Naïve methods, Exponential Smoothing models and the Theta method

Week 2: Statistical Forecasting Methods



Naïve methods

- Naïve: The last known observation is used to produce forecasts
- **sNaive**: The last known observation of the same period is used to produce forecasts
- Naïve 2: The last known observation is used to produce forecasts, adjusted for seasonality
- Naïve with drift: The last known observation and running trend is used to produce forecasts
- Naïve 2 with drift: Like Naïve 2, but with drift





Naïve methods

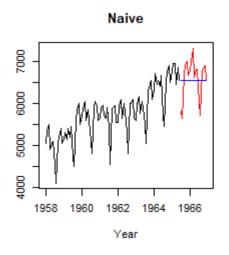
```
library(forecast)
library(Mcomp)
time series <- subset(M3, 12)[[1110]]
insample <- subset(M3, 12)[[1110]]$x
outsample <- subset(M3, 12)[[1110]]$xx
par(mfrow=c(2,3))
Naive <- naive(insample, h=18)$mean
plot(time series, main="Naive")
lines(Naive, col="blue")
accuracy(outsample, Naive)[5]
sNaive <- snaive(insample, h=18)$mean
plot(time_series, main="sNaive")
lines(sNaive, col="blue")
accuracy(outsample,sNaive)[5]
```

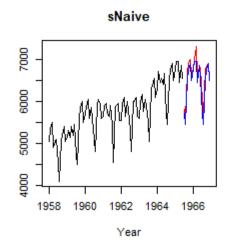
```
SI <- decompose(insample, type="multiplicative")$seasonal
Naive2 <- naive(insample/SI, h=18)$mean*as.numeric(head(tail(SI,12*2),18))
plot(time series, main="Naive 2")
lines(Naive2, col="blue")
accuracy(outsample, Naive2)[5]
NaiveD <- rwf(insample, h=18, drift=T)$mean
plot(time series, main="Naive with drift")
lines(NaiveD, col="blue")
accuracy(outsample, NaiveD)[5]
NaiveD2 <- rwf(insample/SI, h=18,
drift=T)$mean*as.numeric(head(tail(SI,12*2),18))
plot(time series, main="Naive 2 with drift")
lines(NaiveD2, col="blue")
accuracy(outsample, NaiveD2)[5]
```

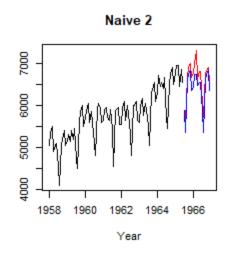


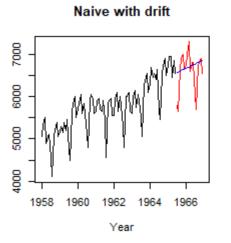


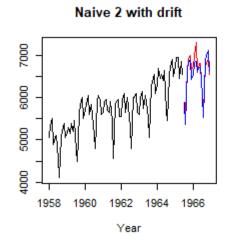
Naïve methods











- The MAPEs of the Naïve models examined are 5.73, 2.36, 3.41, 4.88 and **2.16**, respectively
- So, adequately capturing seasonality and trend gives us a forecasting boost of 59% and 15%, respectively.
- By considering both trend and seasonality, accuracy is improved by 62%





Moving Averages

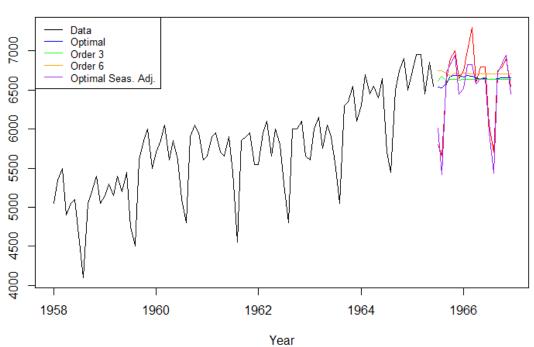
- The last *k* known observations are used to produce forecasts
- *k* is the order of the MA model:
 - ✓ When k is large, forecasts become smooth and account for long term patterns
 - ✓ When k is small, forecasts become more volatile and account for recent level changes
- ✓ All k observations are equally weighted and important for computing the forecasts $F_{t+1} = \frac{1}{k} \sum_{i=1}^{t} Y_i$





Moving Averages

```
Optimal estimation of order
library(smooth)
MA <- forecast(sma(insample), h=18)$mean
plot(time series, main="MA")
lines(MA, col="blue")
                                         Arbitrary selections
accuracy(outsample,MA)[5]
                                                                  9000
MA3 <- forecast(sma(insample, order=3), h=18)$mean
MA6 <- forecast(sma(insample, order=6), h=18)$mean
                                                                  5500
lines(MA3, col="green")
                                                                  5000
lines(MA6, col="orange")
accuracy(outsample,MA3)[5]
                                                                  4500
accuracy(outsample,MA6)[5]
                                                                  4000
MA sa <- forecast(sma(insample/SI),
h=18)$mean*as.numeric(head(tail(SI,12*2),18))
                                                                      1958
lines(MA sa, col="purple")
accuracy(outsample,MA sa)[5]
legend("topleft", legend=c("Data","Optimal", "Order 3", "Order 6", "Optimal
Seas. Adj."),
   col=c("black", "blue", "green", "orange", "purple"), lty=1, cex=0.8)
```



MA

- The MAPEs of the MA models examined are 4.83, 5.18, 4.97 and **2.31**, respectively
- MA improve Naïve by 16% when seasonality is not considered and by 2% otherwise





Exponential Smoothing

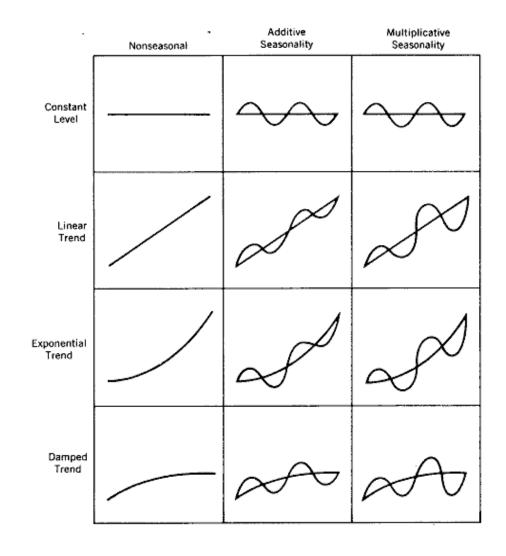
- Forecasting through data smoothing
- Past observations are averaged to predict the next one, using exponential weights
- Recent observations display higher weights than the old ones

- By smoothing the series, randomness is
 removed and the true signal becomes clear
- Typically used for short-term forecasting
- Easy and fast to use
- Little requirements in terms of data availability





Exponential Smoothing models



Simple – Constant level

One-step-ahead forecasts

Holt – Linear trend

Short-term forecasting

Holt – Exponential trend

Damped – Damped trend

Mid-term forecasting





Definition and equations

$$e_{t} = Y_{t} - F_{t}$$

$$S_{t} = S_{t-1} + \alpha \cdot e_{t}$$

$$F_{t+1} = S_{t}$$

$$e_{t-1} = Y_{t-1} - F_{t-1}$$

$$F_{t} = F_{t-1} + \alpha e_{t-1}$$

$$F_{t} = F_{t-1} + \alpha (Y_{t-1} - F_{t-1})$$

$$F_{t} = \alpha Y_{t-1} + (1-\alpha)F_{t-1}$$





$$F_{t} = \alpha Y_{t-1} + (1-\alpha)F_{t-1}$$

$$E_{t-1} = Y_{t-1} - F_{t-1}$$

$$F_{t+1} = \alpha Y_{t} + (1-\alpha)F_{t}$$

$$F_{t+1} = \alpha Y_{t} + \alpha (1-\alpha)Y_{t-1} + (1-\alpha)^{2}F_{t-1}$$

$$\begin{aligned} \mathsf{F}_{\mathsf{t}+1} &= \alpha \mathsf{Y}_{\mathsf{t}} + \alpha (1 - \alpha) \; \mathsf{Y}_{\mathsf{t}-1} + \alpha (1 - \alpha)^2 \; \mathsf{Y}_{\mathsf{t}-2} + \alpha (1 - \alpha)^3 \; \mathsf{Y}_{\mathsf{t}-3} \; \alpha (1 - \alpha)^4 \; \mathsf{Y}_{\mathsf{t}-4} + \dots \\ & \dots + \alpha (1 - \alpha)^{\mathsf{t}-1} \; \mathsf{Y}_{\mathsf{1}} + (1 - \alpha)^{\mathsf{t}} \mathsf{F}_{\mathsf{1}} \end{aligned}$$



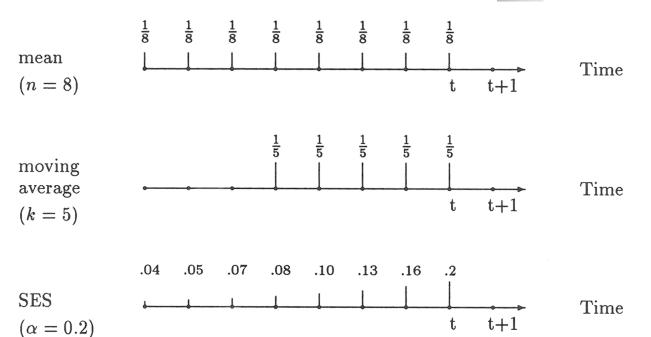


- Weights are exponentially increased through time
- All observations are used for producing the forecasts, but with different weights
- Small values of a indicate that past observations will be heavier weighted and vice-versa
- For a=1 SES is equivalent to the Naïve method, while for a=0, the forecasts are equal to So (initial level).





Weight				
assigned to:	$\alpha = 0.2$	$\alpha = 0.4$	$\alpha = 0.6$	$\alpha = 0.8$
$\overline{Y_t}$	0.2	0.4	0.6	0.8
Y_{t-1}	0.16	0.24	0.24	0.16
Y_{t-2}	0.128	0.144	0.096	0.032
Y_{t-3}	0.1024	0.0864	0.0384	0.0064
Y_{t-4}	$(0.2)(0.8)^{4}$	$(0.4)(0.6)^4$	$(0.6)(0.4)^4$	$(0.8)(0.2)^4$







Level initialization

- Average of series
- Average of first three observations
- First observation

Parameter selection

- a values range in [0,1]
- Minimize in-sample, one-step-ahead
 MSE, MAE or MAPE
- Different criteria different optimal values





(Y1+Y2)/2

t	Υ	F	е	S = F + a*e	S = a*Y + (1-a)*F	S
0						167,5
1	200	167,5	32,5	167,5 + 0.2 * 32,5	0.2 * 200 + 0.8 * 167,5	174,0
2	135	174,0	-39,0	174 + 0.2 * -39	0.2 * 135 + 0.8 * 174	166,2
3	195	166,2	28,8	166,2 + 0.2 * 28,8	0.2 * 195 + 0.8 * 166,2	172,0
4	197,5	172,0	25,5	172 + 0.2 * 25,5	0.2 * 197,5 + 0.8 * 172	177,1
5	310	177,1	132,9	177,1 + 0.2 * 132,9	0.2 * 310 + 0.8 * 177,1	203,7
6	175	203,7	-28,7	203,7 + 0.2 * -28,7	0.2 * 175 + 0.8 * 203,7	197,9
7	155	197,9	-42,9	197,9 + 0.2 * -42,9	0.2 * 155 + 0.8 * 197,9	189,3
8	130	189,3	-59,3	189,3 + 0.2 * -59,3	0.2 * 130 + 0.8 * 189,3	177,5
9	220	177,5	42,5	177,5 + 0.2 * 42,5	0.2 * 220 + 0.8 * 177,5	186,0
10	277,5	186,0	91,5	186 + 0.2 * 91,5	0.2 * 277,5 + 0.8 * 186	204,3
11	235	204,3	30,7	204,3 + 0.2 * 30,7	0.2 * 235 + 0.8 * 204,3	210,4
12	3 555	210,4 🔪				

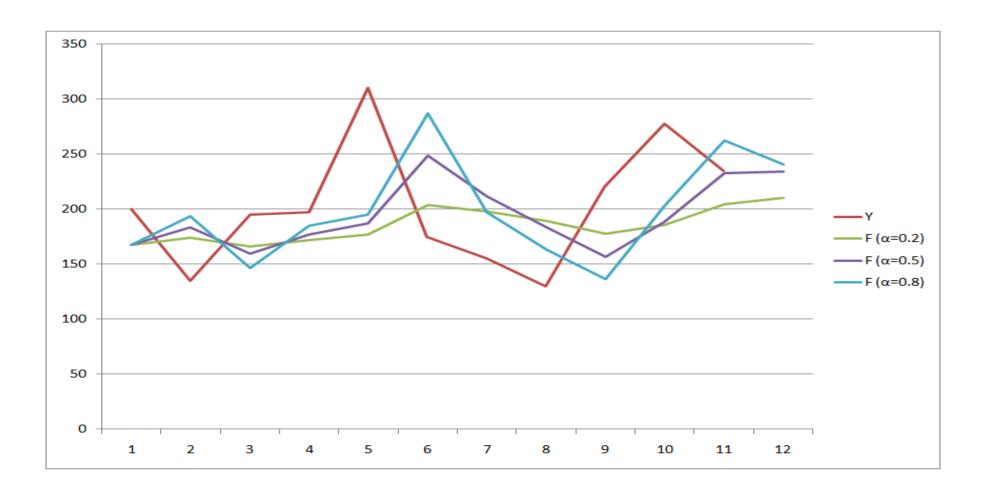




t	Υ	F (α=0.2)	E	AE	APE	SAPE
1	200	167,5	32,50	32,50	0,163	0,177
2	135	174,0	-39,00	39,00	0,289	0,252
3	195	166,2	28,80	28,80	0,148	0,159
4	197,5	172,0	25,54	25,54	0,129	0,138
5	310	177,1	132,93	132,93	0,429	0,546
6	175	203,7	-28,65	28,65	0,164	0,151
7	155	197,9	-42,92	42,92	0,277	0,243
8	130	189,3	-59,34	59,34	0,456	0,372
9	220	177,5	42,53	42,53	0,193	0,214
10	277,5	186,0	91,52	91,52	0,330	0,395
11	235	204,3	30,72	30,72	0,131	0,140
12		210,4				
		α=0.2	19,51	50,41	0,25	0,25
		α=0.5	12,08	54,39	0,27	0,27
		α=0.8	8,30	58,13	0,29	0,29











Holt Exponential Smoothing

$$e_t = Y_t - F_t$$

$$S_t = S_{t-1} + T_{t-1} + a * e_t$$

$$T_t = T_{t-1} + a * b * e_t$$

$$F_{t+m} = S_t + mT_t$$
The forecast is

linearly adjusted at

every step

• $0<\alpha<1$ and $0<\beta<a$

Initial level

Average of first few observations

Initial trend

- First, first difference
- Average of first differences





Damped Exponential Smoothing

$$e_{t} = Y_{t} - F_{t}$$

$$S_{t} = S_{t-1} + \varphi T_{t-1} + a * e_{t}$$

$$T_{t} = \varphi T_{t-1} + a * b * e_{t}$$

$$F_{t+m} = S_{t} + \sum_{i=1}^{m} \varphi^{i} T_{t}$$

The forecast is non-linearly adjusted at every step

Damped can be used to express the rest of the exponential smoothing models

$$\Rightarrow \varphi = 0 - SES$$

$$\rightarrow \phi = 1 - Holt$$

$$> \phi > 1 - exponential trend$$





Seasonal exponential smoothing models

Seasonal Models

$$e_t = Y_t - F_t$$

$$S_{t} = S_{t-1} + \frac{\alpha \cdot e_{t}}{I_{t-p}}$$

$$I_{t} = I_{t-p} + \frac{\gamma \cdot e_{t}}{S_{t}}$$
$$F_{t+m} = S_{t} \cdot I_{t-p+m}$$

$$F_{t+m} = S_t \cdot I_{t-p+m}$$

Seasonal Adjustments

- Remove **additive** seasonality actual data - index = deseasonalized data
- Remove **multiplicative** seasonality actual data / index = deseasonalized data

Forecasts are **reseasonalized** using opposite trasformation





State-space exponential smoothing models

ETS (Error, Trend, Seasonal)

- Error: {A,M}
- Trend:{N, A, A_d, M, M_d}
- Seasonal:{N, A, M}

imple exponential moothing
Iolt's linear method
xponential trend method
dditive damped trend nethod
dditive Holt-Winters nethod
Iolt-Winters damped nethod

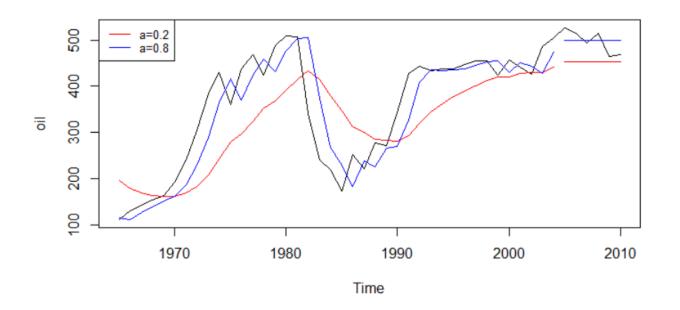
A total of 30 state space models

	Seasonal Component				
Trend	N	Α	М		
Component	(None)	(Additive)	(Multiplicative)		
N (None)	(N,N)	(N,A)	(N,M)		
A (Additive)	(A,N)	(A,A)	(A,M)		
A _d (Additive damped)	(A _d ,N)	(A _d ,A)	(A _d ,M)		
M (Multiplicative)	(M,N)	(M,A)	(M,M)		
M _d (Multiplicativ e damped)	(M _d ,N)	(M _d ,A)	(M _d ,M)		





Fit and evaluate SES for various smoothing parameters (a)







```
#Insample accuracy
mse_in1 <- mean((oildata_train - fit1\fitted)^2)
mse_in2 <- mean((oildata_train - fit2\fitted)^2)
#Outsample accuracy
mse_out1 <- mean((oildata_test - fit1\mean)^2)
mse_out2 <- mean((oildata_test - fit2\mean)^2)

c(mse_in1, mse_in2)
c(mse_out1, mse_out2)

> c(mse_out1, mse_out2)

> c(mse_out1, mse_out2)

[1] 2457.2304 576.7129
```

Although this is not always the case, the model that produced the most accurate forecasts when trained, is also the most accurate model in predicting the future

Fitting the "optimal" SES model

```
#Optimal parameters
model <- ses(oildata_train)</pre>
model model
Simple exponential smoothing
Call:
 ses(y = oildata_train)
   Smoothing parameters:
     alpha = 0.9999
   Initial states:
     1 = 110.8832
   sigma: 52.6202
      ATC
              AICc
                         BTC
468.5515 469.2182 473.6181
```

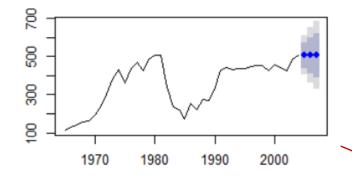




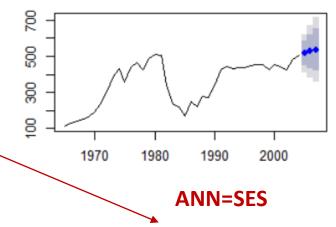
```
#Exponential smoothing models
model1 <- ses(oildata_train, h=3)
model2 <- holt(oildata_train, h=3)
model3 <- holt(oildata_train, damped = TRUE, h=3)
model4 <- forecast(ets(oildata_train), h=3)
par(mfrow=c(2,2))
plot(model1) ; plot(model2)
plot(model3) ; plot(model4)</pre>
```

Fit and evaluate different exponential smoothing models

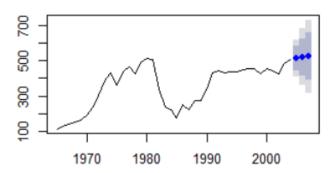
Forecasts from Simple exponential smoothing



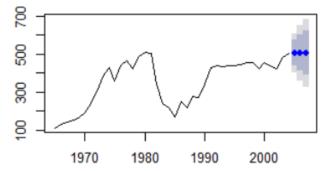
Forecasts from Holt's method



Forecasts from Damped Holt's method



Forecasts from ETS(A,N,N)







```
#Insample accuracy
mse_in1 <- mean((oildata_train - model1$fitted)^2)
mse_in2 <- mean((oildata_train - model2$fitted)^2)
mse_in3 <- mean((oildata_train - model3$fitted)^2)
mse_in4 <- mean((oildata_train - model4$fitted)^2)
#Outsample accuracy
mse_out1 <- mean((oildata_test - model1$mean)^2)
mse_out2 <- mean((oildata_test - model2$mean)^2)
mse_out3 <- mean((oildata_test - model3$mean)^2)
mse_out4 <- mean((oildata_test - model3$mean)^2)
c(mse_in1, mse_in2, mse_in3, mse_in4)
c(mse_out1, mse_out2, mse_out3, mse_out4)</pre>
```

```
SES Holt Damped ETS

> c(mse_in1, mse_in2, mse_in3, mse_in4)
[1] 2630.445 2557.511 2563.338 2630.445

> c(mse_out1, mse_out2, mse_out3, mse_out4)
[1] 212.6920 665.8960 348.9897 212.6920
```

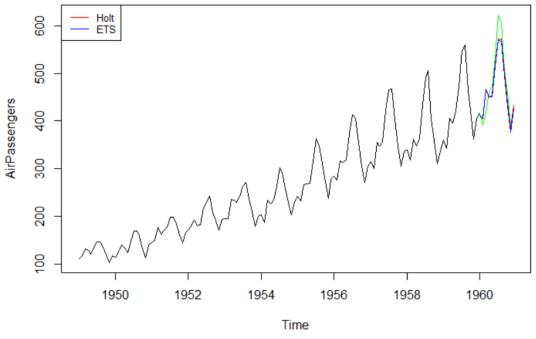
- Holt is considered the most accurate model (based on in-sample data) but SES works much better for the out-of-sample data
- SES is correctly identified by ETS as the most appropriate model for automatic forecasting





Exponential Smoothing for Seasonal Time Series

```
#Seasonal ts
insample <- window(AirPassengers, start=c(1949,1), end=c(1959,12))
outsample <- window(AirPassengers, start=c(1960,1), end=c(1960,12))
SI <- decompose(insample, type="multiplicative") $seasonal
Dy <- insample/SI
frc1 <- holt(Dy, h=12)$mean*as.numeric(tail(SI,12))</pre>
frc2 <- forecast(ets(insample), h=12)$mean</pre>
plot(AirPassengers)
lines(outsample, col="green")
lines(frc1, col="red")
lines(frc2, col="blue")
legend("topleft", legend=c("Holt", "ETS"),
       col=c("red", "blue"), lty=1, cex=0.8)
mean((outsample - frc1)\(^2\)
mean((outsample - frc2)∧2)
                                 > mean((outsample - frc1)^2)
                                 [1] 618.7616
                                 > mean((outsample - frc2)^2)
                                 [1] 750.6526
```







The Theta method

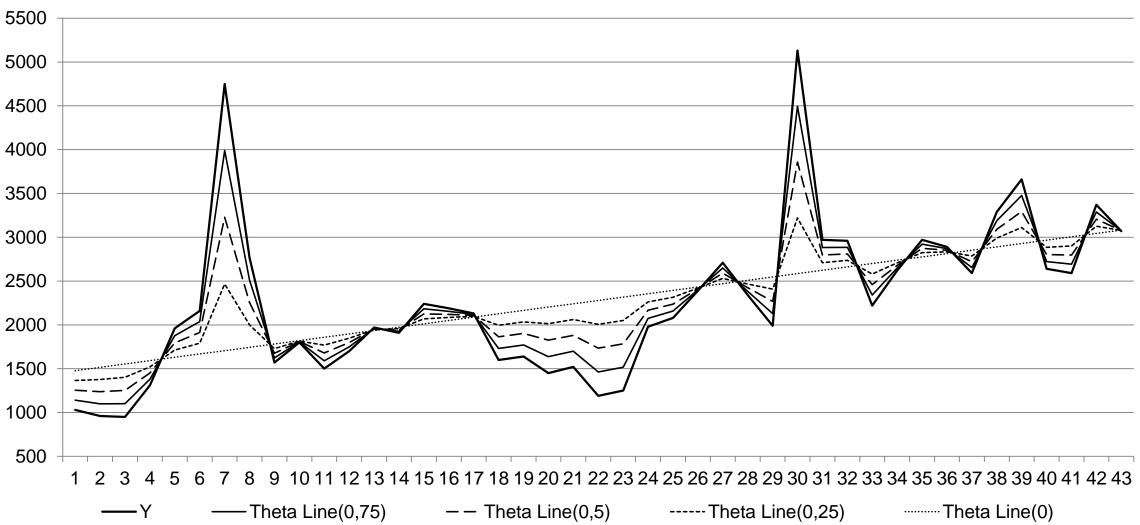
- Introduced by Assimakopoulos & Nikolopoulos (2000)
- The winner of the M3 competition and, for more than 20 years, an unbeatable benchmark
- Probably the most accurate statistical forecasting method till now
- A **univariate** forecasting method based on time series decomposition (θ *transformation*)
- Theta transformation can be used to create various **Theta lines** of the same trend but different curvature to that of the original data
- Different Theta lines can be used to highlight different time series characteristics, like level and trend.
- Also known as "SES with drift"*





Theta lines (1/3)

Emphasize **long-term** characteristics for **0<θ<1**

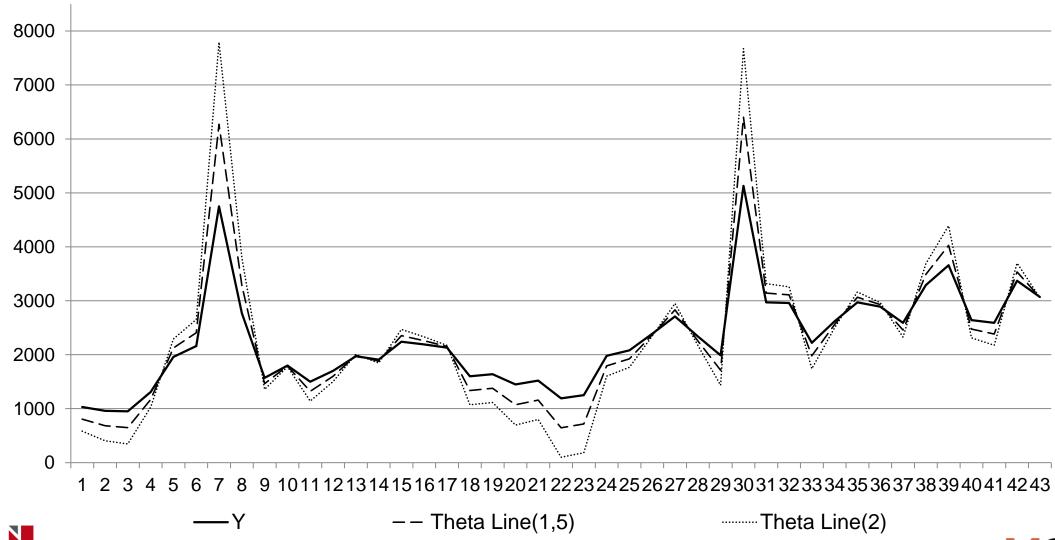






Theta lines (2/3)

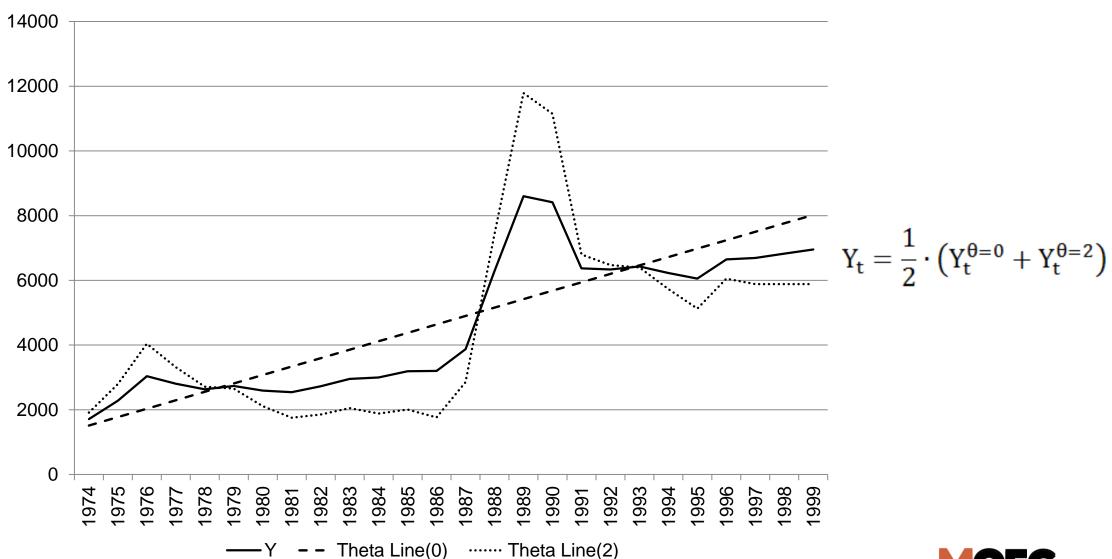
Emphasize **short-term** characteristics for $\theta>1$







Theta lines (3/3)







Classic Theta (1/2)

Step 1. Seasonality test

90% confidence

- Step 2. Deseasonalization (if needed)
- Step 3. Theta decomposition Create Theta lines

Two Theta lines of θ =0 and θ =2

Step 4. Forecasting

Theta line (0) using linear regression in time and Theta line (2) using SES

Step 5. Combine

Equal weights

Step 6. Reseasonalization (if needed)

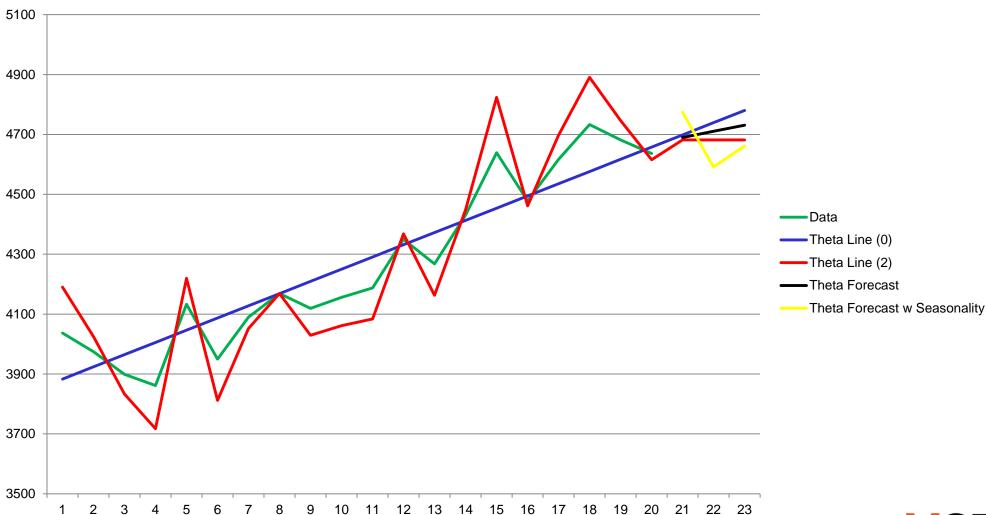
Theta Line(θ) = θ x Data + (1- θ) x LRL

- Theta Line(0) = LRL
- Theta Line(2) = 2 x Data LRL





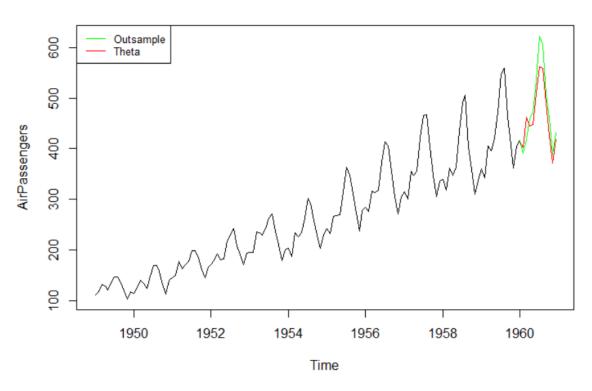
Classic Theta (2/2)







Theta in R







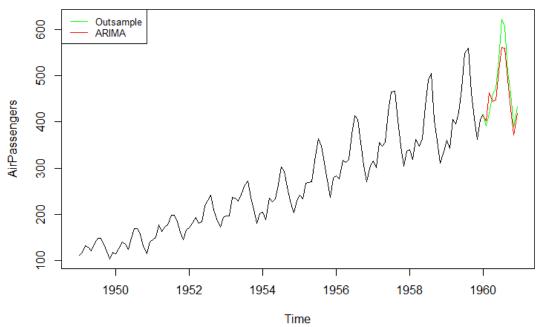
ARIMA models

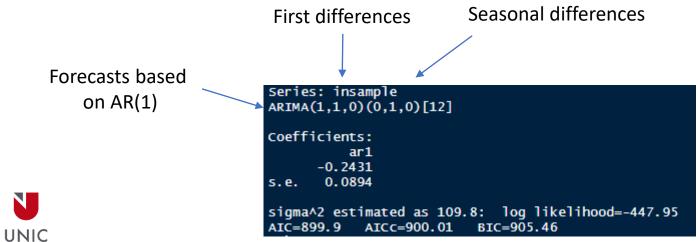
- In auto-regression (AR) models, we forecast the variable of interest using a linear combination of past values of the variable. So, AR models perform a regression of the variable against itself.
- In moving averages (MA) models, forecast errors are used in a regression instead of the past values of the forecast variable
- AR and MA models can be effectively combined (ARMA models) to account both for auto-correlations and past errors
- Given that ARMA models do not capture seasonality and trend, first differences and seasonal differences can be used within ARMA models to account for such systematic variations. These are the ARIMA models





ARIMA models

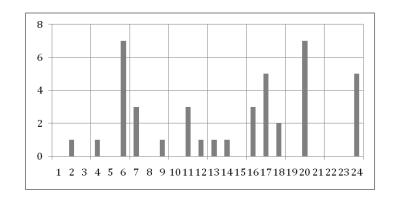




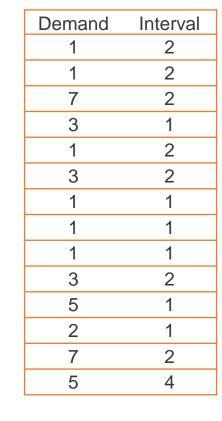


Croston's method

t	Y _t	t	Y _t
1	0	13	1
2	1	14	1
3	0	15	0
4	1	16	3
5	0	17	5
6	7	18	2
7	3	19	0
8	0	20	7
9	1	21	0
10	0	22	0
11	3	23	0
12	1	24	5



Each component is predicted using SES



$$F = \frac{F_{Demand}}{F_{Interval}}$$

There are also many variants of the Croston's method, like SBA, SBJ and TSB, that mitigate the biases of the originally proposed method





Croston's method

```
library(tsintermittent)
insample <- head(ts.data2, 20)
outsample <- tail(ts.data2, 4)
Croston <- ts(crost(insample, type="croston",h=4)$frc.out, start = start(outsample), frequency = 12)
SBA <- ts(crost(insample, type="sba",h=4)$frc.out, start = start(outsample), frequency = 12)
TSB <- ts(tsb(insample,h=4)$frc.out, start = start(outsample), frequency = 12)
```

plot(ts.data2)
lines(Croston, col="blue")
lines(SBA, col="red")
lines(TSB, col="green")

