# Embedded Systems with ARM Cortex-M3 Microcontrollers in Assembly Language and C

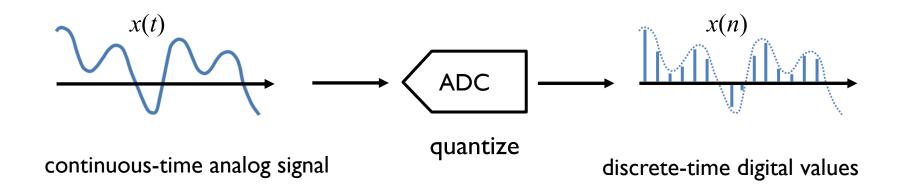
# Chapter 20 Analog-to-Digital Converter (ADC)

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# Analog-to-Digital Converter (ADC)

- ▶ ADC is important to almost all application fields
- Converts a continuous-time voltage signal within a given range to discrete-time digital values to quantify the voltage's amplitudes



### Analog-to-Digital Converter (ADC)

#### Three performance parameters:

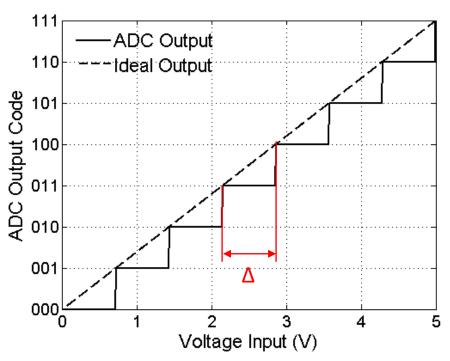
- sampling rate: number of conversions per second (thousands to milions)
- resolution: number of bits in ADC output (6 to 24)
- power dissipation: power efficiency of ADC

#### Many ADC implementations:

- sigma-delta
  - ▶ for apps requiring low sampling rate (<100 kHz) but high resolution (12-24 bit)</p>
  - e.g.: voice and audio apps in cell phones
- successive-approximation (SAR)
  - ▶ for low-power data acquisitions w/ moderate sampling rates (<5MHz)</p>
  - e.g.: STM32 microcontrollers
- pipelined
  - for high-speed apps (sampling rate > 5MHz) and relatively low resolution
  - e.g.: radar communication

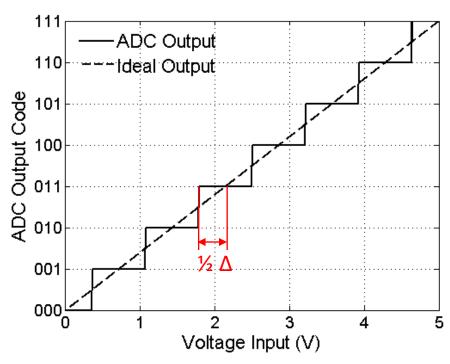
#### Resolution

- ▶ Resolution is determined by number of bits (in binary) to represent an analog input.
- $\triangleright$  Example of two quantization methods (N = 3)



$$Digital \ Result = \ floor\left(2^3 \times \frac{V}{V_{REF}}\right)$$

Max quantization error =  $\Delta = V_{RFF}/2^3$ 



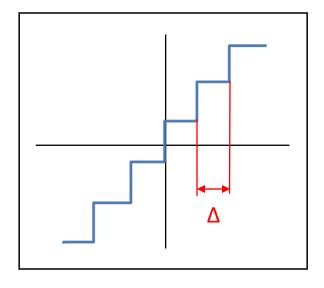
$$Digital \ Result = \ round \left(2^3 \times \frac{V}{V_{REF}}\right)$$

Max quantization error =  $\pm \frac{1}{2} \Delta = \pm V_{REF}/2^4$ 

$$round(x) = floor(x + 0.5)$$

### Quantization Error

- ▶ For N-bit ADC, it is limited to  $\pm \frac{1}{2}\Delta$
- $\Delta$  = is the step size of the converter.

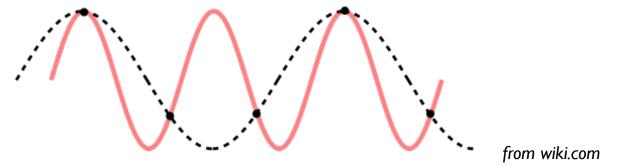


Example: for 12-bit ADC and input voltage range [0, 3V]

Max Quantization Error = 
$$\frac{1}{2}\Delta = \frac{3V}{2\times2^{12}} = 0.367mV$$

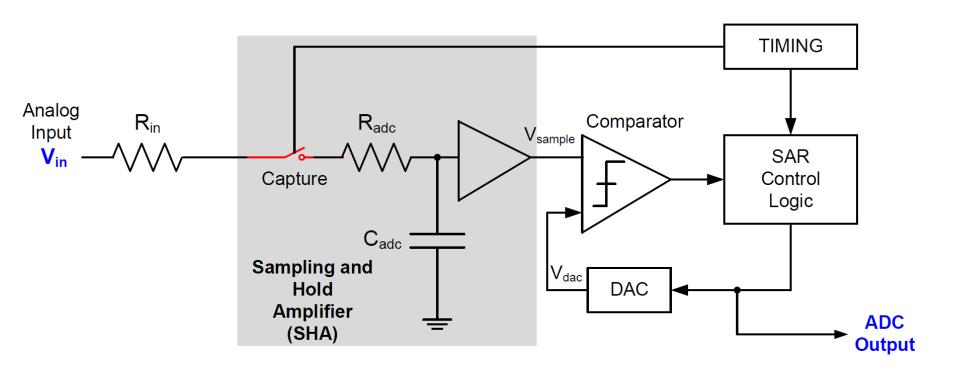
## Minimum Sampling Rate: Nyquist–Shannon Sampling Theorem

- In order to be able to reconstruct the analog input signal, the sampling rate should be at least twice the maximum frequency component contained in the input signal
- Example of two sine waves have the same sampling values. This is called aliasing.

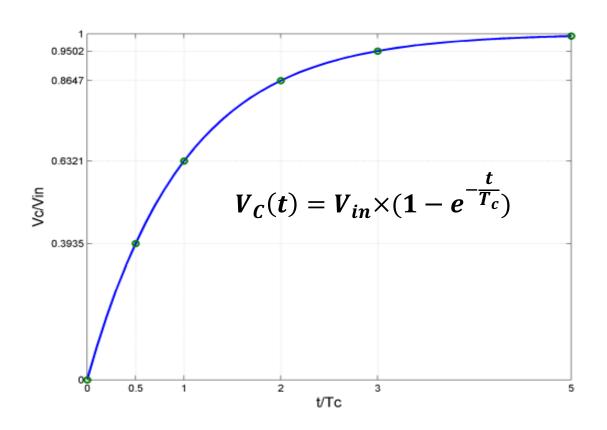


- Antialiasing (beyond the scope of this course)
  - Pre-filtering: use analog hardware to filtering out high-frequency components and only sampling the low-frequency components. The high-frequency components are ignored.
  - Post-filtering: Oversample continuous signal, then use software to filter out high-frequency components

# Successive-approximation (SAR) ADC



### Determining Minimum Sampling Time



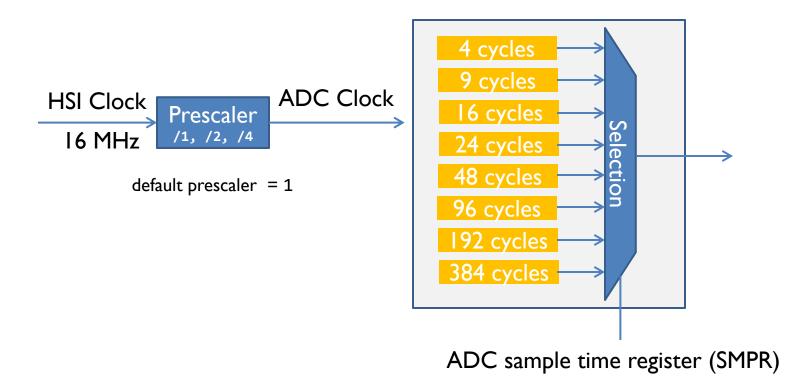
Sampling time is software programmable!

Larger sampling time

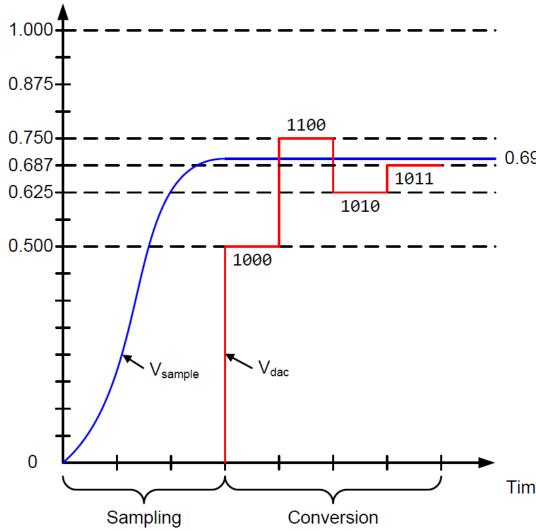
Smaller sampling errorSlower ADC speed

Tradeoff

### Programming ADC Sampling Time



# Successive-approximation (SAR) ADC



- Binary search algorithm to gradually approaches the input voltage
- Settle into ±½ LSB bound within the time allowed

$$T_{ADC} = T_{sampling} + T_{Conversion}$$

$$T_{Conversion} = N \times T_{ADC\_Clock}$$

 $T_{sampling}$  is software configurable

Time (cycles)

#### ADC Conversion Time

$$T_{ADC} = T_{sampling} + T_{Conversion}$$

Suppose ADCCLK = 16 MHz and Sampling time = 4 cycles

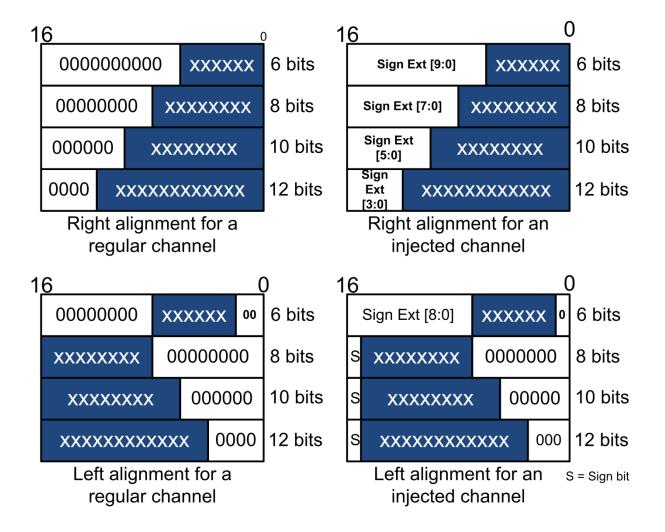
For 12-bit ADC

$$T_{ADC} = 4 + 12 = 16 \ cycles = 1 \mu s$$

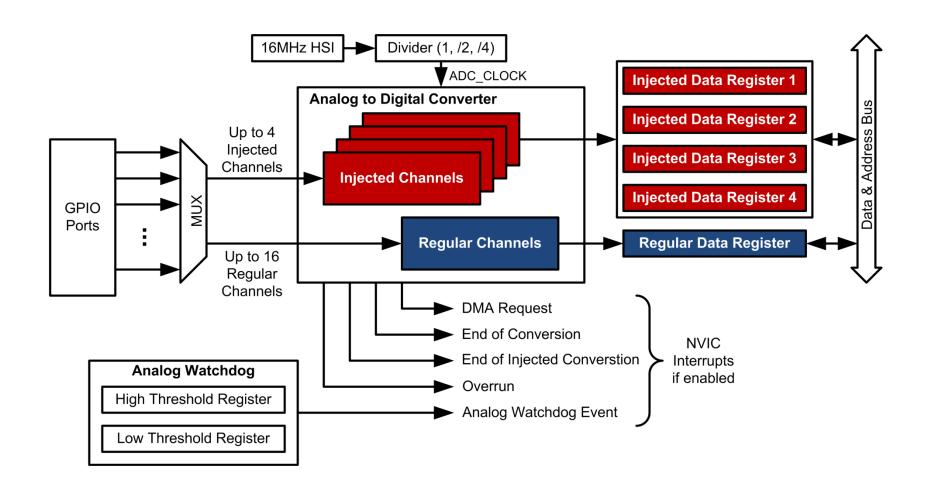
For 6-bit ADC

$$T_{ADC} = 4 + 6 = 10 \ cycles = 625ns$$

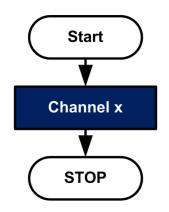
### Data Alignment



### ADC: Regular vs injected

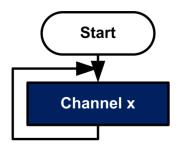


#### ADC Mode



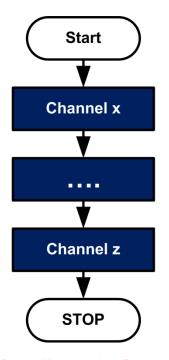
#### Single Channel, Single Conversion Mode

CONT in ADC\_CR2 = 0 SCAN in ADC\_CR2 = 0



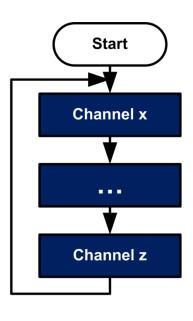
### Single Channel, Continuous Conversion Mode

CONT in ADC\_CR2 = 1 SCAN in ADC\_CR2 = 0



### Scan Mode with Single Conversion

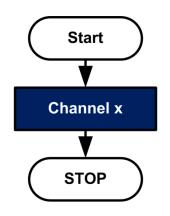
SCAN in ADC\_CR2 = 1 CONT in ADC\_CR2 = 0



### Scan Mode with Continuous Conversion

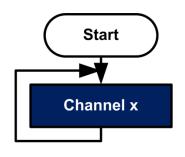
SCAN in ADC\_CR2 = 1 CONT in ADC\_CR2 = 1

#### ADC Mode



#### Single Channel, Single Conversion Mode

CONT in ADC\_CR2 = 0 SCAN in ADC\_CR2 = 0



#### Single Channel, Continuous Conversion Mode

CONT in ADC\_CR2 = 1 SCAN in ADC\_CR2 = 0

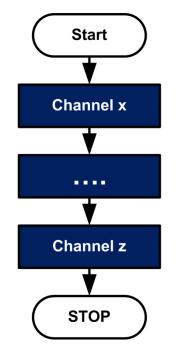
#### Regular channel:

- I. Set SWSTART in ADC\_CR2
- The channel is selected by SQI[4:0] in SQR5
- 3. Result is stored in ADC\_DR
- 4. EOC is set after conversion
- 5. Interrupt is generated if EOCIE is set

#### **Injected channel:**

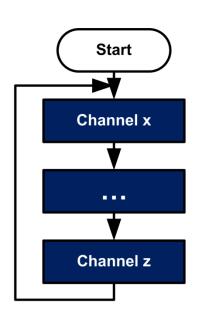
- Set JSWSTART in ADC\_CR2
- The channel is selected by JSQ1[4:0] in JSQR
- 3. Result is stored in ADC\_JDR1
- 4. JEOC is set after conversion
- 5. Interrupt is generated if JEOCIE is set

#### ADC Mode



Scan Mode with Single Conversion

SCAN in ADC\_CR2 = 1 CONT in ADC\_CR2 = 0



Scan Mode with Continuous Conversion

SCAN in ADC\_CR2 = 1 CONT in ADC\_CR2 = 1

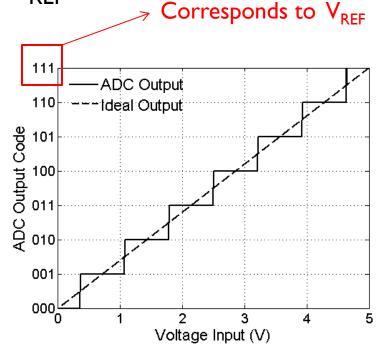
- Channels are selected by ADC\_SQRx registers for regular channels, and by ADC\_JSQR register for injected channel
- All channels in a regular group share the same result register ADC\_DR.
  Make sure to read data between consecutive sampling.

### $V_{REF}$

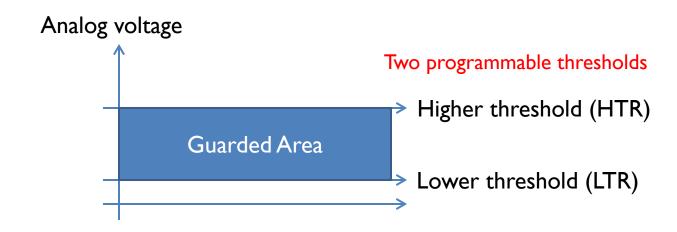
- Some chips does not expose V<sub>REF</sub> to a pin
  - ▶ STM32L LQFP64 does not have V<sub>REF</sub> pin
  - ▶ STM32L LQFP100 does

Infer internal V<sub>REF</sub>

► How?



### Analog Watchdog



- If  $V < V_{LTR}$  or  $V > V_{HTR}$ , the analog watchdog (AWD) flag (in ADC Status Register) is set, generating an interrupt to the processor
- The monitor is automatically performed by hardware, not software
- Convenient and efficient feature
- Help processor detect exceptions and recover from specific situations
  - For example, monitor sensor data and raise alarm on some level.

# Example: ADC with Timer Interrupts

#### Main program **ADC** Set up timer timer interrupt interrupt **ADC** Timer Timer ISR Peripheral Peripheral Set ADC\_Done flag Wait for **ADC ISR** DAC\_Done = I **Process Data** ISR = Interrupt Service Routine TIMER ISR starts ADC Repeat ADC samples multiple channels ADC ISR copies ADC data register to memory

### Example: ADC with Timer and DMA

