

Minimum Spanning Tree

A minimum spanning tree (MST) or minimum weight spanning tree is a subset of the edges of a **connected**, edge-weighted **undirected** graph that **connects all the vertices together**, without any cycles and with the minimum possible total edge weight. That is, it is a spanning tree whose sum of edge weights is as small as possible. More generally, any edge-weighted undirected graph (not necessarily connected) has a minimum spanning forest, which is a union of the minimum spanning trees for its connected components.

Kruskal's Algorithm:

- Sort the graph edges with respect to their weights.
- Start adding edges to the MST from the edge with the smallest weight until the edge of the largest weight.
- Only add edges which doesn't form a cycle, edges which connect only disconnected components. We will use **Disjoint Sets** here.

```
using namespace std;
const int MAX = 1e4 + 5;
int id[MAX], nodes, edges;
pair<long long, pair<int, int>> > p[MAX];
// pair <cost, pair<u, v>> p[MAX]
// we'll have to sort based on cost, and therefore this way of storing data

void initialize()
{
    for(int i = 0; i < MAX; ++i) id[i] = i;
    // initially 'i' is the parent of itself.
}

int root(int x)
{
    while(id[x] != x)
    {
        id[x] = id[id[x]];
        x = id[x];
    }
    return x;
}

void union1(int x, int y)
{
    int p = root(x);
    int q = root(y);
    id[p] = id[q];
}

long long kruskal(pair<long long, pair<int, int>> > p[])
{
    int x, y;
    long long cost, minimumCost = 0;
    for(int i = 0; i < edges; ++i)
    {
        // Selecting edges one by one in increasing order from the beginning
        x = p[i].second.first;
        y = p[i].second.second;
        cost = p[i].first;
        // Check if the selected edge is creating a cycle or not
        if(root(x) != root(y))
        {
            minimumCost += cost;
            union1(x, y);
        }
    }
}
```

```

    }
    return minimumCost;
}

int main()
{
    int x, y;
    long long weight, cost, minimumCost;
    initialize();
    cin >> nodes >> edges;
    for(int i = 0; i < edges; ++i)
    {
        cin >> x >> y >> weight;
        p[i] = make_pair(weight, make_pair(x, y));
    }
    // Sort the edges in the ascending order
    sort(p, p + edges);
    minimumCost = kruskal(p);
    cout << minimumCost << endl;
    return 0;
}

```

Time Complexity: In Kruskal's algorithm, most time consuming operation is sorting because the total complexity of the Disjoint-Set operations will be $O(E \times \log V)$, which is the overall Time Complexity of the algorithm.

Prim's Algorithm

```

using namespace std;
const int MAX = 1e4 + 5;
typedef pair<long long, int> PII;
bool marked[MAX];
vector<PII> adj[MAX];

long long prim(int x)
{
    priority_queue<PII, vector<PII>, greater<PII> > Q;
    int y;
    long long minimumCost = 0;
    PII p;
    Q.push(make_pair(0, x));
    while(!Q.empty())
    {
        // Select the edge with minimum weight
        p = Q.top();
        Q.pop();
        x = p.second;
        // Checking for cycle
        if(marked[x] == true)
            continue;
        minimumCost += p.first;
        marked[x] = true;
        for(int i = 0; i < adj[x].size(); ++i)
        {
            y = adj[x][i].second;
            if(marked[y] == false)
                Q.push(adj[x][i]);
        }
    }
    return minimumCost;
}

int main()

```

```

{
    int nodes, edges, x, y;
    long long weight, minimumCost;
    cin >> nodes >> edges;
    for(int i = 0; i < edges; ++i)
    {
        cin >> x >> y >> weight;
        adj[x].push_back(make_pair(weight, y));
        adj[y].push_back(make_pair(weight, x));
    }
    // Selecting 1 as the starting node
    minimumCost = prim(1);
    cout << minimumCost << endl;
    return 0;
}

```

Time Complexity: The time complexity of the Prim's Algorithm is $O((V + E)\log V)$ because each vertex is inserted in the priority queue only once and insertion in priority queue take logarithmic time.

Use Case: Use Prim's algorithm when you have a graph with lots of edges. For a graph with V vertices E edges, Kruskal's algorithm runs in $O(E\log V)$ time and Prim's algorithm can run in $O(E + V\log V)$ **amortized** time, if you use a **Fibonacci Heap**. Prim's algorithm is significantly faster in the limit when you've got a really dense graph with many more edges than vertices. Kruskal performs better in typical situations (sparse graphs) because it uses simpler data structures.