

High-performance earth system modelling in pure Python

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What is Veros?

The versatile ocean simulator.

- Translation of PyOM2 (Fortan GCM) & MOBI (biogeochemistry) to Python
- Full 3D primitive equations
- Finite difference discretization on Arakawa C grid
- Runs on your laptop, gaming PC (GPU), or cluster
- Idealized and realistic setups
- Accessible, verifiable, adaptable

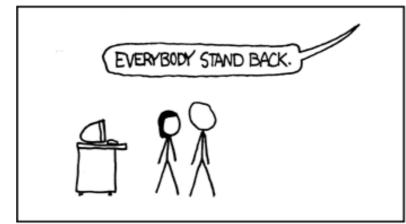
Why Python?

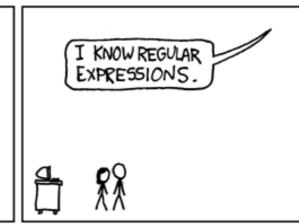
- Your time is more valuable than your computer's
 - Code is part of the user experience
 - Better abstraction, thus higher signal-to-noise ratio
- Interfaceability with scientific Python ecosystem:
 - Internal: Linear algebra, I/O
 - External: Machine learning, orchestration, hybrid models, data pipelines
- People seem to enjoy it

Fortran to Python

xkcd.com/208/

do i=js_pe-1,je_pe





Search:

do
$$(\w) = ((\w|[\+\-]) +, (\w|[\+\-]) +) /$$

Replace:

```
for \1 in range(\2):
```

for i in range(is_pe-1, ie_pe):

Python to NumPy

Straightforward

```
vs.flux_east[1:-2, 2:-2,:] = \
    0.25 * (vs.u[1:-2, 2:-2, :, vs.tau] + vs.u[2:-1, 2:-2, :, vs.tau]) \
    * (vs.utr[1:-2, 2:-2, :] + vs.utr[1:-2, 2:-2, :])
```

Python to NumPy

Intermediate

```
yt(1) = yu(1) - dyt(1) * 0.5
do i = 2, n
    yt(i) = 2*yu(i-1) - yt(i-1)
enddo
```

```
yt[0] = yu[0] - dyt[0] * 0.5
yt[1:] = 2 * yu[:-1]

alternating_pattern = np.ones_like(yt)
alternating_pattern[::2] = -1
yt[...] = alternating_pattern * np.cumsum(alternating_pattern * yt)
```

Python to NumPy

Hard

```
do j=js_pe,je_pe
  do i=is_pe,ie_pe
    k=kbot(i,j)
    if (k>0.and.k<nz) then
       eke_lee_flux(i,j)=c_lee(i,j)*eke(i,j,k,taup1)*dzw(k)
       endif
  enddo
enddo</pre>
```



Demo

A simple 4x4 degree setup

```
In [3]: from veros.setup.global_flexible import GlobalFlexibleResolutionSetup
        class EGUSetup(GlobalFlexibleResolutionSetup):
            min_depth = 50
            def set_parameter(self, vs):
                super().set_parameter(vs)
                vs.nx = 90
                vs.ny = 40
                vs.nz = 15
                vs.dt_tracer = 86400
                vs.dt_mom = 1800
                vs.diskless_mode = True
            def set_diagnostics(self, vs):
                pass
```

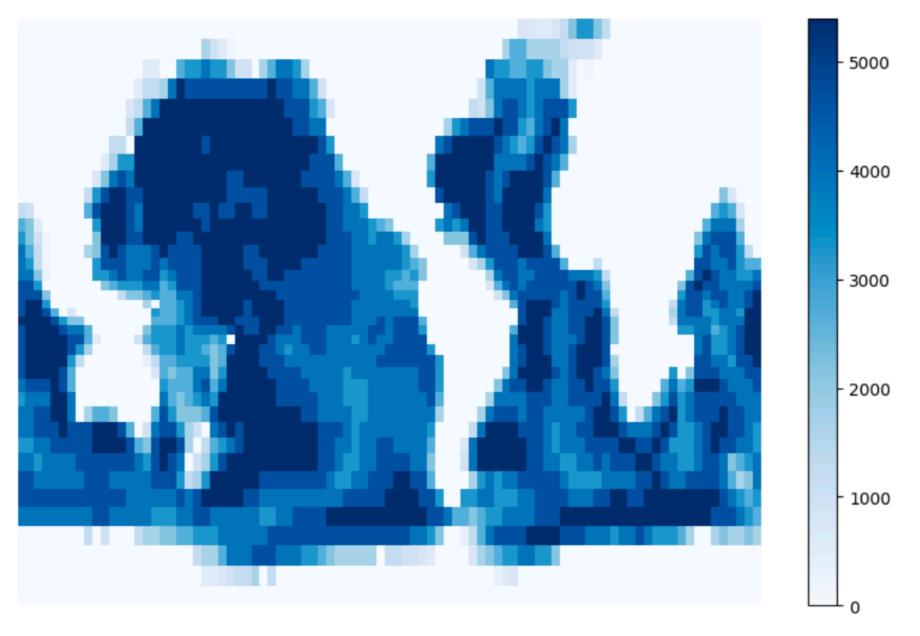
```
In [4]: sim = EGUSetup()
sim.setup()
```

Setting up everything
Initializing streamfunction method
determining number of land masses

Land mass and perimeter

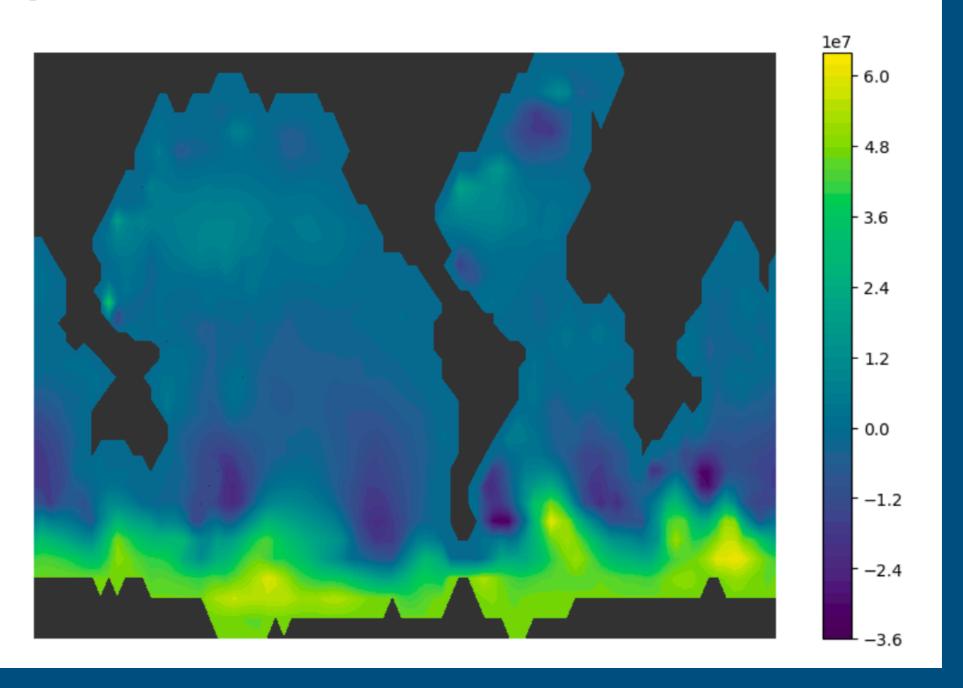
```
0
5
10
15
20
25
30
35
40
45
50
55
60
65
 70
 75
 80
 85
 90
```

```
In [5]: vs = sim.state
In [6]: coords = np.meshgrid(vs.xt[2:-2], vs.yt[2:-2], indexing='ij')
In [7]: plt.pcolormesh(*coords, vs.ht[2:-2, 2:-2], cmap='Blues')
    plt.axis('off')
    plt.colorbar();
```



```
In [8]: vs.runlen = 86400 * 20
In [9]: sim.run()
        Starting integration for 20.0 days
        Current iteration: 1
        Current iteration: 2
        Current iteration: 3
        Current iteration: 4
        Current iteration: 5
        Current iteration: 6
        Current iteration: 7
        Current iteration: 8
        Current iteration: 9
        Current iteration: 10
        Current iteration: 11
        Current iteration: 12
        Current iteration: 13
        Current iteration: 14
        Current iteration: 15
        Current iteration: 16
        Current iteration: 17
        Current iteration: 18
        Current iteration: 19
        Current iteration: 20
```

Out[10]: <matplotlib.colorbar.Colorbar at 0x132700d30>

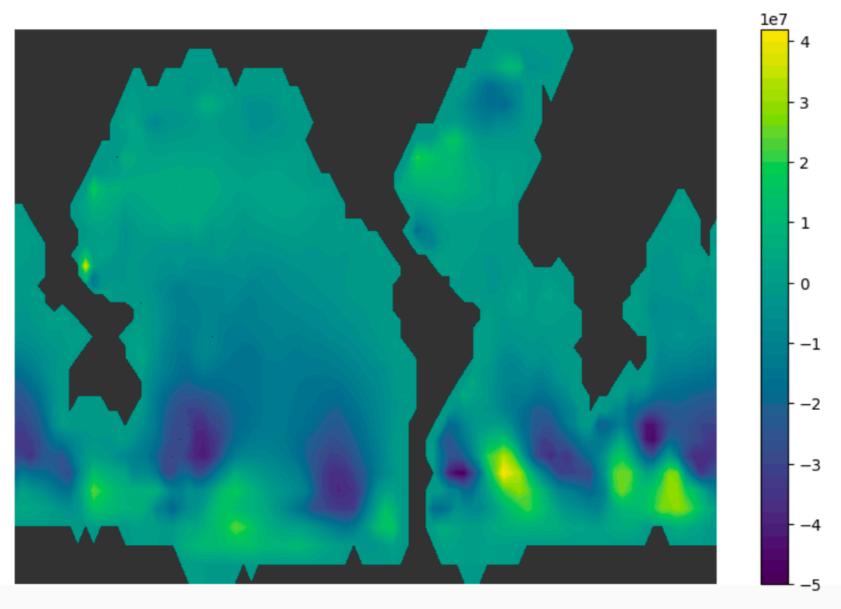


Let's modify that!

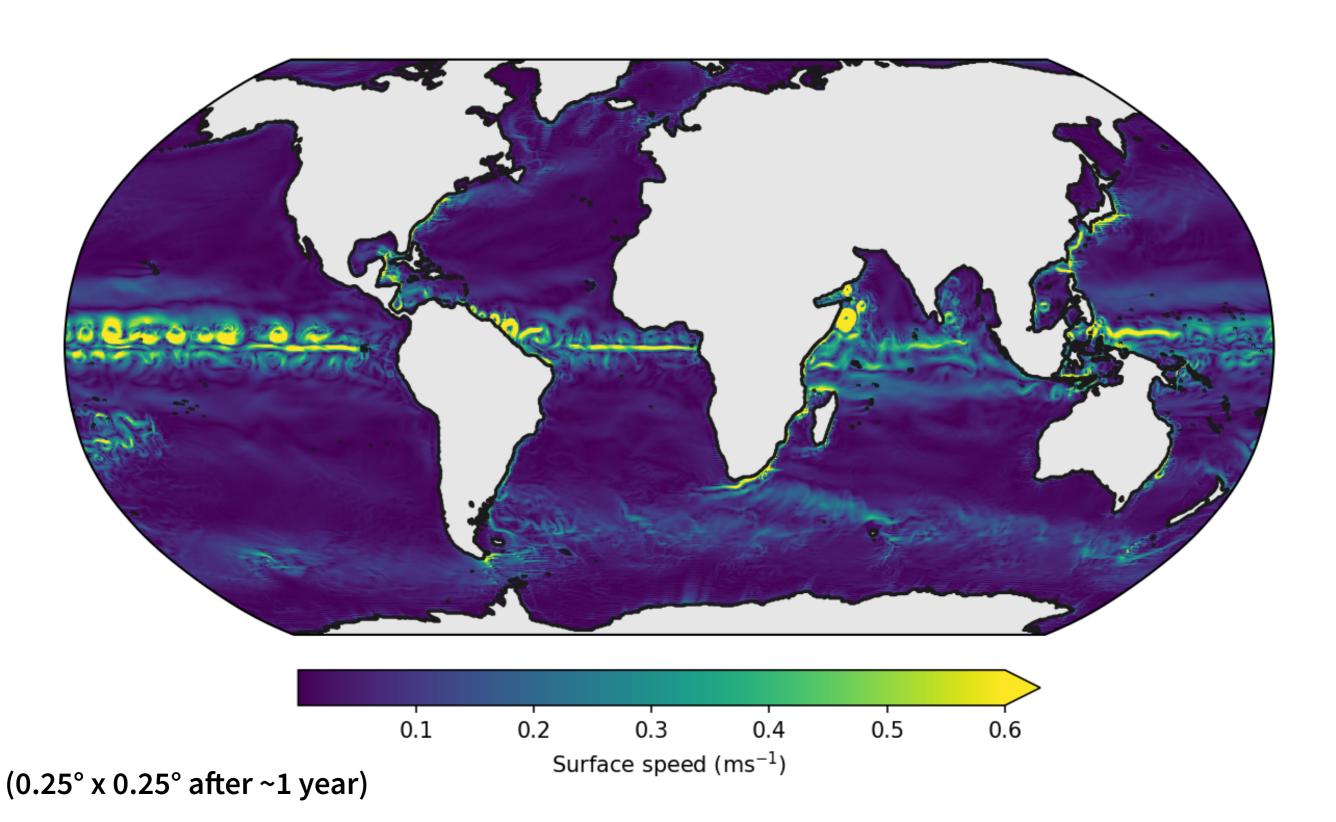
```
In [11]:
         class ModifiedEGUSetup(GlobalFlexibleResolutionSetup):
             min_depth = 50
             def set_parameter(self, vs):
                 super().set_parameter(vs)
                 vs.nx = 90
                 vs.ny = 40
                 vs.nz = 15
                 vs.dt_tracer = 86400
                 vs.dt mom = 1800
                 vs.runlen = 86400 * 20
                 vs.diskless_mode = True
                                                     close Drake passage
             def set_topography(self, vs):
                 super().set_topography(vs)
                 vs.kbot[52:55, 3:8] = 0
             def set_diagnostics(self, vs):
                 pass
```

```
In [15]: vs = sim2.state

cs = plt.contourf(
    *coords,
    vs.psi[2:-2, 2:-2, vs.tau],
    50
)
plt.contourf(
    *coords,
    vs.maskT[2:-2, 2:-2, -1],
    [-1e-3, 1e-3],
    colors='0.2'
)
plt.axis('off')
plt.colorbar(cs);
```



High-resolution setups



Provides a JIT compiler for NumPy code

```
import bohrium as np
a = np.ones((100, 100))
a.sum()
```

Provides a JIT compiler for NumPy code

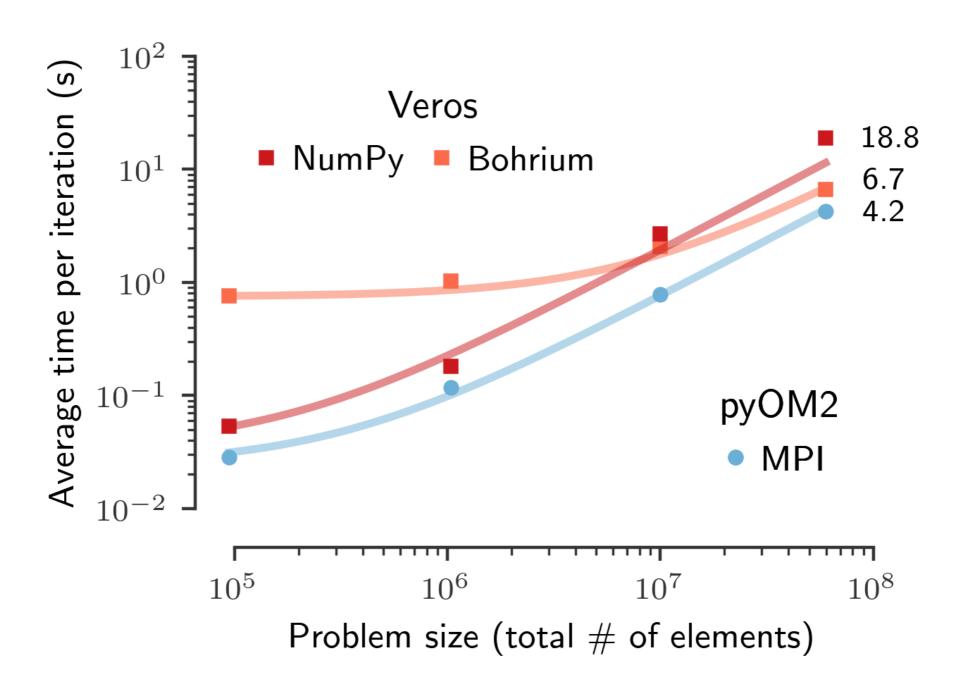
```
#include <stdint.h>
#include <stdlib.h>
#include <stdbool.h>
#include <complex.h>
#include <tgmath.h>
#include <math.h>
void execute(double* restrict a0, uint64 t vo0, uint64 t vs0 0, uint64 t vs0 1,
             uint64 t vo1, uint64 t vs1 0, const double c1) {
    double t2;
    t2 = 0;
    #pragma omp parallel for reduction(+:t2)
    for(uint64 t i0 = 0; i0 < 100; ++i0) {
        double t1;
        t1 = 0;
        #pragma omp simd reduction(+:t1)
        for(uint64 t i1 = 0; i1 < 100; ++i1) {
            const uint64 t idx0= (vo0 +i0*vs0 0 +i1*vs0 1);
           a0[idx0] = c1;
           t1 += a0[idx0];
        t2 += t1;
void launcher(void* data list[], uint64 t offset strides[], union dtype constants[]) {
    double *a0 = data list[0];
    execute(a0, offset strides[0], offset strides[1], offset strides[2],
            offset strides[3], offset strides[4], constants[0].BH FLOAT64);
```

Provides a JIT compiler for NumPy code

```
#pragma OPENCL EXTENSION cl khr fp64 : enable
#include <kernel dependencies/complex opencl.h>
#include <kernel dependencies/integer operations.h>
  kernel void execute( global double* restrict a0, global double* restrict a1,
                      ulong vo0, ulong vs0 0, ulong vs0 1, ulong vo1, ulong vs1 0,
                      const double c1) {
    // The IDs of the threaded blocks:
    const uint q0 = qet qlobal id(0); if <math>(q0 >= 100) { return; } // Prevent overflow
    {const ulong i0 = g0;
        double s1;
        s1 = 0;
        for (ulong i1 = 0; i1 < 100; ++i1) {
            const ulong idx0 = (vo0 + i0*vs0 0 + i1*vs0 1);
            a0[idx0] = c1;
            s1 += a0[idx0];
        a1[vo1 + i0*vs1 0] = s1;
```

Benchmarks

4 nodes (64 CPU cores)



(lower is better)

Our vision I

Modern HPC

- Scale horizontally and vertically
- Native GPU and FPGA support
- Exploit new HPC research as it happens

API Draft

Our vision II

Leverage the Python ecosystem

Let's unify pre-processing, modelling, post-processing:

```
>>> data = sim.state.to xarray()
<xarray.Dataset>
Dimensions:
                       (Time: 2, xt: 90, xu: 90, yt: 40, yu: 40, zt: 15, zw: 15)
Coordinates:
  * Time
                       (Time) float64 15.0 30.0
                       (xt) float64 2.0 6.0 10.0 14.0 ... 350.0 354.0 358.0
  * xt
                       (xu) float64 4.0 8.0 12.0 16.0 ... 352.0 356.0 360.0
  * xu
                       (yt) float64 -78.0 -74.0 -70.0 -66.0 ... 70.0 74.0 78.0
  * yt
                       (yu) float64 -76.0 -72.0 -68.0 -64.0 ... 72.0 76.0 80.0
  * yu
                       (zt) float64 -4.855e+03 -4.165e+03 ... -65.0 -35.0
                       (zw) float64 -4.51e+03 -3.87e+03 -3.28e+03 ... -50.0 0.0
  * ZW
Data variables:
   E iw
                       (Time, zw, yt, xt) float64 ...
    НД
                       (Time, zt, yt, xt) float64 ...
                       (Time, zw, yt, xt) float64 ...
    Nsqr
                       (yt, xt) float64 ...
    area t
>>> data['psi'].sel(Time=30).plot()
```

Our vision II

Leverage the Python ecosystem

- Dynamic model execution:
 - Hybrid models
 - Ensembles / sensitivity studies via machine learning (e.g. Bayesian optimization)

Our vision III

Cut out the boring parts

```
vs.flux_east[1:-2, 2:-2,:] = \
    0.25 * (vs.u[1:-2, 2:-2, :, vs.tau] + vs.u[2:-1, 2:-2, :, vs.tau]) \
    * (vs.utr[1:-2, 2:-2, :] + vs.utr[1:-2, 2:-2, :])
```

Abstraction

```
vs.flux_east.update(
    on('t', vs.u[..., vs.tau]) * on('t', vs.utr)
)
```

Our vision:

A high-level, high-performance earth system model

Thank you for listening

Find these slides:

github.com/dionhaefner/veros-egu-2019

Learn more:

veros.readthedocs.org

Contribute:

github.com/dionhaefner/veros

Give love to:

github.com/bh107/bohrium

References

- (1) Häfner, Dion, et al. "Veros v0. 1–a fast and versatile ocean simulator in pure Python." *Geoscientific Model Development* 11.8 (2018): 3299-3312.
- (2) Muglia, Juan, et al. "Combined effects of atmospheric and seafloor iron fluxes to the glacial ocean." *Paleoceanography and Paleoclimatology* 32.11 (2017): 1204-1218.
- (3) Eden, Carsten (2016). "Closing the energy cycle in an ocean model". In: *Ocean Modelling* 101
- (4) Kristensen, Mads RB, et al. (2013). "Bohrium: un-modified NumPy code on CPU, GPU, and cluster". In: *Python for High Performance and Scientific Computing (PyHPC 2013)*.
- (5) Larsen, Mads Ohm et al. (2016). "Current Status and Directions for the Bohrium Runtime System". In: *Compilers for Parallel Computing 2016.*

Bonus slides

A simple example

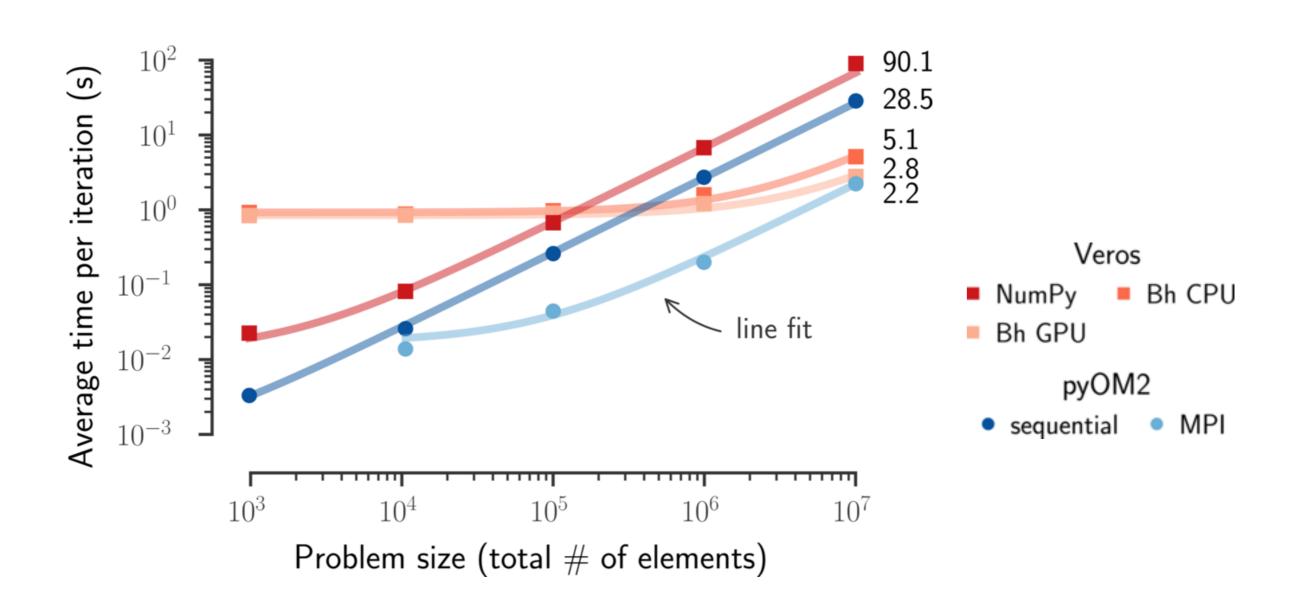
```
In [1]:
        import time
        import numpy as np
In [2]: a = np.random.rand(10000, 10000)
        def bench():
            b = a ** 2
            c = a * b
            d = c * np.sum(a, axis=1)[:, None] - a ** 3 + 17.2
            e = np.sum(a + b + c + d)
             return e
In [3]: while True:
            start = time.time()
            res = bench()
            end = time.time()
            print("result: {:.2e}; time: {:.2f}s".format(float(res), end-state)
        result: 1.27e+11; time: 9.02s
        result: 1.27e+11; time: 9.01s
        result: 1.27e+11; time: 9.00s
        result: 1.27e+11; time: 9.01s
        result: 1.27e+11; time: 9.00s
        result: 1.27e+11; time: 9.00s
```

A simple example

```
In [6]: import bohrium as np
In [7]: a = np.random.rand(10000, 10000)
        def bench():
            b = a ** 2
            c = a * b
            d = c * np.sum(a, axis=1)[:, None] - a ** 3 + 17.2
            e = np.sum(a + b + c + d)
            return e
In [8]: while True:
            start = time.time()
            res = bench()
            try:
                np.flush()
            except AttributeError:
                pass
            end = time.time()
            print("result: {:.2e}; time: {:.2f}s".format(float(res), end-state)
        result: 1.27e+11; time: 1.05s
        result: 1.27e+11; time: 0.55s
        result: 1.27e+11; time: 0.54s
        result: 1.27e+11; time: 0.55s
        result: 1.27e+11; time: 0.54s
```

Benchmarks

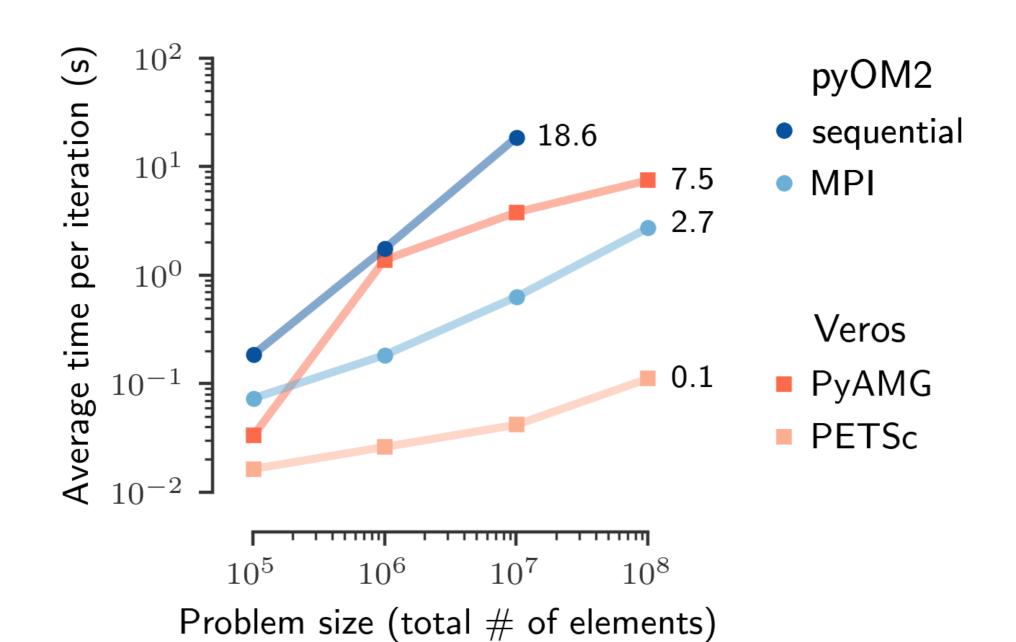
Cluster node with GPU (24 cores + NVIDIA Tesla P100)



(lower is better)

Benchmarks

Streamfunction solver



(lower is better)

Biogeochemistry

