Step 1:
Total Rescued People: 0/3
Number of vertices: 4
Objects in Vertices:
[['K', 'Agent1'], [], [], ['P3']]
Weights:
-1   2   -1   2
2   -1   2   -1
-1   2   -1   2
2   -1   2   -1
Agent States:
A*-RealTime-Search Agent (ID 1), Current Position: 0, Score: 0, rescued 0 people | Agent is ready to take an action.
Agent Actions in Current Step:
Agent 1 is equipping the amphibian kit (action duration is 2 steps).

Step 2:
Total Rescued People: 0/3
Number of vertices: 4
Objects in Vertices:
[['Agent1'], [], [], ['P3']]
Weights:
-1   2   -1   2
2   -1   2   -1
-1   2   -1   2
2   -1   2   -1
Agent States:
A*-RealTime-Search Agent (ID 1), Current Position: 0, Score: -1, rescued 0 people | With Amphibian Kit. | Agent is currently in action. (1 steps left to finish)
Agent Actions in Current Step:
Agent 1 took no action.

Step 3:
Total Rescued People: 0/3
Number of vertices: 4
Objects in Vertices:
[['Agent1'], [], [], ['P3']]
Weights:
-1   2   -1   2
2   -1   2   -1
-1   2   -1   2
2   -1   2   -1
Agent States:
A*-RealTime-Search Agent (ID 1), Current Position: 0, Score: -2, rescued 0 people | With Amphibian Kit. | Agent is ready to take an action.
Agent Actions in Current Step:
Agent 1 is unequipping the amphibian kit (action duration is 1 steps).

Step 4:
Total Rescued People: 0/3
Number of vertices: 4
Objects in Vertices:
[['Agent1', 'K'], [], [], ['P3']]
Weights:
-1   2   -1   2
2   -1   2   -1
-1   2   -1   2
2   -1   2   -1
Agent States:
A*-RealTime-Search Agent (ID 1), Current Position: 0, Score: -3, rescued 0 people | Agent is ready to take an action.
Agent Actions in Current Step:
Agent 1 is equipping the amphibian kit (action duration is 2 steps).

Step 5:
Total Rescued People: 0/3
Number of vertices: 4
Objects in Vertices:
[['Agent1'], [], [], ['P3']]
Weights:
-1   2   -1   2
2   -1   2   -1
-1   2   -1   2
2   -1   2   -1
Agent States:
A*-RealTime-Search Agent (ID 1), Current Position: 0, Score: -4, rescued 0 people | With Amphibian Kit. | Agent is currently in action. (1 steps left to finish)
Agent Actions in Current Step:
Agent 1 took no action.

Step 6:
Total Rescued People: 0/3
Number of vertices: 4
Objects in Vertices:
[['Agent1'], [], [], ['P3']]
Weights:
-1   2   -1   2
2   -1   2   -1
-1   2   -1   2
2   -1   2   -1
Agent States:
A*-RealTime-Search Agent (ID 1), Current Position: 0, Score: -5, rescued 0 people | With Amphibian Kit. | Agent is ready to take an action.
Agent Actions in Current Step:
Agent 1 is unequipping the amphibian kit (action duration is 1 steps).

Step 7:
Total Rescued People: 0/3
Number of vertices: 4
Objects in Vertices:
[['Agent1', 'K'], [], [], ['P3']]
Weights:
-1   2   -1   2
2   -1   2   -1
-1   2   -1   2
2   -1   2   -1
Agent States:
A*-RealTime-Search Agent (ID 1), Current Position: 0, Score: -6, rescued 0 people | Agent is ready to take an action.
Agent Actions in Current Step:
Agent 1 is equipping the amphibian kit (action duration is 2 steps).