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# Diseño y desarrollo de un fragmentador de programas para Java basado en el System Dependence Graph

Trabajo Fin de Máster

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**Autor:** Javier Costa Rosa  
**Tutor:** Josep Francesc Silva Galiana  
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## **Abstract**

The abstract

## **Resumen**

El resumen

***Keywords*** — Java, Program Slicing, System Dependence Graph

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# 1 Introduction

## 1.1 Program Slicing

Program Slicing is a debugging technique firstly introduced by Mark Weiser in 1981 [4] which consists in obtaining a reduced version of a program (the slice) obtaining the parts of it that are relevant for a given slicing criterion. Some of the main applications of Program Slicing are debugging and performing program analysis, among others.

A slicing criterion gives information about what variable or variables are targeted and in what point of the program the slicing will be performed for them, i.e., given a program  $p$ , a slicing criterion  $\langle s, v \rangle$  specifies a statement  $s$  and a set of variables  $v$  in  $p$ .

Depending on the variant of program slicing applied, the slicing criterion may have to give more information. There are many of this variants, but however, they all can be classified into static or dynamic, and forward or backward:

- The static slicing do not take into account any particular execution. As a consequence, the slice will result in all the possibly relevant parts of the code, whatever the program input is. On the other hand, the dynamic program slicing is always related to a particular execution of the program and, therefore, an input for that execution. The slicing criterion will vary depending on whether the slicing is static or dynamic. If it is dynamic, the slicing criterion will have to provide, in addition to the statement and the set of variables, the input of the program
- The backward slicing will get all the parts of the program that can affect the statement specified in the slicing criterion. On the other hand, the forward slicing will do the same but for all the parts that can be affected by the specified statement

Based on this classification, many variants of program slicing have been specified. However, they will not be discussed here, as this work is focused on performing a **static**, **backward** slicing of a Java program.

### Example 1

```
1  void main() {  
3      int x = 1  
        int y = 2;  
5  }
```

To be able to perform slicing to a program, the dependencies between its statements must be computed first. There are three data structures commonly used to compute these dependencies, where each one of them represents different dependencies:

- The Control Flow Graph (CFG) is a directed graph that stores the control flow dependencies. That is, the order in which the statements are executed in the program

- The Program Dependence Graph (PDG) is an oriented graph that stores the control and data dependencies. A statement is control-dependent of other when the second one has to be executed in order to be able to execute the first one. A data dependency occurs when the statement a uses a variable that has been defined in statement b, a can be reached from b in the CFG and in this path the variable is not redefined (i.e. there is a path that connects them without redefining the variable). The PDG is able to represent only intraprocedural control and data dependencies, but not interprocedural
- The System Dependence Graph (SDG) is a graph that is able to represent interprocedural control and data dependencies. Its construction is, in essence, an interconnection of PDGs (each procedure has its own PDG and the SDG is built by connecting them)

## 1.2 Goals

The main goal of this work is to develop a slicer that is able to take a Java program and a slicing criterion as input and make a static, backward slicing of it. The output of the execution will consist of:

- The generated graph (or graphs)
- The executable slice (i.e. the reduced program)

## 2 Background

Program slicing has been researched since its first definition by Mark Weiser in 1981. In this first appearance, the PDG was presented as a way of representing control and data dependencies easily at linear time.

Other variants of program slicing were presented later such as dynamic slicing, hybrid slicing, etc.

Larsen and no se quien presented a paper in no se que año in which they presented a way of representing data and control dependencies in object oriented languages, since until then all the research had been made for procedural languages.

### 2.1 Slicing approaches of Java programs

Nowadays, a few implementations of slicer for Java programs can be found. However, they all are buggy or outdated. In table 1, they are represented with their features and differences between each one of them.

[table 1] slicers with their differences table

## **3 The Java language and JavaParser**

Java is an object oriented language which follows the JDK specification. In this work, the focus is on its version number 12. This is the version that is used and the version the slicer will be able to understand.

Abstract Syntax Tree

JavaParser builds the AST

### **3.1 The Java language**

### **3.2 The Abstract Syntax Tree**

### **3.3 JavaParser**

#### **3.3.1 Declarations**

#### **3.3.2 Statements**

#### **3.3.3 Expressions**

## **4 Developing the slicer**

### **4.1 Scope**

### **4.2 Design**

### **4.3 Implementation**

## **5 Tests/Performance (?)**

## **6 Conclusions**

## **7 Future work**

## References

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