

EM WAVE CHARACTERISTICS :- I:-

EM WAVE:- The combination of Time Varying and Magnetic fields produce a phenomenon which is known as Electromagnetic wave. It is a function of time and Space variables. The direction of E and H wave are perpendicular to each other.

$E \perp H \perp$ direction of wave propagation

EM wave travels with the speed of

velocity of light $= 3 \times 10^8 \text{ m/s}$.

EM waves are also called as

Hertzian waves.

⑤ def:- The waves are the means of transporting energy or information from source to destination the waves consisting of electric and magnetic fields are called as Electromagnetic waves. In general, wave is a function of time and space.

Ex:- Radio waves, light rays, radar beam, T.V signals.

They all follow the following properties.

- They assume properties of waves while travelling
- They travel with high velocity.
- They radiate outwards from source in all directions

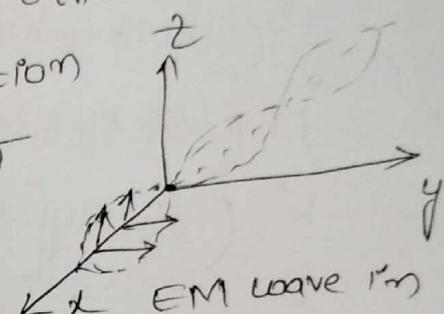
Different medias:-

a) free space ($\sigma = 0, \epsilon = \epsilon_0, \mu = \mu_0$ ($\rho, e, \mu = 1, \epsilon_r = 1$))

b) Perfect (lossless dielectric) ($\sigma = 0, \epsilon = \epsilon_r \epsilon_0, \mu = \mu_0, \sigma = 0, \mu = \mu_0$)

c) lossy dielectric ($\sigma \neq 0, \epsilon = \epsilon_r \epsilon_0, \mu = \mu_0$)

d) Perfect or good conductor ($\sigma = \infty, \epsilon = \epsilon_0, \mu = \mu_0, \sigma \gg \mu \epsilon$),



GENERAL WAVE EQUATION:-

Purpose:- We have two maxwells equations (i) $\nabla \times \vec{H} = \vec{J}_C$
 (ii) $\nabla \times \vec{E} = -\frac{d}{dt}(\vec{B})$
 (iii) $\nabla \times \vec{H} = \frac{d}{dt}(\vec{D})$

$$(iii) \nabla \times \vec{E} = -\frac{d}{dt}(\vec{B})$$

$$\begin{vmatrix} i^1 & j^1 & k^1 \\ \frac{\partial H_x}{\partial y} & \frac{\partial H_y}{\partial z} & \frac{\partial H_z}{\partial x} \\ H_x & H_y & H_z \end{vmatrix} = -\frac{d}{dt}(\vec{D})$$

$$i^1 (\frac{\partial \text{d}y H_z}{\partial z} - \frac{\partial \text{d}z H_y}) = -\frac{d}{dt}(\vec{D})$$

$$j^1 (\frac{\partial \text{d}x H_y}{\partial z} - \frac{\partial \text{d}z H_x}) = -\frac{d}{dt}(\vec{D})$$

$$k^1 (\frac{\partial \text{d}x H_y}{\partial y} - \frac{\partial \text{d}y H_x}) = -\frac{d}{dt}(\vec{D})$$

$$\begin{vmatrix} i^1 & j^1 & k^1 \\ \frac{\partial E_x}{\partial y} & \frac{\partial E_y}{\partial z} & \frac{\partial E_z}{\partial x} \\ e_x & e_y & e_z \end{vmatrix} = -\frac{d}{dt}(\vec{B})$$

$$i^1 (\frac{\partial \text{d}y e_z}{\partial z} - \frac{\partial \text{d}z e_y}) = -\frac{d}{dt}(\vec{B})$$

$$j^1 (\frac{\partial \text{d}x e_z}{\partial z} - \frac{\partial \text{d}z e_x}) = -\frac{d}{dt}(\vec{B})$$

$$k^1 (\frac{\partial \text{d}x e_y}{\partial y} - \frac{\partial \text{d}y e_x}) = -\frac{d}{dt}(\vec{B})$$

So, in order to calculate one sample one component either the $E_x/e_y/e_z/H_x/H_y/H_z$, we need to solve six maxwells equations. These becomes very complex and difficult. Hence, in order to calculate one component separately easily, we go for wave equation. Hence if we want to get individual components, in electro-magnetic problem these can be easily done with maxwell eqn wave equation.

General wave Equation

Consider the medium is linear, homogeneous and source free region. Assume that the medium obeys ohm's law, $\vec{J} = \sigma \vec{E}$. we have maxwell's equation. $B = \mu H$, $D = \epsilon E$

$$\nabla \times \vec{E} = -\omega \cdot \frac{d}{dt}(\vec{H}), \quad \nabla \times \vec{H} = \frac{d}{dt}(\vec{E}) + \vec{J}, \quad \nabla \cdot \vec{B} = 0, \quad \nabla \cdot \vec{D} = 0$$

$$\nabla \times \vec{E} = -\frac{d}{dt}(\omega \vec{H}), \quad \nabla \times \vec{H} = \sigma \vec{E} + \frac{d}{dt}(\vec{D}) \quad \nabla \cdot (\omega \vec{H}) = 0, \quad \nabla \cdot (\vec{E}) = 0$$

$$\boxed{\nabla \times \vec{E} = -\omega \cdot \frac{d}{dt}(\vec{H}), \quad \nabla \times \vec{H} = \sigma \vec{E} + \frac{d}{dt}(\vec{D}), \quad \nabla \cdot \vec{H} = 0, \quad \nabla \cdot \vec{E} = 0}$$

4) Wave Eqⁿ for electric field

$$\nabla \times \bar{E} = -\mu \cdot \frac{d}{dt} (\bar{H}), \quad \nabla \times \bar{H} = \sigma \bar{E} + \epsilon \frac{d}{dt} (\bar{E}), \quad \nabla \cdot \bar{H} = 0, \quad \nabla \cdot \bar{E} = 0$$

$$\nabla \times (\nabla \times \bar{E}) = -\mu \cdot \nabla \left[\frac{d}{dt} (\bar{H}) \right] \quad \text{Applying curl on both sides}$$

$$\nabla \times (\nabla \times \bar{E}) = -\mu \cdot \frac{d}{dt} [\nabla \times \bar{H}] \rightarrow (1)$$

Sub Eqⁿ- (2) in Eqⁿ- (1)

$$\nabla \times (\nabla \times \bar{E}) = -\mu \cdot \frac{d}{dt} [\sigma \bar{E} + \epsilon \cdot \frac{d}{dt} (\bar{E})]$$

$$\text{By vector identity, } \nabla \times (\nabla \times \bar{E}) = \nabla (\nabla \cdot \bar{E}) - \nabla^2 \bar{E}$$

$$\nabla (\nabla \cdot \bar{E}) - \nabla^2 \bar{E} = -\mu \cdot \frac{d}{dt} [\sigma \bar{E} + \epsilon \cdot \frac{d}{dt} (\bar{E})]$$

$$-\nabla^2 \bar{E} = -\mu \cdot \frac{d}{dt} [\sigma \bar{E} + \epsilon \cdot \frac{d}{dt} (\bar{E})]$$

$$\nabla^2 \bar{E} = \mu \cdot \frac{d}{dt} [\sigma \bar{E} + \epsilon \cdot \frac{d}{dt} (\bar{E})]$$

$$\boxed{\nabla^2 \bar{E} = \mu \sigma \cdot \left[\frac{d}{dt} (\bar{E}) \right] + \mu \epsilon \cdot \frac{d^2}{dt^2} (\bar{E})}$$

↓
wave Equation for Electric field, in uniform media

② wave equation for \bar{H}

$$\nabla \times \bar{H} = \sigma \bar{E} + \epsilon \cdot \frac{d}{dt} (\bar{E}) \quad \text{applying curl on both sides}$$

$$\nabla \times (\nabla \times \bar{H}) = \nabla \times \left[\sigma \bar{E} + \epsilon \cdot \frac{d}{dt} (\bar{E}) \right]$$

$$\nabla \times (\nabla \times \bar{H}) = \nabla (\nabla \cdot \bar{H}) - \nabla^2 \bar{H}$$

$$\nabla (\nabla \cdot \bar{H}) - \nabla^2 \bar{H} = \sigma (\nabla \times \bar{E}) + \epsilon \cdot \frac{d}{dt} (\nabla \times \bar{E})$$

$$\text{but } \nabla \times \bar{E} = -\mu \cdot \frac{d}{dt} (\bar{H})$$

$$\nabla (\nabla \cdot \bar{H}) - \nabla^2 \bar{H} = \sigma \left(-\mu \cdot \frac{d}{dt} (\bar{H}) \right) + \epsilon \cdot \frac{d}{dt} \left(-\mu \cdot \frac{d}{dt} (\bar{H}) \right)$$

$$\Rightarrow -\nabla^2 \bar{H} = -\mu \sigma \cdot \frac{d}{dt} (\bar{H}) + (-\mu \epsilon) \cdot \frac{d^2}{dt^2} (\bar{H})$$

$$-\nabla^2 \bar{H} = - \left[\mu \sigma \cdot \frac{d}{dt} (\bar{H}) + \mu \epsilon \cdot \frac{d^2}{dt^2} (\bar{H}) \right] \quad \text{for } \bar{H}$$

$$\boxed{-\nabla^2 \bar{H} = \mu \sigma \cdot \frac{d}{dt} (\bar{H}) + \mu \epsilon \cdot \frac{d^2}{dt^2} (\bar{H})}$$

c) wave eqn for D

$$\text{we have } \nabla^2 \bar{E} = \mu\sigma \cdot \frac{d}{dt} (\bar{E}) + \mu\epsilon \cdot \frac{d^2}{dt^2} (\bar{E}).$$

$$\text{we have } D = \epsilon \bar{E}$$

$$\nabla^2 (\epsilon \bar{E}) = \mu\sigma \cdot \frac{d}{dt} (\epsilon \bar{E}) + \mu\epsilon \cdot \frac{d^2}{dt^2} (\epsilon \bar{E})$$

$$\boxed{\nabla^2 D = \mu\sigma \cdot \frac{d}{dt} (D) + \mu\epsilon \cdot \frac{d^2}{dt^2} (D)}$$

wave Eqn for D

(d) wave Eqn for B

$$\nabla^2 \bar{H} = \mu\sigma \cdot \frac{d}{dt} (\bar{H}) + \mu\epsilon \cdot \frac{d^2}{dt^2} (\bar{H})$$

$$\nabla^2 (\mu \bar{H}) = \mu\sigma \cdot \frac{d}{dt} (\mu \bar{H}) + \mu\epsilon \cdot \frac{d^2}{dt^2} (\mu \bar{H})$$

$$\boxed{\nabla^2 B = \mu\sigma \cdot \frac{d}{dt} (B) + \mu\epsilon \cdot \frac{d^2}{dt^2} (B)} \quad \text{for } B$$

Hence, in general the wave equation is

$$\boxed{\nabla^2 \begin{bmatrix} \bar{E} \\ \bar{D} \\ \bar{B} \\ \bar{H} \end{bmatrix} = \mu\sigma \cdot \frac{d}{dt} \begin{bmatrix} \bar{E} \\ \bar{D} \\ \bar{B} \\ \bar{H} \end{bmatrix} + \mu\epsilon \cdot \frac{d^2}{dt^2} \begin{bmatrix} \bar{E} \\ \bar{D} \\ \bar{B} \\ \bar{H} \end{bmatrix}}$$

This is three dimensional wave equation for all the vector fields.

In general, we have

$$\nabla \times \bar{E} = -\mu \cdot \frac{d}{dt} (\bar{H})$$

$$\nabla \times (\nabla \times \bar{E}) = -\mu \cdot \frac{d^2}{dt^2} (\bar{H}), \quad \nabla \times \bar{H} = \frac{d}{dt} (\bar{D}) = \frac{d}{dt} (\bar{E})$$

$$\nabla (\nabla \cdot \bar{E}) - \nabla^2 \bar{E} = -\mu \cdot \frac{d}{dt} \left[\frac{d}{dt} (\bar{E}) \right]$$

$$\Rightarrow -\nabla^2 \bar{E} = -\mu \cdot \frac{d^2}{dt^2} (\bar{E})$$

$$\boxed{\nabla^2 \bar{E} = \mu\epsilon \cdot \frac{d^2}{dt^2} (\bar{E})}$$

$$\boxed{\nabla^2 \bar{E} - \mu\epsilon \cdot \frac{d^2}{dt^2} (\bar{E}) = 0}$$

variation w.r.t space
either (Ex | Ey | Ez)

variation w.r.t time.

Hence, EM wave
is varied w.r.t
space and time

As the above expression includes electric and magnetic fields and hence it is called EM Wave Equation:

Wave Equation for conducting media

conducting media is characterised by $\sigma = \infty$, $\epsilon = \epsilon_0$,

$\mu = \mu_0$, $\sigma \gg \omega\epsilon$.

$$\text{we have Eqns, } \nabla^2 \vec{E} = \mu \sigma [\partial \vec{H} / \partial t] + \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\nabla^2 \vec{E} = \mu [\sigma \cdot \partial \vec{H} / \partial t + \epsilon \cdot \partial^2 \vec{E} / \partial t^2]$$

$$\nabla^2 \vec{E} = \mu [\sigma \cdot \vec{E} + \epsilon \cdot \frac{\partial \vec{E}}{\partial t}] \text{ where } \mu = \mu_0 \text{ N/A, } \epsilon = \epsilon_0 \text{ C/N}$$

Similarly $\nabla^2 \vec{H} = \mu [\sigma \vec{H} + \epsilon \cdot \frac{\partial \vec{H}}{\partial t}]$

$$\nabla^2 \vec{B} = \mu [\sigma \vec{B} + \epsilon \cdot \frac{\partial \vec{B}}{\partial t}], \quad \nabla^2 \vec{D} = \mu [\sigma \vec{D} + \epsilon \cdot \frac{\partial \vec{D}}{\partial t}]$$

(b) Wave Equation for Dielectric, Perfect dielectric

$$\text{we have } \nabla^2 \vec{E} = \mu (\sigma \vec{E} + \epsilon \frac{\partial \vec{E}}{\partial t})$$

we have dielectric characteristics, $\sigma \neq 0$, $\epsilon = \epsilon_0 \text{ F/m}$, $\mu = \mu_0 \text{ N/A}$

$$\nabla^2 \vec{E} = \mu [\sigma \vec{E} + \epsilon \frac{\partial \vec{E}}{\partial t}] \Rightarrow \nabla^2 \vec{E} = \epsilon \frac{\partial \vec{E}}{\partial t}$$

disadv \rightarrow

wave Equations are second order differential equations and difficult to solve where maxwells

Equations are first order equations

UNIFORM PLANE WAVES

→ Any electromagnetic wave propagating along x_0 direction is said to be uniform if the \vec{E}, \vec{H} are independent of remaining directions ($y & z$) and this uniform plane waves don't have field components along the direction of wave propagation.

Wavefront— When the different signals are travelling with different phase, and we join all the equal phase points means (equal phase), then so called wavefront.

Plane → If the complete line joining any two points on a

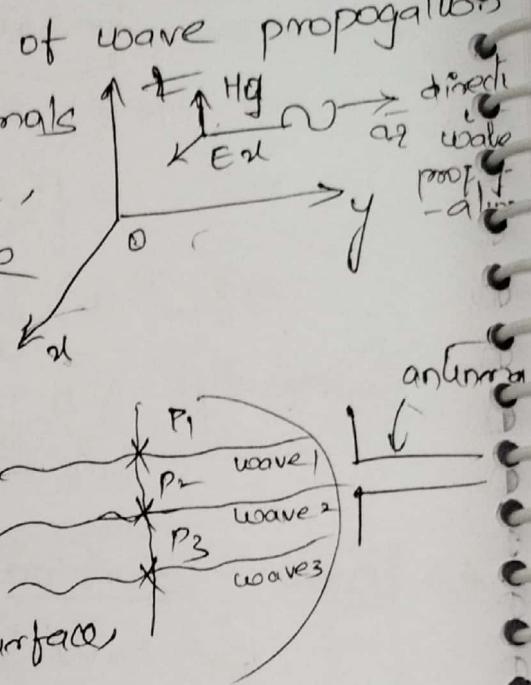
surface they lie on the same surface then so called plane.

If at all the phase points in wavefront, the amplitude is constant, then so called Uniform

Plane wave.

Purpose of Uniform Plane wave

At receiving antenna, the incident plane, if we consider normal waves then the signal strength is less because, of amplitude is different at phase points. But if we consider uniform plane waves, at receiving end, if we gather at end points, as the amplitude is constant at different phase points also, signal strength is high and such that is repeated by receiving antenna.



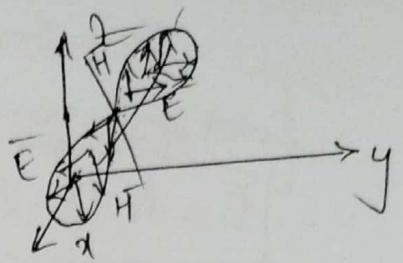
free space at infinite distance from the source
we have for charge free region, $E \propto \frac{1}{r}$

$$\nabla^2 E = \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial r^2} \text{ or } \nabla^2 E = \mu_0 \frac{\partial^2 E}{\partial t^2} \quad (\because \epsilon_r = 1, \mu_r = 1)$$

we have Laplacian operator,

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = \nabla^2$$

$$\nabla^2 E = \frac{\partial^2}{\partial x^2} \bar{E}_x + \frac{\partial^2}{\partial y^2} \bar{E}_y + \frac{\partial^2}{\partial z^2} (\bar{E}_z) \quad (1)$$



Considering wave is propagating in x direction
so, \vec{E} doesn't along y & z direction

$$\bar{E} \neq f(y), \bar{E} \neq f(z)$$

$$\frac{\partial}{\partial y} (\bar{E}) = 0, \frac{\partial}{\partial z} (\bar{E}) = 0$$

$$\bar{E} = E_x \cdot \hat{x} + E_y \cdot \hat{y} + E_z \cdot \hat{z}$$

$$\frac{\partial^2}{\partial x^2} (E_x) + \frac{\partial^2}{\partial y^2} (E_y) + \frac{\partial^2}{\partial z^2} (E_z) = \\ + \mu_0 \epsilon_0 \left[\frac{\partial^2}{\partial t^2} (E_x) + \frac{\partial^2}{\partial t^2} (E_y) + \frac{\partial^2}{\partial t^2} (E_z) \right]$$

Since, y and z components are 0.

$$\frac{\partial^2}{\partial x^2} (E_x) = \mu_0 \epsilon_0 \cdot \frac{\partial^2}{\partial t^2} (E_x) \rightarrow \text{indicates wave is in x-direction}$$

$$\frac{\partial^2}{\partial y^2} (E_y) = \mu_0 \epsilon_0 \cdot \frac{\partial^2}{\partial t^2} (E_y) \rightarrow \text{in y-direction}$$

$$\frac{\partial^2}{\partial z^2} (E_z) = \mu_0 \epsilon_0 \cdot \frac{\partial^2}{\partial t^2} (E_z) \rightarrow \text{in z-direction}$$

\Rightarrow we have $E \propto \frac{1}{r}$, $\nabla^2 E = \mu_0 \epsilon_0 \cdot \frac{\partial^2}{\partial t^2} (\bar{E}) = 0$.

$$\frac{\partial^2}{\partial x^2} (E_x) - \mu_0 \epsilon_0 \cdot \frac{\partial^2}{\partial t^2} (E_x) = 0 \quad \begin{matrix} \uparrow \\ \text{Space} \\ \text{distance} \end{matrix} \quad \begin{matrix} \uparrow \\ \text{time} \end{matrix} \quad \text{since both are not} \\ \text{with same units.}$$

$$\text{Speed} = \frac{\text{Distance}}{\text{Time}} = \text{Velocity} \quad , \quad v = \sqrt{\frac{1}{\mu_0 \epsilon_0}} = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\frac{\partial^2}{\partial x^2} (E_x) = \mu_0 \epsilon_0 \cdot \frac{\partial^2}{\partial t^2} (E_x)$$

$$\mu_0 \epsilon_0 \cdot \frac{\partial^2}{\partial t^2} (E_x) = \frac{1}{v^2} \cdot \frac{\partial^2}{\partial x^2} (E_x)$$

$$\frac{\partial^2}{\partial t^2} (E_x) - \frac{1}{v^2} \cdot \frac{\partial^2}{\partial x^2} (E_x) = 0.$$

$$\frac{\partial^2}{\partial t^2}(Ex) - v^2 \cdot \frac{\partial^2}{\partial x^2}(Ex) = 0,$$

$$\text{or } \frac{\partial^2}{\partial t^2}(Ex) - v^2 \cdot \frac{\partial^2}{\partial x^2}(Ex) = 0 \quad (1)$$

now let us write differential equation

$Ex = E_0 e^{j\omega t}$

Solution for Equation (1) PS

$$[E = f_1(x-v_0 t) + f_2(x+v_0 t)]$$

$$v^2 = \frac{1}{\mu_0 \epsilon_0} \quad v = \sqrt{\frac{1}{\mu_0 \epsilon_0}} = 3 \times 10^8 \text{ m/s}$$

$x \rightarrow$ direction of propagation.

$f_1(x-v_0 t) \rightarrow$ signal in the x direction

$f_2(x+v_0 t) \rightarrow$ signal in backward direction.

As uniform plane wave is passing in charge free region, backward wave PS 0

$$[E = f(x-v_0 t)]$$

$x \rightarrow$ distance, $v_0 \rightarrow$ velocity, both should be of same parameters, they should convert into phase by multiplying with some constant factors

βx , where $\beta \rightarrow$ distance-phase conversion

β for 1 unit distance (d) = 2π radians

$$[\beta = 2\pi/d], \text{ rad/mm.}$$

$v_0 t \rightarrow$ velocity \times time, where $v_0 \rightarrow$ converts time to phase

v_0 for 1 unit velocity (time T) = 2π radians

$$v_0(T) = 2\pi \Rightarrow [v_0 = \omega = \frac{2\pi}{T} = \text{rad/sec.}]$$

now velocity = $v_0/\beta = \frac{2\pi}{T} \cdot \frac{d}{2\pi} = \frac{d}{T} = \text{m/sec.}$

If $\omega-\beta$ are not in linear, it indicates, that the no. of signals travelling towards the Rx travels with different velocity. Hence, all the

signals reaches at different point in end time. So, accumulation of this signals is difficult & results in phase interference.

UNIFORM PLANE WAVES - ALL RELATIONS BETWEEN E & H

let us consider uniform plane wave propagating along \hat{x} direction. $E = E_x \hat{x} + E_y \hat{y} + E_z \hat{z}$ ($E_x = 0$)

$$\nabla \times \bar{E} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} \quad \text{since, } E_x = 0, \frac{\partial}{\partial t} (E_x) = 0$$

$$\nabla \times \bar{E} = \hat{a}_y^* \left[\frac{\partial}{\partial y} (E_z) - \frac{\partial}{\partial z} (E_y) \right] - \hat{a}_z^* \left[\frac{\partial}{\partial z} (E_x) - \frac{\partial}{\partial x} (E_z) \right] \\ + \hat{a}_x^* \left[\frac{\partial}{\partial x} (E_y) - \frac{\partial}{\partial y} (E_x) \right]$$

$$\nabla \times \bar{E} = -\hat{a}_y^* \left[\frac{\partial}{\partial z} (E_x) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (E_y) \right] \quad (\because \frac{\partial}{\partial x} (E_x) = 0) \\ \text{and } \hat{a}_x^* \text{ direction is also } 0$$

Similarly

$$\nabla \times \bar{H} = -\hat{a}_y^* \left[\frac{\partial}{\partial x} (H_z) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (H_y) \right]$$

$$\text{we have } \nabla \times \bar{H} = \frac{\partial}{\partial t} \bar{D} = \frac{\partial}{\partial t} (\epsilon_0 \bar{E}) = \epsilon_0 \cdot \frac{\partial}{\partial t} (\bar{E}) \text{ sub to (1)}$$

$$\nabla \times \bar{H} = -\hat{a}_y^* \left[\frac{\partial}{\partial x} (H_z) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (H_y) \right]$$

$$\epsilon_0 \cdot \frac{\partial}{\partial t} (\bar{E}) = -\hat{a}_y^* \left[\frac{\partial}{\partial x} (H_z) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (H_y) \right]$$

Equating

$$\boxed{\frac{\partial}{\partial x} (E_x) = \epsilon_0 \cancel{\frac{\partial}{\partial x} (H_z)}} \\ \boxed{\frac{\partial}{\partial x} (E_y) \cdot \epsilon_0 = \frac{\partial}{\partial y} (H_y)}$$

$$\boxed{-\frac{\partial}{\partial x} (H_z) = \epsilon_0 \cdot \frac{\partial}{\partial t} (E_z)} \\ \boxed{\frac{\partial}{\partial x} (H_y) = \epsilon_0 \cdot \frac{\partial}{\partial t} (E_y)}$$

\Rightarrow Using Second Maxwell's equation

$$\nabla \times \bar{E} = -\frac{\partial}{\partial t} (\bar{B}).$$

$$-\hat{a}_y^* \left[\frac{\partial}{\partial x} (E_z) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (E_y) \right] = -\frac{\partial}{\partial t} (\bar{B}).$$

$$-\hat{a}_y^* \left[\frac{\partial}{\partial x} (E_z) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (E_y) \right] = -\left[\frac{\partial}{\partial t} (\mu \bar{H}) \right]$$

$$-\hat{a}_y^* \left[\frac{\partial}{\partial x} (E_z) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (E_y) \right] = -\mu \left[\frac{\partial}{\partial t} (\bar{H}) \right]$$

$$-\hat{a}_y^* \left[\frac{\partial}{\partial x} (E_z) \right] + \hat{a}_z^* \left[\frac{\partial}{\partial x} (E_y) \right] = -\mu \left[\frac{\partial}{\partial t} H_z \cdot \hat{a}_x^* + \frac{\partial}{\partial t} H_y \cdot \hat{a}_x^* \right. \\ \left. + \frac{\partial}{\partial t} H_z \cdot \hat{a}_x^* \right]$$

$$-\frac{d}{dx}(E_2) = -\mu \cdot \frac{d}{dt} H_3$$

$$\Rightarrow \frac{d}{dx}(E_2) = \mu \cdot \frac{d}{dt}(H_3) \quad (3)$$

$$\text{Next, } \frac{d}{dx}(E_2) = \frac{d}{dt}(H_3) \mu$$

Hence, relations are from ^{1st Maxwell's equation}

$$\left. \begin{array}{l} -\frac{d}{dx}H_3 = \epsilon \cdot \frac{d}{dt}(E_2) \\ \frac{d}{dx}H_3 = \epsilon \frac{d}{dt}(E_2) \\ \frac{d}{dx}E_2 = \mu \cdot \frac{d}{dt}(H_3) \\ \frac{d}{dx}E_2 = -\mu \cdot \frac{d}{dt}(H_3) \end{array} \right\} \begin{array}{l} \text{Maxwell's - I Equation} \\ \text{Maxwell's - II Equation} \end{array}$$

we have, equation, $E_2 = f_1(x - vt)$,

$$\frac{d}{dt}(E_2) \epsilon_0 = -\frac{d}{dx}H_3 \quad (4)$$

$$\frac{d}{dt}(E_2) = \frac{\epsilon_0}{\mu_0} \cdot f_1'(x - vt), \quad \mu_0 = \frac{1}{\sqrt{\epsilon_0 \mu}}$$

Sub in Eq ⁿ(4)

$$-\frac{d}{dx}H_3 = -\frac{\epsilon_0}{\mu_0} \cdot f_1'(x - vt) \epsilon_0,$$

$$-\frac{d}{dx}H_3 = -\frac{1}{\sqrt{\mu_0 \epsilon_0}} \cdot \epsilon_0 \cdot f_1'(x - vt)$$

$$-\frac{d}{dx}H_3 = -\frac{\epsilon_0}{\sqrt{\mu_0}} \cdot f_1'(x - vt).$$

$$\therefore \frac{d}{dx}H_3 = -\frac{\epsilon_0}{\sqrt{\mu_0}} \cdot \frac{d}{dt}f_1(x - vt),$$

$$H_3 = +\sqrt{\frac{\epsilon_0}{\mu_0}} \cdot f(x - vt).$$

we have
 $f(x - vt) = E_2$

$$H_3 = \sqrt{\frac{\epsilon_0}{\mu_0}} \cdot E_2 \Rightarrow \frac{E_2}{H_3} = \sqrt{\frac{\mu_0}{\epsilon_0}}$$

μ_0, ϵ_0 are constant for free space, and $\eta_0 = \sqrt{\frac{\mu_0}{\epsilon_0}}$

$$\eta_0 - \text{Intrinsic impedance} = \eta_0 = \sqrt{\frac{\mu_0}{\epsilon_0}} = \frac{E_2}{H_3} = 120 \Omega$$

Therefore, intrinsic impedance of free space, $\boxed{\eta_0 = 377 \Omega}$
 For any other media, $\eta = \sqrt{\mu/\epsilon}$.

Wave Equations in Phasor form

let us consider the wave equation $\nabla^2 E = \mu_0 \epsilon_0 \frac{\ddot{E}}{c^2}$

let us consider the solution expansion is

$$Ex = k_1 e^{-jBz} + k_2 e^{jBz}$$

let the electric field representation is $\vec{E} = E_0 \cdot e^{j\omega t}$

$$\begin{aligned}\dot{\vec{E}} &= \frac{d}{dt}(\vec{E}) = \frac{d}{dt} \left[\frac{d}{dt}(\vec{E}) \right] = \frac{d}{dt} \left[\frac{d}{dt} [E_0 \cdot e^{j\omega t}] \right] \\ &= \frac{d}{dt} [E_0 \cdot e^{j\omega t}, j\omega t] = E_0 \cdot e^{j\omega t} \cdot (j\omega)^2.\end{aligned}$$

$$= E_0 \cdot e^{j\omega t} \cdot (j)^2 C \omega^2$$

$$\nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\ddot{E}}{c^2} = \mu_0 \epsilon_0 \left[-E_0 \cdot e^{j\omega t} \cdot \omega^2 \right] = -\mu_0 \epsilon_0 \omega^2 \vec{E}$$

$$\boxed{\nabla^2 \vec{E} = -\mu_0 \epsilon_0 \omega^2 \vec{E}} \quad (1)$$

$\nabla^2 \vec{E} = -B^2 \vec{E}$ — (2), By comparison (1) and (2),

$$B^2 = +\mu_0 \epsilon_0 \omega^2$$

$$\boxed{B = \omega \sqrt{\mu_0 \epsilon_0}} \text{ for free space.}$$

for any other media,

$$\boxed{B = \omega \sqrt{\mu \epsilon}}$$

$$\boxed{B = 2\pi f \sqrt{\mu \epsilon}}$$

Wave Equation in phasor form for Conducting media

let us consider wave equation of conducting media

$$\nabla^2 \vec{E} = \sigma \dot{\vec{E}} + \mu \epsilon \frac{\ddot{\vec{E}}}{c^2}$$

$$\nabla^2 \vec{E} = \mu (\sigma \dot{\vec{E}} + \epsilon \frac{\ddot{\vec{E}}}{c^2})$$

$$\nabla^2 \vec{E} = \mu [j\omega \sigma + (j\omega)^2 \epsilon] \vec{E}$$

$$\nabla^2 \vec{E} = \mu j\omega [\sigma + j\omega \cdot \epsilon] \vec{E}$$

$$\nabla^2 \vec{E} = r^2 \vec{E}$$

$$\text{where } r^2 = j\omega [\sigma + j\omega \cdot \epsilon] \mu$$

$$\vec{E} = E_0 \cdot e^{j\omega t}$$

$$\dot{\vec{E}} = E_0 \cdot (j\omega) \cdot e^{j\omega t}$$

$$\ddot{\vec{E}} = \vec{E} (j\omega)$$

similarly,

$$\ddot{\vec{E}} = (j\omega) (j\omega) \cdot \vec{E}$$

$$\frac{\ddot{\vec{E}}}{\vec{E}} = (j\omega)^2 \vec{E}$$

$$r = \sqrt{j\omega\mu(\sigma + j\omega\epsilon)}$$

$$\alpha = \sigma + j\beta$$

$$r^2 = j\omega\mu(\sigma + j\omega\epsilon)^2$$

$$r = \sqrt{j\omega\mu(\sigma + j\omega\epsilon)}$$

In free space, attenuation is 0, $\alpha = 0$, $\beta = \omega\sqrt{\mu\epsilon_0}$.
Because there is no reflection and absorption of signal.

Transverse EM wave:-

If the wave propagates along x -direction,
 E component exists along y direction and travels with the velocity, $v_0 = \omega/B$. H components exists along z direction with the same velocity.
Generally, when wave propagates through any media its amplitude reduces and phase of pt changes.

$$\alpha + j\beta = r$$

$\alpha \rightarrow$ Attenuation Constant,

$\beta \rightarrow$ Phase Constant.

$r \rightarrow$ propagation Constant.

Attenuation Constant:

The reduction in the amplitude of EM wave through any media is known as attenuation constant. It is measured as ~~Attenuation Constant (α)~~.

Phase Constant (β)

Phase of EM wave changes through any media is known as phase constant (β).

$$\omega_0 = \omega_0/\rho \Rightarrow \beta = \omega_0/\rho_0.$$

Propagation Constant (r)

As EM propagates through any media, the loss in amplitude (α) and phase (β) is called propagation constant. It is the combination of attenuation constant and phase constant.

$$r = \alpha + j\beta$$

Wavelength (λ) :-

Every sinusoidal signal changes its phase after 2π radians / 360° , and hence the length of one complete cycle is called wavelength.

$$\lambda = \frac{2\pi}{\beta} \approx \text{rad} \rightarrow 2\pi$$

WAVE PROPAGATION IN LOSSLESS MEDIA | PERFECT DIELECTRIC | FREE SPACE

Consider wave is propagating through perfect dielectric and its properties are given by $\sigma=0, \mu=\mu_0, \epsilon=\epsilon_0$.

$$\epsilon = \epsilon_0 \epsilon_0$$

Let us consider uniform plane wave propagating along x -direction in free space. Then wave equation in phasor form is $\nabla^2 \bar{E} = -\beta^2 \bar{E}$

$$\frac{\partial^2}{\partial x^2} \bar{E} = -\beta^2 \bar{E}$$

$$\frac{d^2}{dx^2} (E_y \cdot a_y + E_z \cdot a_z) = -\beta^2 (E_y \cdot a_y + E_z \cdot a_z)$$

Consider only one component, then

$$\frac{d^2}{dx^2} E_y \cdot a_y = -\beta^2 E_y \cdot a_y$$

$$\frac{d^2}{dx^2} E_y \cdot a_y + \beta^2 E_y \cdot a_y = 0 \quad (1)$$

The solution for above second order differential

Equation is $E_y(x) = c_1 e^{-j\beta x} + c_2 e^{j\beta x}$

\downarrow
forward wave

\downarrow
backward wave

along +ve x direction

from -ve x direction

c_1, c_2 are arbitrary constants.

$$\begin{aligned} E_y(x, t) &= \operatorname{Re} [E_y(x) e^{j\omega t}] \\ &= \operatorname{Re} [(c_1 e^{-j\beta x} + c_2 e^{j\beta x}) e^{j\omega t}] \\ &= \operatorname{Re} [c_1 e^{j(\omega t - \beta x)} + c_2 e^{j(\omega t + \beta x)}] \\ &= \operatorname{Re} [c_1 e^{j(\omega t - \beta x)} + c_2 e^{j(\omega t + \beta x)}] \end{aligned}$$

$$E_y(x, t) = c_1 \cos(\omega t - \beta x) + c_2 \cos(\omega t + \beta x)$$

\downarrow \downarrow
forward wave backward wave.

$$\sigma = 0, \mu = \mu_0, \epsilon = \epsilon_0, \epsilon_r = \mu_r = 1, \mathcal{J}_c = 0.$$

Characteristics of wave propagation in dielectric lossless medium

(a) Velocity (v)

$$\text{Velocity } (v) = \frac{1}{\sqrt{\mu \epsilon}} = \frac{1}{\sqrt{\mu_0 \epsilon_0 \epsilon_r}} = \frac{1}{\sqrt{\mu_0 \epsilon_0}} \cdot \frac{1}{\sqrt{\epsilon_r}}. \quad c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$v = \frac{c}{\sqrt{\epsilon_r}} \text{ m/s.}$$

$$\text{or } v = \frac{1}{\sqrt{\mu \epsilon}} = \frac{\omega}{\omega \sqrt{\mu \epsilon}} = \frac{\omega}{\beta}, \text{ hence, } \boxed{v = \omega / \beta}$$

(b) Prop. for Attenuation Constant

Since, dielectric media is lossless, attenuation constant, $\alpha = 0$ dB/m

(c) Phase constant (B)

we have phase constant

$$B = \omega \sqrt{\mu \epsilon} = \omega \sqrt{\mu_0 \epsilon_0 \mu_r \epsilon_r} = \omega \sqrt{\epsilon_0 \mu_0}$$

$$\boxed{B = \omega \sqrt{\mu_0 \epsilon_0} \text{ radians/m.}}$$

as $B = 2\pi k$.

(d) propagation constant:- (r)

$$r = \alpha + jB$$

$$\text{but we have } \alpha = 0, B = \omega \sqrt{\mu_0 \epsilon_0}$$

$$r = \omega \sqrt{\mu_0 \epsilon_0} \Rightarrow \boxed{r = j\omega \sqrt{\mu_0 \epsilon_0} \text{ m}^{-1}}$$

(e) wavelength

$$\text{wavelength (d)} = \frac{2\pi}{B} = \frac{2\pi}{\omega \sqrt{\mu_0 \epsilon_0}} \text{ m.}$$

$$\boxed{d = \frac{2\pi}{\omega \sqrt{\mu_0 \epsilon_0}} = \frac{2\pi}{\omega} = \lambda}$$

(f) Intrinsic Impedance:-

$$m_0 = \sqrt{\frac{\mu_0}{\epsilon_0}} \quad (\text{or}) \quad m = \sqrt{\mu/\epsilon}$$

$$\boxed{m = 317 \Omega}$$

(g) Phase velocity (v_p)

The wave phase velocity travels with general velocity, $\boxed{v_p = v_0}$

- (1) Attenuation Constant (α) $\rightarrow 0 \text{ dB/m}$
- (2) Propagation Constant (β) $\rightarrow j\omega\sqrt{\mu_0\epsilon_0} \text{ rad/m}$
- (3) Phase Constant (β) $\rightarrow \omega\sqrt{\mu_0\epsilon_0} \text{ rad/m}$
- (4) Velocity (v_0) $\rightarrow v_0 = \omega/\beta = fd = \frac{1}{\sqrt{\mu_0\epsilon_0}} = 3 \times 10^8 \text{ m/s}$
- (5) Phase velocity (v_p) $\rightarrow v_p = \omega$
- (6) Intrinsic Impedance (η_s) $\rightarrow 377 \Omega = \sqrt{\mu_0/\epsilon_0}$
- (7) Wavelength (λ) $\rightarrow \lambda = \frac{2\pi}{\beta} = \frac{2\pi}{\omega\sqrt{\mu_0\epsilon_0}} \text{ m}$

WAVE PROPAGATION IN CONDUCTING MEDIA / LOSSY MEDIUM

Consider uniform plane wave EM wave is propagating along x direction in conducting media. Wave

Equation in phasor form is

$$\nabla^2 \bar{E} = r^2 \bar{E} \Rightarrow \frac{\partial^2}{\partial x^2} \bar{E} = r^2 \bar{E} \Rightarrow \boxed{\frac{\partial^2}{\partial x^2} \bar{E} - r^2 \bar{E} = 0}$$

Then above equation in time varying form

$$\bar{E}(x, t) = \operatorname{Re} [c_1 e^{rx} + c_2 e^{rx}]$$

Since, Backward wave is neglected.

$$\bar{E}(x, t) = \operatorname{Re} [c_1 e^{-rx} \cdot e^{j\omega t}]$$

$$\bar{E}(x, t) = \operatorname{Re} [c_1 e^{-rx + j\omega t}], \quad \alpha = j\omega$$

$$r = \alpha + j\beta$$

$$\bar{E}(x, t) = \operatorname{Re} [c_1 e^{-(\alpha + j\beta)x + j\omega t}]$$

$$= \operatorname{Re} [c_1 e^{-\alpha x} \cdot e^{-j\beta x + j\omega t}]$$

$$= \operatorname{Re} [c_1 e^{-\alpha x} \cdot e^{j(\omega t - \beta x)}]$$

$$\boxed{\bar{E}(x, t) = c_1 e^{-\alpha x} \cdot \cos(\omega t - \beta x)}$$

$$\bar{E}(x, t) = R [e^{-\alpha x} \cdot e^{j(\omega t - \beta x)}] \quad e^{-\alpha x}$$

$$E(x, t) = ce^{-\alpha x} \cdot \cos(\omega t - \beta x)$$

If $\alpha \uparrow$, $e^{-\alpha x} \downarrow$, it indicates that the Amplitude of EM is reduced factor $e^{-\alpha x}$.

a) Wave characteristics

(a) Attenuation constant (α), dB/m

$$\text{consider, } \nabla^2 E = \nabla^2 \bar{E}$$

$$r^2 = \mu \epsilon (\sigma + j\omega \epsilon) \Rightarrow r = \sqrt{\mu \epsilon (\sigma + j\omega \epsilon)}$$

$$r^2 = \mu \epsilon \cdot \omega \epsilon (\sigma / j\omega \epsilon + 1)$$

$$r^2 = +\omega^2 \epsilon (\sigma / j\omega \epsilon + 1)$$

$$r^2 = +\omega^2 \epsilon \left(\frac{-\sigma}{\omega \epsilon} + 1 \right) \Rightarrow r^2 = \omega^2 \epsilon \left(1 - \frac{\sigma}{\omega \epsilon} \right)$$

$$\text{we have } r = \alpha + j\beta$$

$$(r^2 = (\alpha + j\beta)^2 = \omega^2 \epsilon \left(1 - \frac{\sigma}{\omega \epsilon} \right)) \quad |r| = \sqrt{\alpha^2 + \beta^2} \Rightarrow |r|^2 = \alpha^2 + \beta^2$$

$$\alpha^2 + \beta^2 + j \cdot 2\alpha\beta = \omega^2 \epsilon \left(1 - \sigma / \omega \epsilon \right) \quad \text{(a)}$$

(or)

$$r^2 = (\alpha + j\beta)^2 = \sqrt{\mu \epsilon (\sigma + j\omega \epsilon)}$$

$$r^2 = \mu \epsilon (\sigma + j\omega \epsilon)$$

$$(\alpha + j\beta)^2 = \mu \epsilon (\sigma + j\omega \epsilon)$$

$$\alpha^2 + \beta^2 + 2\alpha\beta = \mu \epsilon \sigma - \omega^2 \epsilon$$

$$(\alpha^2 + \beta^2) + j \cdot 2\alpha\beta = -\omega^2 \epsilon + j\mu \epsilon \sigma \quad \text{--- (1)}$$

Equating both sides for Eqⁿ (1)

$$(\alpha^2 + \beta^2) + j \cdot 2\alpha\beta = -\omega^2 \epsilon + j\mu \epsilon \sigma \quad \text{--- (2)}$$

Equate Imaginary parts and real parts

Compare Eqⁿ (a) & (b)

$$\omega^2 \epsilon \left[\sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} \right] \alpha \quad \text{Eq (c)}$$

$$(\alpha^2 - \beta^2) = -\omega^2 \mu \epsilon,$$

$$2\alpha\beta = \sigma \mu \epsilon$$

we have $(\alpha + \beta^2)^2 = (\alpha - \beta^2)^2 + 4\alpha\beta$.

$$\alpha^2 + \beta^2 + 2\alpha\beta = (\alpha + \beta^2)^2$$

$$\alpha^2 + \beta^2 + \beta^2 = \omega^2 \mu \epsilon \sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} - \omega^2 \mu \epsilon$$

$$2\alpha^2 = \omega^2 \mu \epsilon \left[\sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} - 1 \right]$$

$$\alpha = \frac{\omega^2 \mu \epsilon}{2} \left[\sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} - 1 \right]$$

$$\alpha = \sqrt{\frac{\omega^2 \mu \epsilon}{2} \left[\sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} - 1 \right]}$$

$$\boxed{\alpha = \omega \sqrt{\frac{\mu \epsilon}{2}} \sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} - 1}$$

b) Propagation Phase Constant (β)

$$\alpha^2 + \beta^2 = \omega^2 \mu \epsilon \sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}}$$

$$\alpha^2 - \beta^2 = -\omega^2 \mu \epsilon$$

$$\alpha^2 + \beta^2 - (\alpha^2 - \beta^2) = \omega^2 \mu \epsilon \sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} + \omega^2 \mu \epsilon$$

$$2\beta^2 = \omega^2 \mu \epsilon \left[\sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} + 1 \right]$$

$$\beta^2 = \frac{\omega^2 \mu \epsilon}{2} \left[\sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} + 1 \right]$$

$$\boxed{\beta = \omega \sqrt{\frac{\mu \epsilon}{2}} \sqrt{1 + \frac{\sigma^2}{\omega^2 \epsilon^2}} + 1}$$

(c) Propagation Constant

$$\gamma = \alpha + j\beta$$

$$\gamma^2 = j\omega\mu(\sigma + j\omega\epsilon)$$

$$\Rightarrow \boxed{\gamma = \sqrt{j\omega\mu(\sigma + j\omega\epsilon)} \text{ m}^{-1}}$$

(d) Intrinsic Impedance

$$\eta = \sqrt{\frac{j\omega\mu}{\sigma + j\omega\epsilon}}, \text{ for any media other than free space}$$

(e) wavelength (λ)

$$\lambda = \frac{2\pi}{\beta} = \frac{2\pi}{\omega\sqrt{\frac{\mu\epsilon}{2}\left[1 + \left(\frac{\sigma}{\omega\epsilon}\right)^2 + 1\right]}} \text{ m}$$

(f) Velocity (v_0)

$$v_0 = \frac{\omega}{\beta} = \frac{1}{\sqrt{\mu\epsilon}} \text{ m/s. In general}$$

$$v_0 = \frac{\omega}{\omega\sqrt{\frac{\mu\epsilon}{2}\left[1 + \left(\frac{\sigma}{\omega\epsilon}\right)^2 + 1\right]}}$$

$$v_0 = \frac{1}{\sqrt{\frac{\mu\epsilon}{2}\left[1 + \left(\frac{\sigma}{\omega\epsilon}\right)^2 + 1\right]}}$$

characteristics

(a) Attenuation constant (α) = $\omega\sqrt{\frac{\mu\epsilon}{2}\left[\sqrt{1 + \left(\frac{\sigma}{\omega\epsilon}\right)^2} - 1\right]}$

(b) phase constant (β) = $\omega\sqrt{\frac{\mu\epsilon}{2}\left[1 + \left(\frac{\sigma}{\omega\epsilon}\right)^2\right]} + 1$

(c) $\gamma = \sqrt{\frac{j\omega\mu}{\sigma + j\omega\epsilon}}$

(d) $\lambda = \frac{2\pi}{\beta}, \quad (e) \text{ velocity } v_0 = \frac{1}{\sqrt{\mu\epsilon}}$

WAVE PROPAGATION IN DIELECTRIC MEDIA

Consider the lossy dielectric media.

Consider the maxwells equation $\nabla \times \vec{H} = \vec{J}_c + \vec{J}_d$ where according to ohm's law, $\vec{J} = \sigma \vec{E}$

$$\vec{J}_d = \frac{d\vec{H}}{dt} (\vec{\delta})$$

Substitute both terms in Eqⁿ(1)

$$\nabla \times \vec{H} = \sigma \vec{E} + \frac{d}{dt} (\vec{\delta})$$

$$= \sigma \vec{E} + \frac{d}{dt} (\epsilon \vec{E}) = \sigma \vec{E} + \epsilon \cdot \frac{d}{dt} (\vec{E}).$$

$$\nabla \times \vec{H} = \sigma \vec{E} + \epsilon \cdot \vec{E}$$

$$= \sigma \vec{E} + j\omega \cdot \epsilon \vec{E}$$

$$\left| \frac{\vec{J}_c}{\vec{J}_d} \right| = \frac{\sigma \vec{E}}{\sqrt{(\epsilon \omega)^2}} = \frac{\sigma}{\omega \epsilon}$$

Case i) Consider, $\sigma/\omega \epsilon \gg 1$, $\sigma \gg \omega \epsilon$.

$$\text{we know } \omega = 2\pi f$$

As frequencies decreases, conductivity increases. Then at lower frequencies, the dielectric media acts as good conductor. Hence, the wave propagation is same as like in good conductor media.

Case ii) Consider, $\sigma/\omega \epsilon \ll 1$, $\sigma \ll \omega \epsilon$.

$\omega = 2\pi f$, As f increases, conductor decreases.

Then, at very higher frequencies, dielectric media acts as perfect dielectric media. So, the wave propagation is same as like as perfect/good dielectric media.

Wave propagation in Good conductor

Consider wave equation for conducting media, $\alpha^2 = \mu\omega\sigma(\sigma + \mu\omega\epsilon)$,

$$\alpha = \sqrt{\mu\omega\sigma(1 + \frac{\mu\omega\epsilon}{\sigma})}$$

Case I :- When waves are travelling in good conductor ($\omega/\sigma \ll 1$), so, media acts as good conductor at lower frequencies.

$$\alpha = \sqrt{\mu\omega\sigma} = \sqrt{\omega\mu\sigma} \cdot [45^\circ] = \sqrt{\omega\mu\sigma} [\cos 45^\circ + i \sin 45^\circ]$$

$$\alpha = \beta = \sqrt{\frac{\omega\mu\sigma}{2}}$$

Therefore, good conducting media is always lossy media in practice.

So, $\omega/\sigma \ll 1$, $(1 + \frac{\mu\omega\epsilon}{\sigma})$ eliminated

$$\begin{aligned} \alpha &= \alpha + j\beta \\ &= \sqrt{\pi f \mu} + j \sqrt{\pi f \mu \sigma} \end{aligned}$$

Skin Depth (Depth of Penetration) (δ)

The distance through which the amplitude of travelling Electromagnetic wave reduces to 37% of original amplitude. It is denoted as δ .

$$\delta = \frac{1}{\alpha} = \frac{1}{\beta} = \frac{1}{\sqrt{\omega\mu\sigma}} = \frac{1}{\sqrt{2\pi f \mu \sigma}} = \frac{1}{\sqrt{\pi f \mu \sigma}}$$

$$\boxed{\delta = \frac{1}{\sqrt{\pi f \mu \sigma}} \text{ m}}$$

POLARIZATION:-

It is defined as the time varying behaviour of electric field vector at given point in space.

- 2) It is defined as the tip of locus of electric field vector at given point in space as function of time
- 3) It defines the way in which E changes along the direction of wave propagation

Types of Polarisation

Linear, Circular and Elliptical Polarisation

(a) Linear Polarisation:-

If E oscillates along the straight line and follow the direction of propagation, then it is said called Linear Polarisation.

If the direction is along E_x , x -direction,

$$E_x \neq 0, E_y = 0,$$

$$E = \sqrt{x^2 + y^2},$$

then resultant angle (θ) = $\tan^{-1}(E_y/E_x)$.

If $E_x = 0, E_y \neq 0$, then the wave is polarised along y -direction. If $E_y = 0, E_x \neq 0$, then the wave is said to be polarised along x -direction.

b) Elliptical Polarisation

It is the tip of locus of E traces ellipse in space. If $E_x \neq E_y$ and E_x, E_y are in out of phase, $\theta_y = \theta_x - \pi/2$.

c) Circular Polarisation

It is defined as the tip of locus of E traces circular or circular path in space.

If $E_x = E_y = E_0$, E_x, E_y are out of phase
 $\therefore \theta_y = \theta_x - \pi/2$

EM WAVE CHARACTERISTICS - II

Upto now, we considered that the waves are travelling in unbounded and non homogeneous media. But practically, very often, waves propagate in bounded regions consisting several media of different constitutive parameters ϵ, μ, σ, m etc.

There are two cases that practically happen when the waves are travelling and incident on boundary.

case I:- If consider a transmission line having a characteristic impedance z_0 . Assume that a line is terminated with a load impedance z_L .

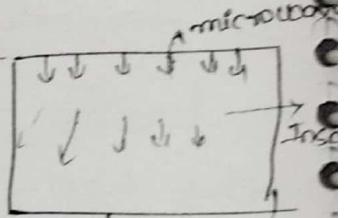
If a load impedance z_L equals to the characteristic impedance z_0 (i.e., $z_L = z_0$) , then line is said to be properly terminated.

If $z_L \neq z_0$, then there is a mismatch between the two impedances and the line is not properly terminated. Consider that the wave travelling along the line incidents at the load. The part of the wave gets absorbed by the load, while the other part is reflected back to the generator so, we can say that reflection occurs at the load if $z_L \neq z_0$. If there are two waves, one is incident in forward direction and other in backward direction, then standing waves are produced along the line or transmission line.

Case 2:-

Now again consider the uniform plane wave E_0 travelling in non-homogeneous media. When a uniform plane wave travels from one boundary of one media to another media having different characteristic or intrinsic impedances, the reflection takes place at the boundary. The part of the wave E_0 is transmitted in medium 2 and remaining part of the wave reflected back to the medium 1, depending upon the constitutive parameters of media.

Eg:- In the microwave oven, or elevators the microwaves will not come outside. The microwaves are generated inside and reflected back to the inside of microwave oven, the inner boundary parts are coated with a conducting material or conductor. These conductor does not allow the microwave frequencies to go outside. The conductivity of conductor determines the percentage of reflected waves. If the conductivity is ∞ , then the waves completely reflected back. This is ideal case, where 100% reflection takes place. If σ is finite, some of the waves reflected back and some of the waves are transmitted. These produces standing waves. Eg:- Isom. If $\sigma=0$, it acts as insulator, then the waves are transmitted completely and there is no reflection.



Reason for reflection of wave by conductor

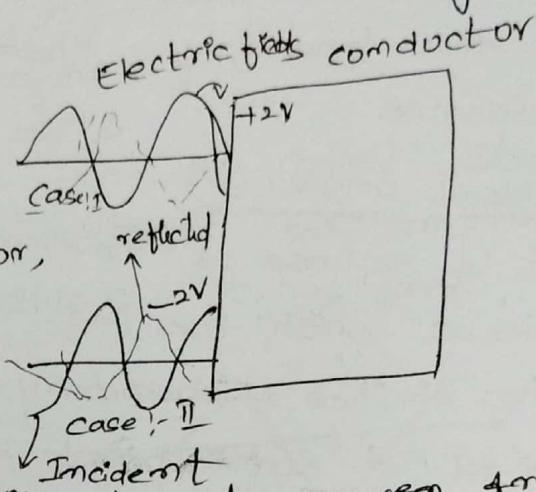
In them the wave is incident on conductor, the waves get reflected back. Here, the conductor, the regenerates the opposite voltage equal to the incident waves and generates the wave. This wave/signal is reflected back.

In case:-I) When the wave with electric field $2V/m$ is incident on conductor, there are free electrons in conductors and these get rearranged. These movement of current free electrons makes the current production, and the voltage also induced. This voltage is with opposite voltage, i.e. $-2V$ as the current direction is one. So, because of this, the waves are reflected back as the current/voltage produced should be opposite direction to the applied field.

We can also conclude, the incident and reflected magnitudes are same but the signs are opposite and they cancel out each other. The net electric field is 0.

In the total process, the currents which vary with time are produced inside conductor continuously.

Another example is capacitor. If we apply field to capacitor, the current/voltage inside the capacitor. If dc voltage is applied, the steady current/voltage is produced. If ac voltage is applied time varying current/voltage is produced.



The reflection of uniform plane wave not only depends on the type of boundary. It also depends on the way in which waves are incident on the boundary or obstacle. Depending upon the manner in which the uniform plane wave is incident on the boundary, there are two types of incidence.

Incident angle (θ_i) :-

It is defined as the angle at which the EM wave strikes a boundary condition at some point.

Reflected angle (θ_r) :-

It is the angle at which the incident EM wave reflected back into same media.

Transmission angle (θ_t) :-

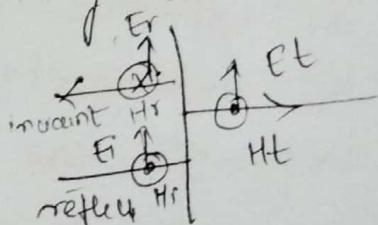
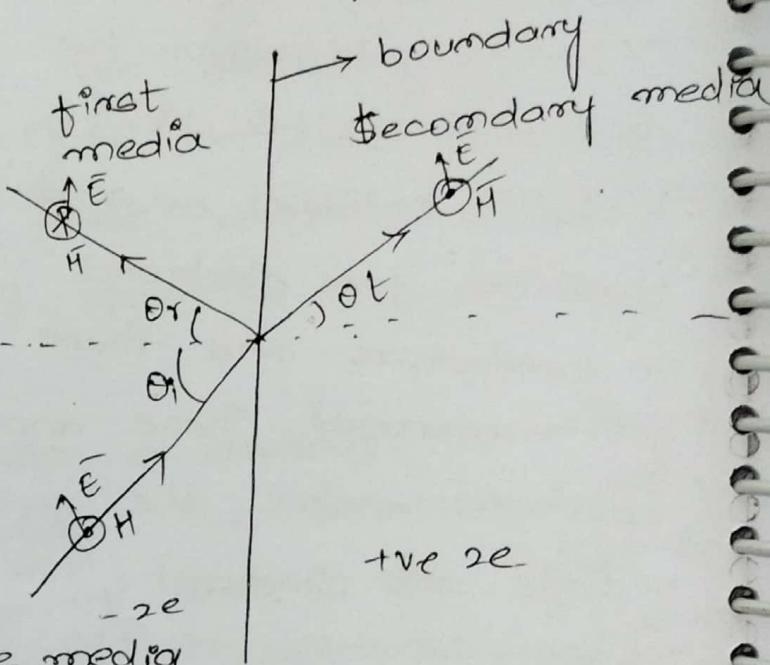
It is the angle at which incident EM wave transmits or passing or refracting into second media.

Types of Incidence

→ Normal Incidence:- It is defined as the EM wave which is striking the boundary $\theta_i = 90^\circ$. In this reflected, the wave is also in the same direction.

Percentage of wave transmitted is less in second media than oblique incidence.

→ Obligee Incidence:- It is defined as the EM wave is striking the boundary other than 90° . $\theta_i \neq 90^\circ$. The % of wave transmission in oblique incidence is more than normal incidence.

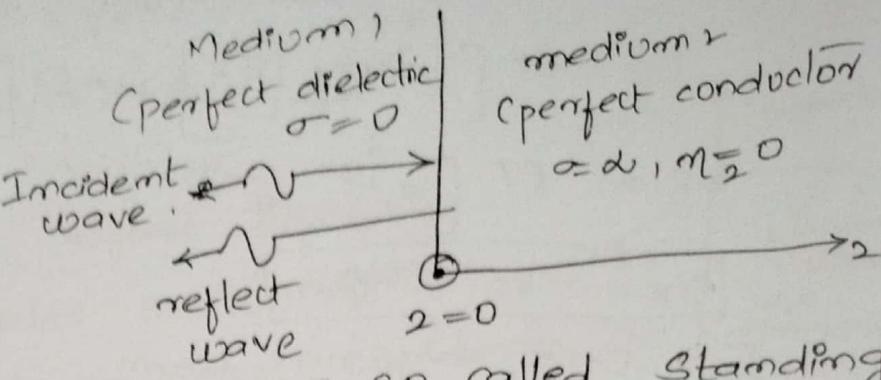


INCIDENCE

When EM travels in air and incidenting on perfect conductor the reflection takes place and produces

standing waves. These waves are so called standing waves because there is a movement in amplitude and phase but not with position. It has fixed points.

using boundary conditions, the tangential components of E is 0.



we have, let incident wave = $E_i e^{-jBz}$

Reflected wave = $E_r e^{jBz}$

Resultant wave = Incident wave + reflected wave

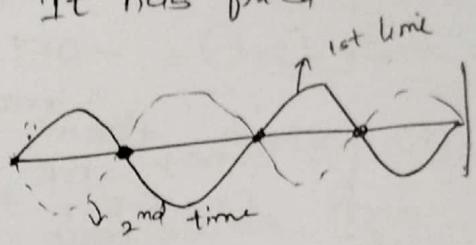
$$E_R = E_i e^{-jBz} + E_r e^{jBz}$$

Incident and reflected waves are phase reversal to satisfy the boundary condition, that the tangential components of E is 0 at boundary. Since, propagation is along z -direction, the resultant wave along z direction is 0. i.e., $E_z = 0$. $E_R = 0$, as it a uniform plane wave.

$$\Rightarrow 0 = E_i e^{-jBz} + E_r e^{jBz} \quad (z=0)$$

$$0 = E_i + E_r \Rightarrow \boxed{E_i^0 = -E_r^0}$$

This indicates that the magnitude of incident wave and magnitude of reflected wave are equal, but they are phase reversal (i.e. out of phase) - anti-node.



$$-jBz$$

$$e^{jBz}$$

In standing wave, energy is $E_R = E_i e^{jB^2} - E_i e^{-jB^2}$.
 cavity resonator

$$E_R = E_i \left[e^{jB^2} + (e^{-jB^2}) \right] = E_i \left[e^{-jB^2} + (-e^{jB^2}) \right]$$

$$E_R = -2E_i \sin B^2 e^{-jB^2}$$

In time varying form,

$$E_R(t) = \operatorname{Re} \left[\left[-2E_i \sin B^2 \right] e^{j\omega t} \right]$$

$$E_R(t) = -2E_i \sin B^2 \sin \omega t$$

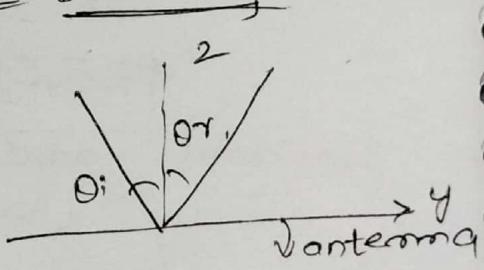
When there is no absorption, that is, $\alpha = 0$, and $E_i = E_R$, then the wave is called complete standing wave.

If there is standing wave and there less absorption such that $E_i > E_R$, then the wave is called incomplete standing wave.

Application of using Conductor as boundary

If we incidence EM wave on conductor, the waves are exactly reflected back. This happens when the incidence is oblique incidence. So, antenna is made of conductor. When the waves are incident on antenna, it exactly reflected back. So, the incident angle is selected in which the reflected wave should reflect back exactly in desired direction.

In the above figure, standing wave is produced in 2 directions, along y-axis. travelling wave is produced.



$$E_i(y, z) = E_0 e^{-jB(y \sin \theta - z \cos \theta)}$$

$$E_r(y, z) = -E_0 e^{-jB(y \sin \theta + z \cos \theta)}$$

$$E_{\text{total}}(y, z) = E_i(y, z) + E_r(y, z)$$

Conductor for normal incidence

Cavity resonators, reflect klystrons are the best examples in which the waves are with normal incidence on boundary. Internally, it produces the standing waves.

Inspections on wave Equation

In The standing wave Equation

- i) The wave Amplitude varies in time by $\sin \omega t$
- ii) The wave varies in space variables by $\sin \beta z$.

$$E_R(2it) = -2E_0 \sin \beta z \cdot \sin \omega t$$

iii) Minima of wave

As $E_R = 0$, $E_R = -2E_0 \sin \beta z \Rightarrow \sin \beta z = 0 \Rightarrow \sin \beta z = \sin \pi n$

$$\boxed{\beta z = m\pi}, m = 0, 1, 2, 3, \dots$$

$$\beta z = m\pi \Rightarrow \frac{2\pi}{\lambda} \cdot z = m\pi \quad (\because \beta = \frac{2\pi}{\lambda})$$

$$z = -\frac{m\lambda}{2}$$

For $m=0 \Rightarrow z=0$

$$m=1 \Rightarrow z = -\frac{\lambda}{2}$$

$$m=2, z = -\lambda$$

$$m=3, z = -\frac{3\lambda}{2}$$

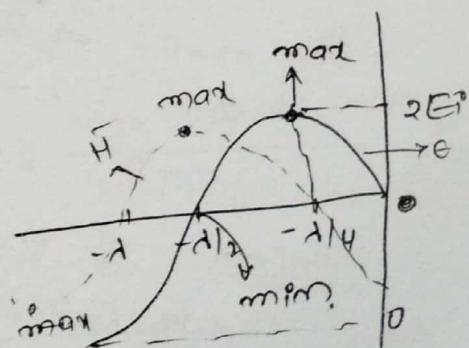
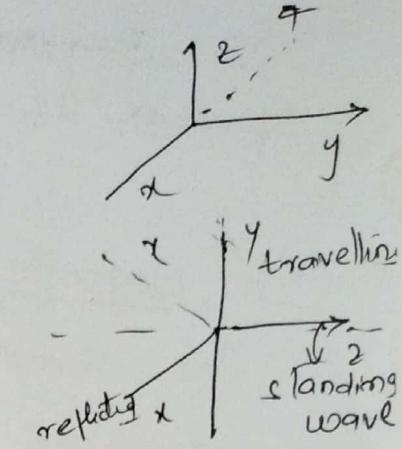
Minima are called points.

(iv) Maxima of ER

$$E_R \text{ max} = 2E_0$$

$$2E_0 = -2E_0 \sin \beta z \Rightarrow \sin \beta z = \sin(m\pi + \frac{\pi}{2})$$

$$\boxed{\beta z = -\left(m\pi + \frac{\pi}{2}\right)} \Rightarrow \frac{2\pi}{\lambda} = -\pi \left(m + \frac{1}{2}\right)$$



Standing wave

$\frac{2\pi}{\lambda} = -\pi \left(m + \frac{1}{2}\right)$

$$2 = -m\lambda - \lambda/4.$$

If $m=0$, $2=-\lambda/4$, If $m=0$, $2=-\lambda/4$,
 $m=1$, $2=-3\lambda/4$.

(iv) Magnetic field

The standing wave equation for magnetic field is given as - $HR = H_i e^{-jB_2 z} + H_i e^{jB_2 z}$.
As $E \perp$ to H , if $[E^i = -ER]$, $[H^i = HR]$

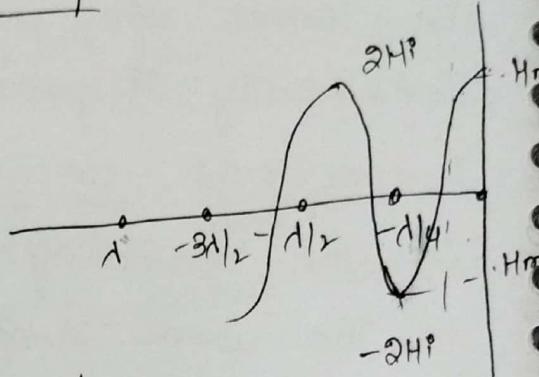
$$HR = H_i e^{-jB_2 z} + H_i e^{jB_2 z}$$

$$HR = 2H_i [e^{-jB_2 z} + e^{jB_2 z}]$$

$$\boxed{HR = 2H_i \cos B_2 z}$$

In Time Varying form

$$HR(2, t) = 2H_i \cos B_2 z \cos \omega t$$



Inspections:-

- i) The wave amplitude varies in time by $\cos \omega t$.
- ii) The wave amplitude varies in space by $\cos B_2 z$.
- iii) $HR = 2H_i \cos B_2 z$.

Maxima of wave

$$HR = 2H_i, \text{ for } 2H_i = 2H_i \cos B_2 z \Rightarrow \cos B_2 z = 1 \Rightarrow \cos B_2 z = \cos m\pi$$

$$B_2 = -m\pi, m = 0, 1, 2, 3, \dots, 2 = -\frac{m\pi}{\lambda} = -\frac{m\pi}{2\pi/\lambda} = -\frac{m\lambda}{2}$$

$$\text{for } m=0, \Rightarrow 2=0$$

$$m=1, \quad 2=\lambda/2$$

$$m=2, \quad 2=-3\lambda/2$$

Minima of wave

$$HR = -2H_i, \text{ for } -2H_i = 2H_i \cos B_2 z \Rightarrow \cos B_2 z = -1 \Rightarrow \cos B_2 z = -\left(m\pi + \frac{\pi}{2}\right)$$

$$B_2 = -\left(m\pi + \frac{\pi}{2}\right) \Rightarrow z = -\frac{m\lambda}{2} - \lambda/4$$

$$\text{If } m=0, \quad 2=-\lambda/4$$

$$m=1, \quad 2=-3\lambda/2$$

Reflection coefficient

5

$$\text{Reflection coefficient} = \frac{\text{Reflected wave}}{\text{incident wave}} = \Gamma$$

(a) for Electric field, $\Gamma_E = \frac{E_R}{E_i}$

In conductors, reflected wave = incident wave, but with opposite magnitude/ sign.

$$\Gamma_E = \frac{E_R}{E_i} = \frac{E_R}{-E_i} \quad (\because E_R = -E_i)$$

$$\Gamma_E = \frac{-E_R}{E_i} \rightarrow \boxed{\Gamma_E = -1}$$

(b) for Magnetic field, $\Gamma_H = \frac{H_R}{H_i}$

Since, $H_R = H_i$

$$\Gamma_H = \frac{H_R}{H_i} = \frac{H_R}{H_R} = 1, \boxed{\Gamma_H = 1}$$

Transmission coefficient

$$\text{Transmission coefficient} = \frac{\text{Transmitted wave}}{\text{Incident wave}} = \Gamma_t$$

(a) for Electric field, $\Gamma_E = \frac{E_t}{E_i}$

Since, $E_t = 0$,

$$\Gamma_E = \frac{E_t}{E_i} = \frac{0}{E_i} = 0, \boxed{\Gamma_E = 0}, \text{ for perfect conductor}$$

(b) for Magnetic field

Since, $H_t = 0$

$$\Gamma_H = \frac{H_t}{H_i} = \frac{0}{H_i} = 0, \boxed{\Gamma_H = 0}$$

Voltage Standing Wave Ratio

$$\text{Voltage Standing Wave Ratio} = \frac{\text{Max. of standing wave}}{\text{Min. of standing wave}}$$

(a) for Electric field, $VSUR = \frac{E_{max}}{E_{min}}$

$$VSUR = \frac{E_{max}}{E_{min}} = \frac{2E_i}{0} = \infty, \boxed{VSUR = \infty}$$

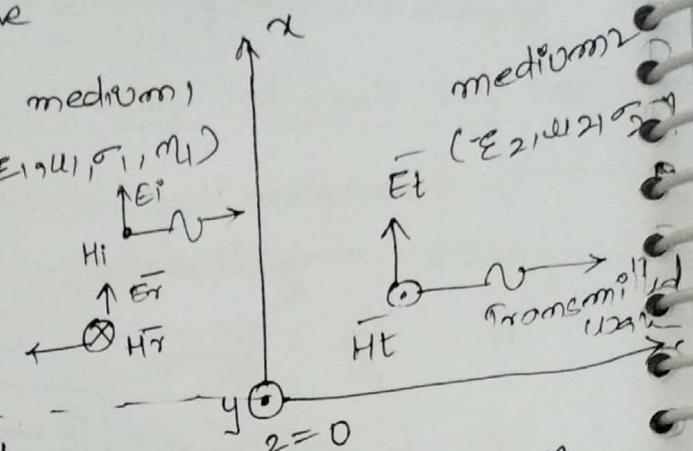
(b) for Magnetic field, $VSUR = \frac{H_{max}}{H_{min}}$

$$VSUR = \frac{H_{max}}{H_{min}} = \frac{2H_i}{-2H_i} \boxed{VSUR = -1}$$

NORMAL INCIDENCE ON PLANE DIELECTRIC BOUNDARY

consider uniform plane wave

is propagating along \hat{x} direction and incidence at right angles at the boundary between two dielectric media, i.e. $\epsilon_2 \neq 0$



let the properties of two media, $\epsilon_1, \mu_1, \sigma_1, n_1, \epsilon_2, \mu_2, \sigma_2, n_2$. Depending upon the values of those two media, part of the wave will be transmitted in medium 2, while the other part is reflected back.

Let E_i^o, H_i^o are the electric field striking the boundary, E_t, H_t are the electric field and magnetic strength of transmitted in the medium 2, and E_r, H_r are the reflected electric field and magnetic fields in media 1.

Now, find, F_E, F_H, T_E & T_H , we have $n_1 = \frac{E_i^o}{H_i^o}$

(a) F_E

$$\text{consider } n_2 = \frac{E_t}{H_t} \rightarrow H_t = \frac{E_t}{n_2} \quad (2)$$

$$\text{we have } [H_i^o = H_t + H_r] \Rightarrow H_i^o - H_r = H_t \quad (1)$$

$$n_1 = \frac{E_i^o}{H_i^o} \Rightarrow H_i^o = \frac{E_i^o}{n_1}$$

sub all the equations in Eqⁿ-(1)

$$\frac{E_i^o}{n_1} + [H_r] = H_t$$

$$\Rightarrow \frac{E_i^o}{n_1} - \frac{E_r}{n_1} = H_t$$

$$\frac{E_i^o}{n_1} - \frac{E_r}{n_1} =$$

$$H_t = H_i^o - H_r$$

we have $E_i = Er + Et$, $H_i = Hr + Lt \rightarrow H_i - Hr = Lt \quad (2)$

$$m_1 = \frac{E_i}{H_i}; -n_1 = \frac{Er}{Hr}; m_2 = \frac{Et}{Lt}$$

$$H_i = \frac{E_i}{m_1}; Hr = \frac{-Er}{n_1}; Lt = \frac{Et}{n_2}$$

Then Sub in eqn (2), $H_i - Hr = Lt$

$$\frac{E_i}{m_1} + \frac{Er}{n_1} = \frac{Et}{n_2}$$

$$\Rightarrow \frac{E_i}{m_1} + \frac{Er}{n_1} = \frac{E_i - Et}{n_2}$$

$$\rightarrow \frac{E_i}{m_1} + \frac{Er}{n_1} = \frac{E_i}{n_2} - \frac{Et}{n_2}$$

$$\Rightarrow \frac{E_i}{m_1} - \frac{E_i}{n_2} = -\frac{Et}{n_2} - \frac{Er}{n_1}$$

$$\Rightarrow E_i \left[\frac{1}{m_1} - \frac{1}{n_2} \right] = -Er \left[\frac{1}{n_1} + \frac{1}{n_2} \right]$$

$$\Rightarrow E_i \left[\frac{1}{n_2} - \frac{1}{m_1} \right] = Er \left[\frac{1}{n_1} + \frac{1}{n_2} \right]$$

$$\Rightarrow E_i \left[\frac{n_1 - n_2}{n_1 n_2} \right] = Er \left[\frac{m_1 + m_2}{n_1 n_2} \right]$$

$$\Rightarrow \frac{ER}{Ei} = \frac{n_1 n_2}{n_1 + n_2}$$

\Rightarrow Reflection coefficient F_E for electric field

$$F_E = \frac{n_1 - n_2}{n_1 + n_2}$$

for Magnetic field:

Reflection coefficient for magnetic field $F_H = \frac{HR}{H_i}$

we have $+m_2 = -\frac{ER}{HR}$, $m_2 = \frac{E_i}{H_i}$

$$F_H = \frac{HR}{H_i} = -\frac{ER/m_1}{Ei/m_1} = -\frac{ER}{Ei} = -\left[\frac{ER}{Ei}\right] = -F_E$$

$$F_H = -F_E \Rightarrow$$

$$F_H = \frac{m_2 - m_1}{n_1 + n_2}$$

b) Transmission coefficient (T)

$$TE/TH = \frac{Et}{Ei} = \frac{Ht}{Hi}$$

For electric field:-

$$TE = \frac{Et}{Ei}, \text{ we have } Et + Er = Ei \Rightarrow I = \frac{Er}{Ei} + \frac{Et}{Ei}$$

$$\frac{Et}{Ei} = I - \frac{Er}{Ei} = I - TE, \text{ we have } TE = \frac{n_1 - n_2}{n_1 + n_2}$$

$$TE = \frac{Et}{Ei} = I - \left[\frac{n_1 - n_2}{n_1 + n_2} \right] = \frac{n_1 + n_2 - n_1 - n_2}{n_1 + n_2} = \frac{2n_2}{n_1 + n_2}$$

$$TE = \frac{2n_2}{n_1 + n_2}$$

For Magnetic field

$$\alpha TH = \frac{Ht}{Hi}, Ht + Hr = Hi \Rightarrow I = \frac{Ht}{Hi} + \frac{Hr}{Hi} \Rightarrow \frac{Hr}{Hi} = I - \frac{Ht}{Hi}$$

$$TH = \frac{Ht}{Hi} \Rightarrow \frac{Ht}{Hi} = I - \frac{Hr}{Hi} \Rightarrow \frac{Ht}{Hi} = I - TH \Leftrightarrow$$

$$TH = I. \text{ In general } TH = \frac{Ht}{Hi} = \frac{Et/n_2}{Ei/n_1} = \frac{Et/n_2}{Ei/n_1}$$

$$= \left(\frac{Et}{Ei} \right) \left(\frac{n_2}{n_1} \right) = TE \cdot \left(\frac{n_2}{n_1} \right), TE = \frac{2n_2}{n_1 + n_2}$$

$$TH = \frac{2n_2}{n_1 + n_2} \left[\frac{n_2}{n_1} \right]$$

$$TH = \frac{2n_2}{n_1 + n_2} \left[\frac{n_2}{n_1} \right]$$

$$TH = \frac{2n_2}{n_1 + n_2}$$

In General

These are the general coefficients for all the media. Depending upon the intrinsic impedances, the above coefficients are calculated.

In General, for normal dielectric, where $\sigma=0$, ω some finite

for Electric fields:-

$$(1) \text{Reflection coefficient } \Gamma_E = \frac{n_1 - n_2}{n_1 + n_2}$$

$$(2) \text{Transmission coefficient } \tau_E = 1 - \Gamma_E = \frac{2n_2}{n_1 + n_2}$$

for Magnetic fields:-

$$(1) \text{Reflection coefficient } \Gamma_H = -\Gamma_E = \frac{n_2 - n_1}{n_1 + n_2}$$

$$(2) \text{Transmission coefficient } \tau_H = \frac{2n_1}{n_1 + n_2} = \tau_E \cdot \left[\frac{n_1}{n_2} \right] [\tau_E]$$

But for pure dielectrics, $\sigma=0$, So, there is no reflected wave, $E_r=0$, $H_r=0$, and $E^o=E_t$.

Transmission coefficient (T)

(1) for Electric field:

$$\tau_E = \frac{E_t}{E^o}, \text{ since } E^o = E_t \Rightarrow \tau_E = \frac{E_t}{E_t} \Rightarrow \boxed{\tau_E = 1}$$

$$\text{So, } \boxed{\tau_E = 1}$$

For Magnetic field:

$$\tau_H = \frac{H_t}{H^o}, \text{ since } H^o = H_t \Rightarrow \tau_H = \frac{H_t}{H_t} \Rightarrow \boxed{\tau_H = 1}$$

$$\text{So, } \boxed{\tau_H = 1}$$

Reflection coefficient

(1) for Electric field:

$$\Gamma_E = \frac{E_R}{E^o} = \frac{0}{E^o} = 0, \quad \Gamma_E = \infty$$

(2) for Magnetic field:

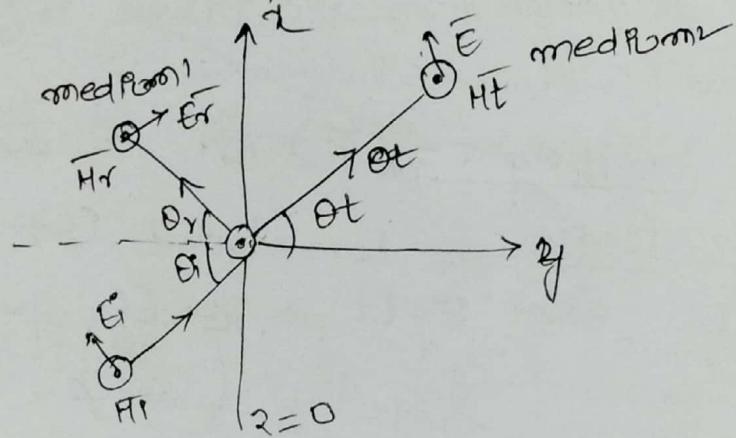
$$\Gamma_H = \frac{H_R}{H^o} = \frac{0}{H^o} = 0, \quad \Gamma_H = \infty.$$

OBLIQUE INCIDENCE

When a uniform plane wave strikes obliquely on the surface (either conductor or dielectric), the behaviour of the reflected wave is decided by the polarization of the incident wave.

case(i) Parallel Polarisation / Vertical :-

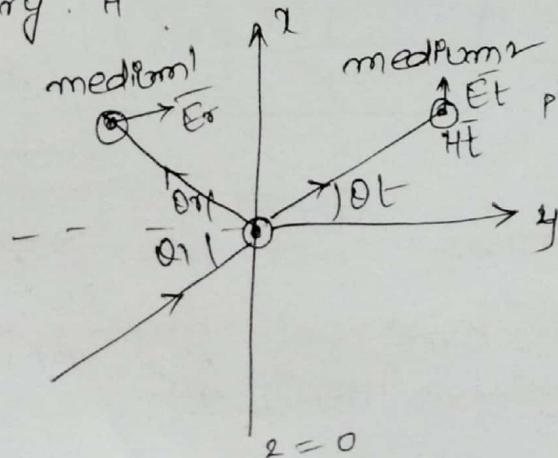
The magnetic field vector is aligned parallel to the boundary surface. In other words, the magnetic field vector is perpendicular to the plane of incidence while E is aligned parallel to the plane of incidence. \vec{E} is parallel to plane of incidence.



Vertical polarization.

Case ii) Horizontal | Perpendicular Polarisation:-

The E is parallel to plane of incidence. \vec{E} is parallel to boundary. H .



A plane of incidence is a plane containing the vector in the direction of propagation of the incident wave and normal to the boundary surface.

OBLIQUE INCIDENCE AT PLANE CONDUCTING BOUNDARY

Consider an interface between a perfect dielectric and perfect conductor.

Horizontal Polarization

Consider that the plane wave incident obliquely at the interface between a conductor, with the electric field vector \vec{E}^i parallel to plane of incidence.

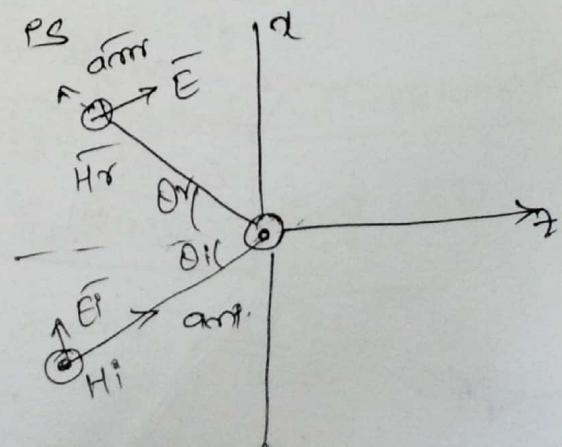
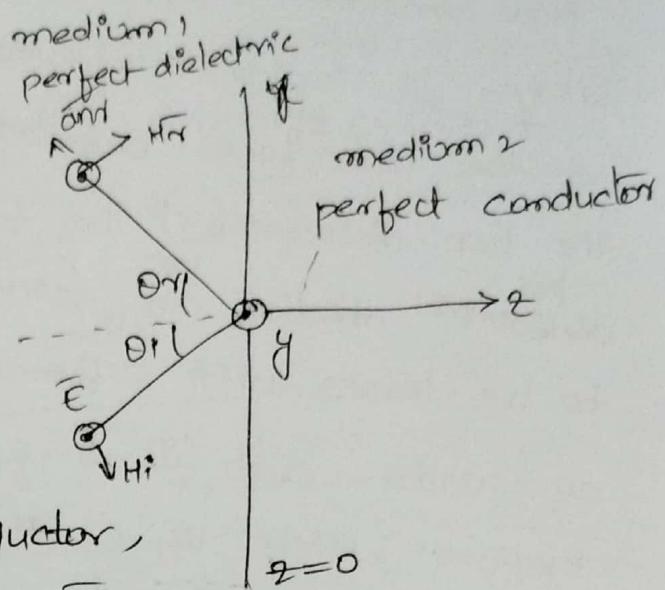
As \vec{E}^i is parallel to plane of incidence to this type of incidence, this type of polarization is also called perpendicular polarization or E-polarization.

The unit vector in the direction of incident wave is \hat{a}_{in} . Let θ_i be the angle of incidence. Then the unit vector is given by -

$$\hat{a}_{\text{in}} = \sin \theta_i \hat{a}_x + \cos \theta_i \hat{a}_z$$

OBLIQUE INCIDENCE AT PLANE CONDUCTING boundary, with vertical polarization.

Consider that the plane wave is obliquely incident with the \vec{E}^i parallel to plane of incidence. This is also called Parallel / H-Polarization.



OBLIQUE INCIDENCE AT PLANE DIELECTRIC BOUNDARY

Now consider a uniform plane wave is incident obliquely at the interface between the two dielectrics. The two dielectric media are assumed to be losses with different constants. Such as ϵ_1, μ_1 for medium¹, while ϵ_2, μ_2 for

medium². As the two media (ϵ_1, μ_1)

having different consecutive boundaries, at the interface there is discontinuity. Because of this, at the interface a part of the incident wave is reflected, while a part is transmitted as shown in fig.

Let the line of intersections of the time plane OA, O'A' and O'B be the plane of incident with the equiphasic surfaces of the incident, reflected and transmitted waves.

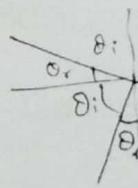
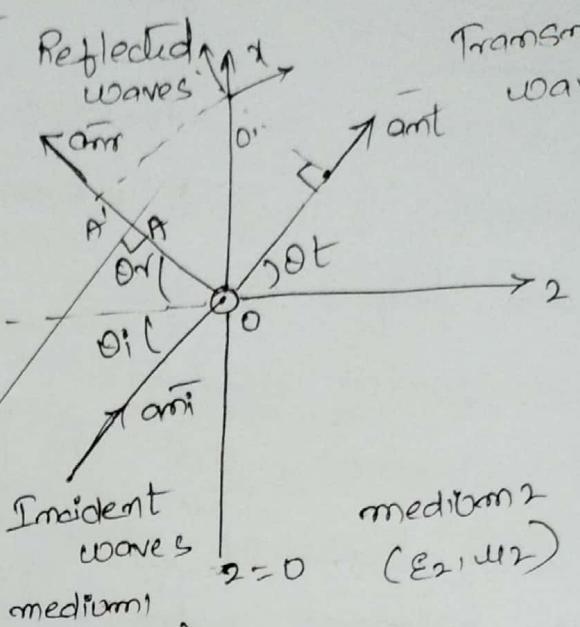
From the diagram, $\sin(\theta_t) = OB$ the distances \overline{OA} and $\overline{A'D}$ are same.

Snell's law; from the diagram, angle of incidence = angle of refraction

$$\frac{\sin \theta_t}{\sin \theta_i} = \frac{\mu_1}{\mu_2}$$

where $n = \frac{c}{v} = \frac{\text{Speed of light in free space}}{\text{Speed of light in medium}}$

$$v_1 = \frac{1}{\sqrt{\mu_1 \epsilon_1}}, v_2 = \frac{1}{\sqrt{\mu_2 \epsilon_2}}$$



$$\frac{\sin\theta_t}{\sin\theta_i} = \frac{c/v_1}{c/v_2} = \frac{v_2}{v_1} = \frac{\sqrt{\mu_1\varepsilon_1}}{\sqrt{\mu_2\varepsilon_2}} = \sqrt{\varepsilon_1/\varepsilon_2} \quad \text{--- (1)}$$

For non-magnetic media, $\mu_1 = \mu_2 = \mu_0$

Intrinsic impedances - $\eta_1 = \sqrt{\mu_1/\varepsilon_1} = \sqrt{\mu_0/\varepsilon_1}$, $\eta_2 = \sqrt{\mu_0/\varepsilon_2}$

$$\frac{\sin\theta_t}{\sin\theta_i} = \sqrt{\frac{\mu_0\varepsilon_1}{\mu_0\varepsilon_2}} = \sqrt{\frac{\varepsilon_1}{\varepsilon_2}} = \frac{\eta_2}{\eta_1}$$

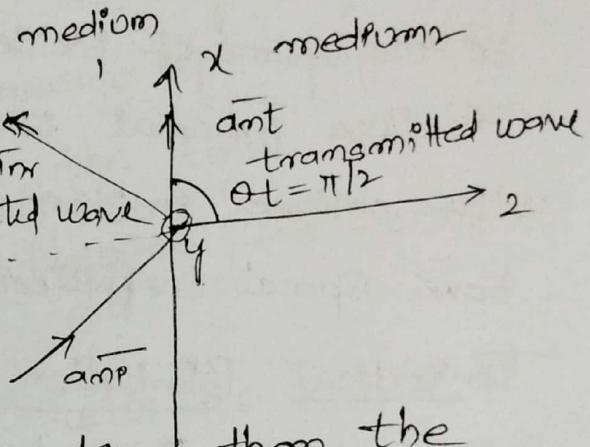
Thus, collectively, we can write Snell's law of refraction as

$$\boxed{\frac{\sin\theta_t}{\sin\theta_i} = \frac{v_2}{v_1} = \frac{\eta_1}{\eta_2} = \frac{\eta_2}{\eta_1} = \frac{\eta_1}{\eta_2}}$$

Total Reflection:

Consider that the medium 2 is denser as compared to medium 1, i.e., $\varepsilon_1 > \varepsilon_2$. Under this condition the angle of

transmission θ_t becomes greater than the angle of incidence. The θ_t increases with θ_i . When $\theta_t = \pi/2$, the wave transmitted is along the interface.



If θ_i is further increased, there will be no total internal reflection such that no wave will be transmitted. The angle of incidence at which total reflection takes place called Critical angle (θ_c). Then at $\theta_t = \pi/2$, $\theta_i = \theta_c$. Then according to Snell's law,

$$\frac{\sin\theta_t}{\sin\theta_i} = \sqrt{\varepsilon_1/\varepsilon_2} \Rightarrow \frac{\sin\theta_c}{\sin\theta_c} = \sqrt{\frac{\varepsilon_1}{\varepsilon_2}}$$

$$\frac{1}{\sin \theta_c} = \sqrt{\frac{\epsilon_1}{\epsilon_2}} \rightarrow \sin \theta_c = \sqrt{\frac{\epsilon_2}{\epsilon_1}}$$

$$\theta_c = \sin^{-1} \left[\sqrt{\frac{\epsilon_2}{\epsilon_1}} \right] = \sin^{-1} \left[\frac{n_2}{n_1} \right]$$

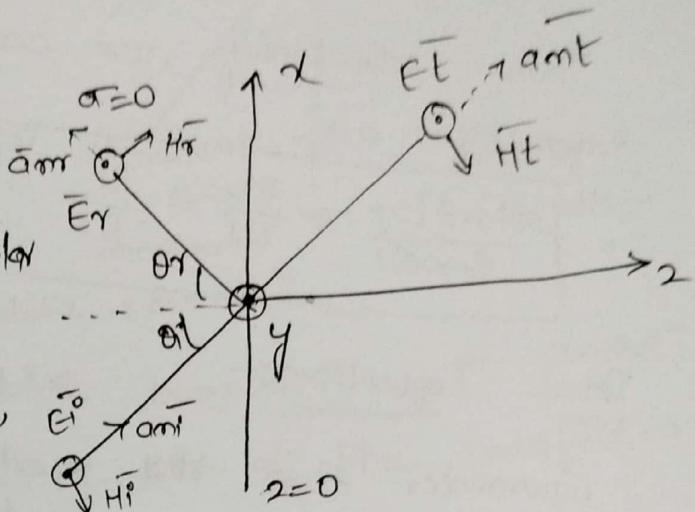
Types of polarization for oblique incidence with dielectric media.

(a) Horizontal Polarization

Consider that a uniform plane wave is incident obliquely with \vec{E} perpendicular to the plane of incidence.

Like normal incidence, for oblique incidence also

have same coefficients



(b) Vertical Polarization

θ_i → called Brewster angle.

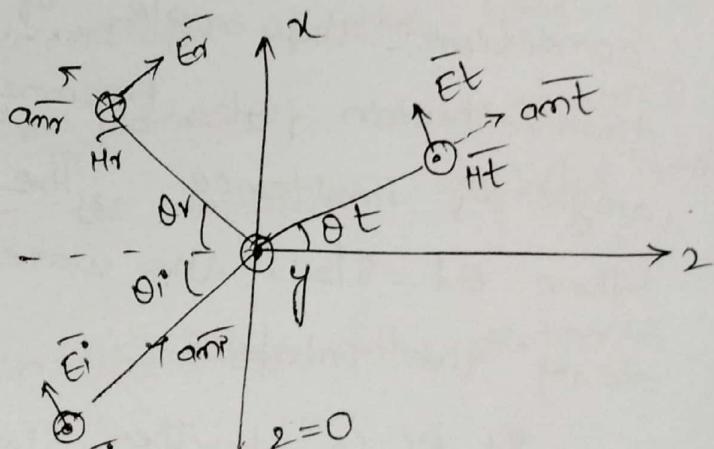
Brewster Angle:

The angle of incidence at which there is no reflection.

For parallel polarization, when $\theta_i = \theta_B$, no reflection takes place. Brewster angle is also called Polarizing angle.

→ Condition for total internal reflection is

$$\theta_i \geq \theta_c$$



SURFACE IMPEDANCE

Surface Impedance is defined as the ratio of the tangential component of the electric field to the surface current density at the conductor surface. The surface impedance is denoted as

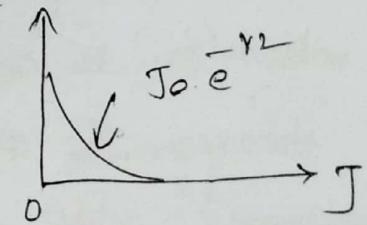
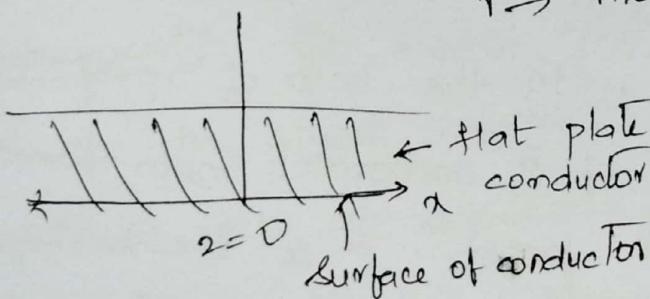
$$Z_s = \frac{E_{tan}}{J_s} \Omega$$

E_{tan} is the tangential component of the electric field which is parallel to the surface of the conductor. The surface current density J_s is the linear current which is the result of tangential component E_{tan} . This indicates the total conduction current per meter width flowing in the thin sheet.

Consider a flat conductor with its surface at $z=0$ plane, then the current distribution is given below.

$$J = J_0 e^{-rz} \quad J_0 \rightarrow \text{current density at surface}$$

$r \rightarrow \text{Propagation Constant}$



Surface Impedance of Good Conductor

$$\delta = \sqrt{\frac{2}{\omega \epsilon_0 \sigma}}$$

$$R_s = \frac{1}{\delta \sigma}$$

POYNTING VECTOR (\vec{P} or S)

It is the measure of rate of energy flow per unit area in the given medium.

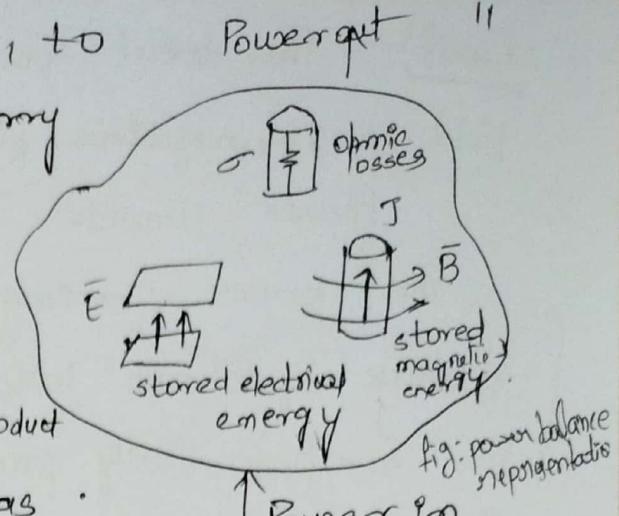
$$\boxed{\text{Poynting vector } (\vec{P}) = \vec{E} \times \vec{H} = V/m \times A/m = W/m^2}$$

It is also called as power density (Power per unit density).

\vec{P} shows the direction of wave propagation which is mutually perpendicular to \vec{E} or \vec{H} . The advantage of the above expression is to find the direction of wave propagation when both \vec{E} or \vec{H} are given, or any of the fields are given. This is done with the help of Maxwell's Equations.

By means of EM waves, an energy can be transported from transmitter to receiver. The energy stored in an electric field and magnetic field to be transmitted at a certain rate of energy which can be calculated with the help of Poynting theorem. The direction of \vec{P} indicates instantaneous power flow at the point. \vec{P} is the instantaneous power density vector associated with the electromagnetic field at a given point. To get a net power flowing out of any surface P is integrated over same closed surface.

As E and H both are vectors, to get power density, we may carry either dot product or cross product. The result of dot product is always a scalar quantity. The result of dot product cannot be performed. But as power flows in a certain direction, it is a vector quantity. To illustrate this, consider that the field is transmitted in the form of electromagnetic waves from an antenna. Both the fields are sinusoidal in nature. The power radiated from antenna has a particular direction. Hence to calculate power density, we must carry out a cross product of E and H . Hence, Power density $P = \bar{E} \times \bar{H}$



POYNTING THEOREM

Statement: It states that the power flowing out of the given volume is equal to the negative rate of decreasing total energy

field (i.e. Electric + Magnetic Energy) within it and minus the ohmic losses or conduction losses in it.

$$\oint_S (\bar{E} \times \bar{H}) \cdot d\vec{s} = - \left[\frac{\partial}{\partial t} \int_V \left(\frac{1}{2} H^2 + \frac{\epsilon}{2} E^2 \right) dV + \int_V (\bar{E} \cdot \bar{J}) dV \right]$$

Proof: The total power is the sum of electric field and magnetic field. This is the power inside.

$$\text{Power Inside} = \text{Electric Field} + \text{Magnetic field}.$$

The power coming out of the surfaces reduces because of ohmic losses inside the surface. This can be mathematically proved as shown below by the Time Varying Maxwell's Equations.

we have $\nabla \times \vec{H} = \vec{J} + \frac{d}{dt}(\vec{D})$, $\nabla \times \vec{E} = -\frac{d}{dt}(\vec{B}) = -\frac{d}{dt}(\mu \vec{H})$

$$\vec{J} = \nabla \times \vec{H} - \frac{d}{dt}(\vec{D})$$

$$= -\mu \cdot \frac{d}{dt} \vec{H}$$

Now, we have, ohmic losses

$$\vec{E} \cdot \vec{J} \Rightarrow \nabla \times \vec{H} = \vec{J} + \frac{d}{dt}(\vec{D})$$

Dot product with \vec{E} on both sides, $\vec{J} = \sigma \vec{E}$

$$\Rightarrow \vec{E} \cdot (\nabla \times \vec{H}) = \vec{E} \cdot \sigma \vec{E} + \vec{E} \cdot \left[\epsilon \cdot \frac{d\vec{E}}{dt} \right]$$

By using vector identity,

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{A} \times \vec{C}) - \vec{C} \cdot (\vec{A} \times \vec{B})$$

$$\vec{H} \cdot (\nabla \times \vec{E}) - \nabla \cdot (\vec{E} \times \vec{H}) = \vec{E} \cdot (\sigma \vec{E}) + \vec{E} \cdot \left[\epsilon \cdot \frac{d\vec{E}}{dt} \right]$$

$$\vec{H} \cdot (\nabla \times \vec{E}) - \nabla \cdot (\vec{E} \times \vec{H}) = \sigma E^2 + \epsilon^2 \cdot \left[\epsilon \frac{d\vec{E}}{dt} \right]$$

we have, $\nabla \times \vec{E} = -\mu \cdot \frac{d}{dt} \vec{H}$ ($\because \nabla \times \vec{E} = -\frac{d}{dt}(\vec{B})$)

$$\vec{H} \cdot [\nabla \times \vec{E}] = \vec{H} \cdot \left[-\mu \cdot \frac{d\vec{H}}{dt} \right] = -\mu \vec{H} \cdot \frac{d\vec{H}}{dt}$$

Now consider term,

$$\frac{d}{dt} (\vec{H} \cdot \vec{H}) = \vec{H} \cdot \frac{d}{dt} \vec{H} + \vec{H} \cdot \frac{d\vec{H}}{dt}$$

$$\frac{d}{dt} H^2 = 2\vec{H} \cdot \frac{d\vec{H}}{dt} \Rightarrow \frac{1}{2} \frac{d}{dt} (H^2) = \vec{H} \cdot \frac{d\vec{H}}{dt}$$

Similarly, we can write,

$$\frac{1}{2} \frac{\partial^2}{\partial t^2} (\bar{E}) = \bar{E} \cdot \frac{\partial \bar{E}}{\partial t}$$

using results.

$$\bar{H} \cdot (\nabla \times \bar{E}) - \nabla \cdot (\bar{E} \times \bar{H}) = \sigma \bar{E} + \bar{E} \cdot \left[\epsilon \cdot \frac{\partial \bar{E}}{\partial t} \right]$$

$$\bar{H} \cdot (\nabla \times \bar{E}) = -\mu \bar{H} \cdot \frac{\partial \bar{H}}{\partial t} \quad (1)$$

$$-\mu \bar{H} \cdot \frac{\partial \bar{H}}{\partial t} - \nabla \cdot (\bar{E} \times \bar{H}) = \sigma \bar{E}^2 + \frac{1}{2} \frac{\partial}{\partial t} (\bar{E}^2) \cdot \frac{1}{2} \epsilon$$

$$-\nabla \cdot (\bar{E} \times \bar{H}) = \sigma \bar{E}^2 + \frac{1}{2} \frac{\partial}{\partial t} [\epsilon \bar{E}^2] + \mu \bar{H} \cdot \frac{\partial \bar{H}}{\partial t}$$

$$-\nabla \cdot (\bar{E} \times \bar{H}) = \sigma \bar{E}^2 + \frac{1}{2} \frac{\partial}{\partial t} [\epsilon \bar{E}^2] + \frac{1}{2} \frac{\partial}{\partial t} [\mu \bar{H}^2]$$

$$-\nabla \cdot (\bar{E} \times \bar{H}) = \sigma \bar{E}^2 + \frac{1}{2} \frac{\partial}{\partial t} [\mu \bar{H}^2 + \epsilon \bar{E}^2]$$

$$P = \bar{E} \times \bar{H}$$

$$-\nabla \cdot P = \sigma \bar{E}^2 + \frac{1}{2} \frac{\partial}{\partial t} [\mu \bar{H}^2 + \epsilon \bar{E}^2]$$

This is Poynting theorem in point form.

If we integrate this power a volume, we get energy distribution as

$$-\int_V \nabla \cdot \bar{P} dV = \int_V \sigma \bar{E} \cdot \frac{\partial \bar{E}}{\partial t} dV + \int_V \frac{1}{2} [\mu \bar{H}^2 + \epsilon \bar{E}^2] dV$$

Now applying theorem in integral form

$$-\int_V \nabla \cdot \bar{P} dV = -\oint_S \bar{P} \cdot ds$$

$$-\oint_S \bar{P} \cdot ds = \int_V \sigma \bar{E}^2 dV + \frac{d}{dt} \int_V \frac{1}{2} [\mu \bar{H}^2 + \epsilon \bar{E}^2] dV$$

$$\oint_S \bar{P} \cdot ds = \oint_S (\bar{E} \times \bar{H}) ds = - \int_V (\epsilon \bar{E}^2) dV + \frac{d}{dt} \int_V \frac{1}{2} [\mu \bar{H}^2 + \epsilon \bar{E}^2] dV$$

Poynting theorem in integral form

The above Equation can also written as

$$\oint_S (\vec{E} \times \vec{H}) ds = -\frac{d}{dt} \left[\int_V \left(\frac{\mu H^2 + \epsilon E^2}{2} \right) dV - \int_V \epsilon E^2 dV \right]$$

$$\oint_S (\vec{E} \times \vec{H}) ds = - \left[+ \frac{d}{dt} \left[\int_V \frac{\mu H^2 + \epsilon E^2}{2} dV + \int_V \epsilon E \cdot \vec{E} dV \right] \right]$$

$$\boxed{\oint_S (\vec{E} \times \vec{H}) ds = - \left[\frac{d}{dt} \int_V \left(\frac{\mu H^2 + \epsilon E^2}{2} \right) dV + \int_V \epsilon E \cdot \vec{E} dV \right]}$$

'-ve' sign indicates power flowing into the volume. Power flowing out of the volume.

$$\oint_S \vec{P}_s ds$$

Applications:-

Used in Antennas