	4.09	5.52	2.30
200×20	18.93	19.43	13.17	12.08	19.67	12.67	11.83	10.39	4.37	12.59	9.99	11.60	8.85	11.50	6.20
500×20	14.07	14.05	7.09	8.55	13.66	8.34	8.38	7.77	2.24	6.75	7.14	6.82	6.06	7.69	3.10
Average	15.99	16.43	10.74	9.96	17.21	11.58	9.17	7.43	3.33	9.69	8.06	9.22	6.21	10.07	6.14

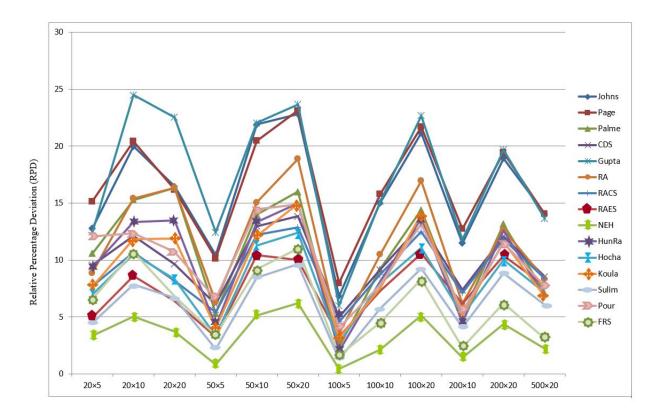


FIGURE 1. Plot of RPDs of Heuristics on Taillard problem Indiances

For a suitable visualization from statistical considerations, we have made a line graph. This graph confirms that the results of FRS are better than 13 well-known heuristics. In Figure 1, the plots depict the average RPD for all heuristics.

Means plots for the compared algorithms show the grade of all 15 algorithms in Figure 2. In this Figure, Y-axis declares average RPD obtained for all instances.

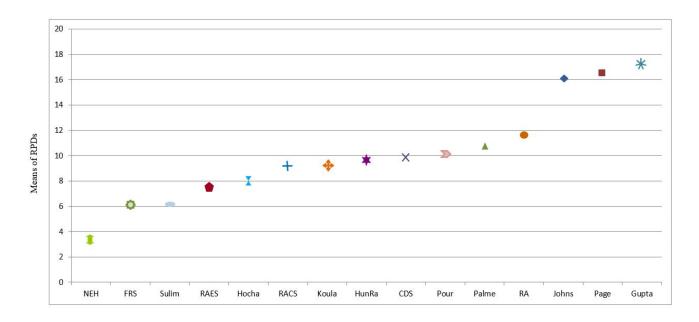


FIGURE 2. Means Plots for the Compared Algorithms

As it mentioned in the comparison, NEH solutions are better than the others and FRS solutions are close to NEH even in the problems number 26 and 92, FRS provides much better solutions. On the contrary, Jin et al. proved that the classical NEH spends a lot of time in order to find the final results in large-scale problems [17] whereas FRS gets more effective in big-size problems. First of all, in NEH the completion time of all jobs on machines could be obtained. Secondly, job sequences might be ordered on the base of the decreasing times of completion. In third place, the already jobs of partial sequences would be made by jobs and initial order iteratively. This happens in two steps to minimize the makespan

- (1) Two jobs are chosen and then an ordered sequence is found by these two.
- (2) For k = 3, 4, ..., n, kth job is inserted among the terms of sequence without changing the order of k 1 remaining jobs.

In this regard, there are k different places to make the partial makespan minimize. The kth job is inserted in ordered sequence with k-1 sentences. Additionally, the minimum of partial makespans is kept. The ordered sequence includes k+1 jobs and minimized makespan. These repetition schedules ordered sequence with the objective of minimizing the makespan of n jobs. This type of NEH is called classic and in order to decrease the quantity of makespan, redundant sequences are inserted too.

In many efficient heuristic methods, inserting job among the others in neighborhood is used for finding high quality solution just like NEH. Thus, the key point is to employ the techniques that accelerate the evaluation of objective function. The earliest of these were devised by Taillard for improvement and also acceleration of NEH [37]. The presented method, called Taillard acceleration,

is usable for PFSP problems with makespan criterion provided that the job is inserted among the other ones. Fernandez et al. discovered that, unfortunately, Taillard acceleration is not applicable to a PFSP problem unless it has the objective of optimizing makespan [8]. FRS algorithm also inserts jobs to evaluate the optimum of C_{max} , that's why running time is saved by Taillard acceleration. Fernandez et al. depicted that Taillard acceleration is not suitable in PFSP with NEH-based algorithms as long as the objective is minimizing makespan [8]. Consider the case of NEHedd famous algorithm. It is intended in improvement heuristics to optimize total completion time i.e. sum of completion times of all jobs in Fernandez et. al. [7]. What gives FRS a distinct advantage over NEH is its hopeful capability of using Taillard acceleration in FRS-based heuristics. The aim in this heuristics is to minimize total completion time.

5. Conclusion

In this paper, a new algorithm (FRS) was proposed that could outperform many famous heuristics for PFSP under the minimization of the makespan on Taillard's benchmark and has the highest rank among them. The validity and effectiveness of the algorithm are shown with tables and statistical evaluations. The line graphs and scatter plots provide a clear mathematical visualization. Both FRS and NEH have brilliant performances. Their easy adoptions to similar problems are going to apply in scheduling problems.

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