



# Computer Vision

**Binary Vision** 

#### **Binary Vision**

- Thresholding
- Threshold Detection
- Variations
- Mathematical Morphology
- Connectivity
- Objects of interest vs background





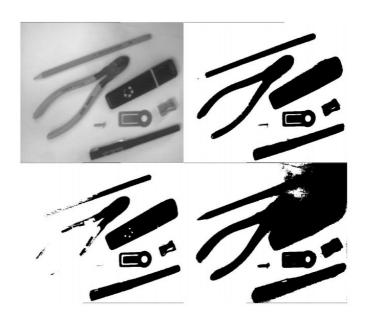


Based on *A Practical Introduction to Computer Vision with OpenCV* by Kenneth Dawson-Howe © Wiley & Sons Inc. 2014



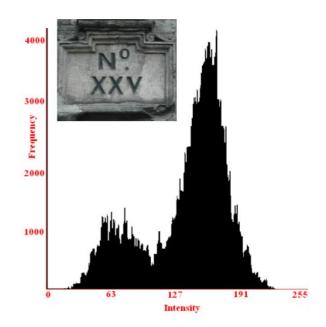
# Thresholding

- Distinct foreground and background
- How to determine the best threshold



#### **Threshold Detection**

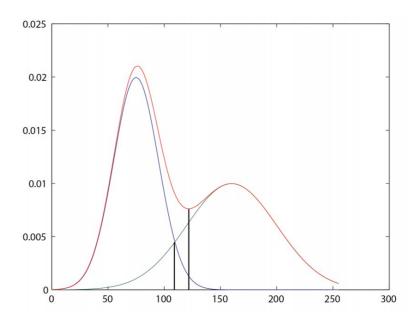
- Manual Setting
- Changing lighting
- Need to determine automatically
- Techniques:
  - Image
  - Histogram
  - Probability Distribution



# Threshold Detection - Optimal Thresholding



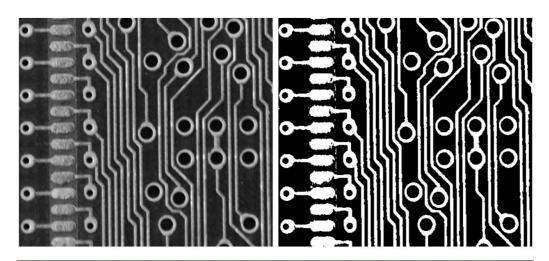
Model as two normal distributions



#### Threshold Detection - Otsu Thresholding



- If it's not two normal distributions
- Minimizes the spread of the pixels



## Adaptive Thresholding

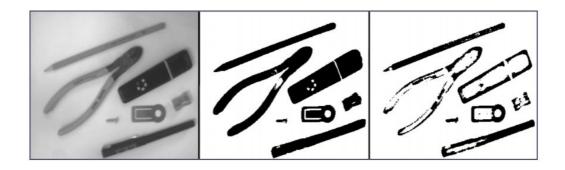


- Divide the image into sub-images
- Compute thresholds for each sub-image
- Interpolate thresholds for every point using bilinear interpolation



# Adaptive Thresholding in OpenCV

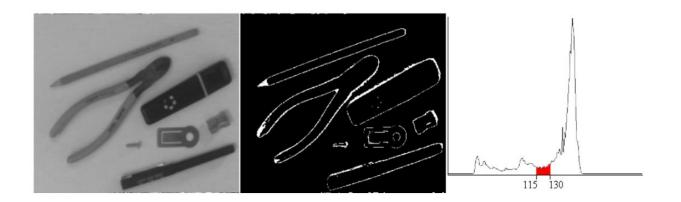




#### **Band Thresholding**



Could be used for edge detection



```
threshold( image, binary1, low_threshold, 255, THRESH_BINARY );
threshold( image, binary2, high_threshold, 255, THRESH_BINARY_INV );
bitwise_and( binary_image1, binary_image2, band_thresholded_image );
```

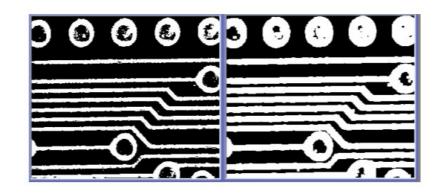
# Mathematical Morphology

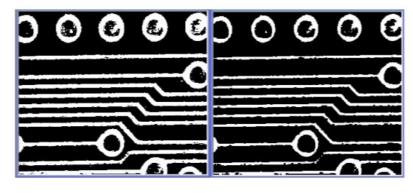


- Based on algebra of non-linear operators operating on object shape
- Performs many tasks better and more quickly than standard approaches
- Seperate part of image analysis
- Main uses:
  - Pre-processing
  - Object structure enhancement
  - Segmentation
  - Description of objects

#### Mathematical Morphology - Dilation and Erosion

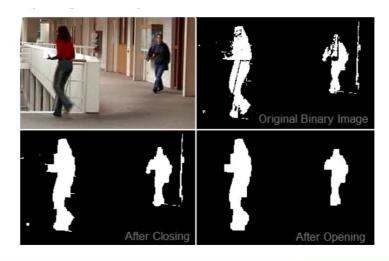


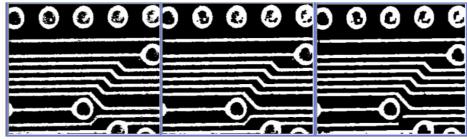




#### Mathematical Morphology - Closing and Opening







# Mathematical Morphology in OpenCV



```
dilate( binary_image, dilated_image, Mat());

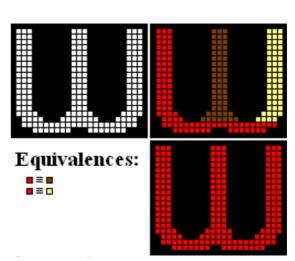
Mat structuring_element( 5, 5, CV_8U, Scalar(1) );
dilate( binary_image, dilated_image, structuring_element);

erode( binary_image, eroded_image, Mat());

Mat structuring_element( 5, 5, CV_8U, Scalar(1) );
erode( binary_image, eroded_image, structuring_element);
```

#### Connectivity

- Search image row by row
  - Label each non-zero pixel
  - Assign new label if previous pixels are background
  - Else pick any label from previous pixels
  - Note equivalence if any of the other pixels have a different label
- Relabel equivalent Labels



# Extracting Regions in OpenCV



```
vector<vector<Point>> contours;
vector<Vec4i> hierarchy;
findContours (binary image, contours, hierarchy,
                   CV_RETR_TREE, CV_CHAIN_APPROX_NONE );
```

#### Labelling Regions in OpenCV



```
for (int contour=0; (contour < contours.size()); contour++)
    Scalar colour( rand() &0xFF, rand() &0xFF, rand() &0xFF );
    drawContours ( contours image, contours, contour, colour,
                                                     CV FILLED, 8, hierarchy);
```