

# CS6135 VLSI Physical Design Automation

## Homework 3: Fixed-outline Slicing Floorplan Design

Due: 23:59, December 4, 2022

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### 1. Introduction

In this homework, you are asked to adapt and implement an existing algorithm, published in the DAC-86 paper entitled “**A New Algorithm for Floorplan Design**” by Wong and Liu, for solving the fixed-outline slicing floorplan design problem with a set of hard blocks.

### 2. Problem Description

#### (1) Input:

- A set  $B$  of hard blocks, where each block  $b_i$  in  $B$  has a rectangular shape specified by 4 corners.
- A netlist  $E$
- The dead space ratio, which is predefined and passed by the argument. The aspect ratio of the floorplan region is 1, so you can calculate the width  $w_{fl}$  and height  $h_{fl}$  of the floorplan region as follows:

$$w_{fl} = h_{fl} = \sqrt{(total\ block\ area) * (1 + (dead\ space\ ratio))}$$

For example, if the total block area is 1100000 and the dead space ratio is 0.1, the width  $w_{fl}$  and height  $h_{fl}$  of the floorplan region are as follows:

$$w_{fl} = h_{fl} = \sqrt{1100000 * 1.1} = 1100$$

Then, the coordinates of the lower-left corner and upper-right corner of the floorplan region are  $(0, 0)$  and  $(w_{fl}, h_{fl})$ , respectively.

#### (2) Output:

- The **total wirelength of all nets**, where the wirelength for each net is defined as the **half-perimeter wirelength (HPWL)** of the minimum bounding box of pins of the net. Each pin of block  $b_i$  is located at the center of  $b_i$ . Note that the x- or y- coordinate, say  $i$ , of each block center is **rounded down to an integer**  $k$  such that  $k \leq i \leq k + 1$ .
- The **coordinates  $(x_i, y_i)$  of the lower-left corner** of each block  $b_i$ , as well as the **rotation status** (1 for rotated, and 0 for un-rotated).

### (3) Objective:

By assuming each block can be rotated by 90 degrees, the **total wirelength** of the floorplanning result and the **runtime** of your program are **minimized** subject to the following constraints.

1. Fixed-outline constraint: Each block must be entirely inside the floorplan region.
2. Non-overlapping constraint: No two blocks overlap with each other.

## 3. Input File

### (1) The .hardblocks file:

The .hardblocks file specifies the name and the other information about each block/terminal node in the floorplan. Each line specifies a single block/terminal node. Here is an example:

```
NumHardRectilinearBlocks : 10
//NumHardRectilinearBlocks : number of hard rectilinear block nodes
NumTerminals : 69
//NumTerminals : number of terminal (pad etc.) nodes
sb0 hardrectilinear 4 (0, 0) (0, 82) (199, 82) (199, 0)
//nodeName hardrectilinear vertexNumber vertex1, vertex2, ..., vertexN
:
p1 terminal
//nodeName terminal
:
```

- nodeName is an arbitrary-length alpha-numeric string, and is case-sensitive.
- hardrectilinear is a literal which declares that the node is a hard rectilinear block.
- vertexNumber is the number of vertices of the corresponding hard rectilinear block.
- vertex1, vertex2, ..., vertexN are a list of all vertices of the corresponding hard rectilinear block in a **clockwise** order,  $vertex1 \neq vertexN$ . Each vertex is a pair of parentheses-enclosed and comma-separated integers indicating the X-, then the Y- coordinate of the vertex, relative to the lower-left corner of the corresponding hard rectilinear block's bounding box.
- terminal is a literal which indicates that the node is a fixed pin.

(2) **The .nets file:**

The .nets file specifies the netlist. Here is an example:

```
NumNets : 118
//NumNets : number of nets
NumPins : 248
//NumPins : number of pins
NetDegree : 2
//NetDegree : number of pins on the net
p1
sb6
//nodeName
:
```

(3) **The .pl file:**

The .pl file specifies the pin coordinates of each terminal node in the floorplan. Here is an example:

```
p1 0 0
//nodeName XY-coordinate
:
```

## 4. Output File

(1) **The .floorplan file:**

The .floorplan file specifies the floorplanning result including the total wirelength of all nets and the coordinates of the lower-left corner of each block with/without rotation.

```
Wirelength 75563
Blocks
sb0 152 284 1
//nodeName lower-left corner coordinates \(x,y\) Rotated
sb1 126 179 0
//nodeName lower-left corner coordinates \(x,y\) Unrotated
```

## 5. Language/Platform

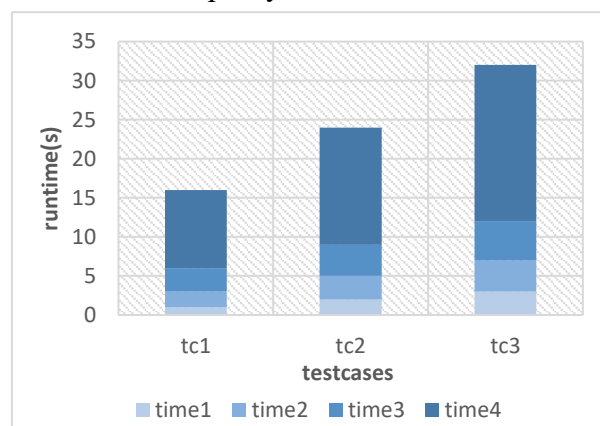
- (1) Language: C/C++
- (2) Platform: Unix/Linux

## 6. Report

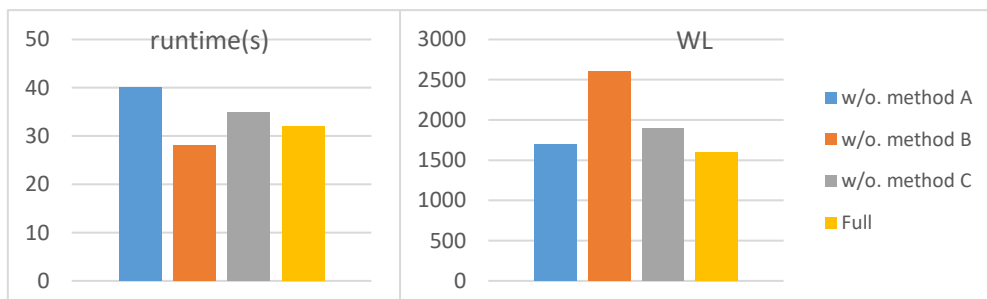
Your report must contain the following contents, and you can add more as you wish.

- (1) Your name and student ID
- (2) How to compile and execute your program and give an execution example.
- (3) The wirelength and the runtime of each testcase with the **dead space ratios 0.15 and 0.1**, respectively.

Notice that the runtime contains I/O, constructing data structures, initial floorplanning, computing (perturbation) parts, etc. The more details your experiments have, the more clearly you will know where the runtime bottlenecks are. You can plot your results like the one shown below.



- (4) Please show that **how small the dead space ratio could be** for your program to produce a legal result in **10 minutes**.
- (5) The details of your implementation. If there is anything different between your implementation and the algorithm in the DAC-86 paper, please reveal the difference(s) and explain the reasons.
- (6) What tricks did you do to speed up your program or to enhance your solution quality? Also plot the effects of those different settings like the ones shown below.



- (7) Please compare your results with the previous top 3 students' results for the case where the dead space ratio is set to 0.15, and show your advantage either in runtime or in solution quality. Are your results better than theirs?

- ✓ If so, please express your advantages to beat them.
- ✓ If not, it's fine. If your program is too slow, then what could be the bottleneck of your program? If your solution quality is inferior, what do you think that you could do to improve the result in the future?

**Top 3 students' results (dead space ratio = 0.15)**

Ranks	Wirelength			Runtime (s)		
	n100	n200	n300	n100	n200	n300
1	<u>207309</u>	<u>367785</u>	<u>504903</u>	<u>13.97</u>	<u>84.54</u>	263.33
2	209351	379674	521749	25.57	99.49	<u>209.78</u>
3	210220	392175	544879	37.45	105.83	486.73

- (8) If you implement parallelization (for algorithm itself), please describe the implementation details and provide some experimental results.
- (9) What have you learned from this homework? What problem(s) have you encountered in this homework?

## 7. Required Items

Please compress HW3/ (using tar) into one with the name CS6135\_HW3\_`\${StudentID}`.tar.gz before uploading it to eeclass.

- (1) src/ contains all your source code, your Makefile and README.
  - README must contain how to compile and execute your program. An example is like the one shown in HW2.
- (2) output/ contains all your outputs of testcases for TAs to verify.
- (3) bin/ contains your executable file.
- (4) CS6135\_HW3\_`\${STUDENT\_ID}`\_report.pdf contains your report.

You can use the following command to compress your directory on a workstation:

```
$ tar -zcvf CS6135_HW3_`${StudentID}`.tar.gz <directory>
```

**For example:**

```
$ tar -zcvf CS6135_HW3_111062500.tar.gz HW3/
```

## 8. Grading

- ✓ 80%: The wirelength (primary) and the runtime (secondary) of each testcase, hidden testcases included. This part will be evaluated with **single thread version**.
- ✓ 20%: The completeness of your report
- ✓ **5% Bonus:** Parallelization

## Notes:

- Make sure the following commands can be executed.
  - Go into directory “src/”, enter “make” to compile your program and generate the executable file, called “hw3”, which will be in directory “bin/”.
  - Go into directory “src/”, enter “make clean” to delete your executable file.
- Please use the following command format to run your program.  
`$ ./hw3 *.hardblocks *.nets *.pl *.floorplan dead_space_ratio`  
E.g.:  
`$ ./hw3 ../testcases/n100.hardblocks ../testcases/n100.nets ../testcases/n100.pl ../output/n100.floorplan 0.15`
- If you implement parallelization, please name your **parallel-version executable file** as “hw3\_parallel” and name your sequential-version executable file as “hw3”.
- Use arguments to read the file path. **Do not write the file path in your code.**
- Your program must be terminated within **10 minutes** for each testcase.
- We will test your program by shell script with GCC 9.3.0 on ic51. **Please make sure your program can be executed by HW3\_grading.sh.**
- For each testcase, you could use **HW3\_printer** to draw your result like the following figure.

