

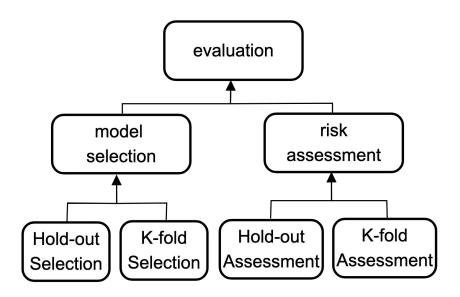


A Deep Graph Networks library for Python

https://github.com/diningphil/PyDGN

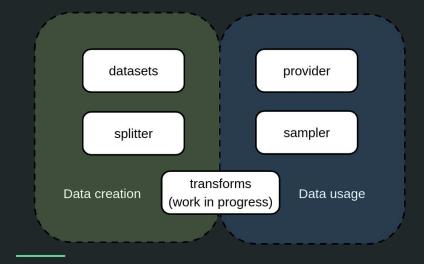
Robust Evaluation

(no more eval. mistakes)



Requirements:

- A dataset implementation
- A data split file







An Example

Data Preprocessing

```
splitter:
  root: SPLITS/
  class_name: datasets.splitter.Splitter
  args:
    n outer folds: 10
   n inner folds: 1
    seed: 42
    stratify: True
    shuffle: True
   val ratio: 0.1
    test ratio: 0.1
dataset:
  root: DATA/
 class name: datasets.datasets.TUDataset
  args:
    root: DATA/
    name: NCT1
  # useful for social datasets with no node features
  transforms:
      - class_name: datasets.transforms.ConstantIfEmpty
        args:
          value: 1
```

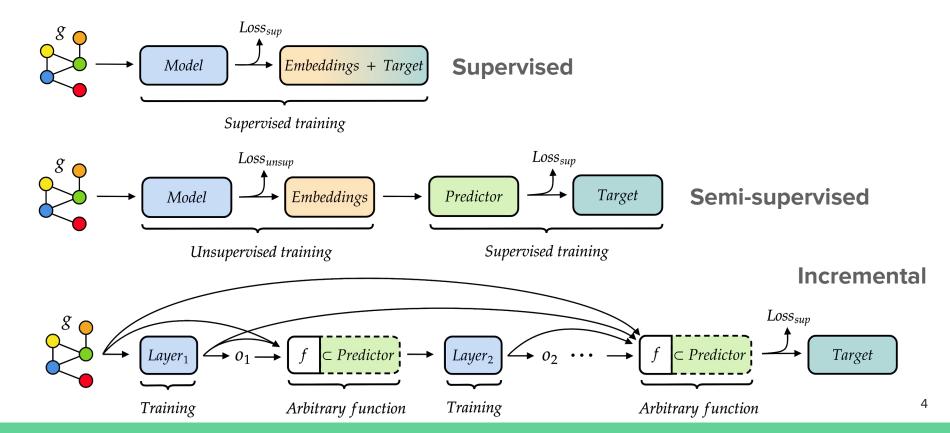








Three experiment classes (more are coming!)



An Example

Supervised Experiment

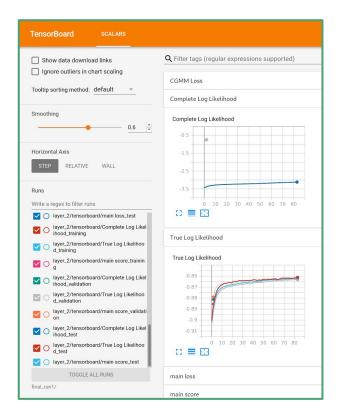
```
model: models.dgns.ToyDGN.ToyDGN
experiment: supervised
higher results are better: True
log every: 1
dataset-getter: datasets.provider.DataProvider
device: cpu
num_dataloader_workers: 0
pin memory: False
grid:
  supervised_config:
    loss:
      - training.callback.loss.MulticlassClassificationLoss
    scorer:
        class_name: training.callback.score.MultiScore
        args:
           # used at model selection time. Should be the one on which
          main_scorer: training.callback.score.MulticlassAccuracyScor
          my_metric2: training.callback.score.Toy1Score
    predictor:
      - models.predictors.GraphPredictor.LinearGraphPredictor
    early_stopper:
        class name:
         - training.callback.early_stopping.PatienceEarlyStopper
        args:
         patience:
            - 5
         # Should be the name of the main scorer in MultiScore
         monitor: validation_Multiclass Accuracy # (train_, validation_)
         mode: max
         checkpoint: True
```







Plotting



Profiling

```
**********

Threshold: le-05

EngineCallback

on_fetch_data --> Avg: 0.014047326353040013 s, Total: 1:15:44.928158
on_forward --> Avg: 0.0027546234653820388 s, Total: 0:14:51.241894

MyLoss

on_backward --> Avg: 0.0018598404143548941 s, Total: 0:04:44.109222
on_training_batch_end --> Avg: 0.0005366264010137462 s, Total: 0:01:21.975049
```

Progress

\$\frac{1}{2} \frac{1}{2} \frac

PyDGN final remarks

- Leverages <u>Pytorch Geometric</u>
 - Data processing
 - Graph convolution



- An extended library w.r.t. <u>our ICLR paper</u>
- In continuous development
 - Every project requires some improvement
- Latest News: Ray support for distributed computing
 - by A.Carta (thanks!)

