Practical_ML DF 11/15/2022

Introduction

Using devices such as Jawbone Up, Nike Fuel Band, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These types of devices are part of the quantified self movement - a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. Six young health participants were asked to perform one set of 10 repetitions of the Unilateral Dumbbell Biceps Curl in five different fashions: exactly according to the specification (Class A), throwing the elbows to the front (Class B), lifting the dumbbell only halfway (Class C), lowering the dumbbell only halfway (Class D) and throwing the hips to the front (Class E). Class A corresponds to the specified execution of the exercise, while the other 4 classes correspond to common mistakes. Participants were supervised by an experienced weight lifter to make sure the execution complied to the manner they were supposed to simulate. The exercises were performed by six male participants aged between 20-28 years, with little weight lifting experience. It was made sure that all participants could easily simulate the mistakes in a safe and controlled manner by using a relatively light dumbbell (1.25kg). My goal here is to predict the "class" with the help of other predictors. This project is a part of Coursera Practical Machine Learning Week 4 - Peer-graded Assignment: Prediction Assignment Writeup.

Data

Load the data

Let's load the data. I have downloaded the data already on my local system. Please download the data from here: Training and Testing. And run this code on the same directory as the data.

```
dfTrain <- read.csv("pml-training.csv", stringsAsFactors = F,na.strings = c("","NA","#DIV/0!"))
dfTest <- read.csv("pml-testing.csv", stringsAsFactors = F,na.strings = c("","NA","#DIV/0!"))
dim(dfTrain); dim(dfTest)</pre>
```

[1] 19622 160 ## [1] 20 160

Let's create a validation for model tuning:

```
#for reproducability
set.seed(101)
inTrain <- createDataPartition(dfTrain$classe, p = 0.8, list = F)
dfVal <- dfTrain[-inTrain,]
dfTrain <- dfTrain[inTrain,]
dim(dfTrain); dim(dfVal)</pre>
```

[1] 15699 160

[1] 3923 160

Now 3 partition of our data is ready, lets dive into analysis but 1st lets look at the proportion of different "classe":

```
table(dfTrain$classe)/nrow(dfTrain)
```

A B C D E

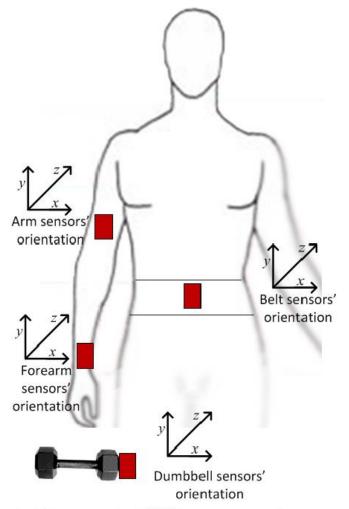
0.2843493 0.1935155 0.1744060 0.1638958 0.1838334

From the above it is clear that there are not that much bias in the data in term of different "classe".

Column overview

The data has 160 columns and for training data 15699 rows. Data was collected with the help of 4 sensors,

shown in the below diagram (diagram source).



The following symbol " designates one of the set of sensors described in the text

Few Key points about the columns:

- "X" is primary key for the data.
- "user_name" is the id of the users. This may help us see interesting patterns for each activity for

different users.

- "classe" is the target for prediction.
- Column 3 to 7 is not necessary for this project. (5 features)
- As mentioned above there are 4 different sensors used for data collection. For each sensor there are 38 different features.
- Each sensor("belt", "arm", "forearm", "dumbbell") has raw accelerometer, gyroscope and magnetometer readings for x, y and z axis. (4 sensor * 3 feature * 3 axis = 36 features)

- Each sensor("belt", "arm", "forearm", "dumbbell") has Euler angles (roll, pitch and yaw) feature. (4 sensor
- * 3 euler angles = 12 features)
- For the Euler angles of each of the four sensors eight features were calculated: mean, variance, standard

deviation, max, min, amplitude, kurtosis and skewness. (4 sensor * 3 feature * 8 measures = 96 features)

• For accelerometer we also have "total" and "variance of total" feature for the 4 sensors. But for

"belt", "variance of total" is given as "var_total_accel_belt", for the other sensors it is given as

("var_accel_arm", "var_accel_dumbbell", "var_accel_forearm"). So I am considering the "belt" one

as a typo. (4 sensor * 2 feature = 8 features)

• There is another thing to note here. For "belt" Euler angles feature skewness is given as "skewness

roll_belt", "skewness_roll_belt.1" and "skewness_yaw_belt". I am also considering "skewness

roll belt.1" as a typo and considering it as "skewness pitch belt".

Missingness in the data

Let's take a quick look at the missingness of the data. As the no of feature is large, its better to see them

by the 4 sensors:

Belt

For Belt sensor:

```
## roll_belt pitch_belt yaw_belt
## 0 0 0
## total_accel_belt kurtosis_roll_belt kurtosis_picth_belt
## 0 15396 15413
## kurtosis_yaw_belt skewness_roll_belt skewness_roll_belt.1
## 15699 15395 15413
## skewness_yaw_belt max_roll_belt max_picth_belt
## 15699 15388 15388
## max_yaw_belt min_roll_belt min_pitch_belt
## 15396 15388 15388
## min_yaw_belt amplitude_roll_belt amplitude_pitch_belt
## 15396 15388 15388
## amplitude yaw belt var total accel_belt avg_roll_belt
```

```
## 15396 15388 15388
## stddev_roll_belt var_roll_belt avg_pitch_belt
## 15388 15388 15388
## stddev_pitch_belt var_pitch_belt avg_yaw_belt
## 15388 15388 15388
## stddev_yaw_belt var_yaw_belt gyros_belt_x
## 15388 15388 0
## gyros_belt_y gyros_belt_z accel_belt_x
## 0 0 0
## accel_belt_y accel_belt_z magnet_belt_x
## 0 0 0
## magnet_belt_y magnet_belt_z
## 0 0
Arm
For Arm sensor:
arm_miss <- sapply(select(dfTrain,names(dfTrain)[grepl("_arm",names(dfTrain))]),</pre>
                  function(x) sum(is.na(x)))
arm miss
## 0 0 0 0
## var_accel_arm avg_roll_arm stddev_roll_arm var_roll_arm
## 15388 15388 15388 15388
## avg_pitch_arm stddev_pitch_arm var_pitch_arm avg_yaw_arm
## 15388 15388 15388 15388
## stddev_yaw_arm var_yaw_arm gyros_arm_x gyros_arm_y
## 15388 15388 0 0
## gyros arm z accel arm x accel arm y accel arm z
## 0 0 0 0
## magnet_arm_x magnet_arm_y magnet_arm_z kurtosis_roll_arm
## 0 0 0 15446
## kurtosis_picth_arm kurtosis_yaw_arm skewness_roll_arm skewness_pitch_arm
## 15448 15398 15445 15448
## skewness_yaw_arm max_roll_arm max_picth_arm max_yaw_arm
## 15398 15388 15388 15388
## min_roll_arm min_pitch_arm min_yaw_arm amplitude_roll_arm
## 15388 15388 15388 15388
## amplitude pitch arm amplitude yaw arm
## 15388 15388
Forearm
```

For Forearm sensor:

```
##
              roll forearm
                                      pitch_forearm
                                                                 yaw forearm
##
##
     kurtosis_roll_forearm
                             kurtosis_picth_forearm
                                                        kurtosis_yaw_forearm
##
                      15448
##
     skewness_roll_forearm
                             skewness_pitch_forearm
                                                        skewness_yaw_forearm
##
                      15447
                                               15449
                                                                        15699
                                                             max_yaw_forearm
##
          max roll forearm
                                  max picth forearm
##
                      15388
                                               15388
                                                                        15448
                                  min_pitch_forearm
                                                             min_yaw_forearm
##
          min_roll_forearm
##
                      15388
                                               15388
                                                                        15448
##
    amplitude_roll_forearm amplitude_pitch_forearm
                                                       amplitude_yaw_forearm
##
                      15388
                                                                        15448
                                               15388
                                  var_accel_forearm
                                                            avg_roll_forearm
##
       total_accel_forearm
##
                                               15388
                                                                        15388
                                                           avg_pitch_forearm
##
       stddev_roll_forearm
                                   var_roll_forearm
##
                      15388
                                               15388
                                                                        15388
##
      stddev_pitch_forearm
                                  var_pitch_forearm
                                                             avg_yaw_forearm
##
                                               15388
                                                                        15388
                      15388
                                    var_yaw_forearm
##
        stddev yaw forearm
                                                             gyros_forearm_x
##
                      15388
                                               15388
                                    gyros_forearm z
##
                                                             accel_forearm_x
           gyros_forearm_y
##
##
           accel_forearm_y
                                    accel_forearm_z
                                                            magnet_forearm_x
```

```
## 0 0 0
## magnet_forearm_y magnet_forearm_z
## 0 0
```

Dumbbell

For Dumbbell sensor:

```
##
              roll_dumbbell
                                       pitch_dumbbell
                                                                   yaw_dumbbell
##
##
                              kurtosis_picth_dumbbell
     kurtosis roll dumbbell
                                                          kurtosis_yaw_dumbbell
##
                       15392
                                                 15390
##
                            skewness_pitch_dumbbell
     skewness_roll_dumbbell
                                                          skewness_yaw_dumbbell
##
                       15391
##
          max_roll_dumbbell
                                   max_picth_dumbbell
                                                               max_yaw_dumbbell
##
                       15388
                                                 15388
                                                                           15392
          min_roll_dumbbell
##
                                   min_pitch_dumbbell
                                                               min_yaw_dumbbell
##
                       15388
                                                 15388
                                                                           15392
    amplitude_roll_dumbbell amplitude_pitch_dumbbell
##
                                                         amplitude_yaw_dumbbell
##
                       15388
                                                 15388
                                                                           15392
##
       total_accel_dumbbell
                                   var accel dumbbell
                                                              avg_roll_dumbbell
##
                                                 15388
                                                                           15388
##
       stddev_roll_dumbbell
                                    var_roll_dumbbell
                                                             avg_pitch_dumbbell
##
                       15388
                                                 15388
                                                                           15388
                                                               avg_yaw_dumbbell
##
      stddev_pitch_dumbbell
                                   var pitch dumbbell
##
                       15388
                                                 15388
                                                                           15388
##
        stddev_yaw_dumbbell
                                     var_yaw_dumbbell
                                                               gyros_dumbbell_x
                       15388
                                                 15388
##
           gyros dumbbell y
                                    gyros_dumbbell_z
                                                               accel dumbbell x
##
                                                     0
           accel_dumbbell_y
                                    accel_dumbbell_z
                                                             magnet_dumbbell_x
##
##
          magnet_dumbbell_y
                                    magnet_dumbbell_z
```

So it is very interesting to see that few of the features are over 90% missing, I would drop those columns for

further analysis. But the interesting thing is that all of those columns have same no of NA values.

[1] 100

So we can drop 100 column as they are mostly missing. After we drop these column there will be 52 predictors left.

Analysis

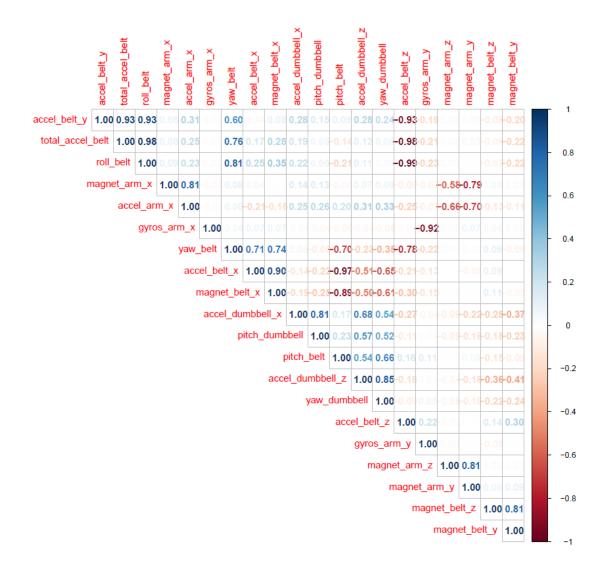
Now lets get into analysis, first let's look at the correlation among the predictors.

```
#dropping the cols
dfAnalize <- tbl_df(dfTrain %>%
                      select(-column_2drop,
                             -c(X,user_name, raw_timestamp_part_1,
                                raw_timestamp_part_2, cvtd_timestamp,
                                new_window,num_window)))
## Warning: 'tbl_df()' was deprecated in dplyr 1.0.0.
## i Please use 'tibble::as_tibble()' instead.
## Warning: Using an external vector in selections was deprecated in tidyselect 1.1.0.
## i Please use 'all_of()' or 'any_of()' instead.
## # Was:
    data %>% select(column_2drop)
##
##
## # Now:
## data %>% select(all_of(column_2drop))
## See <https://tidyselect.r-lib.org/reference/faq-external-vector.html>.
```

```
dfAnalize$classe <- as.factor(dfAnalize$classe)
dfAnalize[,1:52] <- lapply(dfAnalize[,1:52],as.numeric)
dim(dfAnalize)
## [1] 15699 53</pre>
```

Correlation among predictors

```
corr_col <- cor(select(dfAnalize, -classe))</pre>
diag(corr_col) <- 0</pre>
corr_col <- which(abs(corr_col)>0.8,arr.ind = T)
corr_col <- unique(row.names(corr_col))</pre>
corrplot(cor(select(dfAnalize,corr_col)),
         type="upper", order="hclust",method = "number")
## Warning: Using an external vector in selections was deprecated in tidyselect 1.1.0.
## i Please use 'all_of()' or 'any_of()' instead.
##
    # Was:
##
    data %>% select(corr_col)
##
##
    # Now:
##
    data %>% select(all_of(corr_col))
## See <https://tidyselect.r-lib.org/reference/faq-external-vector.html>.
```



Here I have subsetted the data to show only the columns for which absolute correlation is higher than 0.8

with at least one other column. From Correlation plot it is clear that there is lot of columns that are highly

correlated. That might be an issue when we will be in modeling phase. Either we can drop those columns

or we can perform PCA(Principal Components Analysis). One important thing to note from this graph is

that high correlation is only seen between the same sensor i.e. "belt", "arm", "forearm" and "dumbbell".

Correlation with the target

As the target is a categorical variable, we cannot check correlation with the other variables directly. But we

can use **correlationfunnel::correlate** to see the correlation with each level of "classe" and other features.

Lets go by them one by one.

```
# binarizing data
#correlationfunnel website: https://business-science.github.io/correlationfunnel/
corr funl df <- dfAnalize %>% binarize(n bins = 4, thresh infreq = 0.01)
    classe A
    corr_a <- corr_funl_df %>% correlate(target = classe__A)
    corr_a %>% plot_correlation_funnel(interactive = T,limits = c(-0.5,0.5))
    For *classe___A* it seems that the "Arm and Forearm" sensors are more important.
       • "accel_arm_x" is correlated with "magnet_arm_x", so wont consider.

"gyros_arm_y" is correlated with "gyros_arm_x", so wont consider.
So top 5 significant features for "classe__A" are - (magnet_arm_x, pitch_forearm , mag-

         net_dumbbell_y, roll_forearm, gyros_dumbbell_y)
    classe B
    corr b <- corr funl df %>% correlate(target = classe B)
    corr b %>% plot_correlation_funnel(interactive = T, limits = c(-0.5,0.5))
    For *classe__B* it seems that the "Dumbbell and Belt" sensors are more important.
       • So top 5 significant features for "classe__A" are - (magnet_dumbbell_y, magnet_dumbbell_x ,
         roll_dumbbell , magnet_belt_y , accel_dumbbell_x )
    classe\_\_C
    corr_c <- corr_funl_df %>% correlate(target = classe__C)
    corr_c %>% plot_correlation_funnel(interactive = T,limits = c(-0.5,0.5))
    For *classe C* it seems that the "Dumbbell" sensors are more important.
       • So top 5 significant features for "classe__A" are - (magnet_dumbbell_y, roll_dumbbell , ac-
```

cel dumbbell y , magnet dumbbell x , magnet dumbbell z)

```
corr_d <- corr_funl_df %>% correlate(target = classe__D)
corr_d %>% plot_correlation_funnel(interactive = T,limits = c(-0.5,0.5))
```

For *classe D* it seems that the "Forearm, Arm and Dumbbell" sensors are more important.

• So top 5 significant features for "classe__A" are - (pitch_forearm , magnet_arm_y , magnet_forearm_x, accel_dumbbell_y, accel_forearm_x)

classe E

```
corr_e <- corr_funl_df %>% correlate(target = classe__E)
corr_e %>% plot_correlation_funnel(interactive = T,limits = c(-0.5,0.5))
```

For *classe E* it seems that the "Belt" sensors are more important.

- "total_accel_belt" is correlated with "roll_belt", so wont consider.
- "yaw belt" is correlated with "roll belt", so wont consider.
- "accel_belt_z" is correlated with "roll_belt", so wont consider.
- • So top 5 significant features for "classe__A" are - (magnet_belt_y , magnet_belt_z , roll_belt, gyros_belt_z , magnet_dumbbell_y)

Let's make some plots

This document is already too long coursera assignment, so for this section I'll work on top 5 features for each class selected in the last section. So lets select only those columns.

```
## arm forearm belt dumbbell
## 1 2 4 4 7
```

One interesting thing to note here is that the dumbbell sensor turned out to be the most important sensor among the 4. I would like to explore that in future works.

Pairs plot

```
my_dens <- function(data, mapping, ...) {
    ggplot(data = data, mapping=mapping) +
        geom_density(..., alpha = 0.3)+scale_fill_brewer(palette="Set2")
}
my_point <- function(data, mapping, ...) {
    ggplot(data = data, mapping=mapping) +
        geom_point(..., alpha = 0.1)+ scale_fill_brewer(palette="Set2")
}
ggpairs(dfAnalize2, columns = 1:5,aes(color = classe),
        lower = list(continuous = my_point),diag = list(continuous = my_dens))</pre>
```