



DEPARTMENT OF INFORMATICS ENGINEERING

DEPARTMENT OF COMPUTER SCIENCE

# Functional and Logic Programming

Bachelor in Informatics and Computing Engineering 2021/2022 - 1st Semester

# Prolog

Database Modification, Graphs and Search

# Agenda

- Database Modification
  - Memoization
- Cycles
- Graphs and Search
  - Puzzles and Games

#### **Database Modification**

- Prolog allows clauses to be dynamically added or removed from a program
  - This provides great flexibility
  - However, modifying the program is costly, as it requires re-indexing
- In order to add or remove clauses from a predicate, it first needs to be declared dynamic

:-dynamic male/1, female/2, parent/2.

See section 4.12 of the SICStus Manual for more information

# Adding Clauses

- assert/1 adds a new clause to the program; there are two additional variations of this predicate:
  - assertal 1 the new clause is added before all existing predicate clauses (if any)
  - assertz/1 the new clause is added after all existing predicate clauses (if any)

```
ask_and_add_to_kb:-
    write('Insert Parent-Child to add'),nl,
    read(P-C),
    assert(parent(P, C)).
```

When adding a rule, an additional pair of parentheses is required

# Removing Clauses

- retract/1 removes a clause from the program (the first that matches the given clause)
- retractall/1 retracts all clauses matching the specified head
- abolish/1 removes all clauses and properties of the specified predicate

```
retractall(parent(homer, _)).
abolish(parent/2).
```

```
replace_definition:-
    retract(( ancestor(X,Y):-parent(X,Y) )),
    asserta(( ancestor(X,Y):-father(X,Y) )),
    asserta(( ancestor(X,Y):-mother(X,Y) )).
```

# **Predicate Listing**

- *listing/0* lists all clauses from the currently loaded program
- *listing/1* lists all clauses from a given predicate
- These predicates list the code in the current output stream
  - Note that variable naming and code formatting are not preserved

```
a(X, Y) := b(X), !, b(Y).
a(3, 4).
b(2).
               | ?- listing.
b(3).
               a(A, B) :-
                       b(A), !,
                       b(B).
               a(3, 4).
               b(2).
               b(3).
               yes
               | ?- listing(a/2).
               a(A, B) :-
                       b(A), !,
                       b(B).
               a(3, 4).
               yes
```

# Accessing Clauses

clause(+Head, ?Body)
 allows access to the
 clauses of a given
 predicate in the
 knowledge base

```
a(X, Y):- b(X), !, b(Y).
a(3, 4).
b(2).
b(3).
```

```
| ?- clause( a(X,Y), Body ),
     retract((a(X,Y):-Body)),
    a(A, B),
    asserta((a(X,Y):-Body)).
A = 3
B = 4 ?
yes
| ?- listing(a/2).
a(A, B) :-
       b(A), !,
       b(B).
a(3, 4).
yes
| ?- clause( a(X,Y), Body ), retract(( a(X,Y):-Body )).
Body = (b(X),!,b(Y)) ?
yes
| ?- listing(a/2).
a(3, 4).
yes
```

#### **Database Modification**

- Assert and retract should be used sparingly (ideally only for things that do not change often)
  - They are slow operations
  - It can make programs harder to understand / debug

 The effect of database modification predicates is not undone in backtracking (just like input/output)

#### Memoization

 Modifying the database can be used to save partial results, resulting in a dynamic programming approach

Could we use *assertz* instead?

#### **Database Modification**

 We can also use this approach as an alternative to finding all answers to a query

```
get_all_children(Parent, _Children):-
    assert( children(Parent, []) ),
    fail.

get_all_children(Parent, _Children):-
    parent(Parent, Child),
    retract( children(Parent, Current) ),
    assert( children(Parent, [Child|Current]) ),
    fail.

get_all_children(Parent, Children):-
    retract( children(Parent, Children) ).
```

Why is this approach inefficient?

# Failure Driven Loops

- The example above is a failure driven loop
  - The fail forces Prolog to backtrack until all solutions are found

```
failure_driven_loop:-
    find_solution(X),
    do_something_with_solution(X),
    fail.
failure_driven_loop. %ensure predicate succeeds
```

- Efficient in terms of memory use
- Usually only used in situations when only side effects are important (results are not kept)

# Failure Driven Loops

- Failure driven loops are an alternative to recursive ones
  - Compare the following two approaches to implement a predicate  $print_n(N, C)$ , which prints a character C to the console N times

```
print n(0, C) := !.
print n(N, C):-
      write(C),
      N1 is N-1,
                                        fail.
      print n(N1, C).
```

```
print n(N, C):-
     between(1, N, T),
      write(C),
print n(N, C).
```

Which approach is more efficient?

# Failure Driven Loops

• Another example: consulting a program

```
consult(File):-
      see (File),
      loop,
      seen.
loop:-
      repeat,
      read(Clause),
      process (Clause), !.
process(end of file):- !.
process(Clause):-
      assert (Clause),
      fail.
```

DEI / FEUP

#### Generic Game Program

• A generic game program can be coded with a recursive loop

```
play game:-
      initial state (GameState-Player),
      display game (GameState-Player),
      game cycle(GameState-Player).
game cycle(GameState-Player):-
      game over (GameState, Winner), !,
      congratulate (Winner).
game cycle(GameState-Player):-
      choose move (GameState, Player, Move),
      move (GameState, Move, NewGameState),
      next player (Player, NextPlayer),
      display game (GameState-NextPlayer), !,
      game cycle (NewGameState-NextPlayer).
```

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#### Generic Game Program

```
choose move (GameState, human, Move):-
      % interaction to select move
choose move (GameState, computer-Level, Move):-
      valid moves (GameState, Moves),
      choose move (Level, GameState, Moves, Move).
valid moves(GameState, Moves):-
      findall (Move, move (GameState, Move, NewState), Moves).
choose move(1, GameState, Moves, Move):-
      random select (Move, Moves, Rest).
choose move (2, GameState, Moves, Move):-
      setof(Value-Mv, NewState^( member(Mv, Moves),
              move (GameState, Mv, NewState),
              evaluate board (NewState, Value) ), [ V-Move| ]).
% evaluate board assumes lower value is better
```

# Graphs and Search

- Graphs can be represented as the connections between nodes
  - set of facts representing [directed] edges

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

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# Depth-First Search

 Searching for a possible connection between nodes is made easy by Prolog's standard depth-first search mechanism

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

When does this approach fail?

# Depth-First Search

Adapted solution with an accumulator to avoid loops

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

```
connects_dfs(S, F):-
        connects_dfs(S, F, [S]).

connects_dfs(F, F, _Path).
connects_dfs(S, F, T):-
        connected(S, N),
        not( member(N, T) ),
        connects_dfs(N, F, [N|T]).
```

What would we have to change to *return* the connecting path (route)?

#### Breadth-First Search

• We can also easily create a BFS solution using findall

```
connected(porto, lisbon).
connected(lisbon, madrid).
connected(lisbon, paris).
connected(lisbon, porto).
connected(madrid, paris).
connected(madrid, lisbon).
connected(paris, madrid).
connected(paris, lisbon).
```

```
connects_bfs(S, F):-
    connects_bfs([S], F, [S]).

connects_bfs([F|_], F, _V).
connects_bfs([S|R], F, V):-
    findall(N,
        (connected(S, N),
            not(member(N, V)),
            not(member(N, [S|R]))), L),
    append(R, L, NR),
    connects_bfs(NR, F, [S|V]).
```

What would we have to change to return the connecting path (route)?

#### Games and Puzzles

- Prolog (and search) can easily be used to search for a solution to one-person games or puzzles
- States represented as the nodes of the graph
  - Initial state is the starting node
  - Winning conditions define the final nodes
- Movements represented as the transitions between nodes
  - States don't need to be represented in extension transitions can specify new states based on the previous one and the move made

#### Generic Solver

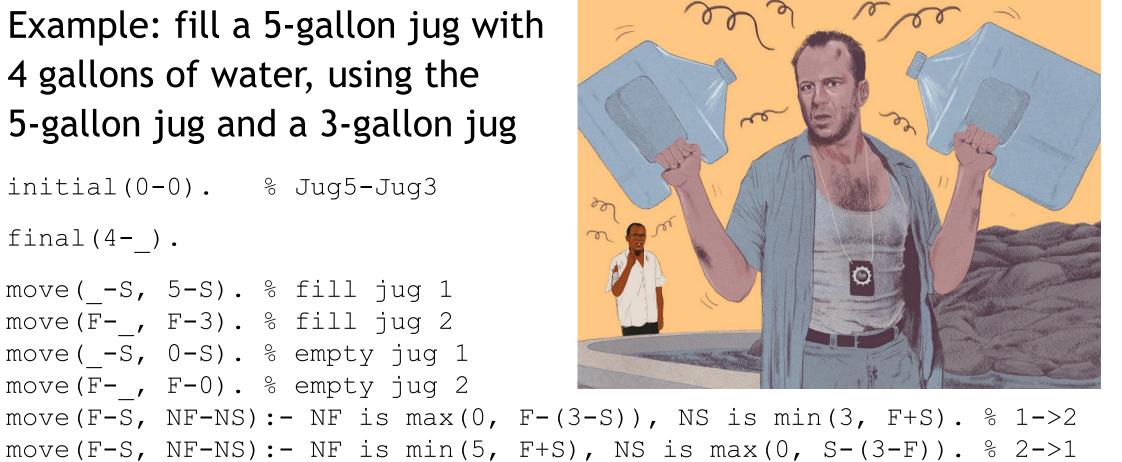
• A generic [abstract] solver to one-person games/puzzles

```
initial (Initial State).
final(State): - winning condition(State).
move (OldState, NewState): - valid move (OldState, NewState).
play:- initial(Init),
         play(Init, [Init], States),
         reverse (States, Path), write (Path).
play(Curr, Path, Path):- final(Curr), !.
play(Curr, Path, States):- move(Curr, Next),
                               not ( member (Next, Path) ),
                               play(Next, [Next|Path], States).
```

#### Games and Puzzles

 Example: fill a 5-gallon jug with 4 gallons of water, using the 5-gallon jug and a 3-gallon jug

```
initial (0-0). % Juq5-Juq3
final(4-).
move(-S, 5-S). % fill jug 1
move (F-, F-3). % fill jug 2
move(-S, 0-S). % empty jug 1
move (F-, F-0). % empty jug 2
```

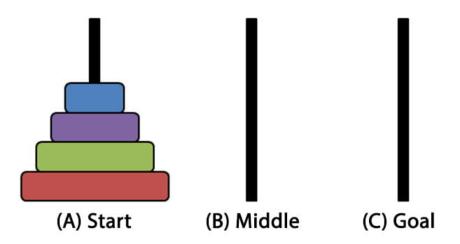


#### **Shortest Path**

- To find the smallest set of plays we just need to find all paths and select the shortest one
  - Easily accomplished using setof

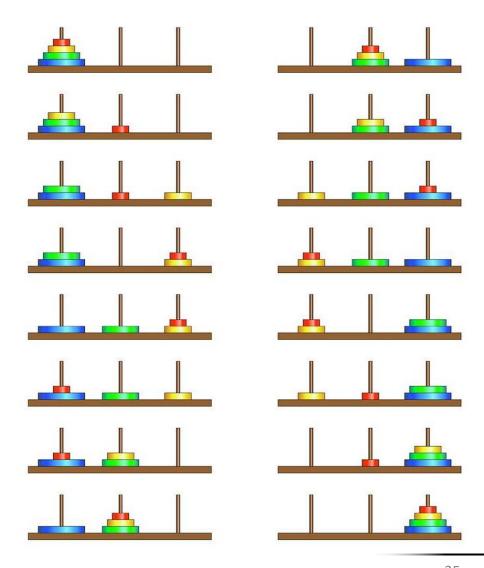
#### Games and Memoization

- Example: Tower of Hanoi
  - Goal: move stack from pole 1 to pole 3
  - Rules:
    - Can only move one disk at a time
    - Disks can only be placed on top of a larger disk

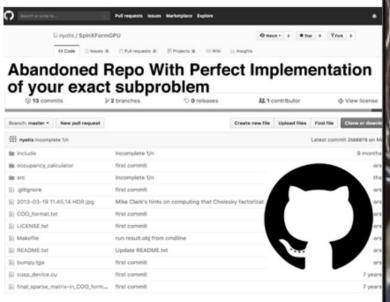


#### Games and Memoization

• To move a stack of size N from pole 1 to pole 3, first move stack of size N-1 to pole 2, move base piece, and then move N-1 stack from pole 2 to pole 3



Q & A



# But it is written in Prolog

