

camera

dimensions: {instrument}

storage class: Camera

cpFlatStatistics

dimensions: {detector, exposure}

storage class: PropertyList

cpFlatNormalize

lsst.cp.pipe.cpFlatMeasure.CpFlatNormalizationTask

dimensions: {physical_filter}

cpFlatNormalizeScales

dimensions: {physical_filter}

storage class: StructuredDataDict