Exercise 3 - Deep Learning

Machine Learning

2020/2021 | Technische Universität Wien

Grupo 06

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Datasets

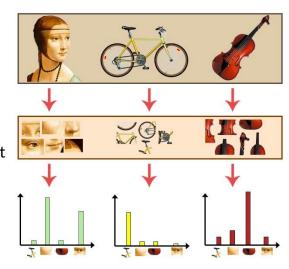
- CIFAR-10 is a data set that consists of 60,000 32x32 colour images divided in 10 classes (e.g. dog, frog, truck, airplane), with 6,000 images per class. There are 50,000 training images and 10,000 test images.
- **Fashion MNIST** is a data set of Zalando's article images consisting of a training set of 60,000 examples and a test set of 10,000 examples. Each example is a 28x28 **grey-scale image**, associated with a label from 10 classes (e.g. coat, shirt).

Bag of Virtual Words (BoVW)- SIFT Based

SIFT (Scale Invariant Feature Detection) is a fast and efficient algorithm to find keypoints (and descriptors) for a given image. The algorithm uses only a <u>monochrome</u> intensity image.

Create a BoVW system:

- Compute the features (SIFT descriptors) for each image from the training set
- Cluster the feature with K-Means
- Create the histograms for each image in the training/test (based on cluster and SIFT)
- Create the model (MLP, KNN ..)
- Fit the model



SIFT based results

Dataset	Classifier	Accuracy	Precision	Recall	Time (s)
	SVM	0.287	0.28	0.29	862
CIFAR 10	K-Nearest Neighbors	0.180	0.18	0.18	107
CIFAR 10	Decision Tree	0.173	0.17	0.17	2.5
	Multi Layer Perceptron	0.255	0.25	0.25	388
	SVM	0.664	0.66	0.66	3600
MNIST	K-Nearest Neighbor	0.476	0.50	0.48	726
MNISI	Decision Tree	0.590	0.58	0.58	206
	Multi Layer Perceptron	0.609	0.61	0.61	919

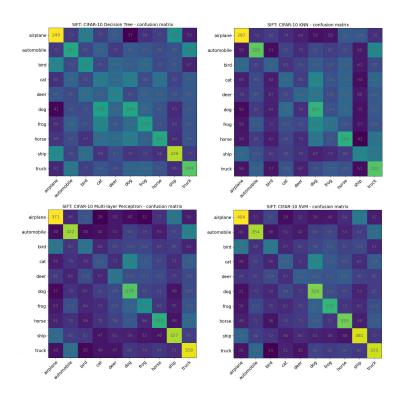
Table 3.1: Classifiers' performance for the two data sets.

Data set	Extraction	Clustering	Train Hist	Test Hist	Overall (s)
CIFAR 10	47	42	357	76	522
MNIST	57	57	295	60	469

- Bad performance over CIFAR-10 probably for the presence of background or too much differences in the classes.
- Reasonable performance for MNIST probably because the images are more "static" (e.g. same view for all the images)
- SVM performed better on both datasets (but very high running time), followed by MLP.
- Running time: BoVW system not too much "expensive". Approximately 10 minutes of computation for both datasets.

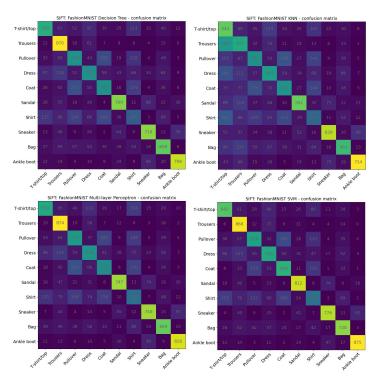
Confusion Matrix - CIFAR-10

- All the matrices have a common pattern. The most confused classes were Bird, Cat and Deer:
 - Cat was confused with Dog
 - Bird was confused with Airplane
- Reasonable performance with the remaining classes



Confusion Matrix - MNIST

- The BoVW system perform well on Fashion MNIST dataset
- All the classes with a good number of True Positives
- Common error over "Shirt" class:
 - Often confused with similar clothes as Coat, Pullover or T-Shirt



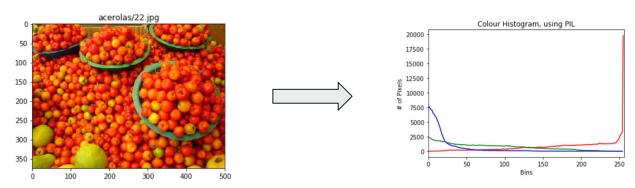
Color Histogram based approach - Theory

Color Histograms were calculated according to the provided script.

Idea: Calculate the frequency of use for each color in each image.

Improvement: Combining the three color channels and calculating frequencies of all possible combinations of the three color values for each pixel.

(i.e. frequency of red having value A, green having value B and blue having value C in each pixel, where A,B,C \in [0,256], for all possible combinations of values for A, B and C)



Example images taken from provided script

Color Histogram based approach - Results

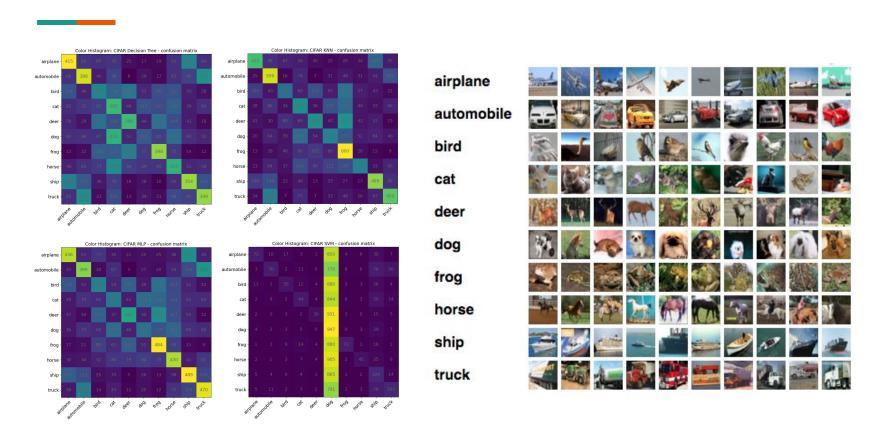
Dataset	Classifier	Accuracy	Recall	Time (s)
	SVM	0.52	0.16	8199
CIFAR 10	K-Nearest Neighbors	0.40	0.39	577
CIFAR 10	Decision Tree	0.30	0.30	4
	Multi Layer Perceptron	0.30 0.35 0.56	0.36	177
	SVM	0.56	0.57	3053
MNIST	K-Nearest Neighbor	0.54	0.51	347
WINISI	Decision Tree	0.46	0.46	6
	Multi Layer Perceptron	0.54	0.56	306

For CIFAR-10 the predictions mediocre, however a little better than our SIFT results for this data set

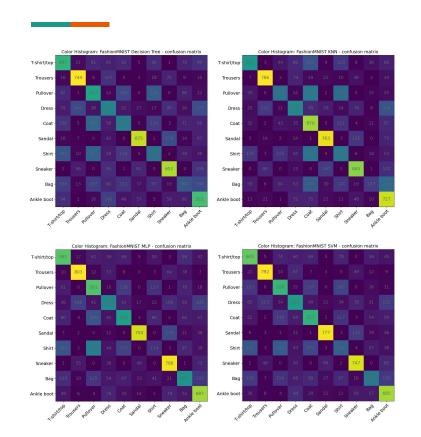
For FashionMNIST the results were better despite only having one color channel, SIFT was better however.

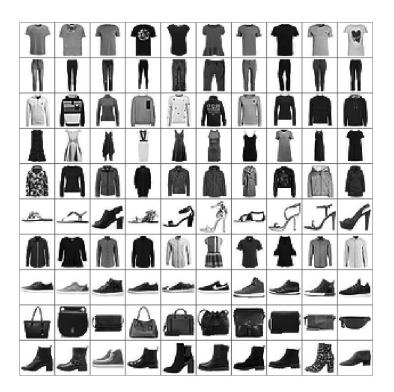
→ Still surprisingly good results for such a simple and quick to compute descriptor

Color Histogram based approach - Confusion Matrix - CIFAR-10



Color Histogram based approach - Confusion Matrix - FashionMNIST





Convolutional Neural Networks

Architectures

Simple:

- Convolution. Input = 28x28x1.
- SubSampling (Max Pooling).
- Dropout.
- Fully Connected #1. Output = 128.
- Output 10.

Lenet5:

- Convolution #1. Input = 28x28x1.
- SubSampling (Max Pooling) #1.
- Convolution #2.
- SubSampling (Max Pooling) #2.
- Fully Connected #1. Output = 256.
- Fully Connected #2. Output = 84.
- Output 10.

Plus:

- Convolution #1. Input = 28x28x1.
- SubSampling (Max Pooling) #1.
- Batch Normalisation #1.
- Convolution #2.
- SubSampling (Max Pooling) #2.
- Batch Normalisation #2.
- Dropout #1.
- Fully Connected #1. Output = 128.
- Dropout #2.
- Fully Connected #2. Output = 50.
- Output 10.

Plusplus:

- Convolution #1. Input = 28x28x1.
- Convolution #2.
- SubSampling (Max Pooling) #1.
- Batch Normalisation #1.
- Dropout #1.
- Convolution #3.
- Convolution #4.
- SubSampling (Max Pooling) #2.
- Batch Normalisation #2.
- Dropout #2.
- Convolution #5.
- Convolution #6.
- SubSampling (Max Pooling) #3.
- Batch Normalisation #3.
- Dropout #3.
- Fully Connected #1. Output = 512.
- Dropout #2.
- Output 10.

FashionMNIST - Learning

Architecture	Data Augmentation	Accuracy	Loss	Processing Time
MLP	No	88.46%	0.333	74.88 s
CNN - Simple	No	91.82%	0.266	439.44 s (~7 min)
CNN - Simple	Yes	81.72%	0.489	646.90 s (~11 min)
CNN - Lenet5	No	91.69%	0.319	1046.09 s (~17 min)
CNN - Plus	No	91.58%	0.237	730.83 s (~12 min)
CNN - Plus Plus	No	92.70%	0.205	2573.60 s (~42 min)

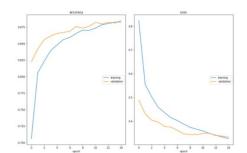


Figure 5.1: Evolution of Accuracy and Loss in FashionMNIST using MLPs

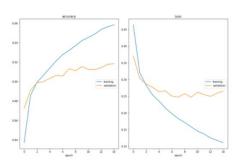


Figure 5.2: Evolution of Accuracy and Loss in Fashion MNIST using CNNs (architecture - simple) $\,$

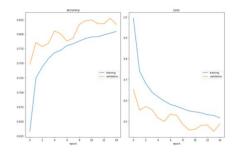


Figure 5.3: Evolution of Accuracy and Loss in Fashion MNIST using CNNs and applying Data Augmentation (architecture - simple)

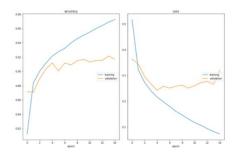


Figure 5.4: Evolution of Accuracy and Loss in Fashion MNIST using CNNs (architecture - Lenet5)

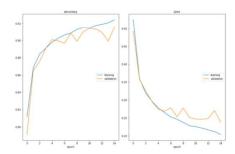


Figure 5.5: Evolution of Accuracy and Loss in Fashion MNIST using CNNs (architecture - plus)

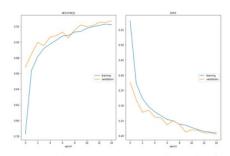


Figure 5.6: Evolution of Accuracy and Loss in Fashion MNIST using CNNs (architecture - plus plus) $\,$

CIFAR-10 - Learning

Architecture	Data Augmentation	Accuracy	Loss	Processing Time
MLP (greyscale)	No	37.15%	1.786	88.15 s
CNN - Simple	No	70.07%	0.895	2094.20 s (~35 min)
CNN - Simple	Yes	60.66%	1.097	2059.43 s (~34 min)
CNN - Lenet5	No	67.80%	1.058	1083.34 s (~18 min)
CNN - Plus	No	77.46%	0.746	3297.38 s (~54 min)
CNN - Plus Plus	No	79.29%	0.613	4035.80 s (~67 min)

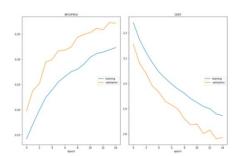


Figure 5.7: Evolution of Accuracy and Loss in CIFAR using MLPs

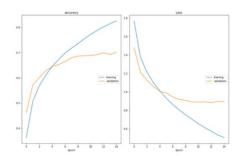


Figure 5.8: Evolution of Accuracy and Loss in CIFAR using CNNs (architecture - simple)

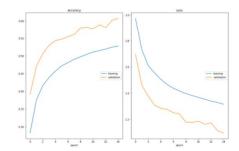


Figure 5.9: Evolution of Accuracy and Loss in CIFAR using CNNs and applying Data Augmentation (architecture - simple)

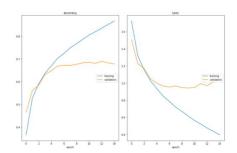


Figure 5.10: Evolution of Accuracy and Loss in CIFAR using CNNs (architecture - Lenet5)

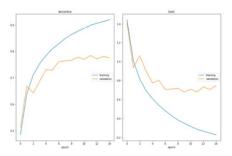


Figure 5.11: Evolution of Accuracy and Loss in CIFAR using CNNs (architecture - plus)

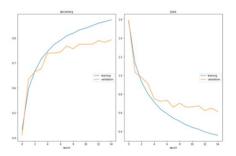
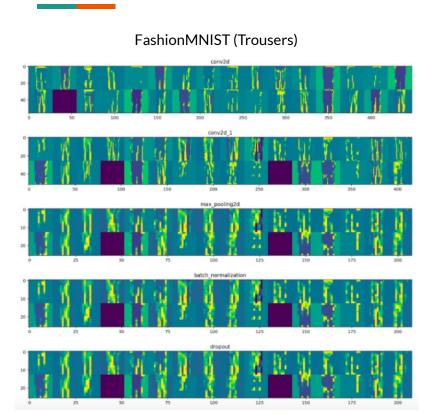
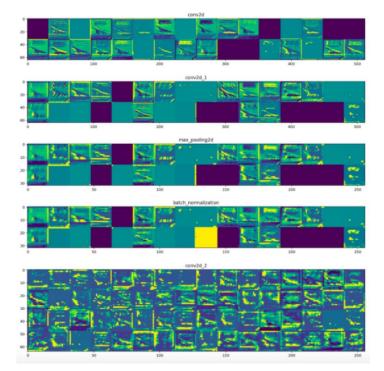


Figure 5.12: Evolution of Accuracy and Loss in CIFAR using CNNs (architecture - plus plus)

Featuremaps Visualization



CIFAR-10 (Frog)



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Q&A

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