

# MA 589 — Computational Statistics

## Project 1

(Due: Friday, 09/28/18)

1. (WaRming up) Write (R) functions that return:

- The inverse or the transpose inverse of an upper triangular matrix. Call this function `inv.upper.tri` and provide a `transpose` argument to specify if the transpose is requested. Hint: use `backsolve`.
- The  $L_2$  norm of vector  $\mathbf{v}$  with  $n$  entries, defined as  $\text{norm2}(\mathbf{v}) = \|\mathbf{v}\| = \sqrt{\sum_{i=1}^n v_i^2} = \sqrt{v^T v}$ . Quick check: if `u <- 1e200 * rep(1, 100)`, what is `norm2(u)`?<sup>1</sup>
- The column-normalization  $U$  of matrix  $A$ ,  $U_{ij} = A_{ij}/\|A_{.j}\|$  (call this function `normalize.cols`, and feel free to use `norm2` above).
- The projection of vector  $\mathbf{a}$  into  $\mathbf{u}$  (called as `proj(a, u)`),

$$\text{proj}_{\mathbf{u}}(\mathbf{a}) = \frac{\mathbf{u}^T \mathbf{a}}{\|\mathbf{u}\|^2} \mathbf{u}.$$

Quick check: what is `proj(1:100, u)`,  $\mathbf{u}$  as in (b) above?

- The Vandermonde matrix of vector  $\mathbf{a} = [a_i]_{i=1,\dots,n}$  and degree  $d$ ,

$$\mathbb{V}(\mathbf{a}, d) = \begin{bmatrix} 1 & a_1 & a_1^2 & \cdots & a_1^d \\ 1 & a_2 & a_2^2 & \cdots & a_2^d \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & a_n & a_n^2 & \cdots & a_n^d \end{bmatrix} = [a_i^{j-1}]_{i=1,\dots,n, j=1,\dots,d+1}$$

(called as `vandermonde(a, d)`).

2. The *machine epsilon*,  $\epsilon$ , can be defined as the smallest floating point (with base 2) such that  $1 + \epsilon > 1$ , that is,  $1 + \epsilon/2 == 1$  in machine precision.

- Write a function that returns this value by starting at `eps = 1` and iteratively dividing by 2 until the definition is satisfied.
- Write a function that computes  $f(x) = \log(1 + \exp(x))$  and then evaluate:  $f(0)$ ,  $f(-80)$ ,  $f(80)$ , and  $f(800)$ .
- How would you specify your function to avoid computations if  $x \ll 0$  ( $x < 0$  and  $|x|$  is large)? (Hint:  $\epsilon$ .)
- How would you implement your function to not overflow if  $x \gg 0$ ?

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<sup>1</sup>1e201, of course.

3. (QR via Gram-Schmidt) If  $A = [\mathbf{a}_1 \mathbf{a}_2 \cdots \mathbf{a}_p]$  is a  $n$ -by- $p$  matrix with  $n > p$  then we can obtain a “thin” QR decomposition of  $A$  using Gram-Schmidt orthogonalization<sup>2</sup>. To get  $Q$ , we start with  $\mathbf{u}_1 = \mathbf{a}_1$ , then compute iteratively, for  $i = 2, \dots, p$ ,

$$\mathbf{u}_i = \mathbf{a}_i - \sum_{j=1}^{i-1} \text{proj}_{\mathbf{u}_j}(\mathbf{a}_i),$$

and finally, with  $\mathbf{q}_i = \mathbf{u}_i / \|\mathbf{u}_i\|$ , set  $Q = [\mathbf{q}_1 \mathbf{q}_2 \cdots \mathbf{q}_p]$  as a column-normalized version of  $U = [\mathbf{u}_i]_{i=1, \dots, p}$ .

- (a) Show that  $C = Q^\top A$  is upper triangular and that  $C$  is the Cholesky factor of  $A^\top A$ .
- (b) Write a R function that computes the  $Q$  orthogonal factor of a Vandermonde matrix with base vector  $\mathbf{x}$  and degree  $d$  *without computing the Vandermonde matrix explicitly*, that is, as your function iterates to compute  $\mathbf{u}_i$ , compute and use the columns of the Vandermonde matrix on the fly.
- (c) It can be shown that with  $\eta_1 = 1$ ,

$$\eta_{i+1} = \mathbf{u}_i^\top \mathbf{u}_i, \quad \text{and} \quad \alpha_i = \frac{\mathbf{u}_i^\top \text{Diag}(\mathbf{x}) \mathbf{u}_i}{\mathbf{u}_i^\top \mathbf{u}_i}, \quad \text{for } i = 1, \dots, d+1,$$

where  $\text{Diag}(\mathbf{x})$  is a diagonal matrix with diagonal entries  $\mathbf{x}$ , the  $U$  matrix can be computed using the recurrence relation:  $\mathbf{u}_1 = \mathbb{1}_n$ ,  $\mathbf{u}_2 = \mathbf{x} - \alpha_1 \mathbb{1}_n$ , and, for  $i = 2, \dots, d$ ,

$$(\mathbf{u}_{i+1})_j = (x_j - \alpha_i)(\mathbf{u}_i)_j - \frac{\eta_{i+1}}{\eta_i} (\mathbf{u}_{i-1})_j, \quad \text{for } j = 1, \dots, n.$$

Write a R function that, given  $\eta$  and  $\alpha$ , computes  $Q$ .

- (d) Now modify your function in (a) to also compute  $\alpha$  and  $\eta$ . Quick check for the “compact” representation of  $Q$ : show that  $\alpha_1 = \bar{\mathbf{x}}$ ,  $\eta_2 = n$ , and  $\eta_3 = (n-1)s_{\mathbf{x}}^2$ , where  $\bar{\mathbf{x}}$  and  $s_{\mathbf{x}}^2$  are the sample mean and variance of  $\mathbf{x}$  respectively.
4. (Orthogonal staged regression) Suppose we observe  $\mathbf{y} \sim N(X\beta, \sigma^2 I_n)$ ,  $X$  a  $n$ -by- $p$  full rank matrix, and wish to test

$$H_0 : \beta_j = \beta_{j+1} = \cdots = \beta_p = 0$$

for some  $j \geq 1$ . It can be shown that the ML estimator  $\hat{\beta} = (X^\top X)^{-1} X^\top \mathbf{y}$  has distribution  $\hat{\beta} \sim N(\beta, \sigma^2 (X^\top X)^{-1})$ .

- (a) If  $X$  has thin QR decomposition  $X = QR$ , show that  $H_0$  is equivalent to testing  $\gamma_j = \cdots = \gamma_p = 0$  where  $\gamma = R\beta$ , and so we can regress  $\mathbf{y}$  on  $Q$  instead of  $X$ , that is, estimate  $\gamma$  from  $\mathbf{y} \sim N(Q\gamma, \sigma^2 I_n)$ .

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<sup>2</sup>This is not recommended in practice because it is numerically unstable. Orthogonalizations are usually performed using Givens rotations or Householder reflections.

- (b) Show that the ML estimator for  $\gamma$  is  $\hat{\gamma} = Q^\top \mathbf{y}$  and the components of  $\hat{\gamma}$  are *independent*.
- (c) Using  $R$ , explain how you compute: (i) the ML estimate  $\hat{\beta}$  as a function of  $\hat{\gamma}$ , and (ii) the correlation matrix of  $\hat{\beta}$  using only `crossprod`, `normalize.cols`, and `inv.upper.tri`.
- (d) As a concrete example, let us use the `cars` dataset<sup>3</sup> to fit a polynomial regression of degree  $d = 3$ . Take `dist` to be the response  $\mathbf{y}$  and `speed` to be the base vector  $\mathbf{x}$  to define  $X = \mathbb{V}(\mathbf{x}, d)$ , a Vandermonde design.
- Compute  $Q$  using the routine from 3.b, obtain  $\hat{\gamma} = Q^\top \mathbf{y}$  and compare it to the estimate from `coef(lm(dist ~ Q - 1))`.
  - Compute  $\hat{\beta}$  according to (c) and compare it to the estimate from `coef(lm(dist ~ vandermonde(speed, 3) - 1))`
  - (\*) Compare the  $p$ -values when testing  $\gamma_j = 0$  and  $\beta_j = 0$  for  $j = 1, \dots, 4$  from the above regression fits. How would you explain the discrepancies based on the results from (b) and (c)? What degree would you recommend for a polynomial regression of `dist` on `speed`?
- (e) (\*) Suppose we use another routine to obtain a QR decomposition of  $X$ . Under what conditions is  $R$  the Cholesky factor of  $X^\top X$ ? Write a function that returns a QR decomposition of  $X$  satisfying these conditions.

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<sup>3</sup>Load it in R with `data(cars)`.