

CAUSAL THINKING

Linking scientific and statistical models

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WHAT ARE MODELS FOR?

PREDICTION VS CAUSAL INFERENCE

CORRELATION AND CAUSATION

Why does correlation not imply causation?

GRAPH MODEL REPRESENTATION

- We can use graphs to represent our putative causal model.
- An arrow between variables represents a potential causal effect.



This is a Directed Acyclic Graph, a **DAG**

ELEMENTAL TRIADS

- All DAGs can be decomposed into a set of 3 elemental motifs:
 - The pipe, the fork and the collider
- We can use these to structure our thinking about our models and decide what variable to include or exclude

The pipe:



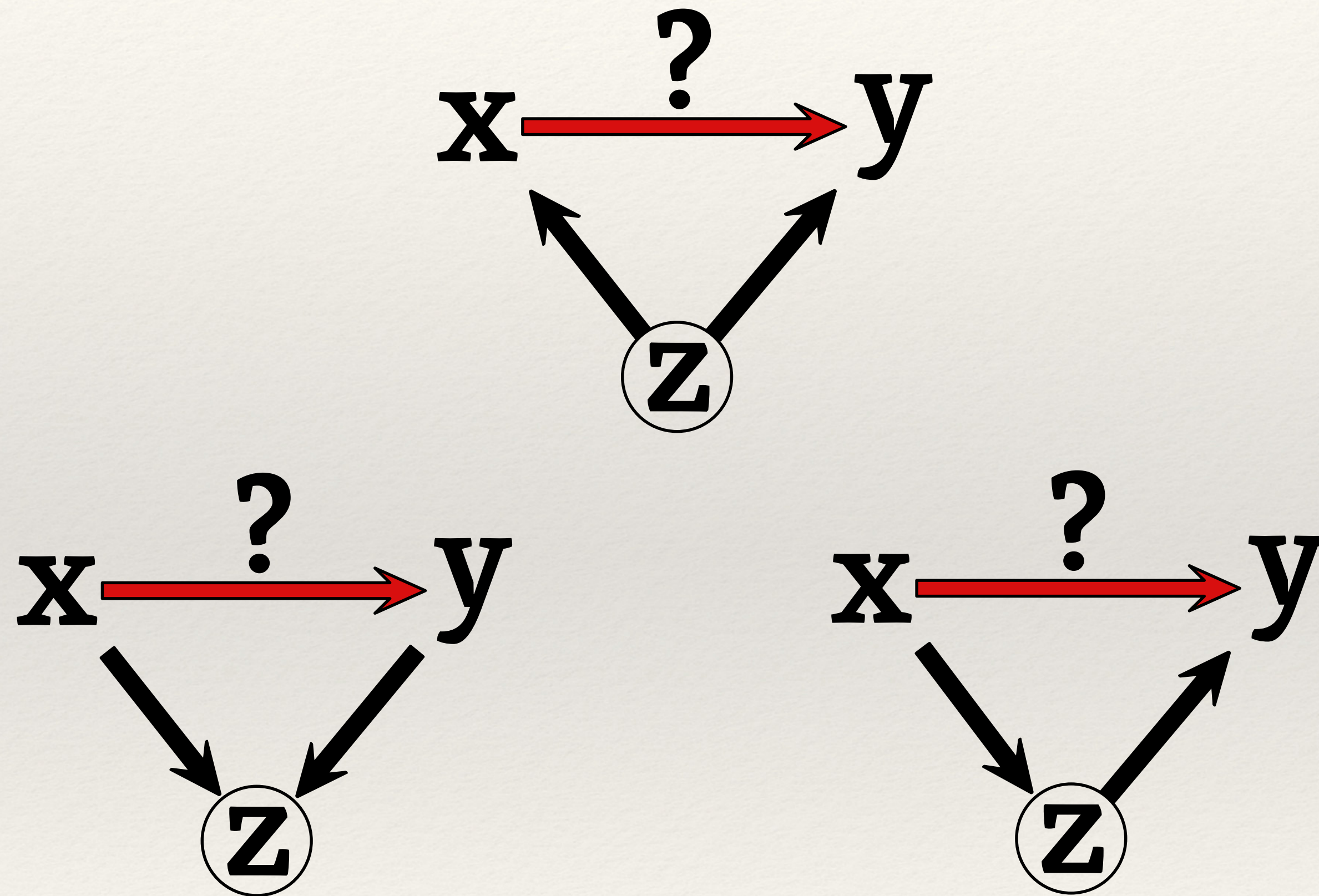
The fork:



The collider:



HOW DOES A CONFOUNDER AFFECT OUR ESTIMATE OF THE EFFECT OF X ON Y?



THE FORK

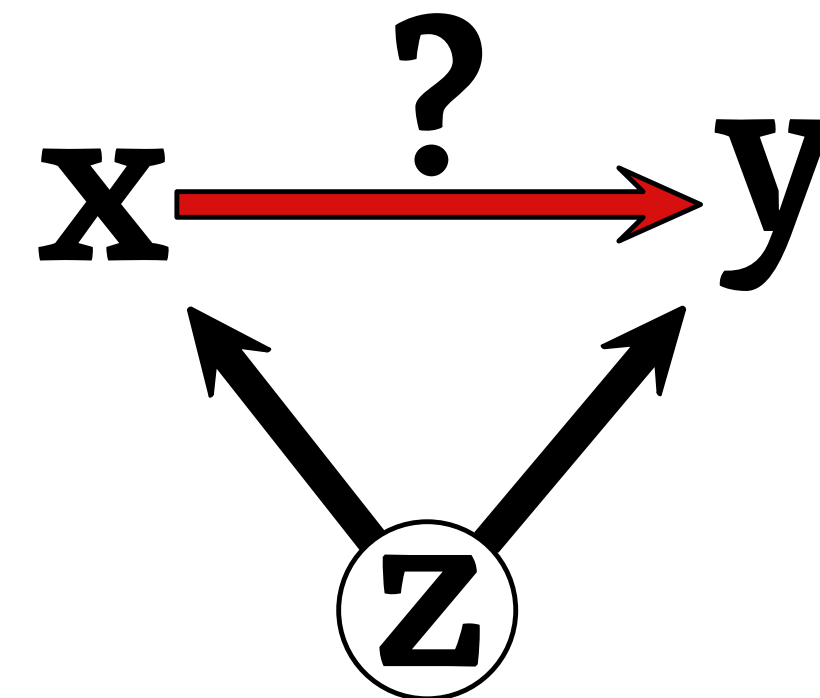
SIMULATING THE EFFECT OF A FORK

- Every DAG implies a causal relation between variables.
- We can use distributions to simulate the generative model implied by this DAG:

$$y \sim \text{Normal}(\alpha_y + \beta_{yx}x + \beta_{yz}z, \sigma_y)$$

$$x \sim \text{Normal}(\alpha_x + \beta_{xz}z, \sigma_x)$$

$$z \sim \text{Normal}(\alpha_z, \sigma_z)$$



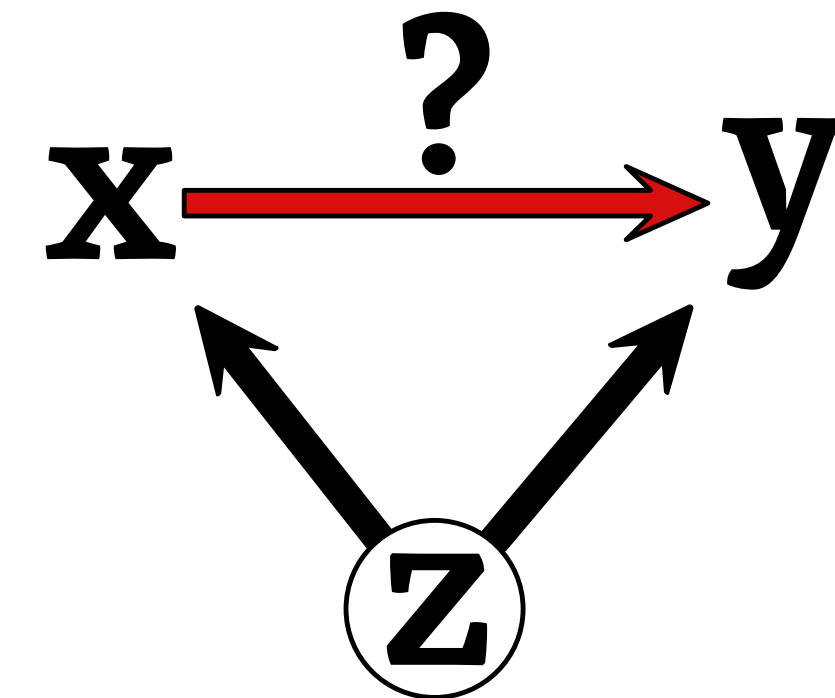
SIMULATING THE EFFECT OF A FORK

Math

$$y \sim \text{Normal}(\alpha_y + \beta_{yx}x + \beta_{yz}z, \sigma_y)$$

$$x \sim \text{Normal}(\alpha_x + \beta_{xz}z, \sigma_x)$$

$$z \sim \text{Normal}(\alpha_z, \sigma_z)$$



R Code

```
N = 100
z = rnorm(N)           # z ~ normal(0, 1)
x = rnorm(N, 1 + z)    # x ~ normal(1 + z, 1)
y = rnorm(N, 1 + x + z) # y ~ normal(1 + x + z, 1)
```


STATISTICAL MODEL WITHOUT THE CONFOUNDER Z

Math

$X \longrightarrow y$

$$y \sim \text{Normal}(\mu, \sigma)$$

$$\mu = a + bx$$

$$a \sim \text{Normal}(0, 0.3)$$

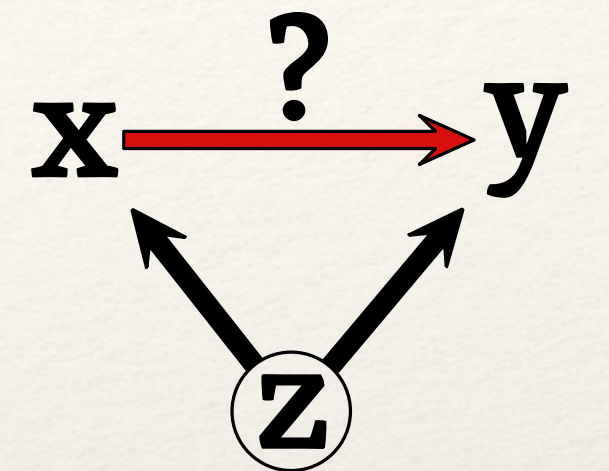
$$b \sim \text{Normal}(0, 0.3)$$

$$\sigma \sim \text{Exponential}(1)$$

Rethinking Code

$X \longrightarrow y$

```
m1 = ulam(alist(  
  y ~ normal(mu, sigma),  
  mu = a + bx*x,  
  a ~ normal(0, 0.3),  
  bx ~ normal(0, 0.3),  
  sigma ~ exponential(1)  
) , data = list(y = y, x = x))
```



MODEL ESTIMATES WITHOUT THE CONFOUNDER

```
> precis(m1)
```

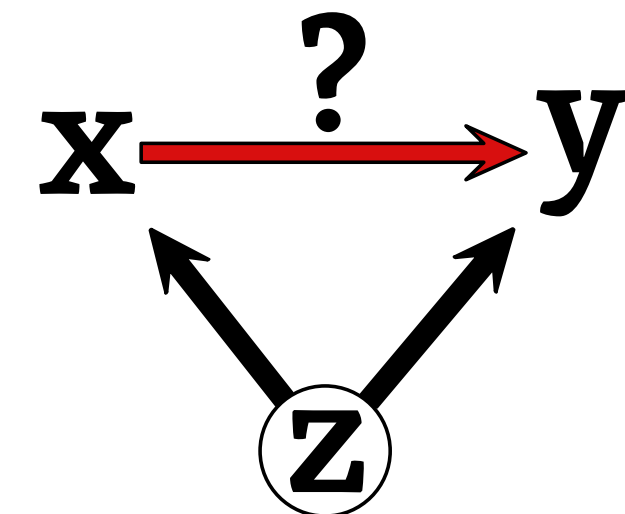
	mean	sd	5.5%	94.5%	n_eff	Rhat4
a	0.54	0.14	0.32	0.77	1274	1
bx	1.47	0.08	1.34	1.60	1432	1
sigma	1.53	0.10	1.19	1.49	1418	1

$X \longrightarrow y$

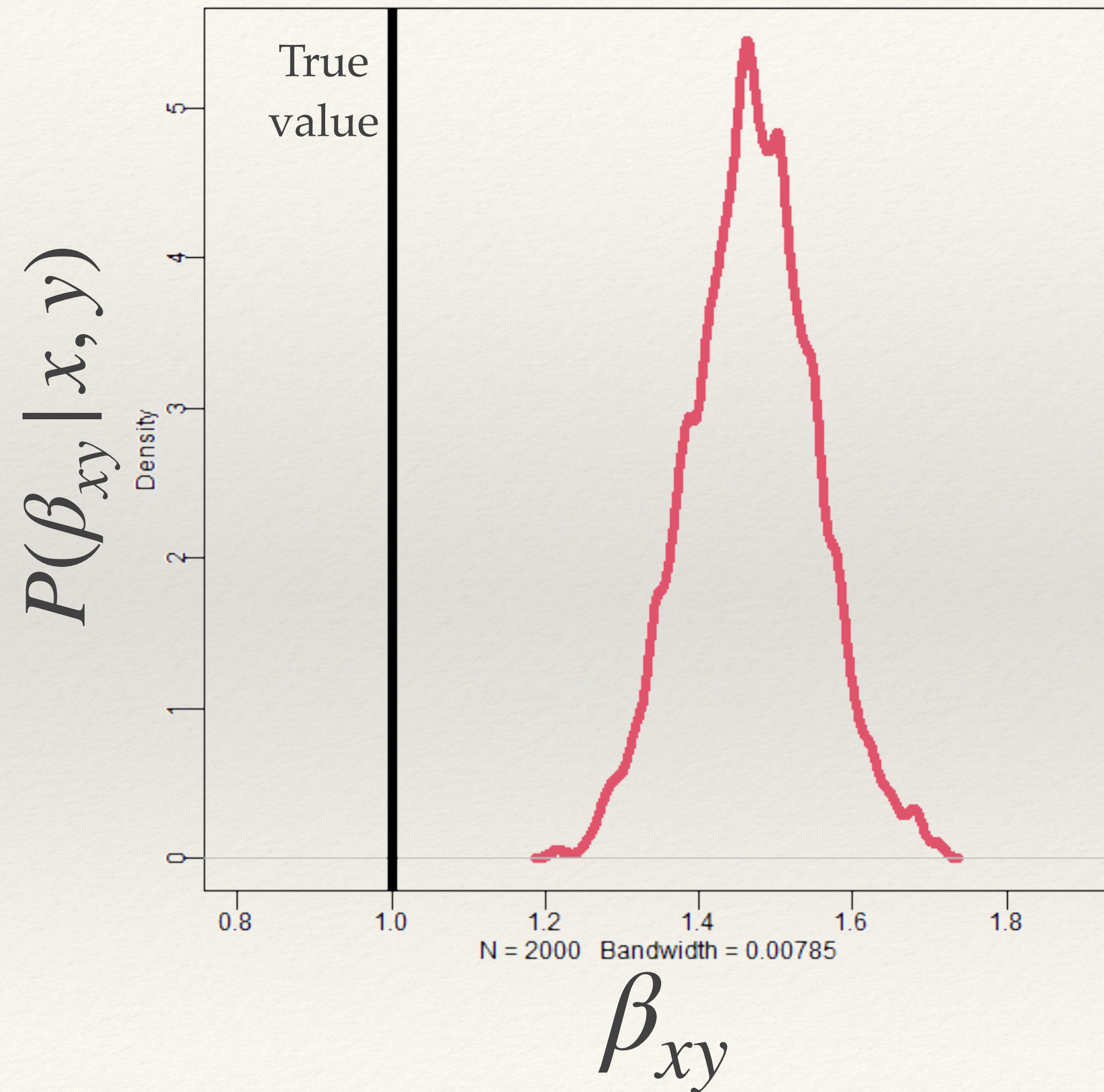
Estimate of the effect of x on y

Simulation R code

```
N = 100
z = rnorm(N) # z ~ normal(0, 1)
x = rnorm(N, 1 + z) # x ~ normal(1 + z, 1)
y = rnorm(N, 1 + x - z) # y ~ normal(1 + x + z, 1)
```



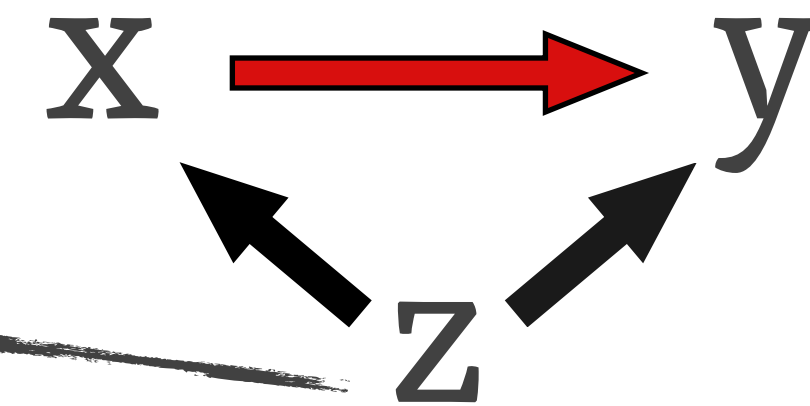
POSTERIOR DISTRIBUTION OF β_{xy} WITHOUT THE CONFOUNDER



$x \rightarrow y$

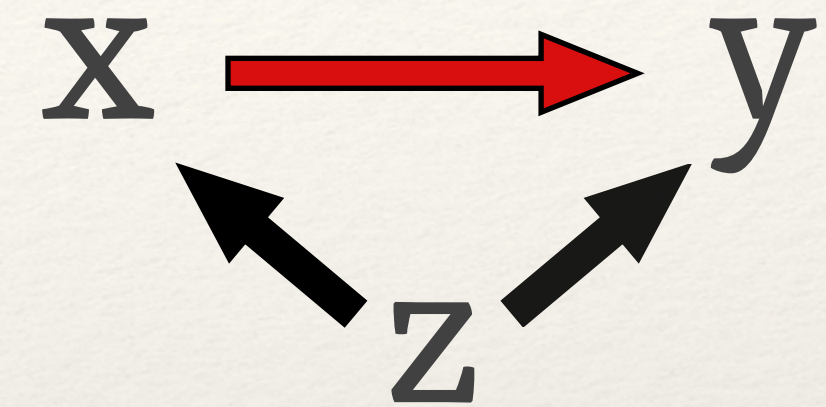
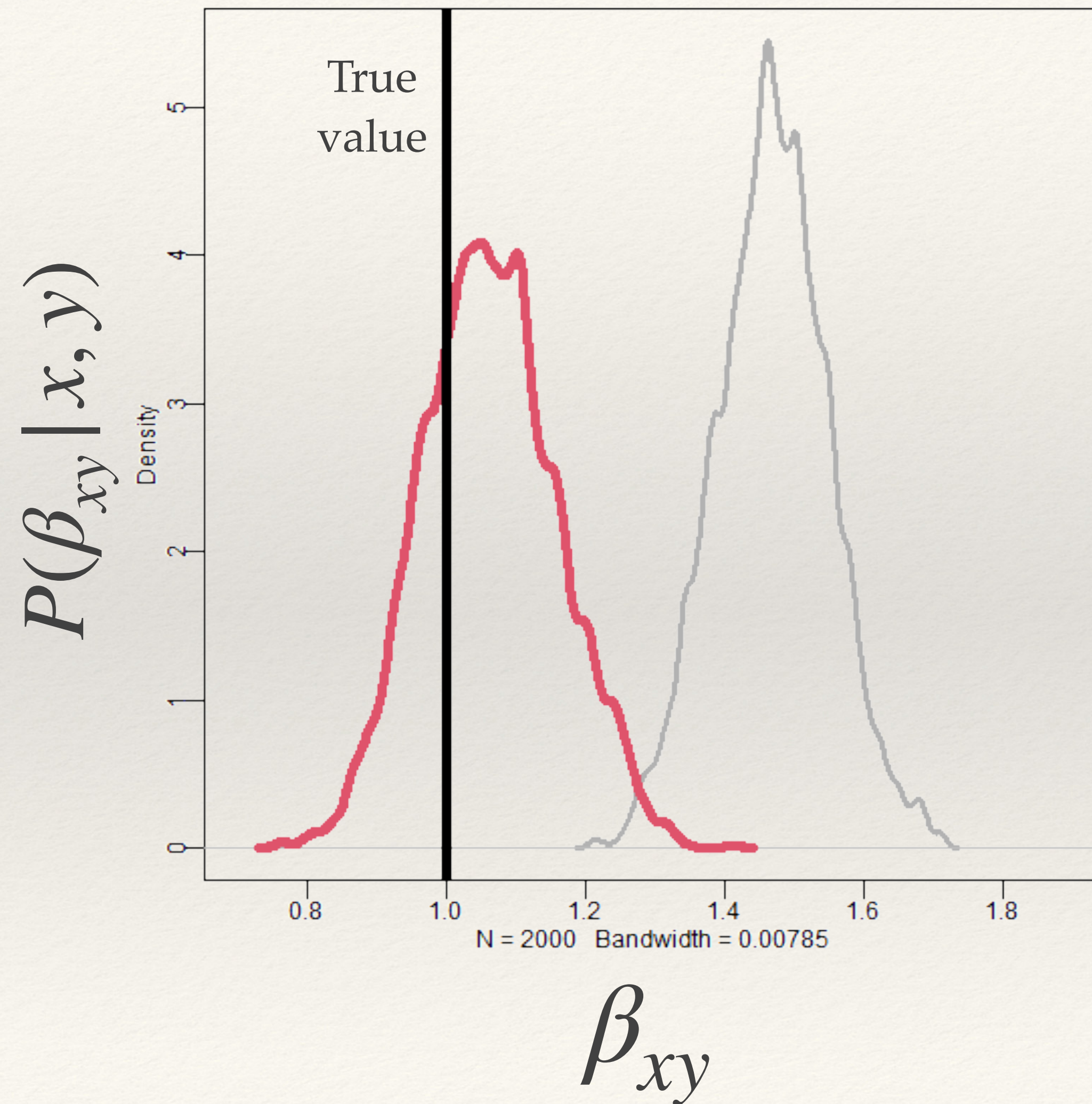
INCLUDING THE CONFOUNDER

```
m2 = ulam(alist(  
  y ~ normal(a + bx*x + bz*z, sigma),  
  a ~ normal(0, 0.3),  
  bx ~ normal(0, 0.3),  
  bz ~ normal(0, 0.3), # New parameter for confounder  
  sigma ~ exponential(1)  
, data = list(y = y, x = x, z = z))  
> precis(m2)
```



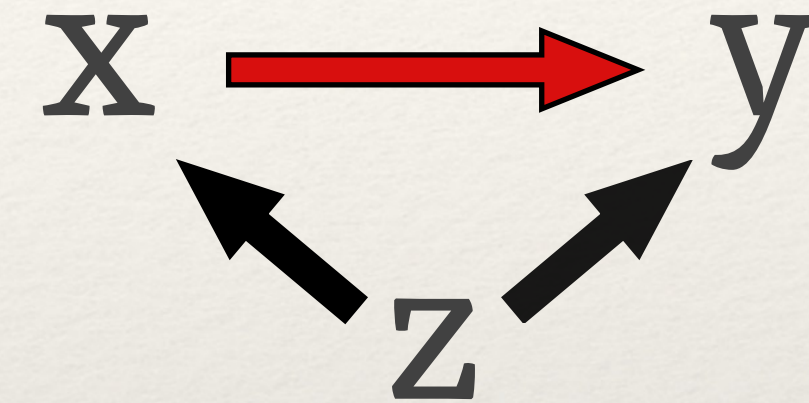
	mean	sd	5.5%	94.5%	n_eff	Rhat4
a	0.95	0.14	0.72	1.17	942	1
bx	1.06	0.10	0.91	1.22	837	1
bz	0.82	0.12	0.62	1.02	889	1
sigma	1.09	0.08	0.97	1.22	1200	1

POSTERIOR DISTRIBUTION OF β_{xy} WITH THE CONFOUNDER



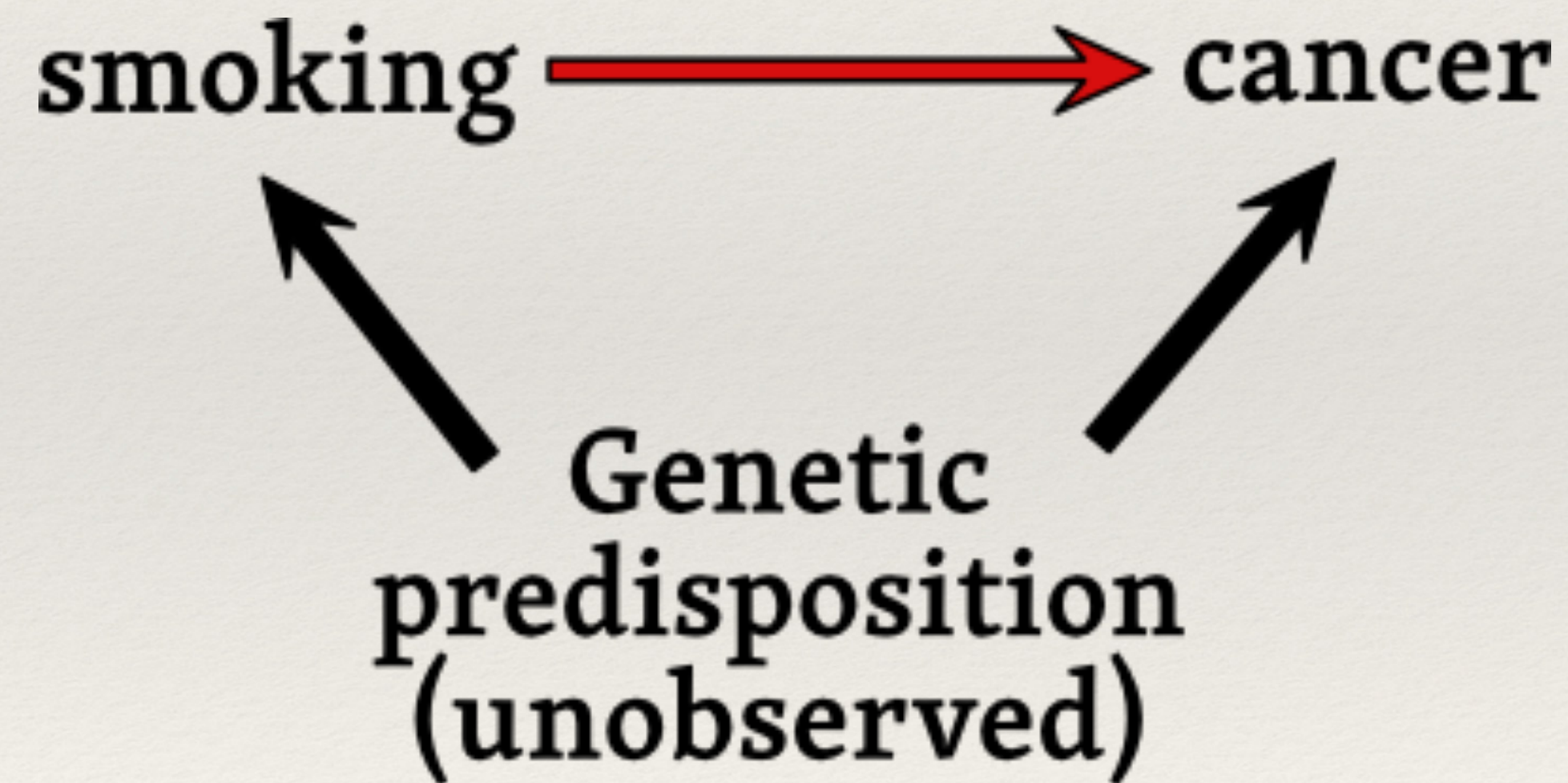
EXAMPLES OF FORKS OR CONFOUNDERS

- This is the quintessential “control” variable.
- Most variables are included in the model under the assumption that they are confounders and need have their effects taken into consideration.



SMOKING AND CANCER

Famously, R. A. Fisher was not convinced that smoking caused cancer, and proposed that an unobserved propensity variable caused both cancer and smoking



OMITTED VARIABLE BIAS

Making sense of sensitivity: extending omitted variable bias

Carlos Cinelli and Chad Hazlett

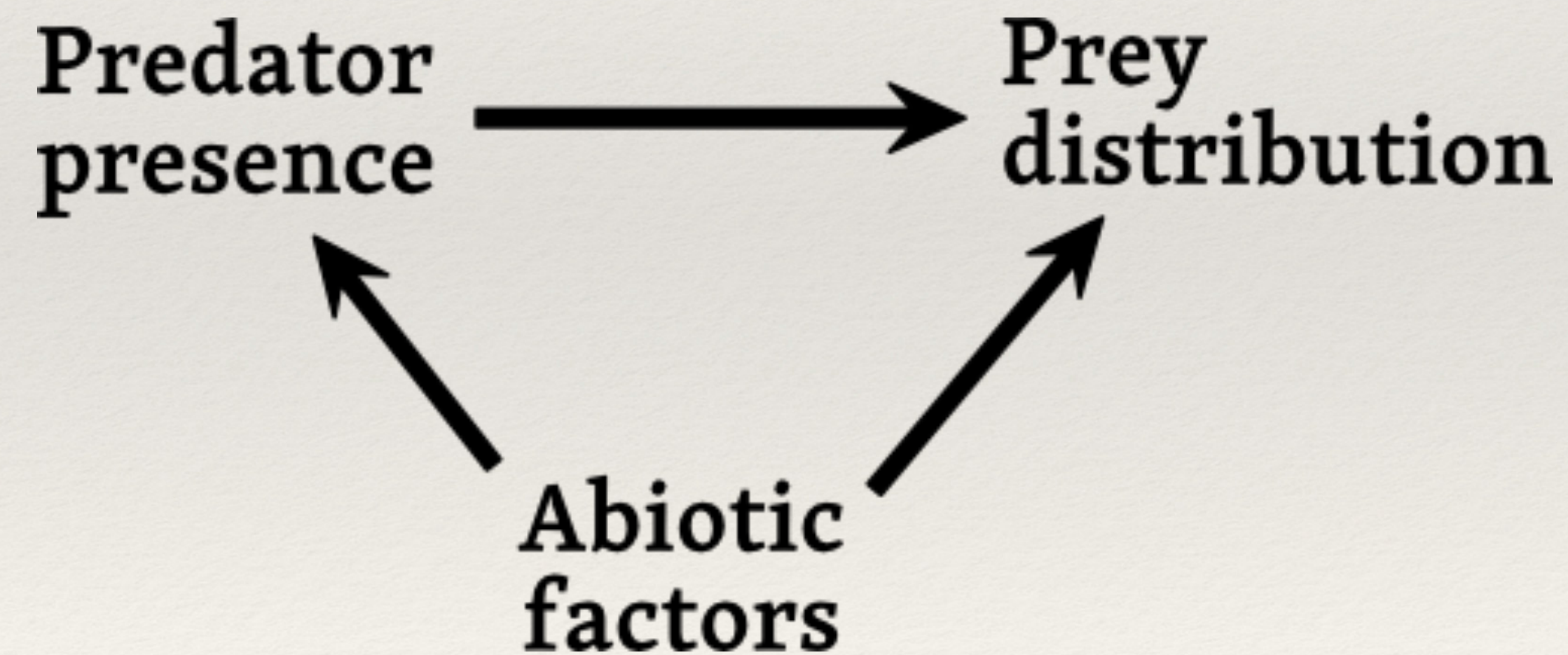
University of California, Los Angeles, USA

[Received August 2018. Final revision October 2019]

Summary. We extend the omitted variable bias framework with a suite of tools for sensitivity analysis in regression models that does not require assumptions on the functional form of the treatment assignment mechanism nor on the distribution of the unobserved confounders, naturally handles multiple confounders, possibly acting non-linearly, exploits expert knowledge to bound sensitivity parameters and can be easily computed by using only standard regression results. In particular, we introduce two novel sensitivity measures suited for routine reporting. The robustness value describes the minimum strength of association that unobserved confounding would need to have, both with the treatment and with the outcome, to change the research conclusions. The partial R^2 of the treatment with the outcome shows how strongly confounders explaining all the residual outcome variation would have to be associated with the treatment to eliminate the estimated effect. Next, we offer graphical tools for elaborating on problematic confounders, examining the sensitivity of point estimates and t -values, as well as ‘extreme scenarios’. Finally, we describe problems with a common ‘benchmarking’ practice and introduce a novel procedure to bound the strength of confounders formally on the basis of a comparison with observed covariates. We apply these methods to a running example that estimates the effect of exposure to violence on attitudes toward peace.

SPECIES DISTRIBUTION

Maybe want to evaluate the effect of some predator on the distribution of a prey. But the spacial distribution of both the predator and the prey are affected by some abiotic factor:



PIPE

ALL THE EFFECT OF X ON Y IS MEDIATED BY Z

X



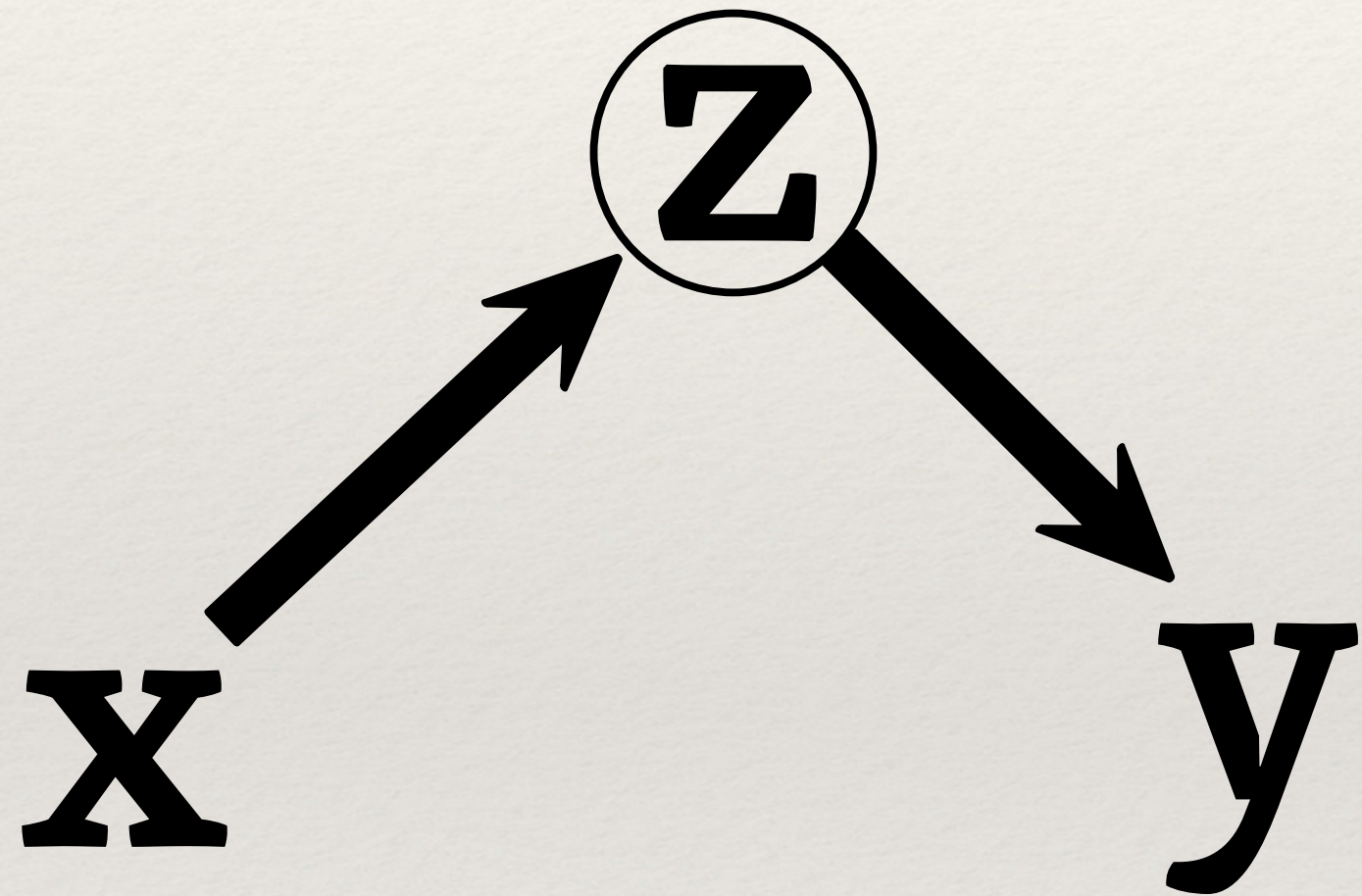
Math

$$y \sim \text{Normal}(\alpha_y + \beta_{yz}z, \sigma_y)$$

$$z \sim \text{Normal}(\alpha_z + \beta_{zx}x, \sigma_z)$$

$$x \sim \text{Normal}(\alpha_x, \sigma_x)$$

MODEL WITHOUT THE MEDIATOR

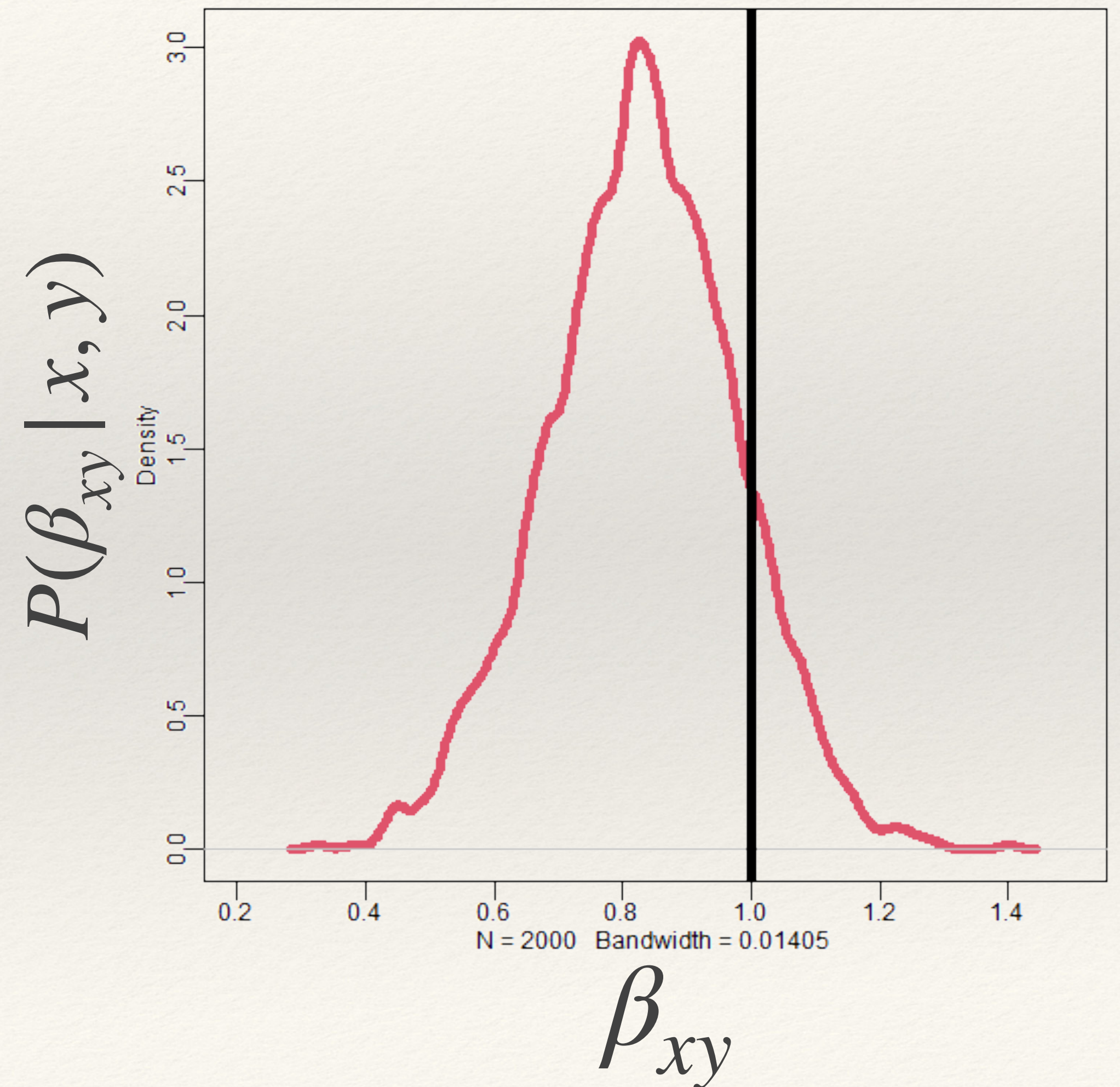


```
set.seed(1)
N = 100
x = rnorm(N)           # x ~ normal(0, 1)
z = rnorm(N, 1 + x)    # z ~ normal(1 + x, 1)
y = rnorm(N, 1 + z)    # y ~ normal(1 + z, 1)

m1 = ulam(alist(
  y ~ normal(a + bx*x, sigma),
  a ~ normal(0, 0.3),
  bx ~ normal(0, 0.3),
  sigma ~ exponential(1)),
  data = list(y = y, x = x),
  iter = 1000, chains = 4, cores = 4)
```

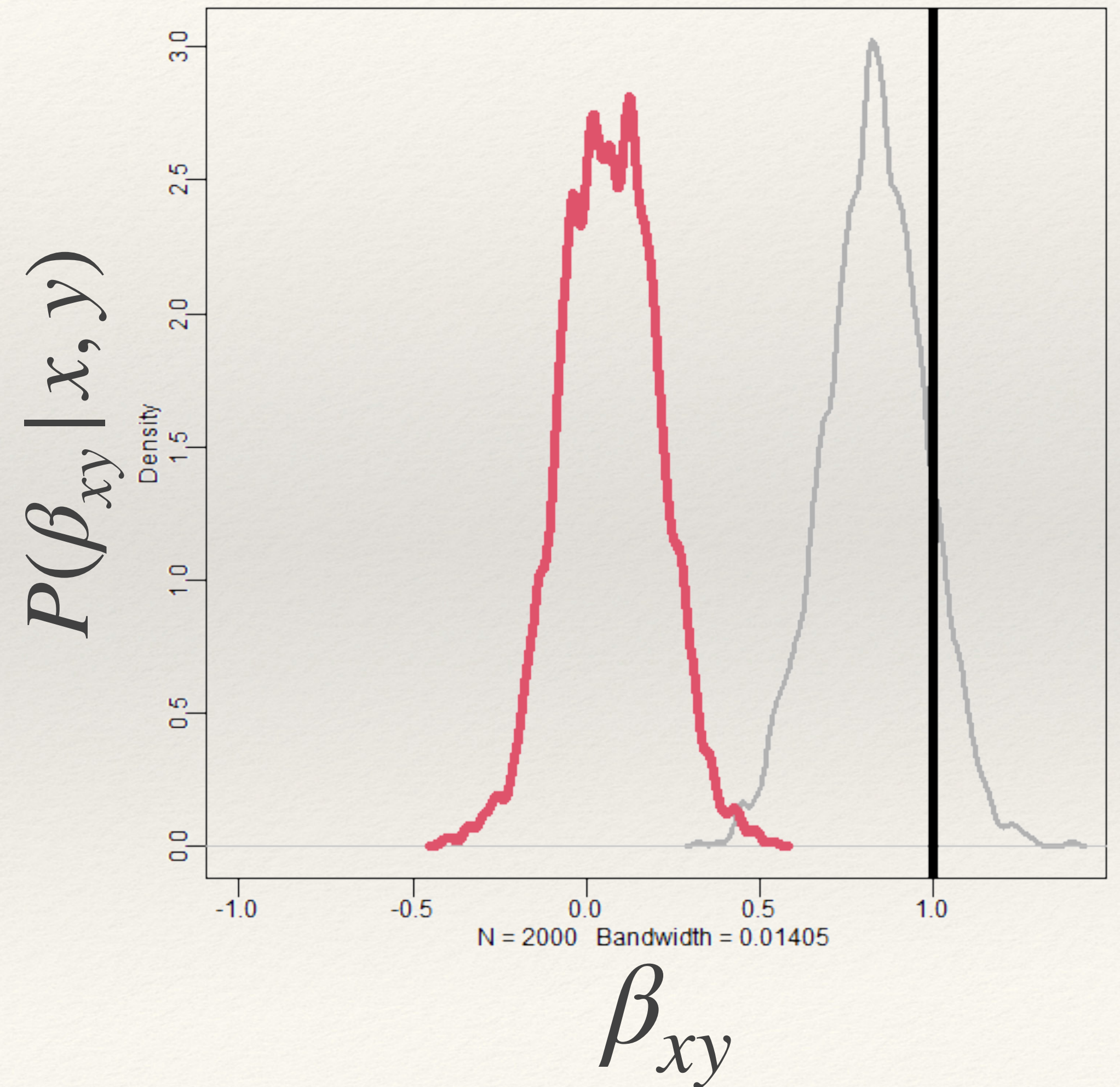

MODEL WITHOUT THE MEDIATOR

```
m1 = ulam(alist(  
  y ~ normal(a + bx*x, sigma),  
  a ~ normal(0, 0.3),  
  bx ~ normal(0, 0.3),  
  sigma ~ exponential(1)),  
  data = list(y = y, x = x),  
  iter = 1000, chains = 4, cores = 4)
```

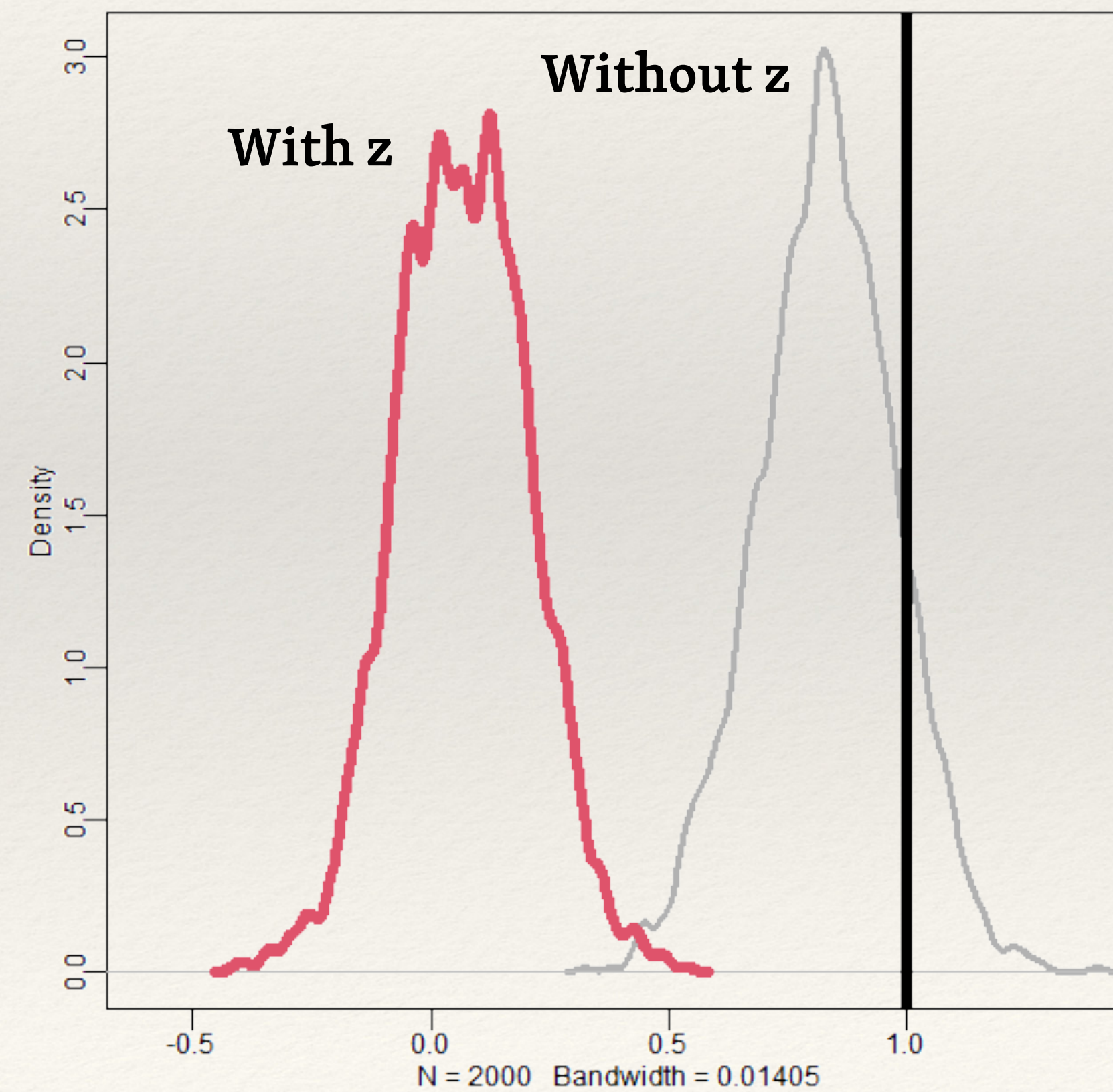
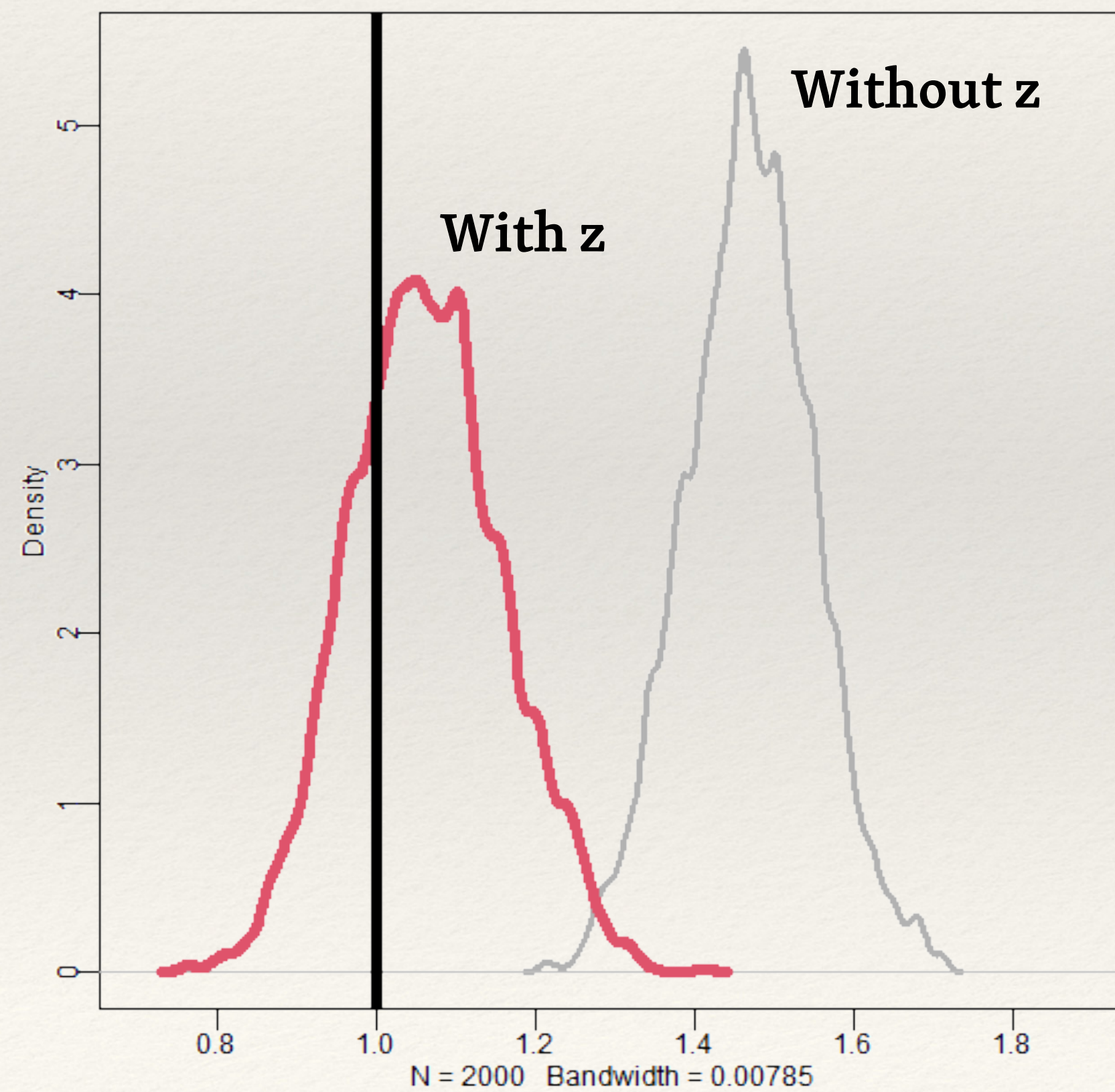
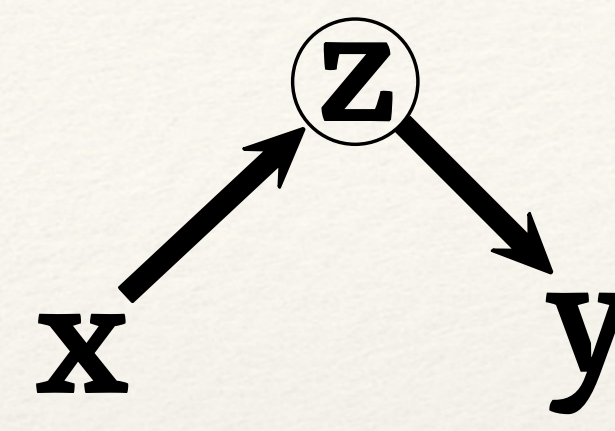
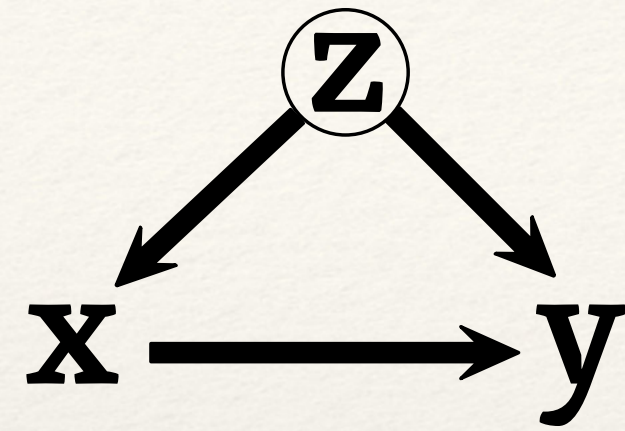


INCLUDING THE MEDIATOR

```
m2 = ulam(alist(  
  y ~ normal(a + bx*x + bz*z, sigma),  
  a ~ normal(0, 0.3),  
  bx ~ normal(0, 0.3),  
  bz ~ normal(0, 0.3), # Mediator  
  sigma ~ exponential(1)),  
  data = list(y = y, x = x, z = z),  
  iter = 1000, chains = 4, cores = 4)
```

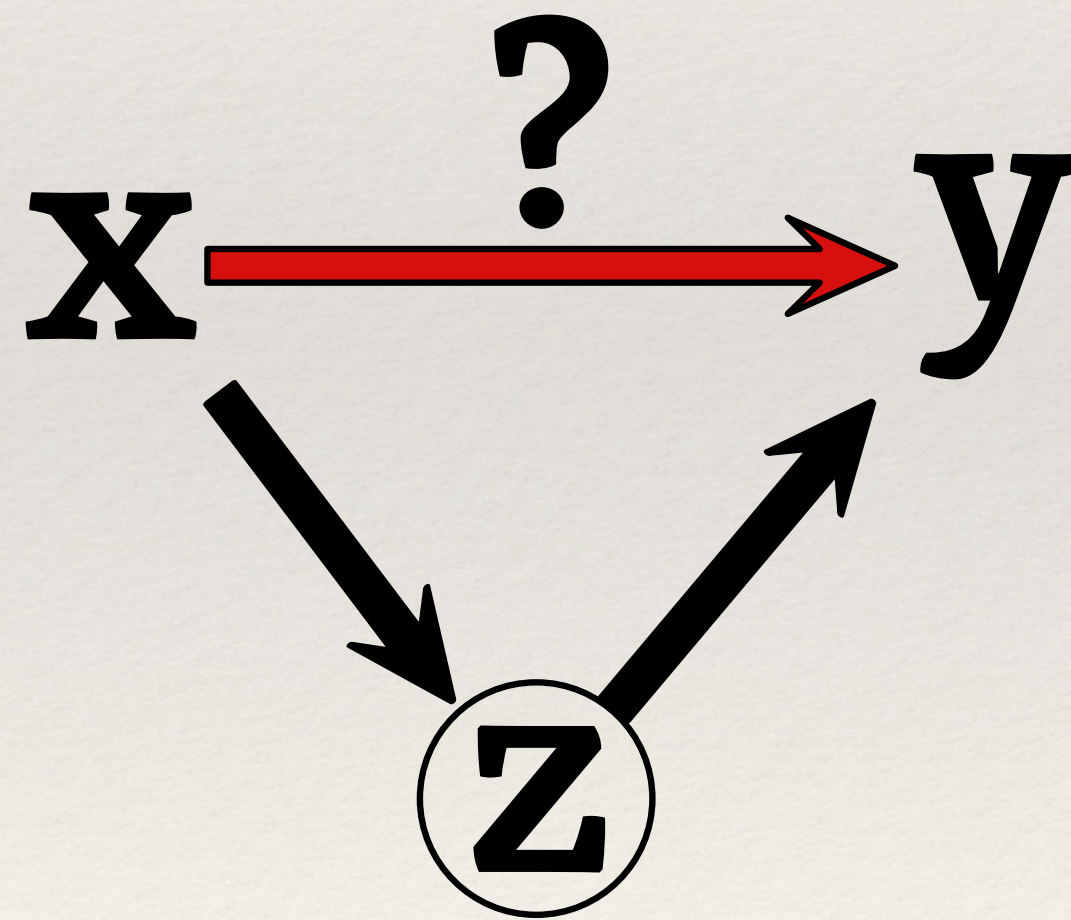


PIPE VS. FORK



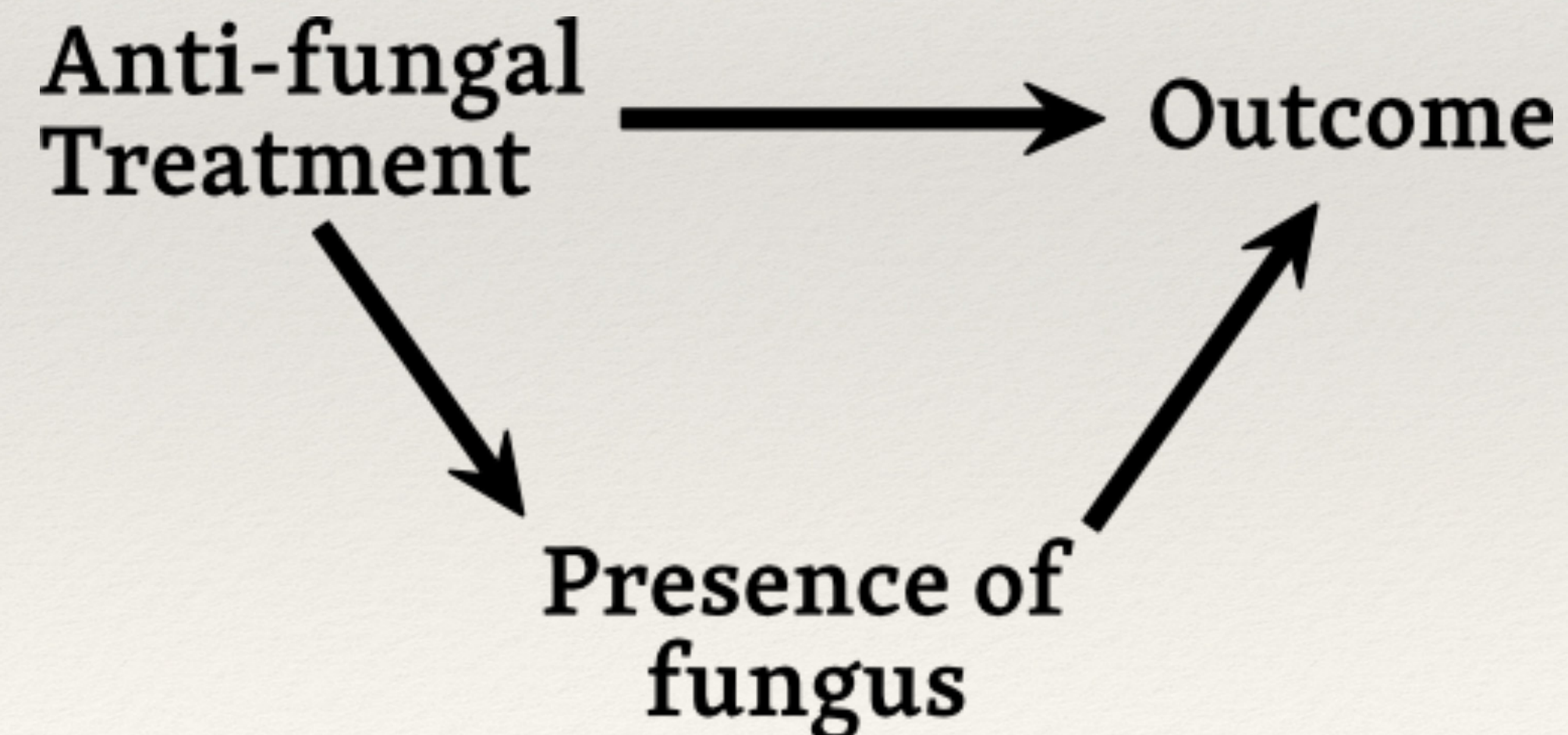
EXAMPLES OF PIPES OR MEDIATORS

Including a mediator in our models can have catastrophic effects. A common mistake is to include post-treatment variables in the model.



POST-TREATMENT VARIABLES

If we are evaluating the effectiveness of a fungal treatment, most of the effect of the treatment could be mediated by the presence of fungus. So, using presence of fungus in our model would mask the effect of the treatment.



CONDITIONING ON POSTTREATMENT VARIABLES



How Conditioning on Posttreatment Variables Can Ruin Your Experiment and What to Do about It

Jacob M. Montgomery Washington University in St. Louis
Brendan Nyhan Dartmouth College
Michelle Torres Washington University in St. Louis

Abstract: In principle, experiments offer a straightforward method for social scientists to accurately estimate causal effects. However, scholars often unwittingly distort treatment effect estimates by conditioning on variables that could be affected by their experimental manipulation. Typical examples include controlling for posttreatment variables in statistical models, eliminating observations based on posttreatment criteria, or subsetting the data based on posttreatment variables. Though these modeling choices are intended to address common problems encountered when conducting experiments, they can bias estimates of causal effects. Moreover, problems associated with conditioning on posttreatment variables remain largely unrecognized in the field, which we show frequently publishes experimental studies using these practices in our discipline's most prestigious journals. We demonstrate the severity of experimental posttreatment bias analytically and document the magnitude of the potential distortions it induces using visualizations and reanalyses of real-world data. We conclude by providing applied researchers with recommendations for best practice.

COLLIDER

NO EFFECT OF X ON Y, BUT BOTH AFFECT Z

X



Math

$$y \sim \text{Normal}(\alpha_y, \sigma_y)$$

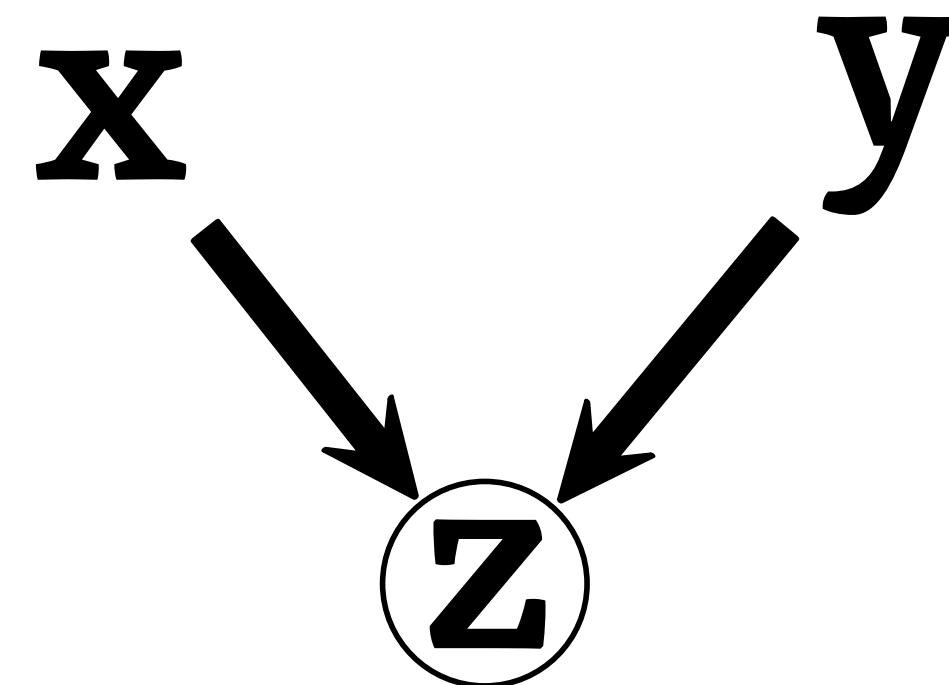
$$x \sim \text{Normal}(\alpha_x, \sigma_x)$$

$$z \sim \text{Normal}(\alpha_z + \beta_{zx}x + \beta_{zy}y, \sigma_z)$$

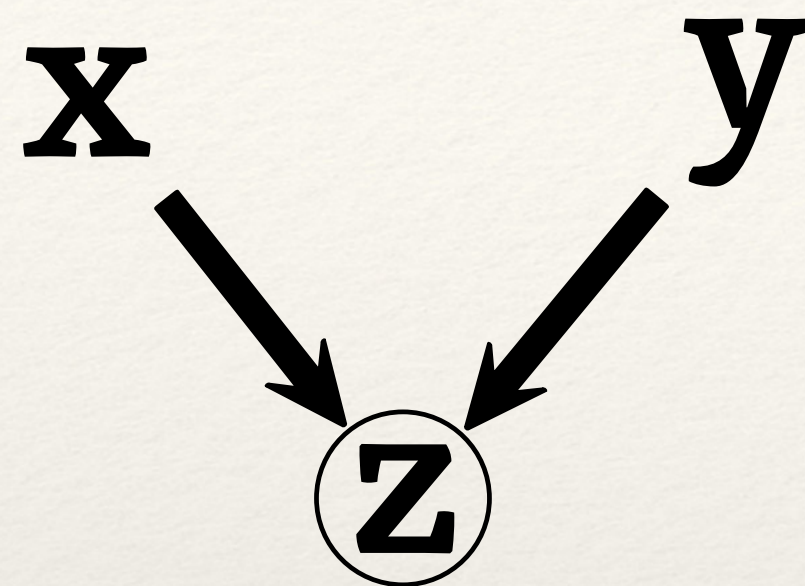
NO EFFECT OF X ON Y, BUT BOTH AFFECT Z

```
set.seed(1)
N = 100
x = rnorm(N)          # x ~ normal(0, 1)
y = rnorm(N)          # y ~ normal(0, 1)
z = rnorm(N, 1 + x + y) # z ~ normal(1 + x + y, 1) -> collider

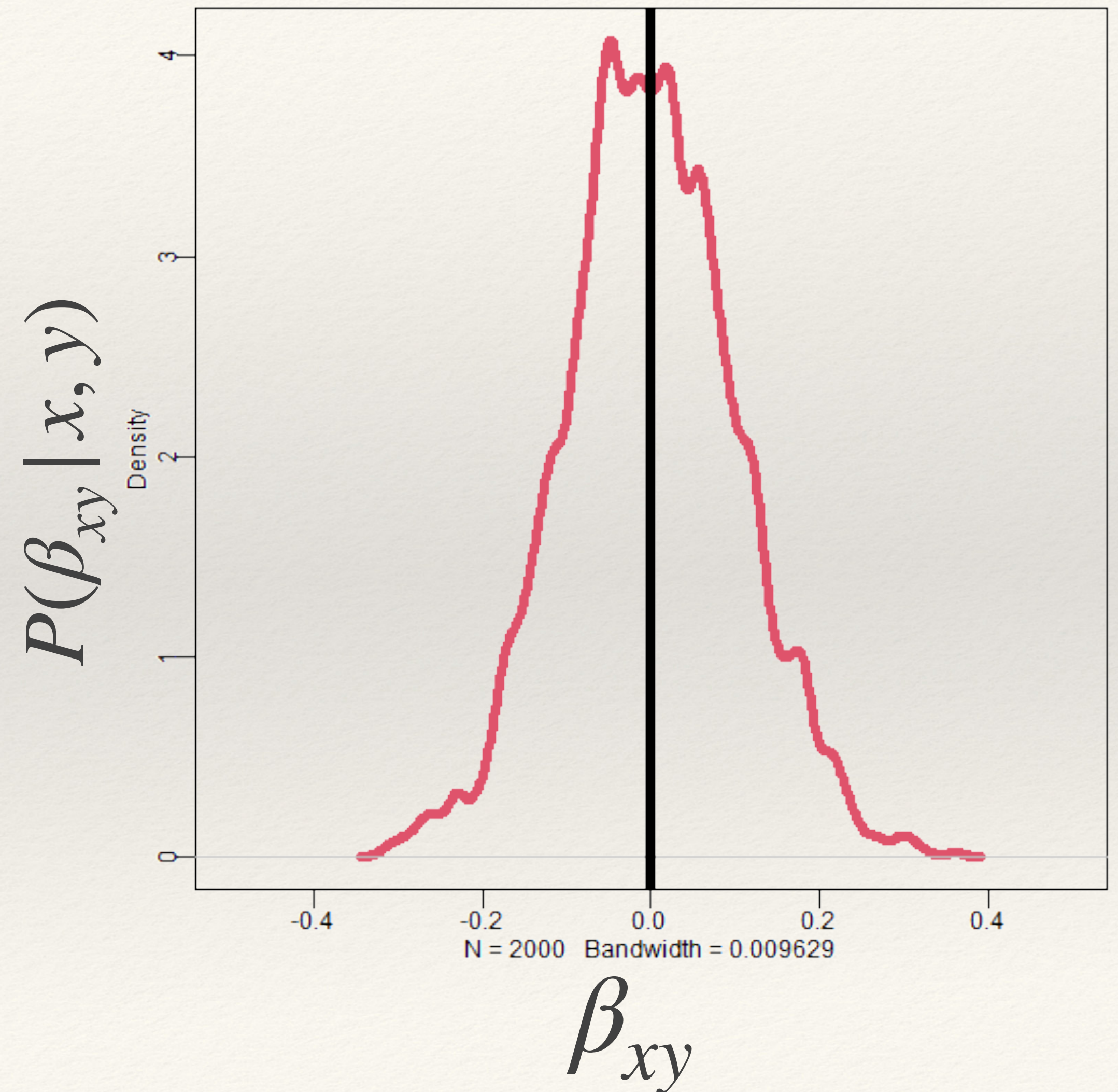
m1 = ulam(alist(
  y ~ normal(a + bx*x, sigma),
  a ~ normal(0, 0.3),
  bx ~ normal(0, 0.3),
  sigma ~ exponential(1),
  data = list(y = y, x = x),
  iter = 1000, chains = 4, cores = 4)
```



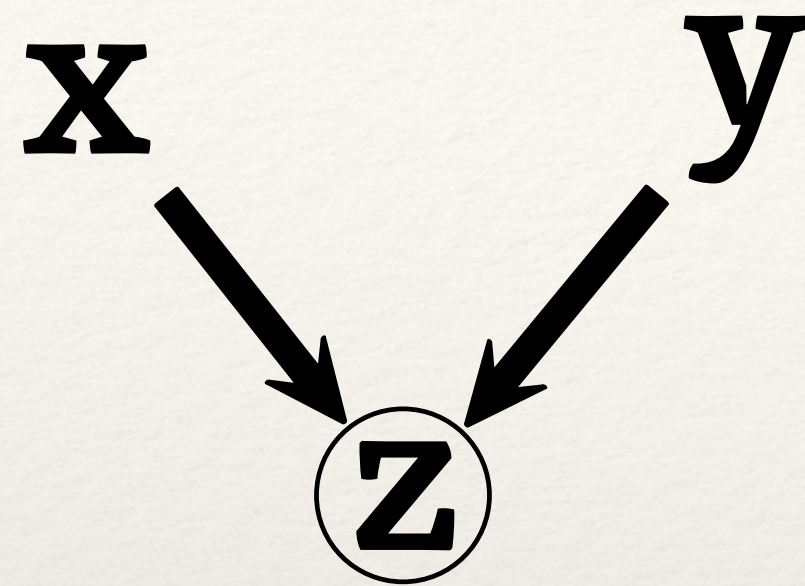
EFFECT OF X ON Y WITHOUT THE COLLIDER



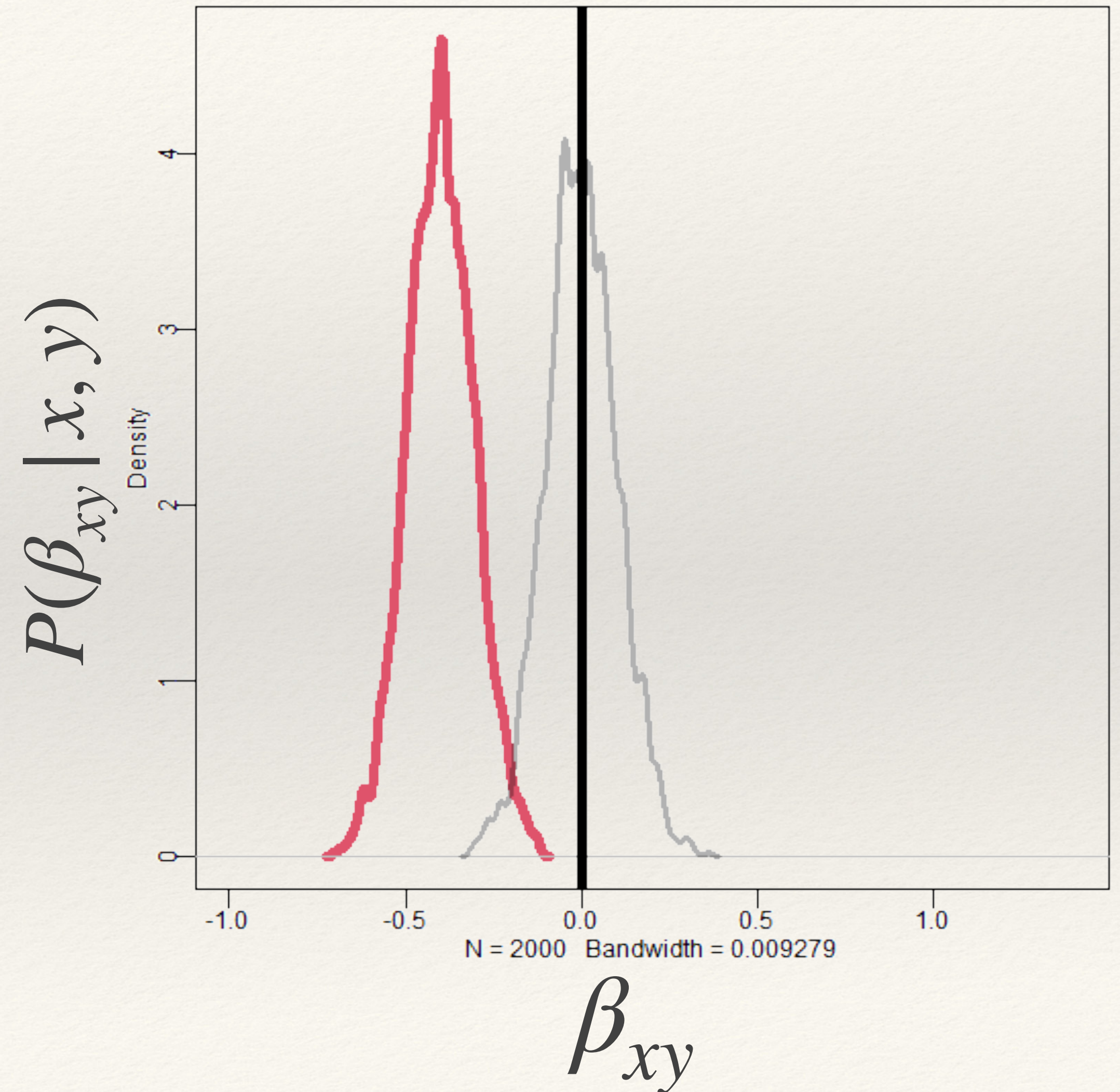
```
m1 = ulam(alist(  
  y ~ normal(a + bx*x, sigma),  
  a ~ normal(0, 0.3),  
  bx ~ normal(0, 0.3),  
  sigma ~ exponential(1)),  
  data = list(y = y, x = x),  
  iter = 1000, chains = 4, cores = 4)
```



EFFECT OF X ON Y WITH THE COLLIDER



```
m2 = ulam(alist(  
  y ~ normal(a + bx*x + bz*z, sigma),  
  a ~ normal(0, 0.3),  
  bx ~ normal(0, 0.3),  
  bz ~ normal(0, 0.3), # Collider  
  sigma ~ exponential(1)),  
  data = list(y = y, x = x, z = z),  
  iter = 1000, chains = 4, cores = 4)
```



COLLIDERS CAN CAUSE OUR SAMPLES TO BE BIASED

Good food

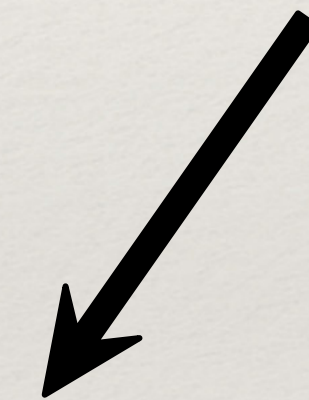
Good location



**Restaurant
exists**

**Research
quality**

**Research
newsworthiness**



Funding

WHAT NOW?!

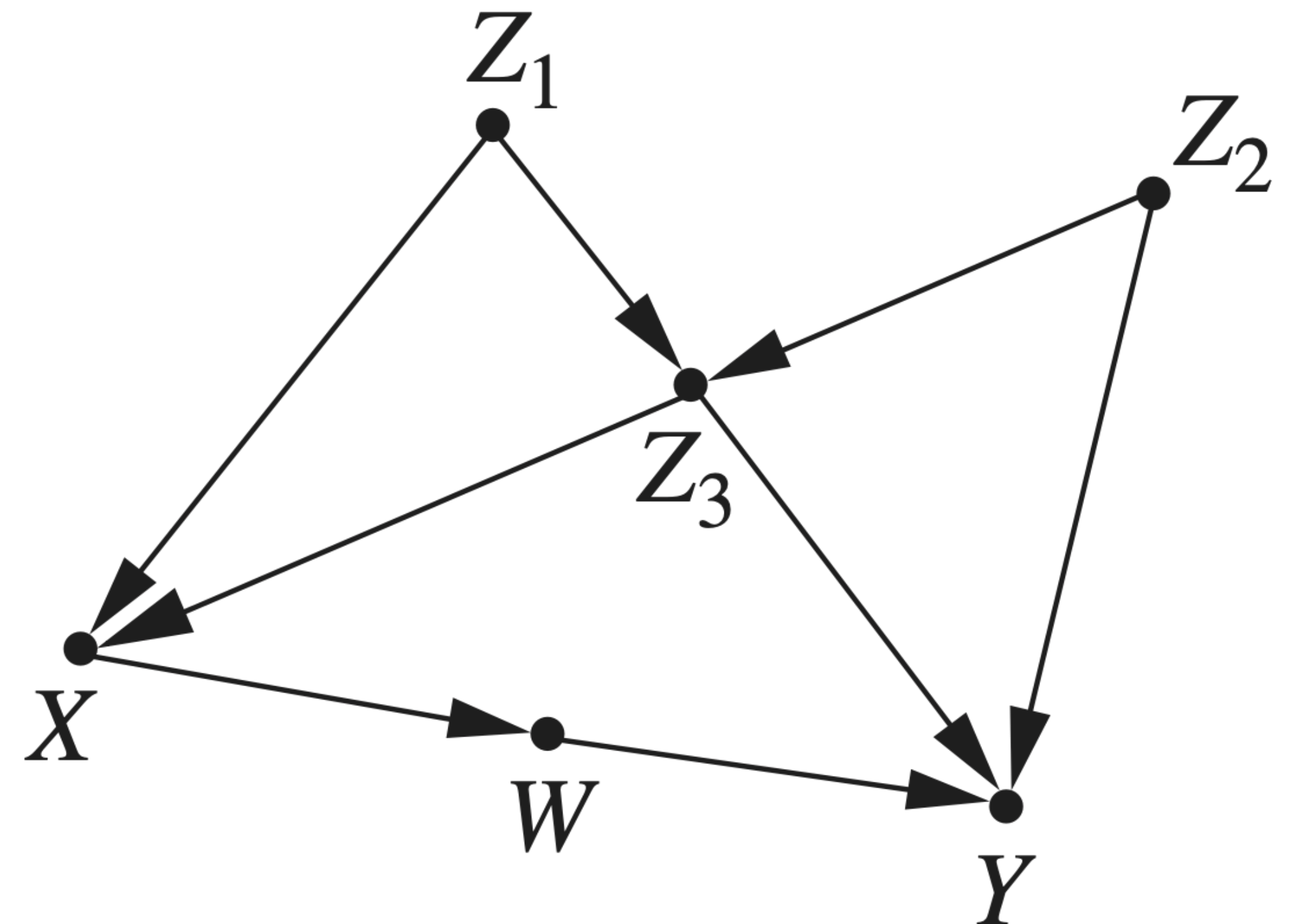
USING DAGS TO BUILD MODELS

If we represent our putative causal relations using DAGs, we have a set of rules that tells us what variables we need to include in the model in order to calculate a particular effect.

OPEN AND CLOSED PATHS

- Paths containing uncontrolled **pipes** and **forks** are open
- Paths containing **colliders** are **closed by default**, but open if we condition on the collider
- To estimate the true causal effect of x on y , we need **all non-causal paths from x to y** to be closed in our model

Identify all the open paths from X to Y



BACK DOOR CRITERION

To estimate the causal effect of X on Y , identify a set of control variables such that no descendants of X are in the control set, and all paths between X and Y that contain an arrow into X are blocked.


NOT ALL ESTIMATES ARE CAUSAL

The Table 2 Fallacy: Presenting and Confounder and Modifier Coefficien

Daniel Westreich , Sander Greenland [Author Notes](#)

American Journal of Epidemiology, Volume 177, Issue 4, 15 Feb
<https://doi.org/10.1093/aje/kws412>

Published: 30 January 2013 **Article history** ▾

 PDF  Split View  Cite  Permissions

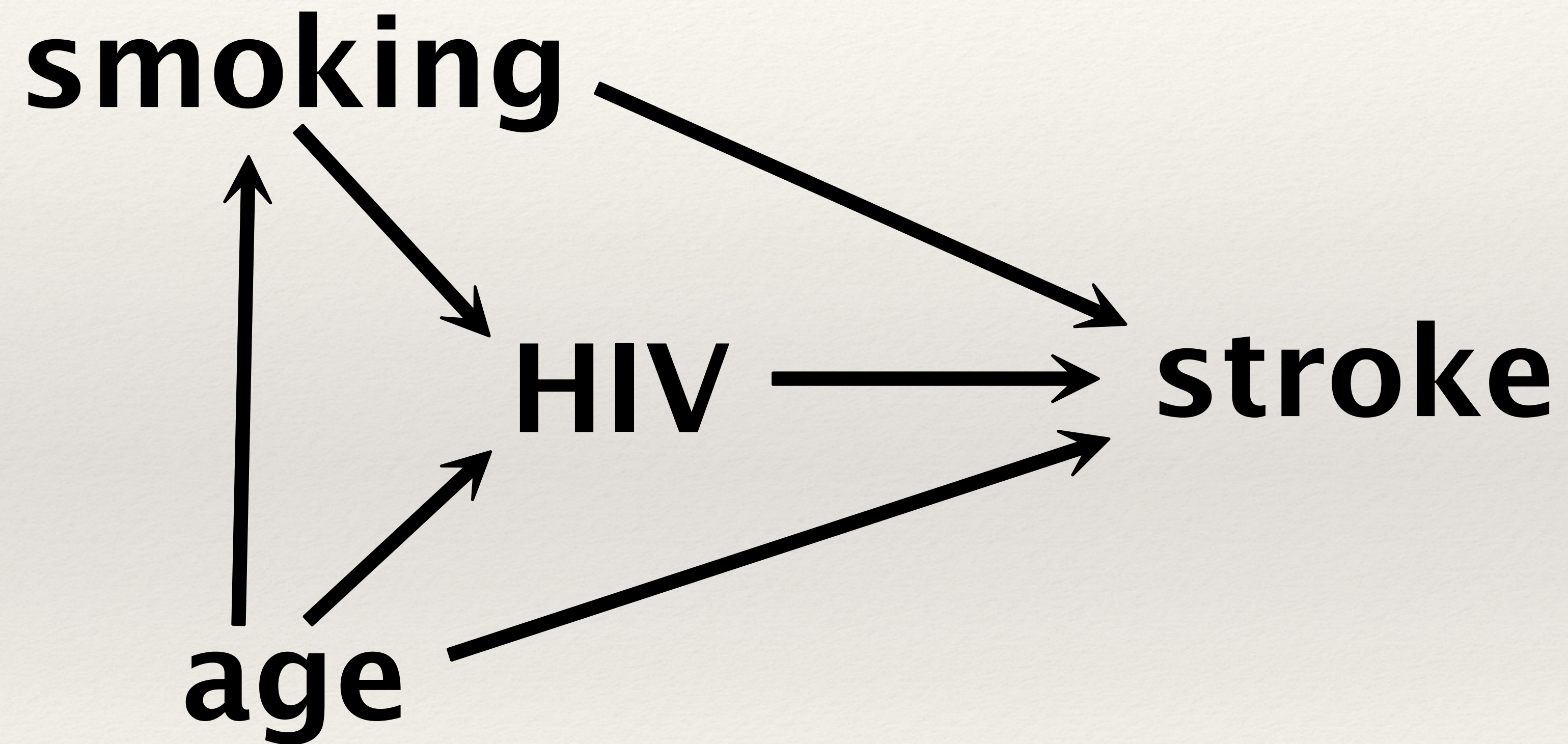
Abstract

It is common to present multiple adjusted effect estimates in a single table. For example, a table might show odds ratios for exposures and also for several confounders from a single model. This can lead to mistaken interpretations of these estimates. We present diagrams to display the sources of the problems. Presenting confounder effect estimates from a single model may lead to interpretative difficulties, inviting confusion of direct- and total-effect estimates for covariates in the model. These estimates also be confounded even though the effect estimate for the exposure is not confounded. Interpretation of these effect estimates is further complicated by heterogeneity (variation, modification) of the exposure effect across covariate levels. We offer suggestions to limit potential for misinterpretation when multiple effect estimates are presented, including distinguishing between total and direct effect measures from a single model and presenting multiple models tailored to yield total-effect estimates.

Table 1. Characteristics of the Patients at Baseline.*						
Characteristic	General Linear Model			Ordinary Least Squares		
	df	MS	F	p	β ^a	SE
Age	49 (39–57)			49 (37–56)	49 (38–57)	
Median (IQR) — yr						
Distribution — no. (%)						
≤50 yr	1	44.7	1.8	.175	−.04	.024
>50 yr	1	294.7	12.1	.001	.10	.391
Gender (male)	1	383 (56.4)	1.4	.229	.04	.052
Female sex — no. (%)	1	687.9	28.3	.000	.14	.206
Race — no. (%)†	1	95.9	3.9	.047	.05	.409
White	1	95.6	3.9	.048	.05	.021
Black	1	264.4	10.9	.001	−.09	.168
Unknown	1	202.1	8.3	.004	.08	.074
Body-mass index — no. (%)	1	591.3	24.3	.000	−.13	.082
<30	1	1145.1	47.1	.000	−.21	.103
≥30	1	1508.2	62.1	.000	−.24	.045
Time since onset of symptoms — no. (%)	1	66.5	2.74	.021	−.11	.175
0–3 days	3	22.1	1.0	.965	−.04	.169
4–14 days	9	12.1	0.5	.876	.01	.160
≥15 days	26	577.9	23.8	.000		
Daily activity limitations						
Risk factors — no. (%)						
Chronic cardiac disease	3	14 (2.1)	10 (1.5)		.24 (1.8)	
Uncontrolled hypertension	3	55 (8.1)	59 (8.0)		−.04 (8.4)	
Chronic pulmonary disease	9	18 (2.7)	23 (3.4)		.41 (3.0)	
Asthma	9	54 (8.0)	60 (8.8)		.114 (8.4)	
Chronic kidney disease	26	2 (0.3)	9 (0.7)		.7 (0.5)	
Type 1 diabetes mellitus		3 (0.4)	9 (1.3)		.12 (0.9)	
Type 2 diabetes mellitus		79 (12)	89 (13)		.168 (12)	
Autoimmune disease		2 (0.3)	2 (0.3)		.4 (0.3)	
Any other risk factor or coexisting condition		22 (3.2)	19 (2.8)		.41 (3.0)	

* Missingness in covariate data was handled with multiple imputation by chained equations.¹⁶ IQR denotes interquartile range.
† Race was reported by the patient.

HIV AND STROKE



GOOD AND BAD CONTROLS

Good controls

- Block non-causal paths
- Improve precision
- Allow inference of causal effects

Bad controls

- Block causal paths (blocking pipes)
- Open non-causal paths (opening colliders)
- Reduce precision
- Prevents causal inference