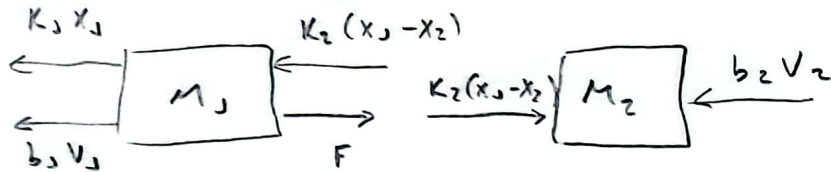


$$\frac{X_2(s)}{F(s)} = ?$$

$$F_k = K X$$

$$F_b = b \dot{x}$$



sem rodas
(trictio)

$$F_1 = M_1 a_1$$

$$M_1 a_1 = F - K_1 x_1 - b_1 v_1 - K_2 (x_1 - x_2)$$

$$M_1 \ddot{x}_1 = F - K_1 x_1 - b_1 \dot{x}_1 - K_2 x_1 + K_2 x_2$$

$$M_1 s^2 X_1(s) =$$

$$F(s) - K_1 X_1(s) - b_1 s X_1(s) - K_2 X_1(s) + K_2 X_2(s)$$

$$(M_1 s^2 + b_1 s + (K_1 + K_2)) X_1(s) - K_2 X_2(s) = F(s)$$

$$X_2 \frac{(M_1 s^2 + b_1 s + (K_1 + K_2))(M_2 s^2 + b_2 s + K_2) - K_2^2}{K_2} = F$$

$$X_2 \left(\frac{(M_1 s^2 + b_1 s + K_2 + K_1)(M_2 s^2 + b_2 s + K_2) - K_2^2}{K_2} \right) = F$$

$$\frac{X_2(s)}{F(s)} = \frac{K_2}{(M_1 s^2 + b_1 s + (K_1 + K_2))(M_2 s^2 + b_2 s + K_2) - K_2^2}$$

$$F_2 = M_2 a_2$$

$$M_2 a_2 = K_2 (x_1 - x_2) - b_2 v_2$$

$$M_2 \ddot{x}_2 = K_2 x_1 - K_2 x_2 - b_2 \dot{x}_2$$

$$K_2 x_1 = M_2 \ddot{x}_2 + b_2 \dot{x}_2 + K_2 x_2$$

$$x_1 = \frac{M_2 \ddot{x}_2}{K_2} + \frac{b_2 \dot{x}_2}{K_2} + \frac{K_2 x_2}{K_2}$$

$$X_1(s) = \frac{X_2(s) (M_2 s^2 + b_2 s + K_2)}{K_2}$$