# 106119029, Algos Lab $8 ({\rm Matrix~Chain~Multiplication})$

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## Question 1

• Given a sequence of matrices such that any matrix may be multiplied by the previous matrix, write a program to find the best association such that the result is obtained with the minimum number of arithmetic operations.

#### $\mathbf{Code}$

```
#include <algorithm>
#include <iomanip>
 2 #include <iostream>
3 #include <numeric>
4 #include <sstream>
5 #include <string>
6 #include <string_view>
7 #include <unordered_map>
12 #define INF INT32 MAX
  retuin;
}
for (int k = i; k < j; k++) {
    solve_rec(m, s, mats, i, k);
    solve_rec(m, s, mats, k + 1, j);
    if (m[i][j] > m[i][k] + m[k + 1][j] + mats[i - 1] * mats[k] * mats[j]) {
        s[i][j] = k;
        m[i][j] = m[i][k] + m[k + 1][j] + mats[i - 1] * mats[k] * mats[j];
}
 void print_parens(vector<vector<int>>> &s, int i, int j) {
     std::cout << "(";
  print_parens(s, i, s[i][j]);
  print_parens(s, s[i][j] + 1, j);
  std::cout << ")";</pre>
   string print_elem(int elem) { return elem == INF ? "INF" : to_string(elem); }
```

#### Question 2

• Which programming paradigm will be useful for you and why?

Dynamic Programming is the programming paradigm that will be useful to solve this problem.

if we have four matrices ABCD, we compute the cost required to find each of (A)(BCD), (AB)(CD), and (ABC)(D), making recursive calls to find the minimum cost to compute ABC, AB, CD, and BCD. We then choose the best one.

However, this algorithm has exponential runtime complexity making it as inefficient as the naive approach of trying all permutations. The reason is that the algorithm does a lot of redundant work. For example, above we made a recursive call to find the best cost for computing both ABC and AB. But finding the best cost for computing ABC also requires finding the best cost for AB. As the recursion grows deeper, more and more of this type of unnecessary repetition occurs.

One simple solution is called memoization: each time we compute the

minimum cost needed to multiply out a specific subsequence, we save it. If we are ever asked to compute it again, we simply give the saved answer, and do not recompute it. Since there are about  $n^2/2$  different subsequences, where n is the number of matrices, the space required to do this is reasonable. It can be shown that this simple trick brings the runtime down to  $O(n^3)$  from  $O(2^n)$ , which is more than efficient enough for real applications. This is top-down dynamic programming.

## Question 3

• Show the stepwise execution(e.g. tabular structure) of your programfor three different set of inputs (varying both the number of matrices in the chain and the dimension of the matrices).

#### Output

```
Resultant Matrix m:
           INF
Resultant Matrix
           TNF
                      TNF
TNF
           INF
INF
                      INF
FOR dimensions: 46 32 55 53 35
204160
(A1((A2A3)A4))
Resultant Matrix m:
           TNF
                      INF
                                  INF
                                             204160
152640
                      80960
                                 171296
93280
INF
           INF
INF
INF
                                  INF
Resultant Matrix
                      TNF
                                  TNF
                                             TNF
TNF
           TNF
INF
           INF
INF
           INF
                      INF
                                  INF
INF
           INF
GOR dimensions: 62 47 79 29 81 23 70
358961
((A1(A2(A3(A4A5))))A6)
Resultant Matrix m:
                       INF
                       230206
                                              218080
INF
           INF
                       INF
                                              185571
                                                                      233910
                                   INF
                                                          54027
                                              INF
                                                         0
INF
INF
           INF
                       INF
                                   INF
                                                                      130410
                       TNF
                                   INF
INF
           INF
                                              INF
Resultant Matrix
INF
                       INF
                                   INF
           INF
                                              INF
                                                          INF
                                                                     INF
INF
           INF
INF
                       INF
INF
                       INF
INF
                                                                     INF
TNF
           INF
                       INF
                                              TNF
                                                          INF
                                   INF
```

### Question 4

• Find the worst case time and space complexity of your program and tally theoretically.

Space Complexity for this dp approach is pretty straight forward  $n^2$ , as we only need a matrix to store the computations.

Time complexity for this approach is  $O(n^3)$ . This isnt that obvious from the top down dp approach but when we find out the dependencies and make it a bottom up algorithm, it is obvious. The bottom up approach is done in  $solve_non_rec$  function in my code. One way to reason about this is, we are trying to fill a N X N matrix and to get the value of each of

the cell, we must do O(N) work (calculation of the minimum multiplication costs from all possible splits). To find out m[i][j], we must find the cost of splitting (i,j) at all k, i <k<j and take the minimum of those. Hence we can say it is a  $\mathrm{O}(N^3)$  algorithm.