Support Vector Machines



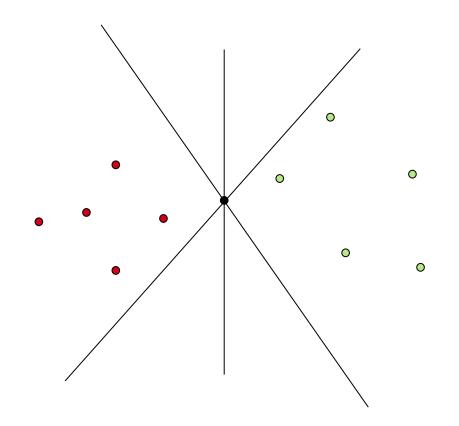


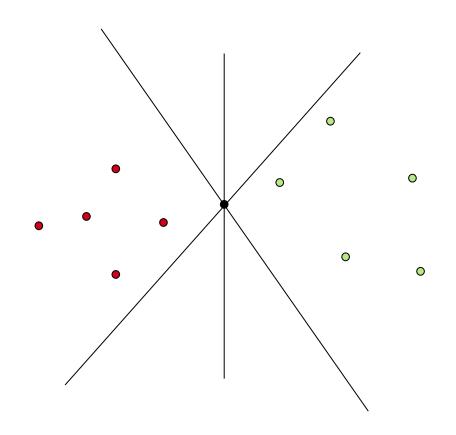
Agenda

- Hard-margin SVM
 - theory (brief)
 - implementation
- Soft-margin SVM
 - theory (brief)
 - implementation
- Closing remarks

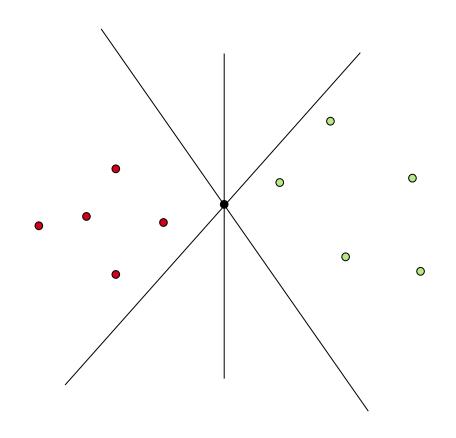
https://tiny.cc/mlt_workshop

- Colabs_Slides_Day_3
 - SVM.ipynb
 - Make a copy
- Code along

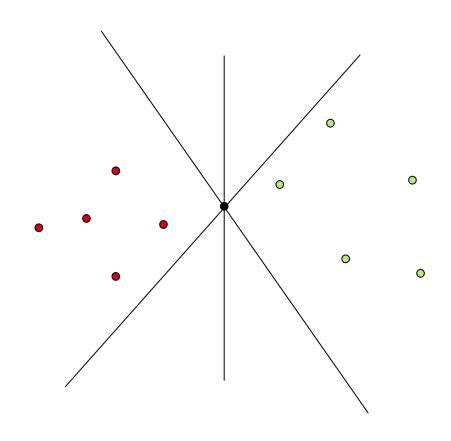




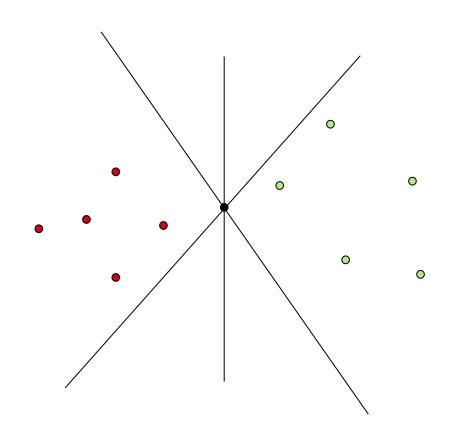
For linearly separable data with γ margin: (1) Infinite number of valid linear classifiers.



- (1) Infinite number of valid linear classifiers.
- (2) Perceptron returns a valid linear classifier.

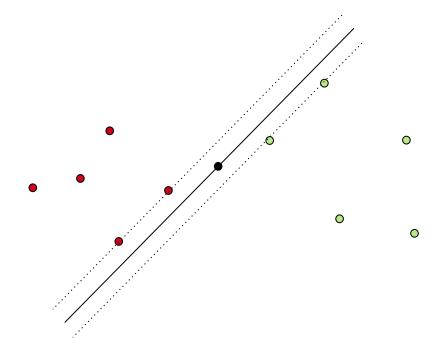


- (1) Infinite number of valid linear classifiers.
- (2) Perceptron returns a valid linear classifier.
- (3) Is it the "best"?

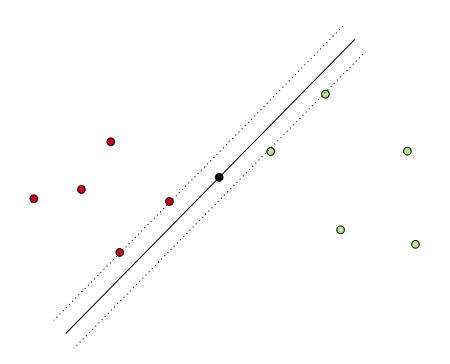


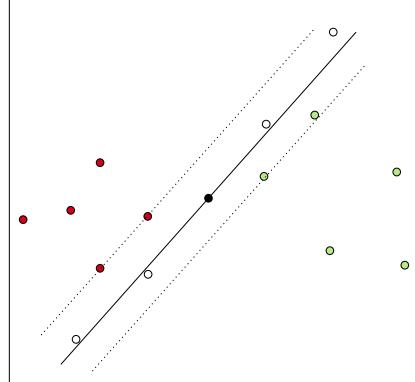
- (1) Infinite number of valid linear classifiers.
- (2) Perceptron returns a valid linear classifier.
- (3) Is it the "best"?
- (4) What is a good notion of "best"?

Margin



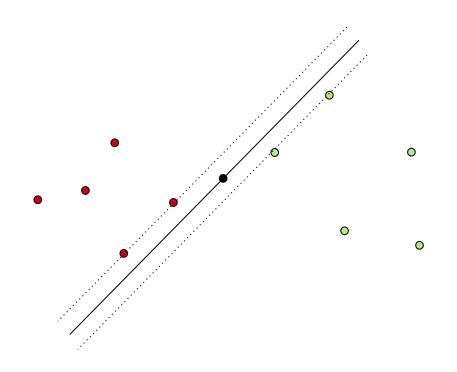
Margin

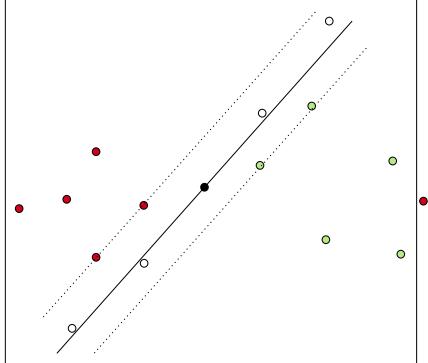




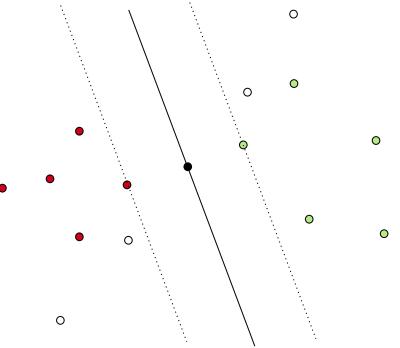
Small margin Doesn't generalize well

Margin

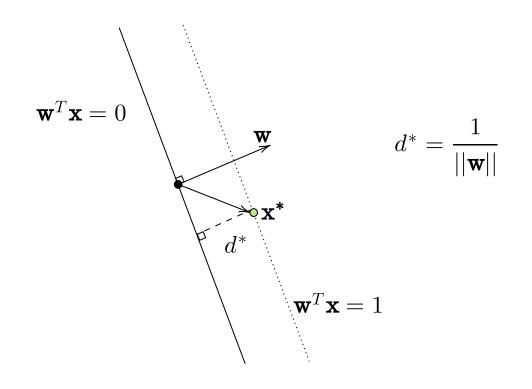


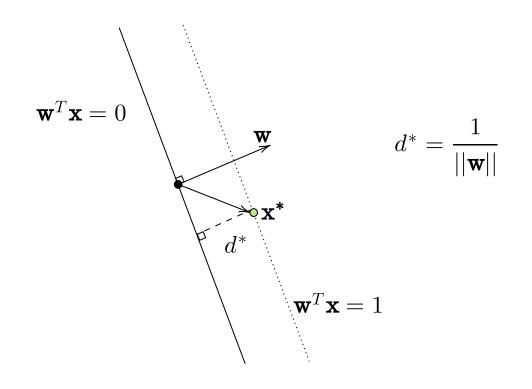






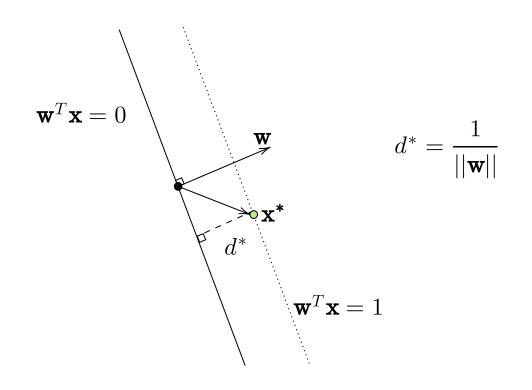
Large margin Better generalization



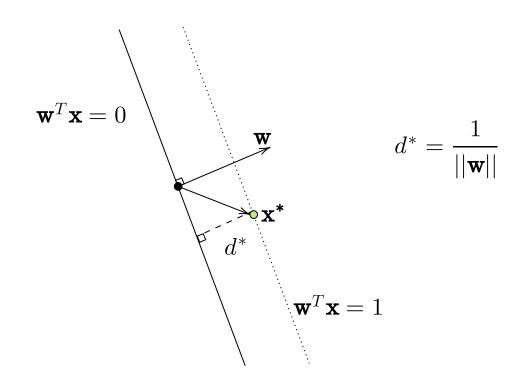


For any linear classifier represented by \mathbf{w} :

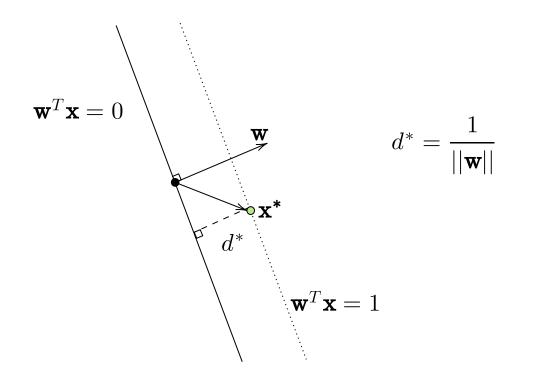
(1) Find the point closest to it \rightarrow x^*



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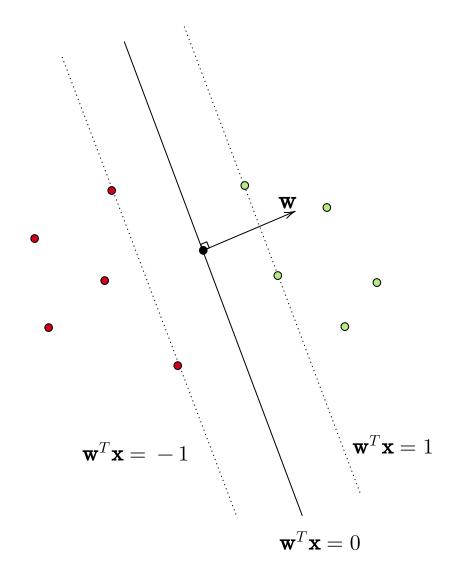


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- (3) Distance of \mathbf{x}^* from the line is $\frac{1}{||\mathbf{w}||}$



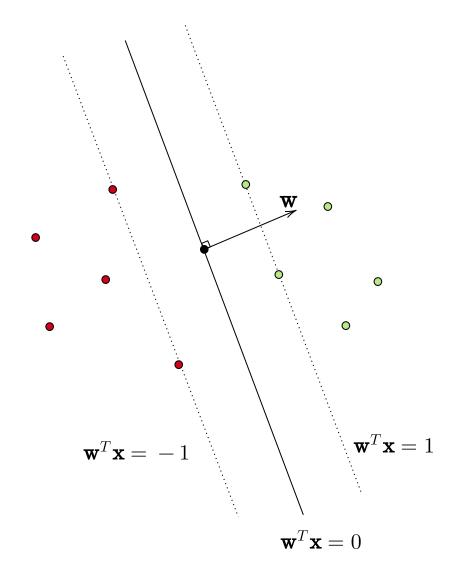
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- (4) This is the (geometric) margin for this linear classifier.

Beyond the "margin"



$$(\mathbf{w}^T \mathbf{x}_i) y_i \ge 1, \quad 1 \le i \le n$$

Max-Margin Classifier

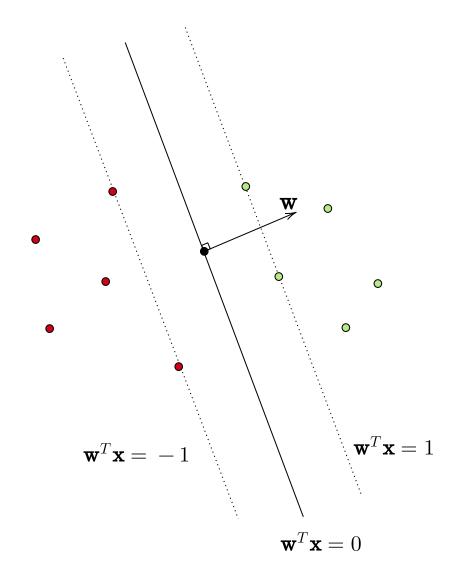


$$\max_{\mathbf{w}} \frac{1}{||\mathbf{w}||}$$

sub. to

$$(\mathbf{w}^T \mathbf{x}_i) y_i \ge 1, \quad 1 \le i \le n$$

Max-Margin Classifier



$$\min_{\mathbf{w}} \quad \frac{||\mathbf{w}||^2}{2}$$

sub. to

$$(\mathbf{w}^T \mathbf{x}_i) y_i \ge 1, \quad 1 \le i \le n$$

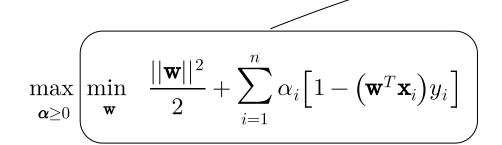
Primal and Dual

$$\min_{\mathbf{w}} \ \frac{||\mathbf{w}||^2}{2}$$

$$\equiv \min_{\mathbf{w}} \max_{\boldsymbol{\alpha} \geq 0} \ \frac{||\mathbf{w}||^2}{2} + \sum_{i=1}^n \alpha_i \Big[1 - \left(\mathbf{w}^T \mathbf{x}_i\right) y_i\Big] \ \equiv \max_{\boldsymbol{\alpha} \geq 0} \min_{\mathbf{w}} \ \frac{||\mathbf{w}||^2}{2} + \sum_{i=1}^n \alpha_i \Big[1 - \left(\mathbf{w}^T \mathbf{x}_i\right) y_i\Big]$$
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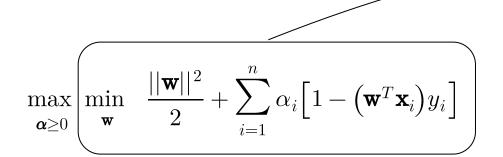
$$\left(\mathbf{w}^{T}\mathbf{x}_{i}\right)y_{i}\geq1,\quad1\leq i\leq n$$
 $\boldsymbol{lpha}=\begin{bmatrix}lpha_{1}\ dots\\lpha_{n}\end{bmatrix}$

Formulating the Dual



$$\mathbf{w} = \sum_{i=1}^{n} \alpha_i \mathbf{x}_i y_i$$

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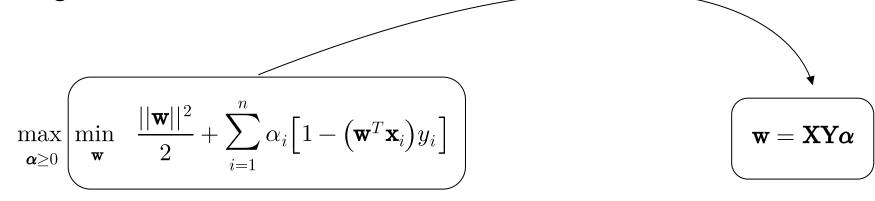
$$d \times n$$

$$n \times n$$

$$\mathbf{Y} = \left[egin{array}{ccc} y_1 & & 0 \ & \ddots & \ 0 & & y_n \end{array}
ight]$$

$$\mathbf{XY}\boldsymbol{\alpha} = \begin{bmatrix} & & & | \\ y_1\mathbf{x}_1 & \cdots & y_n\mathbf{x}_n \\ | & & | \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} = \sum_{i=1}^n \alpha_i(y_i\mathbf{x}_i) = \mathbf{w}$$

Formulating the Dual



$$d \times n$$

$$\mathbf{X} = egin{bmatrix} | & & & | & & | & & & | & & & | & & & | & & & | & & & | & & | & & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & & | & & & | & & | & & & | & & & | & & & | & & & | & & | & & & | & & | & & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & & | & | & & | & & | & & | & & | & & | & & | & & | & | & & | & & | & & | & & | & & | & & | & | & & | & & | & & | & | & | & | & & | & | & | & | & | & & | & | & | & & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | & | &$$

$$n \times n$$

$$\mathbf{Y} = \begin{bmatrix} y_1 & & 0 \\ & \ddots & \\ 0 & & y_n \end{bmatrix}$$

$$\left(\frac{\boldsymbol{\alpha}^T (\mathbf{Y}^T \mathbf{X}^T \mathbf{X} \mathbf{Y}) \boldsymbol{\alpha}}{2} \right)$$

$$oldsymbol{lpha}^* = egin{bmatrix} lpha_1^* \ dots \ lpha_n^* \end{bmatrix} \qquad \qquad oldsymbol{w}^* = \sum_{i=1}^n lpha_i^* oldsymbol{x}_i y_i$$

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Complementary Slackness

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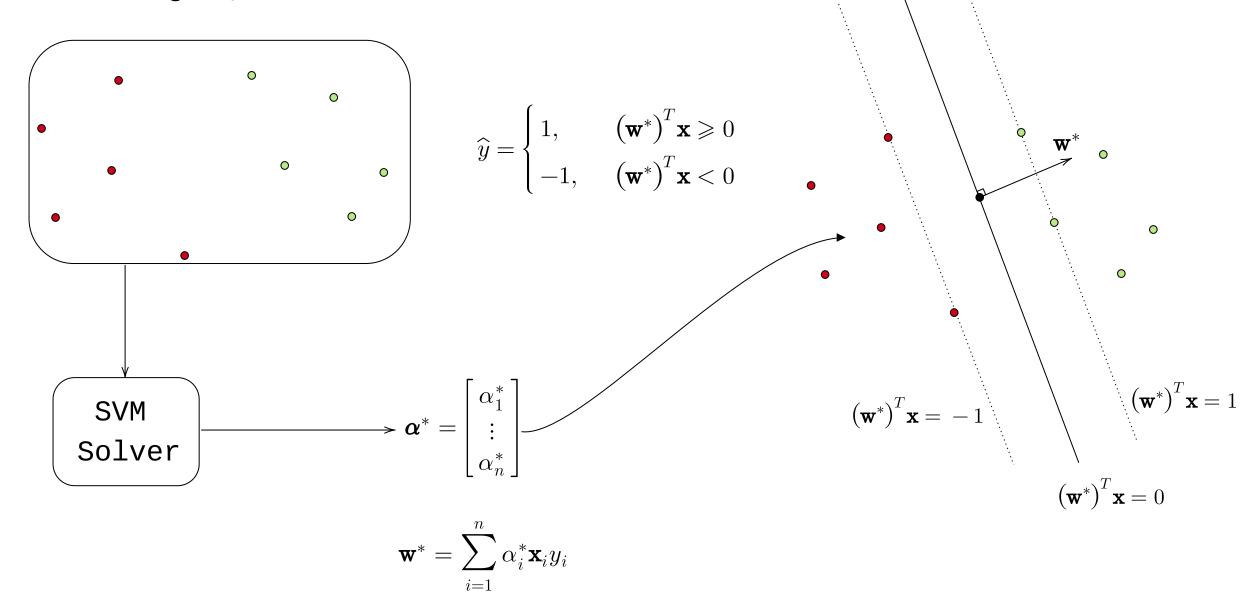
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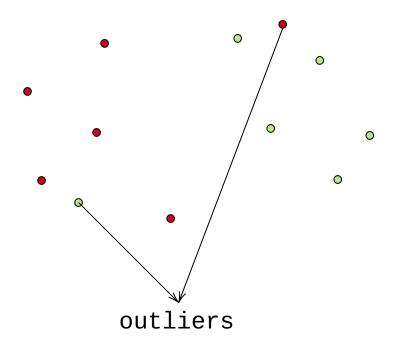
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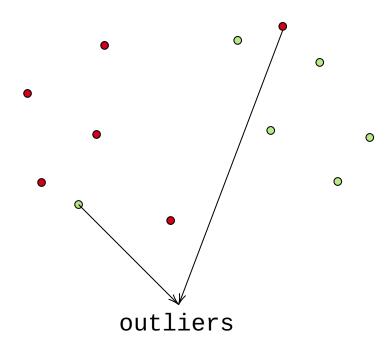
Every point that is **not** on one of the two supporting hyperplanes has $\alpha_i^* = 0$.

Hard-Margin, Linear-SVM



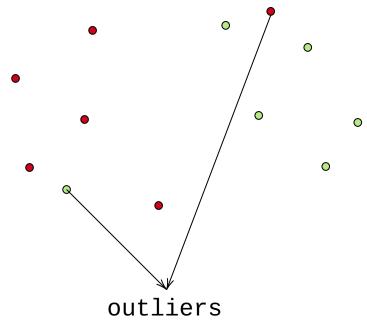


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- (2) Statistical (outliers)



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- Ideally, we want $(\mathbf{w}^T\mathbf{x}_i)y_i\geqslant 1$.
- Not true for outliers.
- Use a non-negative bribe to push them

$$(\mathbf{w}^T \mathbf{x}_i) y_i + \xi_i \geqslant 1$$



$$\min_{\mathbf{w}} \quad \frac{||\mathbf{w}||^2}{2} + C \cdot \sum_{i=1}^{n} \xi_i$$

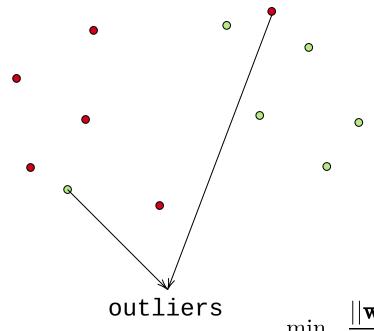
sub. to

$$(\mathbf{w}^T \mathbf{x}_i) y_i + \xi_i \ge 1, \quad 1 \le i \le n$$

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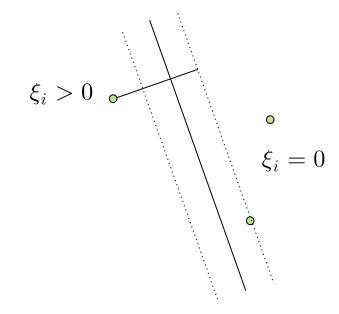
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Dual for Soft-SVM

$$\max_{0 \leqslant \boldsymbol{\alpha} \leqslant C} \boldsymbol{\alpha}^T \mathbf{1} - \frac{\boldsymbol{\alpha}^T (\mathbf{Y}^T \mathbf{X}^T \mathbf{X} \mathbf{Y}) \boldsymbol{\alpha}}{2}$$

- Only change is the constraints
- Earlier there was only a lower-bound
- Now, we have an upper-bound
- These are called box-constraints

Soft-Margin, SVM: Hinge-loss formulation

 \equiv

$$\min_{\mathbf{w}} \quad \frac{||\mathbf{w}||^2}{2} + C \cdot \sum_{i=1}^n \xi_i$$

sub. to

$$(\mathbf{w}^T \mathbf{x}_i) y_i + \xi_i \ge 1, \quad 1 \le i \le n$$

 $\xi_i \ge 0, \quad 1 \le i \le n$

$$\min_{\mathbf{w}} \ \frac{||\mathbf{w}||^2}{2} + C \cdot \sum_{i=1}^n \max \Big(0, \ 1 - \Big(\mathbf{w}^T \mathbf{x}_i\Big) y_i \Big)$$

Regularization

Hinge Loss

Soft-Margin, SVM: Hinge-loss formulation

$$\min_{\mathbf{w}} \frac{||\mathbf{w}||^2}{2} + C \cdot \sum_{i=1}^n \max(0, 1 - (\mathbf{w}^T \mathbf{x}_i) y_i)$$
(1)
$$\sum_{i=1}^n \max(0, 1 - (\mathbf{w}^T \mathbf{x}_i) y_i)$$
(2)
$$\sum_{i=1}^n \max(0, 1 - (\mathbf{w}^T \mathbf{x}_i) y_i)$$
 is the hinge-loss. Wider the margin larger the loss

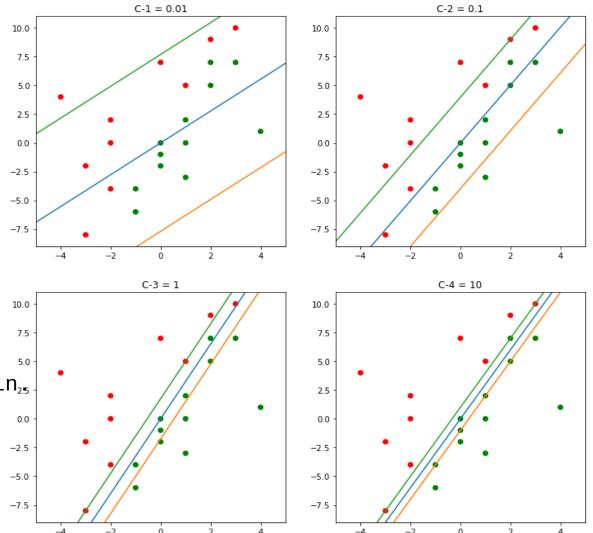
Terms in the objective:

- the margin, larger the loss.

Soft-Margin, SVM: Hinge-loss formulation

$$\min_{\mathbf{w}} \frac{||\mathbf{w}||^2}{2} + C \cdot \sum_{i=1}^n \max(0, 1 - (\mathbf{w}^T \mathbf{x}_i) y_i)$$
(1) (2)

- (1) and (2) work in opposite directions
- If $||\mathbf{w}||$ decreases, the margin becomes wider, which increases the hinge-loss.
- C controls the tradeoff between (1) and (2):
 - If C is small, we are fine with a wide margin $_{\scriptscriptstyle 25}$
 - If ${\it C}$ is large, we prefer a narrow margin.
 - If $C \! \to \! \infty$, we do not tolerate bribery at all. -2.5



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 - Native Python over NumPy
 - C over Python
 - Assembly language over C
 - Build a computer

- ...