

AiM Infotech

AiM CAN protocol

Release 1.00





AiM has designed and developed a complete proprietary CAN protocol.

It is already included in Race Studio software so to allow ECU Manufacturer, developing teams and technicians to connect their ECU to AiM devices.

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AiM CAN Protocol template

AiM CAN protocol features are:

- 500 Kbits
- little endian.

Here below is AiM CAN template.

| | ID | CHANNEL NAME | SHORT NAME | BYTE HIGH | BYTE LOW | MULT | DIV | OFFSET | SIGN | SENSOR | LOW RANGE | HIGH RANGE |
|---|-----|--------------|------------|-----------|----------|------|-----|--------|------|---------|-----------|------------|
| 0 | 5F0 | ECU_RPM | RPM | 1 | 0 | 1 | 1 | 0 | 0 | RPM | 0 | 65535 |
| 1 | 5F0 | ECU_TPS | TPS | 3 | 2 | 1 | 65 | 0 | 0 | %x10 | 0,0 | 100,8 |
| 2 | 5F0 | ECU_PPS | PPS | 5 | 4 | 1 | 65 | 0 | 0 | %x10 | 0,0 | 100,8 |
| 3 | 5F0 | ECU_VEH_SPD | VSDP | 7 | 6 | 1 | 10 | 0 | 0 | km/hx10 | 0,0 | 655,3 |



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|----|-----|----------------|------|---|---|---|----|------|---|----------|-------|--------|
| 4 | 5F1 | ECU_WS_FR | WSFR | 1 | 0 | 1 | 10 | 0 | 0 | km/hx10 | 0,0 | 655,3 |
| 5 | 5F1 | ECU_WS_FL | WSFL | 3 | 2 | 1 | 10 | 0 | 0 | km/hx10 | 0,0 | 655,3 |
| 6 | 5F1 | ECU_WS_RR | WSRR | 5 | 4 | 1 | 10 | 0 | 0 | km/hx10 | 0,0 | 655,3 |
| 7 | 5F1 | ECU_WS_RL | WSRL | 7 | 6 | 1 | 10 | 0 | 0 | km/hx10 | 0,0 | 655,3 |
| 8 | 5F2 | ECU_INT_AIR_T | IAT | 1 | 0 | 1 | 19 | -450 | 0 | Cx10 | -45,0 | 299,9 |
| 9 | 5F2 | ECU_ENG_T | ECT | 3 | 2 | 1 | 19 | -450 | 0 | Cx10 | -45,0 | 299,9 |
| 10 | 5F2 | ECU_FUEL_T | FUET | 5 | 4 | 1 | 19 | -450 | 0 | Cx10 | -45,0 | 299,9 |
| 11 | 5F2 | ECU_OIL_T | OILT | 7 | 6 | 1 | 19 | -450 | 0 | Cx10 | -45,0 | 299,9 |
| 12 | 5F3 | ECU_MAN_AIR_P | MAP | 1 | 0 | 1 | 10 | 0 | 0 | mBar | 0 | 6553 |
| 13 | 5F3 | ECU_BARO | BARO | 3 | 2 | 1 | 10 | 0 | 0 | mBar | 0 | 6553 |
| 14 | 5F3 | ECU_OIL_P | OILP | 5 | 4 | 1 | 1 | 0 | 0 | barx1000 | 0,000 | 65,535 |
| 15 | 5F3 | ECU_FUEL_P | FUEP | 7 | 6 | 1 | 1 | 0 | 0 | barx1000 | 0,000 | 65,535 |
| 16 | 5F4 | ECU_BOOST | BOST | 1 | 0 | 1 | 10 | 0 | 0 | barx1000 | 0 | 6,553 |
| 17 | 5F4 | ECU_V_BATT | VBAT | 3 | 2 | 1 | 32 | 0 | 0 | Vx100 | 0 | 20,47 |
| 18 | 5F4 | ECU_FUEL_USE | FUEU | 5 | 4 | 1 | 10 | 0 | 0 | lx10 | 0 | 655,3 |
| 19 | 5F4 | ECU_GEAR | GEAR | 7 | 6 | 1 | 1 | 0 | 0 | puro | 0 | 65535 |
| 20 | 5F5 | ECU_SHIFT_FLAG | GESH | 1 | 0 | 1 | 1 | 0 | 0 | puro | 0 | 65535 |
| 21 | 5F5 | ECU_GEAR_TIME | GETM | 3 | 2 | 1 | 1 | 0 | 0 | us | 0 | 65535 |
| 22 | 5F5 | ECU_THRT_VOLT | TPSV | 5 | 4 | 1 | 32 | 0 | 0 | Vx100 | 0 | 20,47 |
| 23 | 5F5 | ECU_FUEL_LEV | FULV | 7 | 6 | 1 | 10 | 0 | 0 | IX10 | 0 | 655,3 |



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|----|-----|------------------|-------|---|---|---|----|------|---|-------------|----------|--------|
| 24 | 5F6 | ECU_LAMBDA1 | LAM1 | 1 | 0 | 1 | 1 | 0 | 0 | lambdaX1000 | 0 | 65,535 |
| 25 | 5F6 | ECU_LAMBDA2 | LAM2 | 3 | 2 | 1 | 1 | 0 | 0 | lambdaX1000 | 0 | 65,535 |
| 26 | 5F6 | ECU_LAMBDA_T1 | LAT1 | 5 | 4 | 1 | 6 | -450 | 0 | Cx10 | -45,0 | 1047,2 |
| 27 | 5F6 | ECU_LAMBDA_T2 | LAT2 | 7 | 6 | 1 | 6 | -450 | 0 | Cx10 | -45,0 | 1047,2 |
| 28 | 5F7 | ECU_LAMB1_ERR | LA1E | 1 | 0 | 1 | 1 | 0 | 0 | puro | 0 | 65535 |
| 29 | 5F7 | ECU_LAMB2_ERR | LA2E | 3 | 2 | 1 | 1 | 0 | 0 | puro | 0 | 65535 |
| 30 | 5F7 | ECU_LAMB1_TARGET | LTA1 | 5 | 4 | 1 | 6 | -450 | 0 | Cx10 | -45,0 | 1047,2 |
| 31 | 5F7 | ECU_LAMB2_TARGET | LTA2 | 7 | 6 | 1 | 6 | -450 | 0 | Cx10 | -45,0 | 1047,2 |
| 32 | 5F8 | ECU_STEER_POS | STAG | 1 | 0 | 1 | 3 | 0 | 1 | DEGx10 | -1.092,7 | 1092,8 |
| 33 | 5F8 | ECU_STEER_SPD | STSP | 3 | 2 | 1 | 1 | 0 | 1 | DEGsX10 | -3.276,8 | 3276,7 |
| 34 | 5F8 | ECU_BRK_P | BRKP | 5 | 4 | 1 | 43 | 0 | 0 | barx10 | 0,0 | 152,4 |
| 35 | 5F8 | ECU_CLUCH_P | CLUP | 7 | 6 | 1 | 43 | 0 | 0 | barx10 | 0,0 | 152,4 |
| 36 | 5F9 | ECU_BRK_P_FR | BKFR | 1 | 0 | 1 | 43 | 0 | 0 | barx10 | 0,0 | 152,4 |
| 37 | 5F9 | ECU_BRK_P_FL | BKFL | 3 | 2 | 1 | 43 | 0 | 0 | barx10 | 0,0 | 152,4 |
| 38 | 5F9 | ECU_BRK_P_RR | BKRR | 5 | 4 | 1 | 43 | 0 | 0 | barx10 | 0,0 | 152,4 |
| 39 | 5F9 | ECU_BRK_P_RL | BK_RL | 7 | 6 | 1 | 43 | 0 | 0 | barx10 | 0,0 | 152,4 |
| 40 | 5FA | ECU_ACC_LAT | ACLA | 1 | 0 | 1 | 32 | 0 | 1 | m/s2x100 | 10,24 | -10,23 |
| 41 | 5FA | ECU_ACC_LONG | ACLO | 3 | 2 | 1 | 32 | 0 | 1 | m/s2x100 | 10,24 | -10,23 |
| 42 | 5FA | ECU_GYRO | GYRO | 5 | 4 | 1 | 3 | 0 | 1 | degX100 | -109,2 | 109,23 |
| 43 | 5FA | ECU_GEAR_BOX_T | GBOT | 7 | 6 | 1 | 6 | -450 | 0 | Cx10 | -45,0 | 1047,2 |



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|----|-----|-----------------|------|---|---|---|----|---|---|---------|----------|--------|
| 44 | 5FB | ECU_ENG_TORQ | ETRQ | 1 | 0 | 1 | 1 | 0 | 1 | Nmx10 | -3.276,8 | 3676,7 |
| 45 | 5FB | ECU_SLIP_ANG | SLIP | 3 | 2 | 1 | 65 | 0 | 0 | %x10 | 0,0 | 100,8 |
| 46 | 5FB | ECU_IGN_ANG1 | IGN1 | 5 | 4 | 1 | 3 | 0 | 1 | degX100 | -109,2 | 109,23 |
| 47 | 5FB | ECU_IGN_ANG2 | IGN2 | 7 | 6 | 1 | 3 | 0 | 1 | degX100 | -109,2 | 109,23 |
| 48 | 5FC | ECU_INJ_TIME1 | IJT1 | 1 | 0 | 1 | 1 | 0 | 0 | us | 0 | 65535 |
| 49 | 5FC | ECU_INJ_TIME2 | IJT2 | 3 | 2 | 1 | 1 | 0 | 0 | us | 0 | 65535 |
| 50 | 5FC | ECU_INJ_P1 | IJP1 | 5 | 4 | 1 | 21 | 0 | 0 | BARx10 | 0,0 | 312,0 |
| 51 | 5FC | ECU_INJ_P2 | IJP2 | 7 | 6 | 1 | 21 | 0 | 0 | BARx10 | 0,0 | 312,0 |
| 52 | 5FD | ECU_SPARK_ANG_1 | SAN1 | 1 | 0 | 1 | 3 | 0 | 1 | degX100 | -109,2 | 109,23 |
| 53 | 5FD | ECU_SPARK_ANG_2 | SAN2 | 3 | 2 | 1 | 3 | 0 | 1 | degX100 | -109,2 | 109,23 |
| 54 | 5FD | ECU_SPARK_ADV_1 | SAD1 | 5 | 4 | 1 | 3 | 0 | 1 | degX100 | -109,2 | 109,23 |
| 55 | 5FD | ECU_SPARK_ADV_2 | SAD2 | 7 | 6 | 1 | 3 | 0 | 1 | degX100 | -109,2 | 109,23 |
| 56 | 5FE | ECC_USER01 | US01 | 1 | 0 | 1 | 1 | 0 | 1 | PUROx10 | 0,0 | 6553,5 |
| 57 | 5FE | ECC_USER02 | US02 | 3 | 2 | 1 | 1 | 0 | 1 | PUROx10 | 0,0 | 6553,5 |
| 58 | 5FE | ECC_USER03 | US03 | 5 | 4 | 1 | 1 | 0 | 1 | PUROx10 | 0,0 | 6553,5 |
| 59 | 5FE | ECC_USER04 | US04 | 7 | 6 | 1 | 1 | 0 | 1 | PUROx10 | 0,0 | 6553,5 |
| 60 | 5FF | ECC_USER05 | US05 | 1 | 0 | 1 | 1 | 0 | 1 | PURO | 0 | 65535 |
| 61 | 5FF | ECC_USER06 | US06 | 3 | 2 | 1 | 1 | 0 | 1 | PURO | 0 | 65535 |
| 62 | 5FF | ECC_USER07 | US07 | 5 | 4 | 1 | 1 | 0 | 1 | PURO | 0 | 65535 |
| 63 | 5FF | ECC_USER08 | US08 | 7 | 6 | 1 | 1 | 0 | 1 | PURO | 0 | 65535 |

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AiM Logger configuration

Before connecting the device to the ECU set it up using AiM Race Studio software. The parameters to select in the device configuration are:

- ECU manufacturer: "AIM"
- ECU Model: "CAN "

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Available channels

Channels received by AiM devices connected to "AIM" "CAN" protocol are:

| ID | CHANNEL NAME | FUNCTION |
|--------|---------------|--------------------------|
| ECU_1 | ECU_RPM | RPM |
| ECU_2 | ECU_TPS | Throttle position sensor |
| ECU_3 | ECU_PPS | Pedal position sensor |
| ECU_4 | ECU_VEH_SPD | Vehicle speed |
| ECU_5 | ECU_WS_FR | Front right wheel speed |
| ECU_6 | ECU_WS_FL | Front left wheel speed |
| ECU_7 | ECU_WS_RR | Rear right wheel speed |
| ECU_8 | ECU_WS_RL | Rear left wheel speed |
| ECU_9 | ECU_INT_AIR_T | Intake air temperature |
| ECU_10 | ECU_ENG_T | Engine temperature |
| ECU_11 | ECU_FUEL_T | Fuel temperature |
| ECU_12 | ECU_OIL_T | Oil temperature |
| ECU_13 | ECU_MAN_AIR_P | Manifold air pressure |
| ECU_14 | ECU_BARO | Barometric pressure |
| ECU_15 | ECU_OIL_P | Oil pressure |
| ECU_16 | ECU_FUEL_P | Fuel pressure |



| | | |
|--------|----------------|----------------------------|
| ECU_17 | ECU_BOOST | Boost pressure |
| ECU_18 | ECU_V_BATT | Battery supply |
| ECU_19 | ECU_FUEL_USE | Used fuel |
| ECU_20 | ECU_GEAR | Engage gear |
| ECU_21 | ECU_SHIFT_FLAG | Shift flag |
| ECU_22 | ECU_GEAR_TIME | Gear timing |
| ECU_23 | ECU_THRT_VOLT | Throttle voltage |
| ECU_24 | ECU_FUEL_LEV | Fuel level |
| ECU_25 | ECU_LAMBDA1 | Lambda 1 value |
| ECU_26 | ECU_LAMBDA2 | Lambda 2 value |
| ECU_27 | ECU_LAMB_T1 | Lambda 1 temperature |
| ECU_28 | ECU_LAMB_T2 | Lambda 2 temperature |
| ECU_29 | ECU_LAMB1_ERR | Lambda 1 error |
| ECU_30 | ECU_LAMB2_ERR | Lambda 1 error |
| ECU_31 | ECU_LAMB1_TARG | Lambda 1 target |
| ECU_32 | ECU_LAMB2_TARG | Lambda 2 target |
| ECU_33 | ECU_STEER_POS | Steering position |
| ECU_34 | ECU_STEER_SPD | Steering speed |
| ECU_35 | ECU_BRK_P | Brake pressure |
| ECU_36 | ECU_CLUCH_P | Clutch pressure |
| ECU_37 | ECU_BRK_P_FR | Front right wheel pressure |
| ECU_38 | ECU_BRK_P_FL | Front left wheel pressure |
| ECU_39 | ECU_BRK_P_RR | Rear right wheel pressure |
| ECU_40 | ECU_BRK_P_RL | Rear left wheel pressure |
| ECU_41 | ECU_ACC_LAT | Lateral accelerometer |
| ECU_42 | ECU_ACC_LONG | Longitudinal accelerometer |
| ECU_43 | ECU_GYRO | Gyroscope |
| ECU_44 | ECU_GEAR_BOX_T | Gearbox temperature |
| ECU_45 | ECU_ENG_TORQ | Engine torque |
| ECU_46 | ECU_SLIP_ANG | Slip percentage |
| ECU_47 | ECU_IGN_ANG1 | Ignition angle 1 |
| ECU_48 | ECU_IGN_ANG2 | Ignition angle 2 |



| | | |
|--------|----------------|----------------------|
| ECU_49 | ECU_INJ_TIME1 | Injection time 1 |
| ECU_50 | ECU_INJ_TIME2 | Injection time 2 |
| ECU_51 | ECU_INJ_P1 | Injection pressure 1 |
| ECU_52 | ECU_INJ_P2 | Injection pressure 2 |
| ECU_53 | ECU_SPARK_ANG1 | Spark angle 1 |
| ECU_54 | ECU_SPARK_ANG2 | Spark angle 2 |
| ECU_55 | ECU_SPARK_ADV1 | Spark advance 1 |
| ECU_56 | ECU_SPARK_ADV2 | Spark advance 2 |
| ECU_57 | ECU_USER01 | Custom channel 1 |
| ECU_58 | ECU_USER02 | Custom channel 2 |
| ECU_59 | ECU_USER03 | Custom channel 3 |
| ECU_60 | ECU_USER04 | Custom channel 4 |
| ECU_61 | ECU_USER05 | Custom channel 5 |
| ECU_62 | ECU_USER06 | Custom channel 6 |
| ECU_63 | ECU_USER07 | Custom channel 7 |
| ECU_64 | ECU_USER08 | Custom channel 8 |