

# CODE:

```
// GAS SENSOR (MQ2)
#define GAS_SENSOR_PIN A0
#define BUZZER_PIN 8
#define GAS_LED_PIN 0
const int GAS_THRESHOLD = 400;

// TEMPERATURE SENSOR (LM35)
#define LM35_PIN A5
#define MOTOR_PIN 5
const int TEMP_THRESHOLD = 38;

// LDR SENSOR
#define LDR_PIN A0
#define LDR_LED_PIN 7

// ULTRASONIC SENSOR
#define TRIG_PIN 12
#define ECHO_PIN 11

void setup() {
    Serial.begin(9600);

    pinMode(BUZZER_PIN, OUTPUT);
    pinMode(GAS_LED_PIN, OUTPUT);
    pinMode(MOTOR_PIN, OUTPUT);
    pinMode(LDR_LED_PIN, OUTPUT);

    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
```

```
}
```

```
void loop() {
    // GAS SENSOR
    int gasValue = analogRead(GAS_SENSOR_PIN);
    Serial.print("Gas Level: ");
    Serial.println(gasValue);
```

```
if (gasValue > GAS_THRESHOLD) {
    Serial.println("⚠️ High Gas Level!");
    digitalWrite(GAS_LED_PIN, HIGH);
    digitalWrite(BUZZER_PIN, HIGH);
    delay(2000);
    digitalWrite(BUZZER_PIN, LOW);
} else {
    digitalWrite(GAS_LED_PIN, LOW);
    digitalWrite(BUZZER_PIN, LOW);
}
```

```
// TEMPERATURE SENSOR
int tempValue = analogRead(LM35_PIN);
float temperature = (tempValue * 5.0 * 100.0) / 1024.0;
```

```
Serial.print("Temperature: ");
Serial.print(temperature);
Serial.println("°C");
```

```
if (temperature > TEMP_THRESHOLD) {
    Serial.println("🔥 High Temp! Fan ON");
    analogWrite(MOTOR_PIN, 255);
} else {
```

```
Serial.println(" ✅ Normal Temp. Fan OFF");
analogWrite(MOTOR_PIN, 0);
}
```

```
// LDR SENSOR
int lightValue = analogRead(LDR_PIN);
Serial.print("Light Intensity: ");
Serial.println(lightValue);
```

```
if (lightValue < 150) {
    Serial.println(" 🌙 Dark - LED ON");
    digitalWrite(LDR_LED_PIN, HIGH);
} else {
    Serial.println("☀️ Bright - LED OFF");
    digitalWrite(LDR_LED_PIN, LOW);
}
```

```
// ULTRASONIC SENSOR
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
```

```
long duration = pulseIn(ECHO_PIN, HIGH);
float distance = (duration * 0.0343) / 2;
```

```
Serial.print("Distance: ");
Serial.print(distance);
Serial.println(" cm");
```

```
// ♦ Increased delay (5 seconds)
delay(5000);
}
```