

CODE:

```
// GAS SENSOR (MQ2)

#define GAS_SENSOR_PIN A0

#define BUZZER_PIN 8

#define GAS_LED_PIN 0

const int GAS_THRESHOLD = 400;

// TEMPERATURE SENSOR (LM35)

#define LM35_PIN A5

#define MOTOR_PIN 5

const int TEMP_THRESHOLD = 38;


// LDR SENSOR

#define LDR_PIN A0

#define LDR_LED_PIN 7


// ULTRASONIC SENSOR

#define TRIG_PIN 12

#define ECHO_PIN 11


void setup() {

    Serial.begin(9600);


    pinMode(BUZZER_PIN, OUTPUT);

    pinMode(GAS_LED_PIN, OUTPUT);

    pinMode(MOTOR_PIN, OUTPUT);

    pinMode(LDR_LED_PIN, OUTPUT);


    pinMode(TRIG_PIN, OUTPUT);

    pinMode(ECHO_PIN, INPUT);
```

```
}
```

```
void loop() {
```

```
  // GAS SENSOR
```

```
  int gasValue = analogRead(GAS_SENSOR_PIN);
```

```
  Serial.print("Gas Level: ");
```

```
  Serial.println(gasValue);
```

```
  if (gasValue > GAS_THRESHOLD) {
```

```
    Serial.println(" 🚒 High Gas Level!");
```

```
    digitalWrite(GAS_LED_PIN, HIGH);
```

```
    digitalWrite(BUZZER_PIN, HIGH);
```

```
    delay(2000);
```

```
    digitalWrite(BUZZER_PIN, LOW);
```

```
  } else {
```

```
    digitalWrite(GAS_LED_PIN, LOW);
```

```
    digitalWrite(BUZZER_PIN, LOW);
```

```
  }
```

```
  // TEMPERATURE SENSOR
```

```
  int tempValue = analogRead(LM35_PIN);
```

```
  float temperature = (tempValue * 5.0 * 100.0) / 1024.0;
```

```
  Serial.print("Temperature: ");
```

```
  Serial.print(temperature);
```

```
  Serial.println("°C");
```

```
  if (temperature > TEMP_THRESHOLD) {
```

```
    Serial.println(" 🔥 High Temp! Fan ON");
```

```
    analogWrite(MOTOR_PIN, 255);
```

```
  } else {
```

```
Serial.println("✅ Normal Temp. Fan OFF");  
analogWrite(MOTOR_PIN, 0);  
}
```

```
// LDR SENSOR
```

```
int lightValue = analogRead(LDR_PIN);  
Serial.print("Light Intensity: ");  
Serial.println(lightValue);
```

```
if (lightValue < 150) {  
    Serial.println("🌑 Dark - LED ON");  
    digitalWrite(LDR_LED_PIN, HIGH);  
} else {  
    Serial.println("🌞 Bright - LED OFF");  
    digitalWrite(LDR_LED_PIN, LOW);  
}
```

```
// ULTRASONIC SENSOR
```

```
digitalWrite(TRIG_PIN, LOW);  
delayMicroseconds(2);  
digitalWrite(TRIG_PIN, HIGH);  
delayMicroseconds(10);  
digitalWrite(TRIG_PIN, LOW);
```

```
long duration = pulseIn(ECHO_PIN, HIGH);  
float distance = (duration * 0.0343) / 2;
```

```
Serial.print("Distance: ");  
Serial.print(distance);  
Serial.println(" cm");
```

```
// ♦ Increased delay (5 seconds)  
delay(5000);  
}
```