

# DESIGN AND REALIZATION OF VORTEX-INDUCED VIBRATION CONVERTER

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**ME420- Mechanical Engineering Individual Research Project**

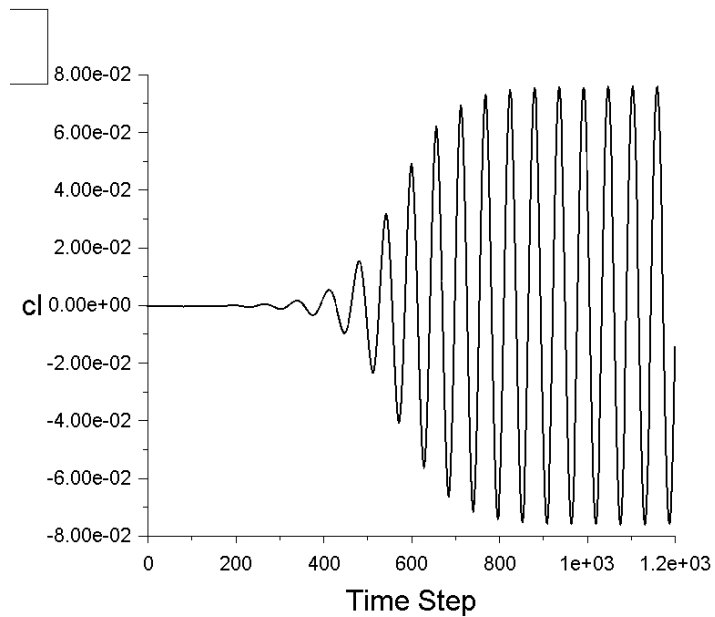
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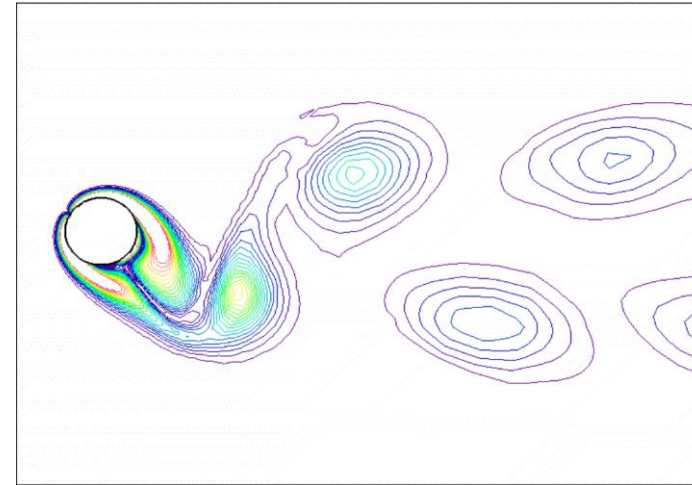


# INTRODUCTION

- When a fluid flows past a bluff body, such as a cylinder vortex shedding occurs and it generate oscillating transverse force component on the cylinder.
- If the cylinder is free to oscillate/vibrate, vortex induced vibrations occurs.

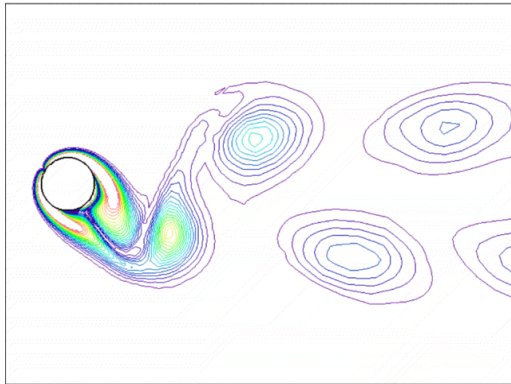


Variation of the lift coefficient on the cylinder with time



# INTRODUCTION

What is vortex induced vibration converter?



Power take-off  
system

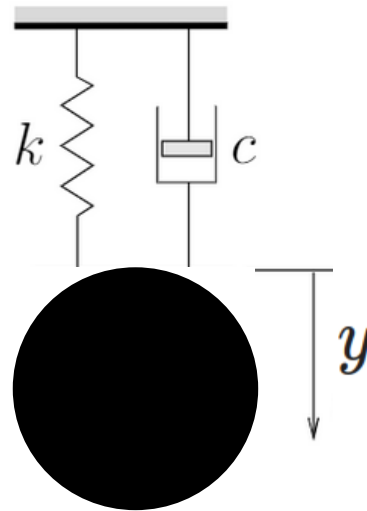
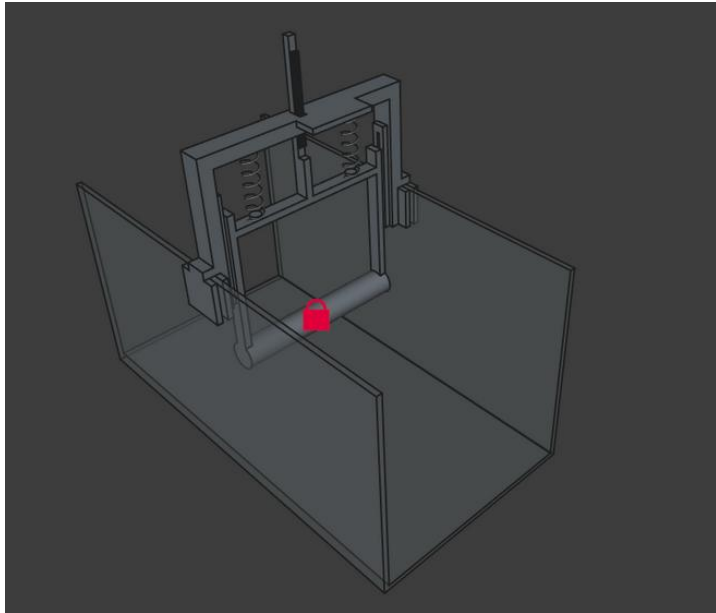


# OBJECTIVES

- Obtain a conceptual understanding of the phenomenon and review existing models.
- Design a mathematical model to analyze the performance of a vortex-induced vibration converter.
- Design a lab-scale prototype.
- Fabricate the prototype
- Validate the prototype.
- Calculate design specifications for different application scales.

# UPTO PREVIOUS EVALUATION

- Literature survey about the existing models.
- Mathematical model was developed to simulate the amplitude response of the device.
- Basic 3D model was developed.



$$(m + m')\ddot{y} + c_1\dot{y} + c_2|\dot{y}|\dot{y} + ky = F_L$$

$$c_2 = \frac{1}{2}\rho C_D D |\dot{y}|$$

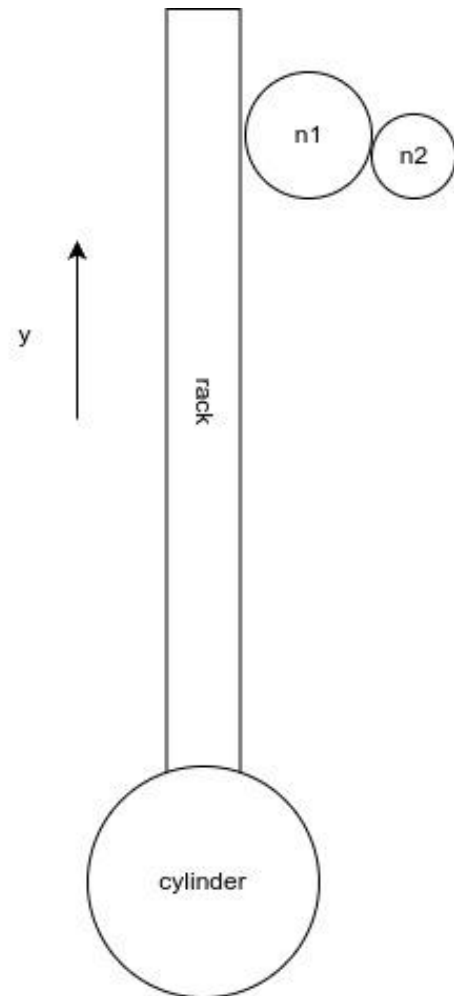
$$F_L = \frac{1}{2}\rho C'_F D U_{stream}^2$$

$$C'_L = \sqrt{2}C_{L,rms} \sin(\omega_v t)$$

Variation of the lift coefficient on the cylinder with time

# UPTO PREVIOUS EVALUATION

Basic PTO design with rack and pinion mechanism



if the motor is mounted to the n2 gear shaft, angular velocity of n2 shaft,

$$\omega_2 = -\frac{y_m}{r_2} \omega_{cyl} \cos(\omega_{cyl} t + \phi)$$

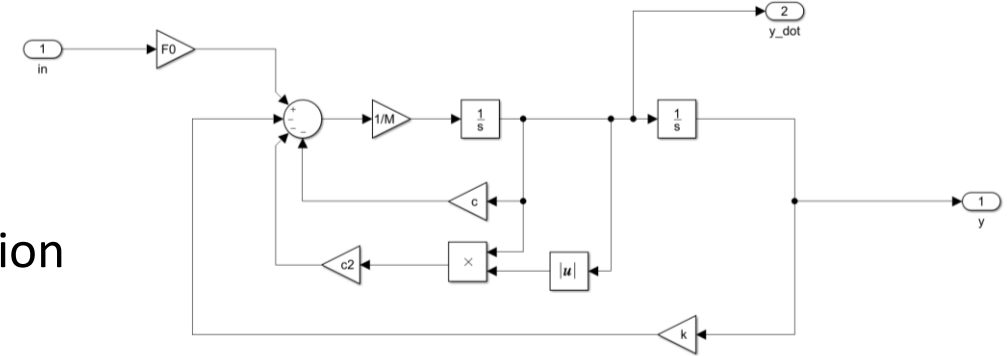
If separately excited DC generator is used, generated terminal voltage,

$$E_a = -\frac{K\phi y_m}{r_2} \omega_{cyl} \cos(\omega_{cyl} t + \phi)$$

**PROGRESS**

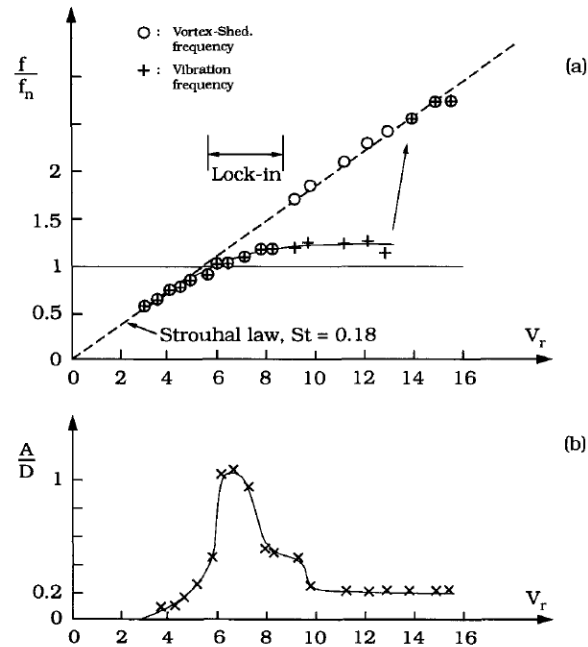
# Mathematical model limitations

- Inability to simulate the synchronization region.
- Cannot simulate lift force magnification with cylinder motion

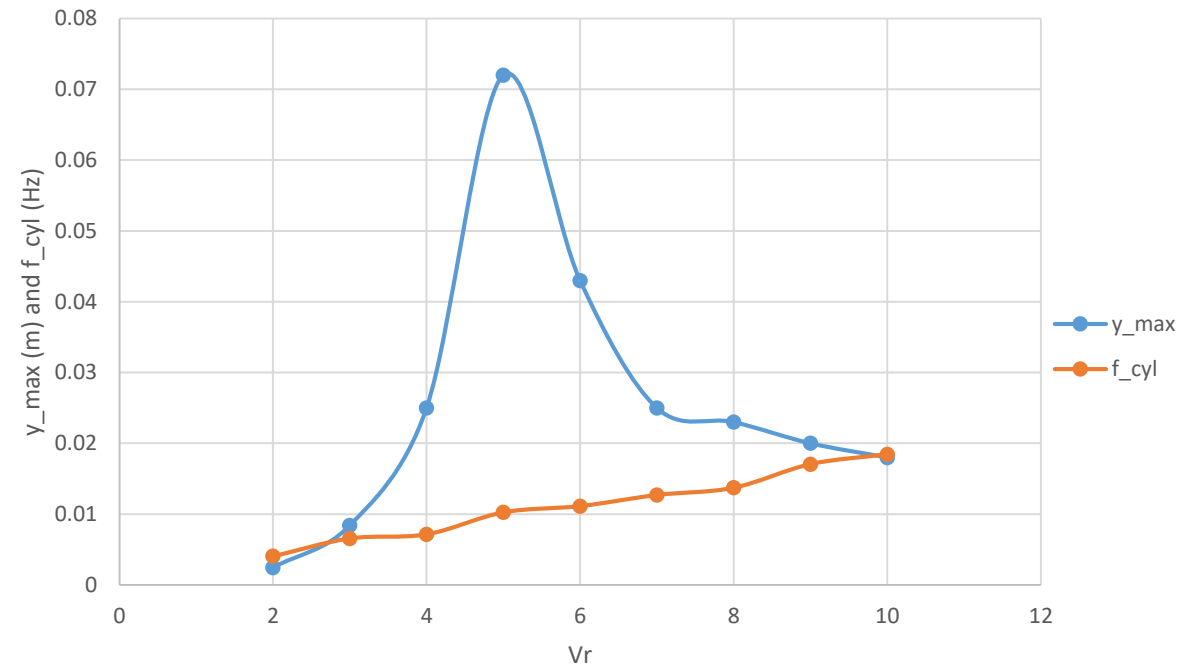


$$\text{reduced velocity}(V_r) = \frac{U}{fD}$$

Simulink implementation



Response of cylinder in a steady fluid flow  
(Anand 1985 - from Sumer & Fredsoe)



Variation of the lift coefficient on the cylinder with time



# Wake-Oscillator model

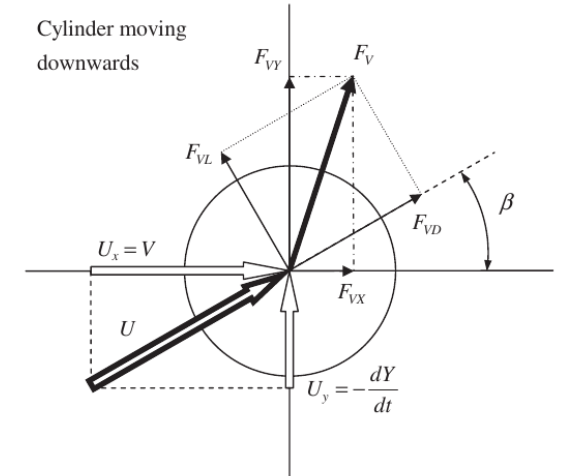
- Initially introduced 1953 introduced by Garrett Brikoff. Many developments have made throughout the years.
- Wake's behavior and cylinder's behavior is modeled using 2 coupled differential equations.
- In most cases Wake is modeled as Van Der Pole oscillator.
- Facchinetti (2004) model

$$\frac{d^2y}{dt^2} + 2\zeta\omega_n \left(\frac{dy}{dt}\right) + \omega_n^2 y = \frac{\frac{1}{2}\rho D L V^2 C_{VY}}{(m+m_a)}$$

where,

$$C_{VY} = \left[ \frac{q}{2} C_{LO} - \frac{\frac{dy}{dt} C_{DO}}{V} \right] \sqrt{1 + \left( \frac{dy}{dx} \times \frac{1}{V} \right)^2}$$

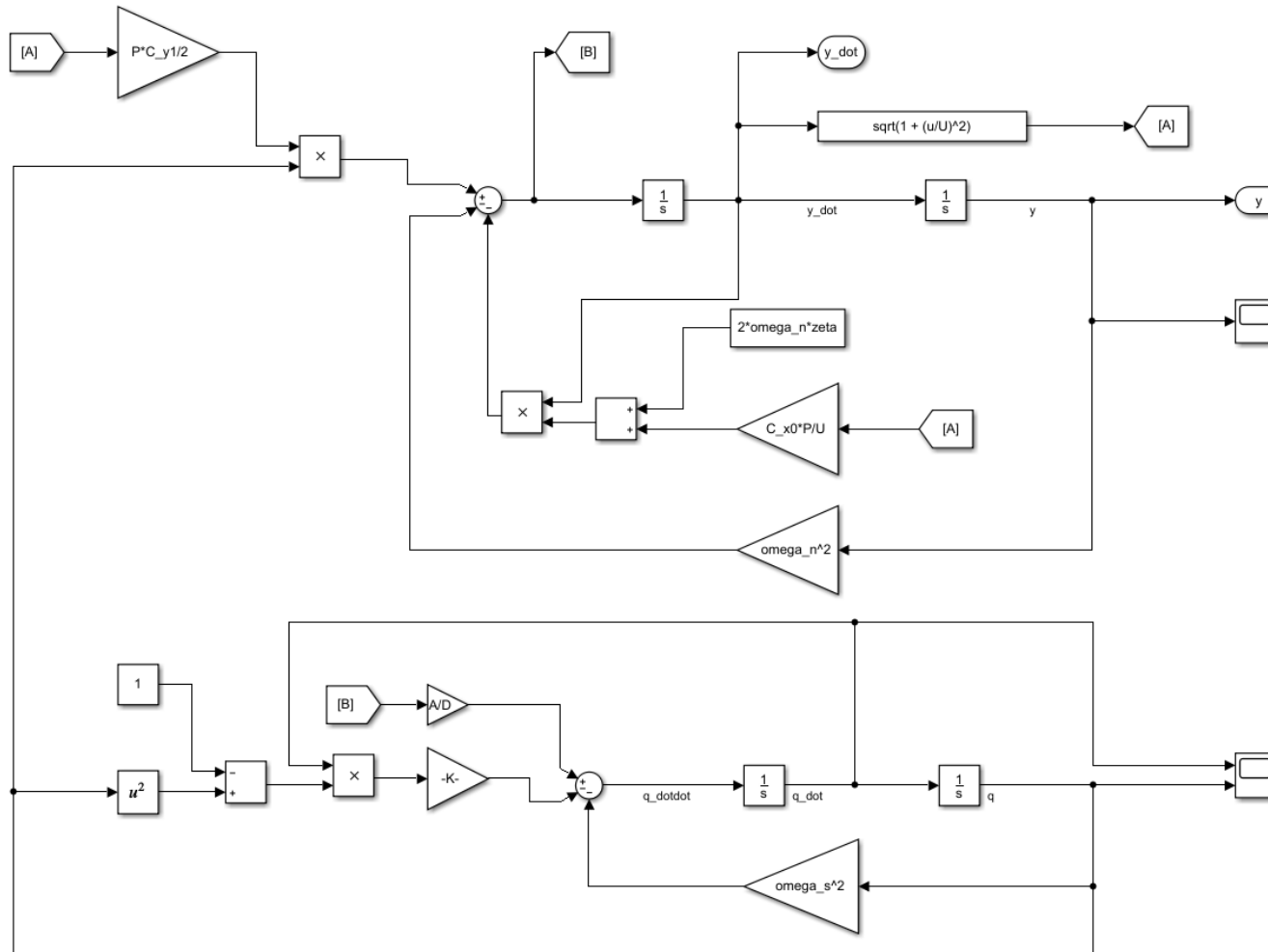
$$\frac{d^2q}{dt^2} + \epsilon\omega_v(q^2 - 1) \cdot \frac{dq}{dt} + \omega_v^2 q = \frac{A}{D} \ddot{y}$$



From Ogink and Metrikine (2010)

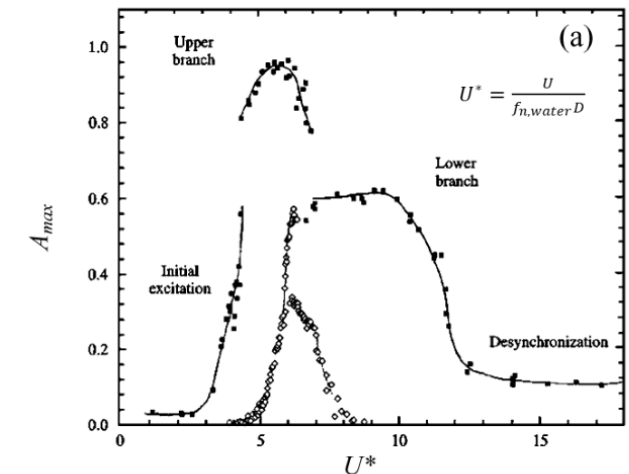
# Wake-Oscillator model Implementation

Model parameters ( $\epsilon$  and  $A$ ), values proposed by Ogink and Metrikine (2010) were used



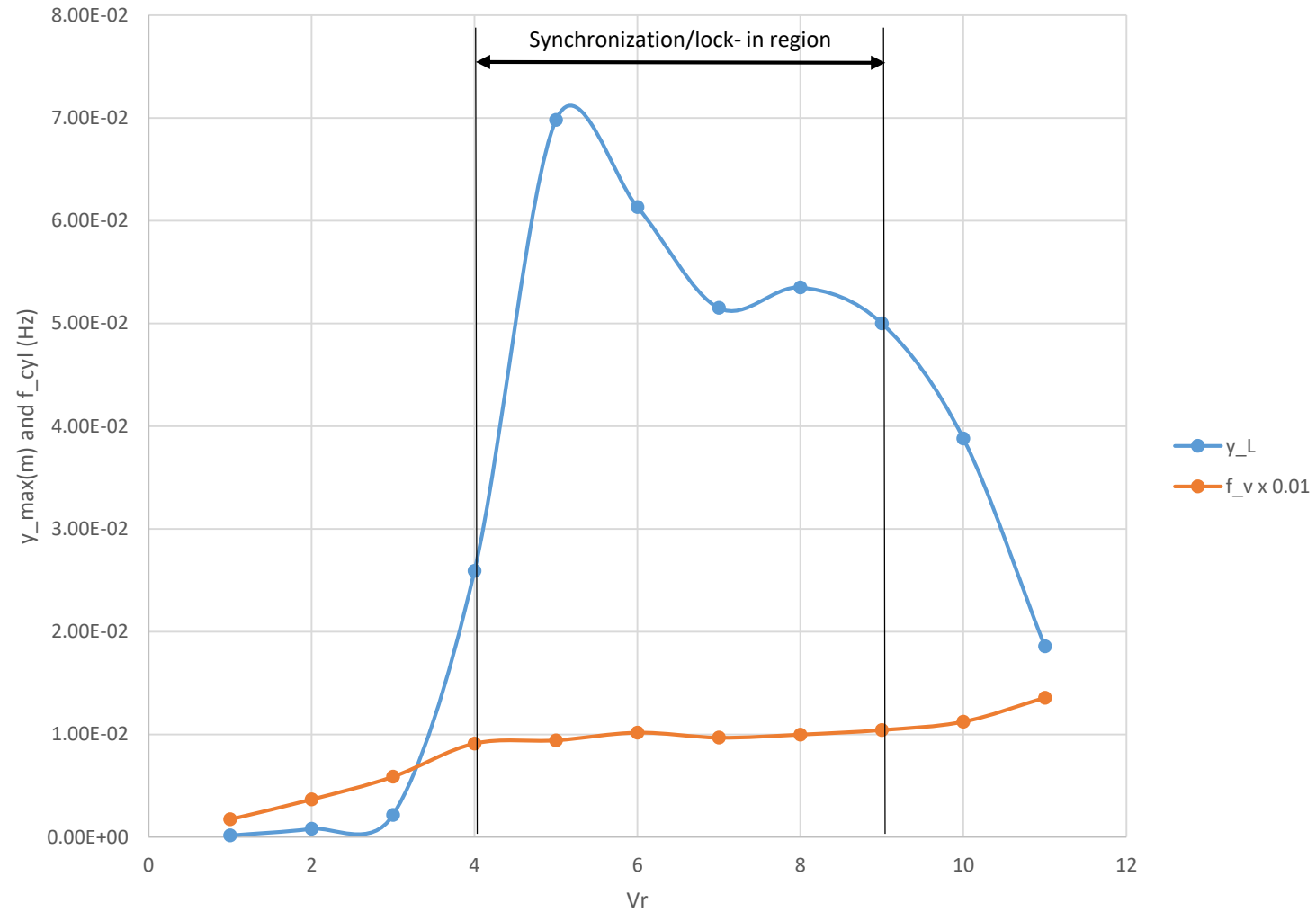
## Upper branch Lower branch

$\hat{C}_{x0}^0 = 1.1856,$	$\hat{C}_{x0}^0 = 1.1856,$
$\hat{C}_{y1}^0 = 0.3842,$	$\hat{C}_{y1}^0 = 0.3842,$
$St = 0.1932,$	$St = 0.1932,$
$A = 4.0,$	$A = 12.0,$
$\epsilon = 0.05,$	$\epsilon = 0.7.$



Amplitude vs Reduced velocity plotted for a smooth cylinder in water (black dots) - (Williamson & Roshko 1988)

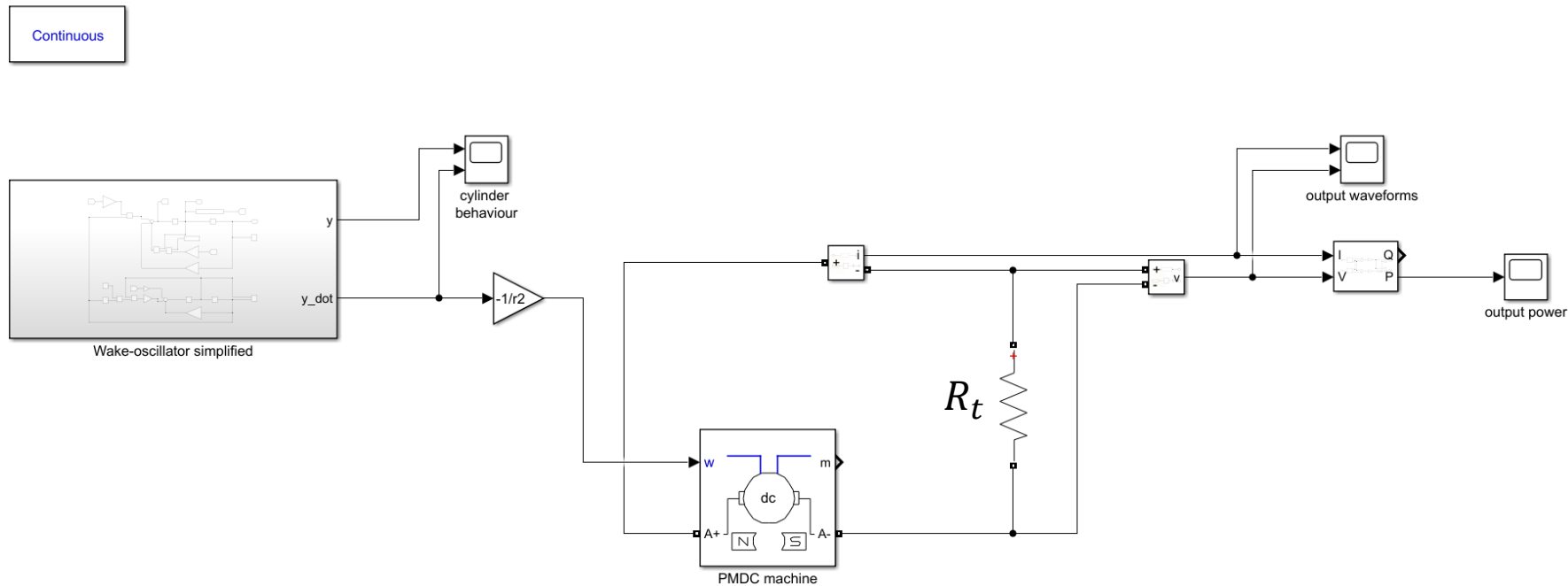
# Wake-Oscillator model response



Maximum amplitude and frequency variation with reduced velocity

# PTO System Implementation

## Implementation in MATLAB



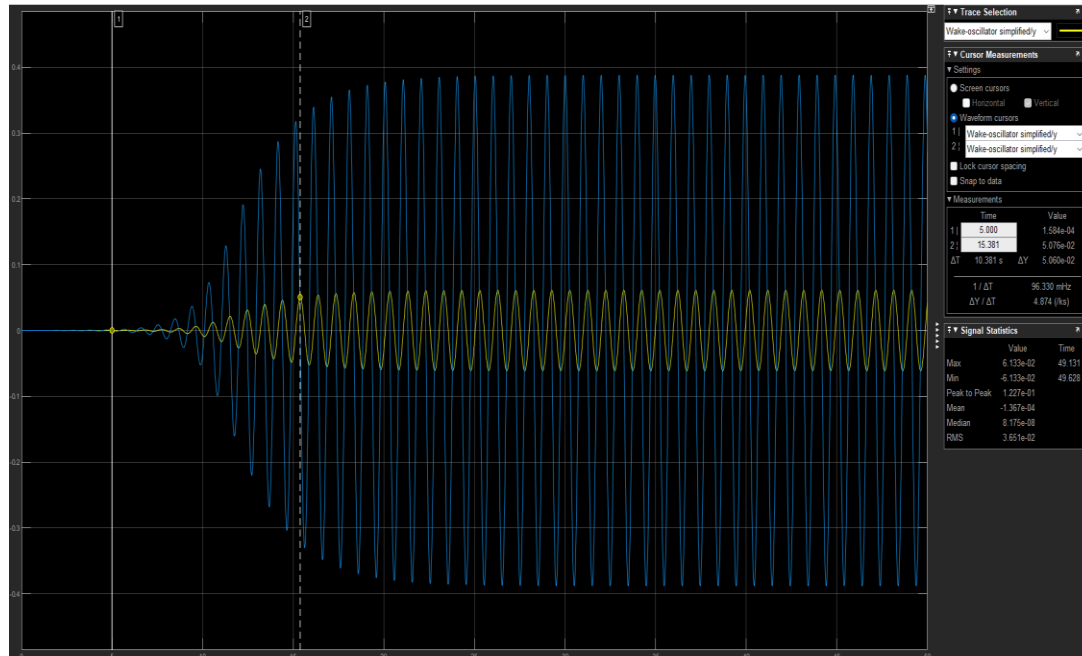
Damping induced by the DC generator on the oscillator,

$$c_{gen} = \frac{k^2}{r^2 R_T}$$

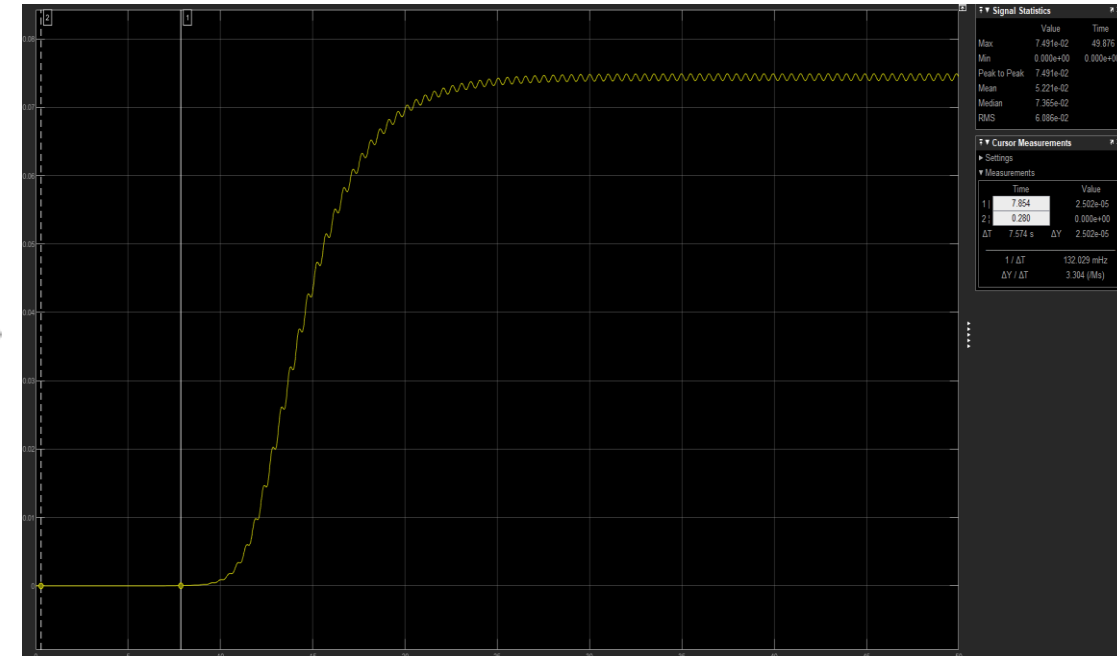
RS755 12V DC motor has  $k=0.1$ ,  
 $R_t = 100$  and  $r = 0.01$  then,

$$c_{gen} = 0.1$$

# Power output



Cylinder motion



Power generation

According to the simulation with the RS775 motor 75 mW power can be generated at the resonance frequency.

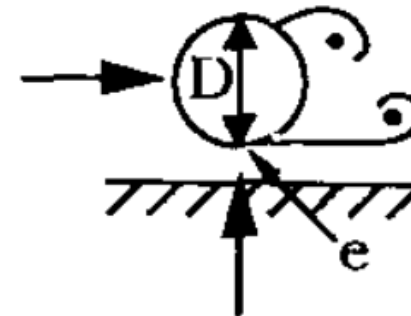
# Prototype Development

# Constraints

- According to the requirements and availability device can be tested in towing tank or in a Flume.
- To observe vortex shedding  $Re \in (300, 3 \times 10^5)$ .
- Amplitude of the oscillation depends on the cylinder diameter. ( high D => high amplitudes).
- Span-wise length of the cylinder should be according to the table below.
- VIV amplitude get significantly effected if bottom gap ratio,  $\frac{e}{D} < 0.7$ .

Reynolds number	Correlation length	Source
$40 < Re < 150$	$(15-20)D$	Gerlach and Dodge (1970)
$150 < Re < 10^5$	$(2-3)D$	Gerlach and Dodge (1970)
$1.1 \times 10^4 < Re < 4.5 \times 10^4$	$(3-6)D$	El-Baroudi (1960)
$\geq 10^5$	$0.5D$	Gerlach and Dodge (1970)
$2 \times 10^5$	$1.56D$	Humphreys (1960)

from Sumer and Fredsoe (2006)



# 20m Flume check

- Dimensions
  - Width = 400mm
  - Maximum water level = 380mm
- Flume Velocity profile was tested using current meter. Maximum possible velocity (stable) is 0.47 m/s



Distance from the bottom (cm)	Velocity (m/s)
3	0.457
6	0.468
16	0.451
27	0.446
34	0.426
37	0.446





# Prototype Scaling

- Cylinder diameter = 80mm
- Maximum obtainable Reynold's number,

$$Re_{max} = 0.45 \times \frac{0.08}{10^{-6}} = 3.6 \times 10^4$$

- Cylinder length = 330 mm (table #)
- Vortex shedding frequency,

$$f_{v,max} = St \times \frac{U}{D} = 1.125 H_z$$

- $f_n < f_{n,max}$  to observe synchronization.

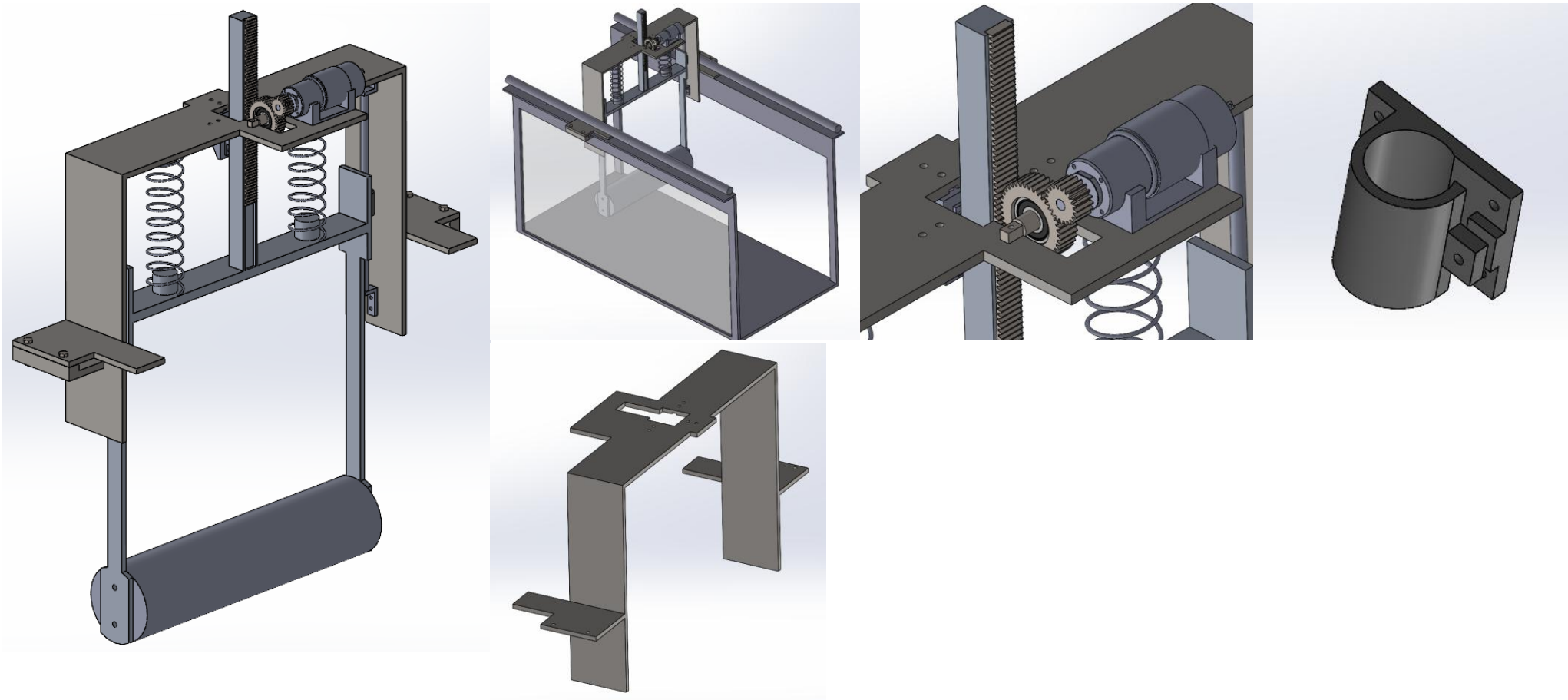
$$1.125 > \frac{1}{2\pi} \sqrt{\frac{k}{m + m_a}}$$
$$k < (1.125 \times 2\pi)^2 (m + m_a)$$

- Hence for stiffness of single spring,

$$k_s = \frac{k}{2}$$

# Prototype design

- Prototype was developed in SolidWorks



# Ongoing Fabrication

- Materials have selected and purchased.

Item	size/quantity	Total price (Rs)
Steel strips	5' x 3" x 1/4"	1580
Al tube	D = 80mm L = 450 mm	980
Steel (other)	3.5 kg	900
Linear bearings	2	600
6000RS bearing	1	850
3D printing		1400
<b>Total price</b>		<b>6310</b>



# References

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4. Bernitsas, M.M., Raghavan, K., Ben-Simon, Y. and Garcia, E.M.H. (2008). VIVACE (Vortex Induced Vibration Aquatic Clean Energy): A New Concept in Generation of Clean and Renewable Energy From Fluid Flow. *Journal of Offshore Mechanics and Arctic Engineering*, 130(4). doi: <https://doi.org/10.1115/1.2957913>.

Thank you !