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ECE341 – Lab02

## Lab02-Readme

Because I have described in the assembly code (and write down everything I coded in MIPS is too painful, so I think I just show you the code I translated from C++ to MIPS, and you can compare it to my MIPS code and understand it via comments in .asm file and in .cpp file), so I just show you the C++ version of these Search and Sort algorithms. **Note that all of them were written down by me in both C++ and MIPS languages.**

Linear Search:

Binary Search:

```
//This is the implement function, not the interface function. The interface
function is simple so I do not bring it to this document.
int ImplementBinarySearch (int * a, int n, int x, int left, int right) {
    if (left > right) //left > right likes n > (n+1)
        return -1;

    int middle = (left + right) / 2;

    if (a[middle] == x) //If the x value is found
        return middle;
    else if (a[middle] < x) //Search in right-half
        return ImplementBinarySearch (a, n, x, middle + 1, right);
    else //Search in left-half
        return ImplementBinarySearch (a, n, x, left, middle - 1);
}
```

Bubble Sort:

```
//Ascending order version
void BubbleSort (int * a, int n) {
    for (int i = 1 ; i < n ; i++) {
        for (int j = n - 1 ; j >= i ; j--) {
            if (a[j] < a[j-1])
                Swap (a[j], a[j-1]) ; //Swap if decreasing
        }
    }
}
```

Insertion Sort:

```
//Descending order version
void InsertionSort (int * a, int n) {
    for (int i = 1, j ; i < n ; i++) {
        int temp = a[i];
        for (j = i - 1 ; j >= 0 && temp > a[j] ; j--)
            a[j+1] = a[j]; //Shifting forward

        a[j+1] = temp;
    }
}
```

### Divide Positive Negative:

// Used to divide the array A into 2 arrays nega and notnega, where nega keeps the negative numbers, and notnega keeps the non-negative numbers.

```
void DividePositiveNegative (int * a, int n, int * &neg, int & n_neg, int *
&not_neg, int & n_not_neg){

    n_neg = n_not_neg = 0;
    int j = 0, k = 0;
    for (int i = 0; i < n ; ++i) {
        if (a[i] < 0) {
            // If negative => keep in negative array
            neg[j] = a[i];
            ++j;
        }
        else {
            // Otherwise, keep in non-negative array
            not_neg[k] = a[i];
            ++k;
        }
    }
    n_neg = j;
    n_not_neg = k;
}
```

### Merge Sort:

//Strategy for Question 3: I divide array 'arr' into to 'nega' and 'not\_neg', then sort 'nega' with descending merge sort and 'not\_neg' with ascending merge sort. After that, print out 'nega' next to 'not\_neg'.

```
//Ascending and Descending version
void MergeSort(int * a, int n, bool asc) {
    if (n <= 1) return;

    int * b = &a[n / 2];
    //Divide the first half
    MergeSort(a, n / 2, asc);
    int * temp1 = new int[n / 2];
    for (int i = 0; i < n / 2; i++)
        temp1[i] = a[i];
```

//In MIPS code version of mine for Merge sort, I have used stack to backup the content of array temp1, but haven't done the same thing for array temp2, why I have to do that? Because the content of array temp1 is not guaranteed after the 2<sup>nd</sup> recursive call. It maybe replaced by the child call. So, I push the content into stack then recover them immediately after 2<sup>nd</sup> recursive call. But with temp2, I don't have to backup its content, because after the 2<sup>nd</sup> recursive call, we have no recursive call, it means that after some done all linear code below, the current procedure will finish and backtrack to its parent procedure. In the parent one, this child maybe the 1<sup>st</sup> recursion -> it's fine because we haven't need temp2 yet, or this child maybe the 2<sup>nd</sup> recursion -> temp2 will be calculated now.

```
//Divide the second half
MergeSort(b, n - n / 2, asc); //Different from n/2
int * temp2 = new int[n - n / 2];
for (int i = 0; i < n - n / 2; i++)
    temp2[i] = b[i];
```

//All the code below just merges temp1 and temp2 into 1 array with ascending order.

```
int i, j, k;
for (i = 0, j = 0, k = 0; i < n; i++){
```

```

        if (j < n / 2 && k < n - n / 2) {
            if (asc) {
                //Ascending version
                if (temp1[j] < temp2[k]) {
                    a[i] = temp1[j];
                    j++;
                }
                else {
                    a[i] = temp2[k];
                    k++;
                }
            }
            else {
                //Descending version
                if (temp1[j] > temp2[k]) {
                    a[i] = temp1[j];
                    j++;
                }
                else {
                    a[i] = temp2[k];
                    k++;
                }
            }
        }
        else break;
    }

    if (j >= n / 2){
        if (k > j)
            i = k;

        for (; i < n; i++, k++)
            a[i] = temp2[k];
    }
    else if (k >= n - n / 2){
        if (j > k)
            i = j;

        for (; i < n; i++, j++)
            a[i] = temp1[j];
    }

    delete[] temp2, temp1;
}

```

Quick Sort:

```

//Ascending version
void ImplementQuickSort(int * a, int start, int end){
    if (start >= end) //start and end converge
        return;
    int pivot = a[(start + end) / 2];
    int i = start, j = end;

    do {
        while (a[i] < pivot) ++i;
        while (a[j] > pivot) --j;

        if (i <= j) {
            if (i < j)
                Swap(a[i], a[j]);
            i++, j--;
        }
    }
}

```

```

    } while (i <= j);
    ImplementQuickSort(a, start, j);
    ImplementQuickSort(a, i, end);
}

void QuickSort(int * a, int n){
    ImplementQuickSort(a, 0, n - 1);
}

```

### Joint Array Interpose:

```

//Used to join 2 array with interpose order (xen kẽ nhau)
int * JointArrayInterpose (int * a, int na, int * b, int nb){
    int i = 0;
    int j = 0;

    int * c = new int [na + nb];

    for (int k = 0 ; k < na + nb;) {
        if (i < na) {
            c[k] = a[i];
            ++i;
            k++;
        }
        if (k < na + nb && j < nb) {
            c[k] = b[j];
            ++j;
            k++;
        }
    }

    return c;
}

```